# Image Super-Resolution using Deep Learning

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#### Introduction

- Resolution: The number of distinct pixels in each spatial dimension, that can be displayed.
- **Super-Resolution** is the method of obtaining **High-Resolution(HR)** images from their respective **Low Resolution(LR)** images.
- The super-resolved image not only has finer details, but also has a bigger image dimension.

#### Problem Statement

- As this problem of Super-Resolution(SR) is of ill-posed nature, there are multiple ways to approach the problem.
- Multiple methods include Motion-based SR[1], Zoom-based SR[2], and Learning-based SR[3].
- We attempt to solve the problem using Deep Learning-based SR.

[1] H.Demirel, S. Izadpanahi, and G.Anbarjafari, "Improved Motion-Based Localized Super Resolution Technique using discrete wavelet transform for low resolution video enhancement", 17th European Signal Processing Conference (EUSIPCO 2009), 1097-1101

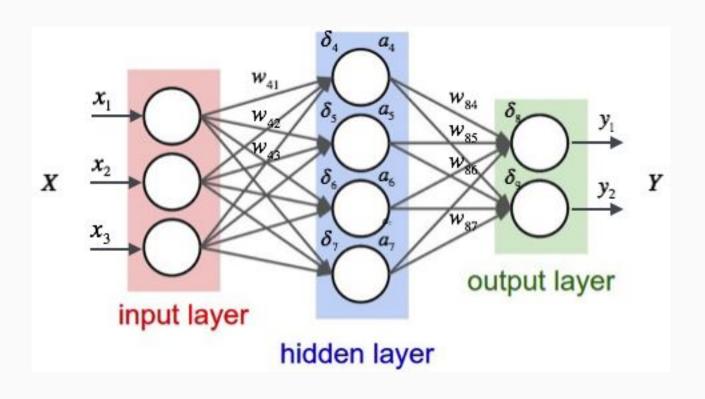
[2] M.V. Joshi, S. Chaudhuri, Super-resolution imaging: use of zoom as a cue, Indian Conf. Comput. Vis. Graph. Image Process., Ahmedabad (2002)

[3] Chao Dong, Chen Change Loy, Kaiming He, Xiaoou Tang, "Learning a Deep Convolutional Network for Image Super-Resolution", in Proceedings of European Conference on Computer Vision (ECCV), 2014

#### **Problem Statement**

Our goal in this project is to achieve magnification factors of 2x, 4x and 8x on an image with minimum depletion in image quality / details, by training a deep-learning model(a Convolutional Neural Network) which learns how to reconstruct details in the super-resolved(SR) image.

#### Neural Network



# **Tools and Technologies Used**

- Keras: A neural network API in python.
- Tensorflow: Neural-Network API used by Keras in the backend.
- OpenCV: A Computer Vision library.
- NumPy: Library for performing matrix computations.
- Python 2.7: Language used









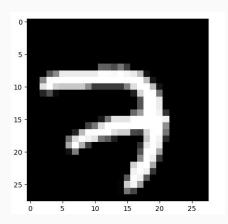


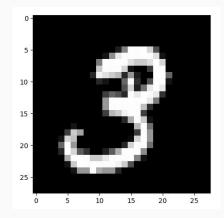
# Work Done: Stage 1

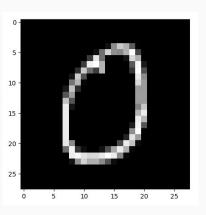
In order to get comfortable with **programming** the **neural network** and working with the **Tensorflow** and **Keras APIs**, we first took up the project of developing a classifier for **MNIST(0-9 digit)** database.

#### **Training & Testing Dataset used:**

We used Prof. Yann LeCun's **MNIST** database of handwritten digits. All of them have a dimension of **28** x **28**. It is a good database to try out **learning** and **pattern recognition** techniques on real world data while spending minimal efforts on **pre-processing** and **formatting**.







## Implementation Details

We used Tensorflow's Neural-Network API to create the Convolution Neural Network(CNN) classifier. The MNIST dataset has 60000 images for training and 10000 images for testing. The training was done in batches of 100 images. The training includes approximately 20000 such steps or about 34 epochs.

#### Our CNN architecture:

- 1. **Convolutional Layer #1:** Applies 32 5x5 filters (extracting 5x5-pixel subregions), with ReLU activation function.
- 2. **Pooling Layer #1:** Performs max pooling with a 2x2 filter and stride of 2 (which specifies that pooled regions do not overlap)
- 3. **Convolutional Layer #2:** Applies 64 5x5 filters, with ReLU activation function
- 4. **Pooling Layer #2:** Again, performs max pooling with a 2x2 filter and stride of 2
- 5. **Dense Layer #1:** 1,024 neurons, with dropout regularization rate of 0.4 (probability of 0.4 that any given element will be dropped during training to decrease overfitting).
- 6. **Dense Layer #2 (Logits Layer):** 10 neurons, one for each digit target class (0–9).

