

Homework 5.

1. Eigenvalues + Eigenvectors.

$$a) M = \begin{bmatrix} 5 & 0 \\ 0 & 2 \end{bmatrix}$$

$$Mx = \lambda x.$$

$$(Mx - \lambda x) = 0.$$

$$(M - \lambda I)x = 0.$$

$$\therefore \det(M - \lambda I) = 0.$$

$$\therefore \det \begin{bmatrix} 5-\lambda & 0 \\ 0 & 2-\lambda \end{bmatrix} = 0.$$

$$\therefore (5-\lambda)(2-\lambda) = 0$$

$$10 - 5\lambda - 2\lambda + \lambda^2 = 0$$

$$\lambda^2 - 7\lambda + 10 = 0$$

$$\therefore (\lambda - 2)(\lambda - 5) = 0$$

$$\lambda = \underline{5}, \lambda = \underline{2}$$

$$\text{Let } \lambda = 2$$

$$\begin{bmatrix} 3 & 0 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 0 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$$x = 0$$

$$y = t$$

$$\therefore V_2 = \underline{\underline{\begin{bmatrix} 0 \\ 1 \end{bmatrix}}}$$

$$\text{Eigenspace} = \left\{ \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right\}$$

$$\text{Subst. } \lambda = 5$$

$$\therefore (M - 5I)x = 0.$$

$$\therefore \begin{bmatrix} 5-5 & 0 & | & 0 \\ 0 & 2-5 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 0 & 0 & | & 0 \\ 0 & -3 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 0 & 0 & | & 0 \\ 0 & -3 & | & 0 \end{bmatrix}$$

$$\therefore \begin{bmatrix} x = t \\ y = 0 \end{bmatrix} \rightarrow V_1 = \underline{\underline{\begin{bmatrix} 1 \\ 0 \end{bmatrix}}}$$

$$b) M = \begin{bmatrix} 22 & 6 \\ 6 & 13 \end{bmatrix}$$

$$Mx = \lambda x$$

$$(M - \lambda I)x = 0.$$

$$\therefore \begin{bmatrix} 22-\lambda & 6 \\ 6 & 13-\lambda \end{bmatrix} x = 0.$$

$$\therefore \det \begin{pmatrix} 22-\lambda & 6 \\ 6 & 13-\lambda \end{pmatrix} = 0.$$

$$(22-\lambda)(13-\lambda) - 36 = 0.$$

$$286 - 22\lambda - 13\lambda + \lambda^2 - 36 = 0.$$

$$\lambda^2 - 35\lambda + 250 = 0.$$

$$\lambda^2 - 25\lambda - 10\lambda + 250 = 0$$

$$(\lambda - 25)(\lambda - 10) = 0$$

$$\lambda = 25, \lambda = 10.$$

Let $\lambda = -25$.

$(M + 25I)x = 0$.

$$\begin{bmatrix} -3 & 6 & | & 0 \\ 6 & -12 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & -2 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$x = 2\epsilon$

$y = \epsilon$

$\therefore V_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$

Let $\lambda = 10$.

$(M - 10I)x = 0$.

$$\begin{bmatrix} 12 & 6 & | & 0 \\ 6 & 3 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 12 & 6 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 2 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$x = -\frac{1}{2}\epsilon$

$y = \epsilon$

$\therefore V_2 = \begin{bmatrix} -1/2 \\ 1 \end{bmatrix}$

Eigenspace = $\left\{ \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} -1/2 \\ 1 \end{bmatrix} \right\}$

c) $M = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}$

$Mx = \lambda x$

$(M - \lambda I)x = 0$

$\det \begin{bmatrix} 1-\lambda & 2 \\ 2 & 4-\lambda \end{bmatrix} = 0$

$\therefore (4-\lambda)(1-\lambda) - 4 = 0$

$4 - 4\lambda - \lambda + \lambda^2 - 4 = 0$

$\lambda^2 - 5\lambda + 0 = 0$

$\lambda(\lambda - 5) = 0$

$\therefore \lambda = 5, \lambda = 0$

Let $\lambda = 5$.

$$\begin{bmatrix} -4 & 2 & | & 0 \\ 2 & -1 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 2 & -1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$\therefore x = \frac{1}{2}\epsilon$

$y = \epsilon$

$\therefore V_1 = \begin{bmatrix} 1/2 \\ 1 \end{bmatrix}$

Let $\lambda = 0$.

$$\begin{bmatrix} 1 & 2 & | & 0 \\ 2 & 4 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 2 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$\therefore x = -2\epsilon$

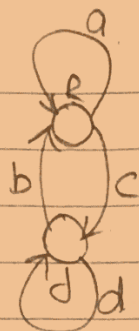
$y = \epsilon$

$\therefore V_2 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$

Eigenspace

= $\left\{ \begin{bmatrix} 1/2 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \end{bmatrix} \right\}$

$$2. \quad R[n+1] = aR[n] + bJ[n] \\ J[n+1] = cR[n] + dJ[n]$$



q) Core: $a+b=c+d$

Aim: $V_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ is an Eigenvector of A.

