

#Q1

$eq := \text{diff}(u(x), x^2) - \text{diff}(u(x), x) - 6 \cdot u(x) = -18 \cdot \sin(x);$

$$eq := \frac{d^2}{dx^2} u(x) - \frac{d}{dx} u(x) - 6 u(x) = -18 \sin(x) \quad (1)$$

#a) bounded sol = Find a particular solution $u(x)$ that doesn't go to $\pm \infty$ as $x \rightarrow \pm \infty$.

$sol1 := \text{dsolve}(eq, u(x));$

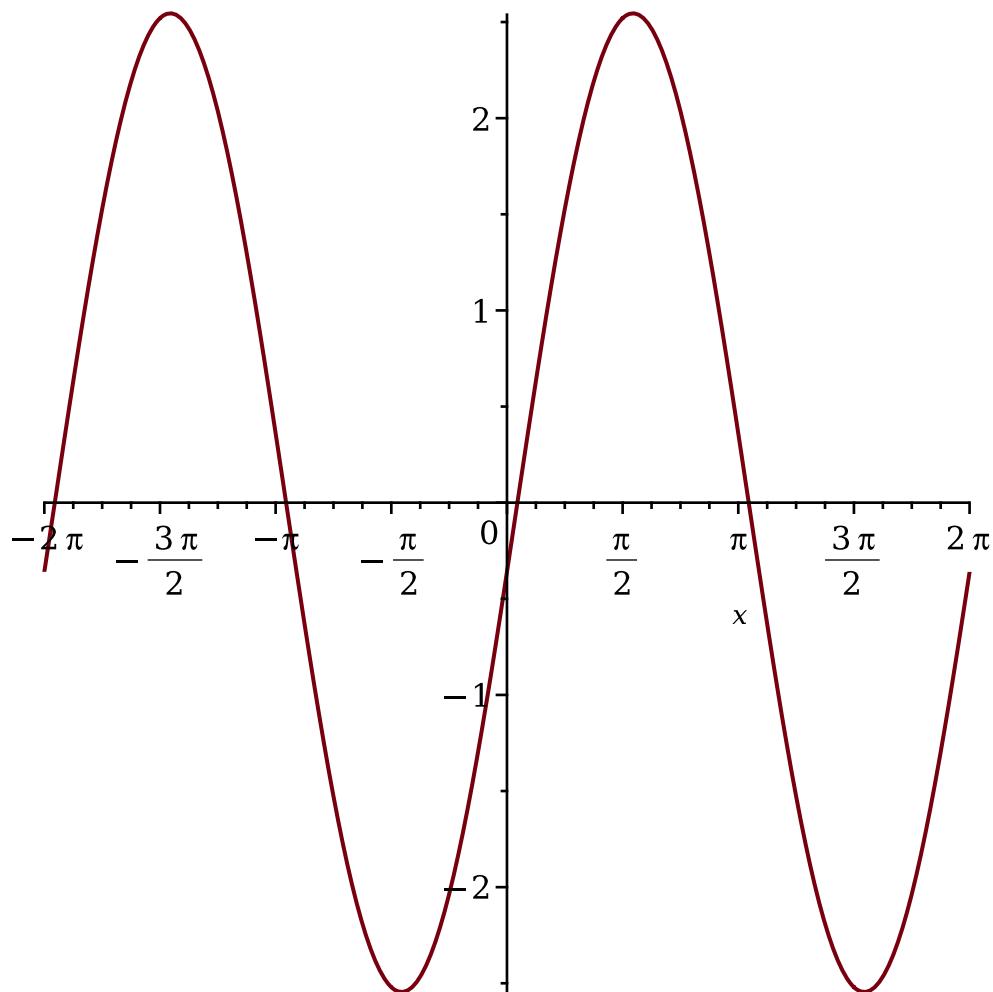
$$sol1 := u(x) = e^{-2x} c_2 + e^{3x} c_1 - \frac{9 \cos(x)}{25} + \frac{63 \sin(x)}{25} \quad (2)$$

$ps := \text{subs}(\{c_1 = 0, c_2 = 0\}, sol1);$

$$ps := u(x) = -\frac{9 \cos(x)}{25} + \frac{63 \sin(x)}{25} \quad (3)$$

#b)[-2·Pi,2·Pi]

$\text{plot}(\text{rhs}(ps), x = -2 \cdot \text{Pi}..2 \cdot \text{Pi});$



#c)

$$\text{evalf}(\text{subs}(x = \text{Pi} \cdot \sqrt{6}, \text{rhs}(ps)));$$

$$2.431453171 \quad (4)$$

#d)

$$\text{evalf}(\text{subs}(x = \text{Pi} \cdot \sqrt{6}, \text{diff}(-(9 \cdot \cos(x))/25 + (63 \cdot \sin(x))/25, x)));$$

$$0.7536812850 \quad (5)$$

#Q2-----

#x'=y,y'=-9x-6y,x(0)=1,y(0)=-2
with(linalg): with(VectorCalculus):
#a)

$$A := \text{Matrix}([[0, 1], [-9, -6]]);$$

$$A := \begin{bmatrix} 0 & 1 \\ -9 & -6 \end{bmatrix} \quad (6)$$

$$\det(A);$$

$$9 \quad (7)$$

#b)

$$\text{eigenvalues}(A);$$

$$-3, -3 \quad (8)$$

#c)

$$\text{MatrixExponential}(t \cdot A);$$

$$\text{MatrixExponential} \left(\begin{bmatrix} 0 & t \\ -9t & -6t \end{bmatrix} \right) \quad (9)$$