#### Results

We achieved an accuracy of **96.97**% on the test data by training the model for **20000 steps** or about **34 epochs**, where 1 step indicates training the network on 1 batch(1 batch= 100 image vectors together). For improving the accuracy of the model at every step, we used **gradient descent optimizer** for **backpropagation** at a learning rate of **0.001**, to optimize the filter values. We have also used a **dropout rate** of **0.4**, to address the problem of **overfitting**.

```
INFO:tensorflow:loss = 0.243901, step = 20704
INFO:tensorflow:Loss for final step: 0.243901.
INFO:tensorflow:Starting evaluation at 2018-02-28-23:27:39
INFO:tensorflow:Restoring parameters from mnist_convnet_model/model.ckpt-20704
INFO:tensorflow:Finished evaluation at 2018-02-28-23:27:50
INFO:tensorflow:Saving dict for global step 20704: accuracy = 0.9697, global_step = 20704, loss = 0.101608
{'loss': 0.1016076, 'global_step': 20704, 'accuracy': 0.96969998}
kunal@kunal-Lenovo-Z50-70:~/Desktop/MNIST_dataclassification$
```

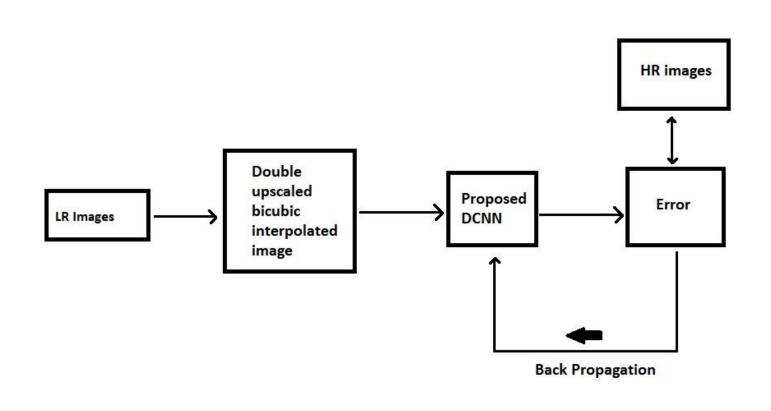
# Work Done: Stage 2

Coming back to Image Super-Resolution, we attempt to utilize the **learning property** of the **CNN** here to **reconstruct** details, rather than using it as a **classifier**.

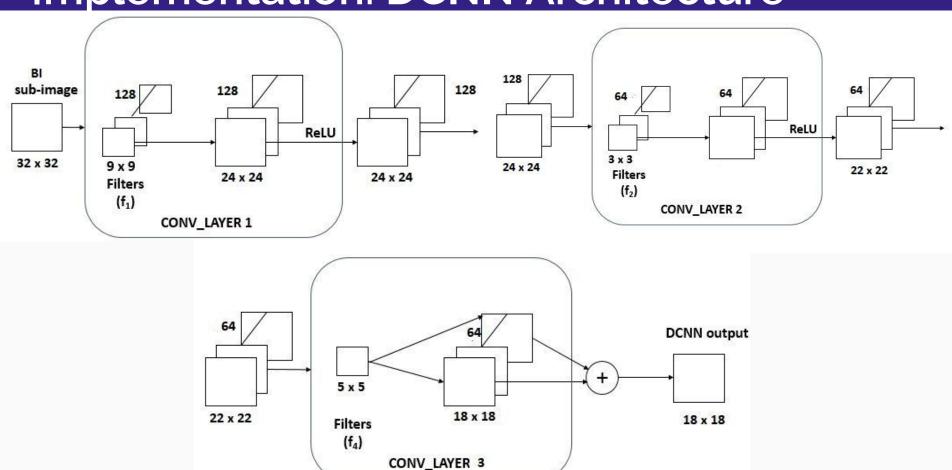
#### Implementation: Pre-processing images

For creating the LR images, we first down-scale the size of the ground truth image by 2. We then double the size by using bicubic interpolation, thus creating the LR image. We diminish the size by 2 and then super-resolve it by 2 in order to compare the SR image with the ground truth. For feeding the images in the **DCNN**, we create overlapping patches of the LR input image of size 32 x 32 and the respective HR ground truth. They are stored in the form of vectors in h5py files. We retrieve them from the h5py files for the purpose of training and testing.

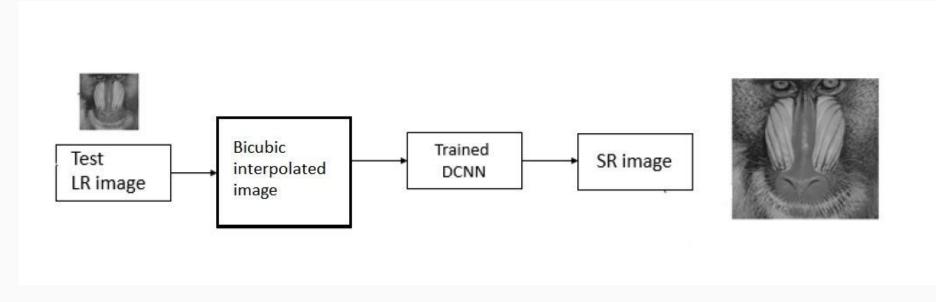
# Implementation: Training



#### Implementation: DCNN Architecture



# Implementation: Testing



#### Implementation: Dataset used

We have used the same dataset as in paper [4]. Training images comprises 91 color images of varying sizes. The 5 images in the Set5 section of the dataset is used to evaluate the performance.









Sample Training Images











Testing images from Set5 section

# Implementation: Regularization

As the problem of super-resolution is ill-posed, we further try to improve the image quality by adding a **regularization** parameter in the **loss/error function** of the neural network, which is as follows:

$$loss \ function = MSE (true \ image - reconstructed \ image) + \lambda (\sum_{i=1}^{m} \sum_{j=1}^{n} (reconstructed \ image(i,j) - reconstructed \ image(i,j-1))^2 + \sum_{i=1}^{m} \sum_{j=1}^{n} (reconstructed \ image(i,j) - reconstructed \ image(i-1,j))^2)$$

MSE= Mean Square Error function,  $\lambda$ = Smoothness parameter,

m,n= dimensions of the image

#### Results: Low Resolution(LR) Input Image



Input

#### Results: Bicubic Interpolation v SR



#### Results: Ground Truth v SR



**Ground Truth** 

SR

## Results: 2x Super-Resolved(SR) Image



Non-Regularized SR

Regularized SR

Work Done: Stage 2



Work Done: Stage 2

Results: Bicubic Interpolation v SR



#### Results: Ground Truth v SR



Results: 2x Super-Resolved(SR) Image



#### Results: 4x Super-Resolved(SR) Image



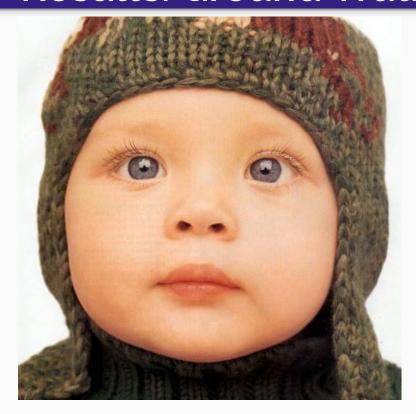
#### Results: Bicubic Interpolation v SR

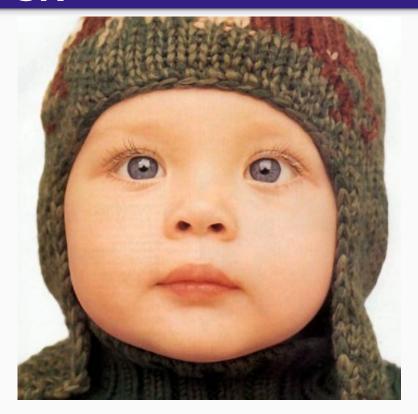




Bicubic Interpolated Image

#### Results: Ground Truth v SR





Ground Truth SR

# Results: 2x Super-Resolved(SR) Image



Non-Regularized SR



Regularized SR

Results: 4x Super-Resolved(SR) Image



#### Results

The metric used for quantitative comparison here is the **PSNR**( **Peak Signal to Noise Ratio**)[5], measured in dB and the formula to compute it is as follows:

**PSNR** = 
$$10 * \log_{10}((255)^2 / MSE)$$

Where MSE is the **Mean Square Error** between the ground truth image vector and the Super-resolved image vector.

## Results: PSNR Values

Test images	Bicubic-Interpolated image(in dB)	Non-Regularized SR (in dB)	Regularized SR (in dB)
Baby	36.00	31.56	31.86
Bird	36.75	31.52	32.84
Butterfly	27.01	23.99	25.88
Head	33.55	30.60	30.69
Woman	31.76	27.23	28.69

#### Conclusion

- We attain higher magnification by reusing the neural network, and using the super-resolved image as input generates 4x magnification and similarly we can do it for 8x.
- We also tweak the loss function of the network with a regularization parameter to produce a better output.
- The results obtained using this approach, show observable qualitative and quantitative improvements in the image quality, as compared to a digital zoom performed using bicubic interpolation.

# Thank You