#d)

#x'=y,y'=-9x-6y,x(0)=1,y(0)=-2
eq1 := diff(x(t), t) = y(t);

$$\text{eq1} := \frac{d}{dt} x(t) = y(t) \quad (10)$$

$$\text{eq2} := \text{diff}(y(t), t) = -9 \cdot x(t) - 6 \cdot y(t);$$

$$\text{eq2} := \frac{d}{dt} y(t) = -9x(t) - 6y(t) \quad (11)$$

$$\text{ic} := x(0) = 1, y(0) = -2;$$

$$ic := x(0) = 1, y(0) = -2 \quad (12)$$

$dsolve(\{eq1, eq2, ic\}, [x(t), y(t)]);$

$$\left\{ x(t) = -\frac{e^{-3t}(-9t-9)}{9}, y(t) = e^{-3t}(-3t-2) \right\} \quad (13)$$

#e)

$Jm := Jacobian([y, -9 \cdot x - 6y], [x, y]);$

$$Jm := \begin{bmatrix} 0 & 1 \\ -9 & -6 \end{bmatrix} \quad (14)$$

$eigenvalues(Jm);$

$$-3, -3 \quad (15)$$

#stable node

#f) eigenvals are real and negative

#Q3-----

#a)

$solve(\{-x + y + x^2 = 0, y - 2 \cdot x \cdot y = 0\});$

$$\{x = 0, y = 0\}, \{x = 1, y = 0\}, \left\{x = \frac{1}{2}, y = \frac{1}{4}\right\} \quad (16)$$

#b)

$Jm1 := Jacobian([-x + y + x^2, y - 2 \cdot x \cdot y], [x, y]);$

$$Jm1 := \begin{bmatrix} 2x-1 & 1 \\ -2y & -2x+1 \end{bmatrix} \quad (17)$$

#c)

$J1 := \text{subs}([x = 1, y = 0], Jm1);$

$$J1 := \begin{bmatrix} 1 & 1 \\ 0 & -1 \end{bmatrix} \quad (18)$$

#d)

$\text{eigenvalues}(J1);$

$$1, -1 \quad (19)$$

#e)

#real part !=0 => hyperbolic

#f),g)

#saddle point,unstable

restart;

with(DEtools) :

$\text{sys} := [\text{diff}(x(t), t) = -x(t) + y(t) + x(t)^2, \text{diff}(y(t), t) = y(t) - 2 \cdot x(t) \cdot y(t)];$

$$\text{sys} := \left[\frac{d}{dt} x(t) = x(t)^2 - x(t) + y(t), \frac{d}{dt} y(t) = y(t) - 2 x(t) y(t) \right] \quad (20)$$

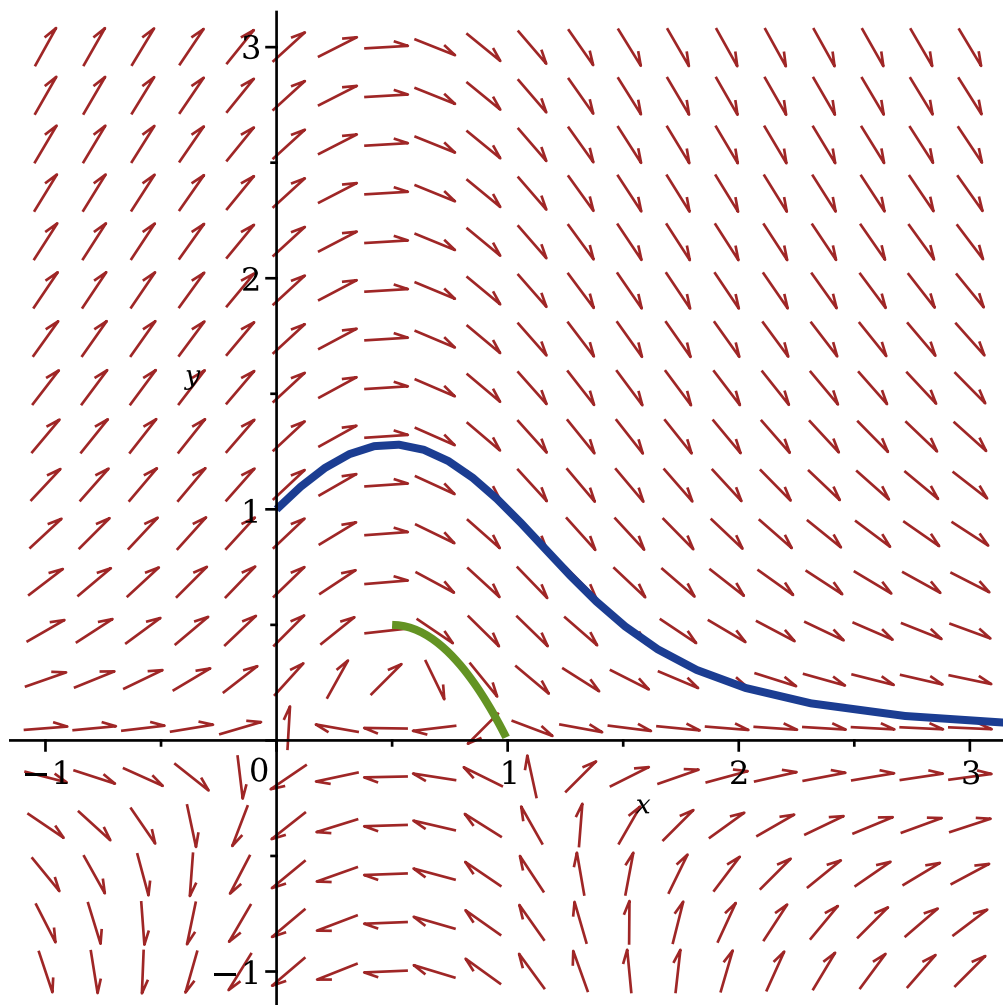
$IC1 := [x(0) = 0, y(0) = 1];$

$$IC1 := [x(0) = 0, y(0) = 1] \quad (21)$$

$IC2 := [x(0) = 0.5, y(0) = 0.5];$

$$IC2 := [x(0) = 0.5, y(0) = 0.5] \quad (22)$$

$\text{DEplot}(\text{sys}, [x(t), y(t)], t = 0 .. 5, [IC1, IC2], x = -1 .. 3, y = -1 .. 3,);$



#Q4-----

$$\#y' = y^2 - x^2 + 2$$

$$xx := 0; y := 1$$

$$xx := 0$$

$$y := 1 \quad (23)$$

$$h := 0.02;$$

$$h := 0.02 \quad (24)$$

$$f := (x, y) \mapsto y^2 - x^2 + 2;$$

$$f := (x, y) \mapsto y^2 - x^2 + 2 \quad (25)$$

$$\text{phi} := \text{dsolve}(\{ \text{diff}(y(x), x) = f(x, y(x)), y(0) = 1 \});$$

Error, (in dsolve) required an indication of the solving variables for the given system
 restart

restart;

$f := (x, y) \mapsto y^2 - x^2 + 2;$

$f := (x, y) \mapsto y^2 - x^2 + 2$ (26)

$h := 0.02; x := 1; y := 0;$

$h := 0.02$

$x := 1$

$y := 0$

(27)

#in [1, 2]

#length: 2-1 = 1

#h = 0.02

#number of steps = (interval length) : step size = 1 : 0.02 = 50 steps

for i **from** 1 **to** 50 **do** $y := y + \frac{h}{2} \cdot f(x, y) + \frac{h}{2} \cdot f(x + h, y + h \cdot f(x, y))$: $\text{psi}(i) := y$: $x := x$
+ h : *print*(x, y); **od**:

1.02, 0.01960000000

1.04, 0.03839889575

1.06, 0.05639389879

1.08, 0.07358044006

1.10, 0.08995223147

1.12, 0.1055013234

1.14, 0.1202181590

1.16, 0.1340916265

1.18, 0.1471091104

1.20, 0.1592565428

1.22, 0.1705184555

1.24, 0.1808780338

1.26, 0.1903171739

1.28, 0.1988165436

1.30, 0.2063556480

1.32, 0.2129129013

1.34, 0.2184657056

1.36, 0.2229905376

1.38, 0.2264630438
1.40, 0.2288581460
1.42, 0.2301501576
1.44, 0.2303129114
1.46, 0.2293199001
1.48, 0.2271444298
1.50, 0.2237597871
1.52, 0.2191394212
1.54, 0.2132571394
1.56, 0.2060873179
1.58, 0.1976051268
1.60, 0.1877867692
1.62, 0.1766097326
1.64, 0.1640530536
1.66, 0.1500975920
1.68, 0.1347263145
1.70, 0.1179245840
1.72, 0.09968045314
1.74, 0.07998495801
1.76, 0.05883240897
1.78, 0.03622067424
1.80, 0.01215145227
1.82, −0.01336947204
1.84, −0.04033199200
1.86, −0.06872146971
1.88, −0.09851855771
1.90, −0.1296990565
1.92, −0.1622338132
1.94, −0.1960886651
1.96, −0.2312244323
1.98, −0.2675969636
2.00, −0.3051572363