$$Ax = \lambda x$$

$$A \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \lambda_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \lambda_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

By substitution.

$$\begin{bmatrix} a+b \\ c+d \end{bmatrix} = \begin{bmatrix} \lambda_1 \\ \lambda_1 \end{bmatrix} \Rightarrow \begin{bmatrix} a+b \\ a+b \end{bmatrix} = \begin{bmatrix} \lambda_1 \\ \lambda_1 \end{bmatrix}$$

$$\boxed{a+b = \lambda_1}$$

$$(a+b) \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \lambda_1 \begin{bmatrix} 1 \\ 1 \end{bmatrix} \rightarrow \therefore \lambda_1 = a+b$$

Aim: $V_2 = \begin{bmatrix} b \\ -c \end{bmatrix}$ is an Eigenvector.

$$a+b=c+d \\ a-c=d-b$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} b \\ -c \end{bmatrix} = \lambda_2 \begin{bmatrix} b \\ -c \end{bmatrix}$$

$$\begin{bmatrix} ab - bc \\ bc - dc \end{bmatrix} = \begin{bmatrix} b\lambda_2 \\ -c\lambda_2 \end{bmatrix}$$

$$\begin{bmatrix} b(a-c) \\ -c(d-b) \end{bmatrix} = \begin{bmatrix} b\lambda_2 \\ -c\lambda_2 \end{bmatrix}$$

$$\boxed{\lambda_2 = a-c}$$

$$\Rightarrow \begin{bmatrix} b(a-c) \\ -c(a-c) \end{bmatrix} = \begin{bmatrix} b\lambda_2 \\ -c\lambda_2 \end{bmatrix}$$

$$2. b) \quad A = \begin{bmatrix} 0.75 & 0.25 \\ 0.25 & 0.75 \end{bmatrix}$$

$$\therefore \lambda_1 = a+b = 1. \quad \therefore \lambda_2 = a-c = 0.5$$

$$\therefore V_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \therefore V_2 = \begin{bmatrix} 0.25 \\ -0.25 \end{bmatrix}$$

$$c) \text{ Steady states } \Rightarrow \begin{bmatrix} 1 \\ 1 \end{bmatrix} \text{ and } \begin{bmatrix} 0.25 \\ -0.25 \end{bmatrix}$$

$$d) \quad Ax = \lambda x$$

$$\therefore AV_2 = \lambda_2 V_2$$

$$\therefore A \begin{bmatrix} 0.25 \\ -0.25 \end{bmatrix} = 0.5 \begin{bmatrix} 0.25 \\ -0.25 \end{bmatrix}$$

$$\therefore S[n] = (0.5)^n \begin{bmatrix} 0.25 \\ -0.25 \end{bmatrix} \xrightarrow{(n \rightarrow \infty)} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

\Rightarrow This means that as $n \rightarrow \infty$,
 $S[n]$ tends to $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$.

Therefore, as $n \rightarrow \infty$, Romeo
 and Juliet have Neutral feelings.

$$e) \quad A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$\therefore \lambda_1 = a+b = 2 \quad \therefore \lambda_2 = a-c = 0$$

$$V_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$V_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$2.f) \quad S[0] = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\therefore \lambda = 0$$

Using equation $Av = \lambda v$,

$$\text{As } n \rightarrow \infty, \quad 0^n \begin{bmatrix} 1 \\ -1 \end{bmatrix} \rightarrow \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

\therefore Romeo and Juliet have neutral feelings as $n \rightarrow \infty$.

$$g) \quad S[0] = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\therefore \lambda = 2$$

$$\text{As } n \rightarrow \infty, \quad 2^n S[0] = 2^n \begin{bmatrix} 1 \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} \infty \\ \infty \end{bmatrix}$$

\therefore As $n \rightarrow \infty$, Romeo likes Juliet.

$$h) \quad A = \begin{bmatrix} 1 & -2 \\ -2 & 1 \end{bmatrix}$$

$$\therefore Ax = \lambda x$$

$$(A - \lambda I)x = 0$$

$$\det(A - \lambda I) = 0$$

$$\therefore \det \left(\begin{bmatrix} 1-\lambda & -2 \\ -2 & 1-\lambda \end{bmatrix} \right) = 0$$

$$\therefore (1-\lambda)(1-\lambda) - 4 = 0$$

$$1 - \lambda - \lambda + \lambda^2 - 4 = 0$$

$$\lambda^2 - 2\lambda - 3 = 0$$

$$\therefore (\lambda - 3)(\lambda + 1) = 0$$

$$\therefore \lambda = 3 \text{ or } \lambda = -1$$

Continued.



Let $\lambda = 3$

$$\begin{bmatrix} -2 & -2 & | & 0 \\ -2 & -2 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$$\therefore x = -\epsilon$$

$$y = \epsilon$$

$$\therefore v_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Let $\lambda = -1$

$$\begin{bmatrix} 2 & -2 & | & 0 \\ -2 & 2 & | & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & -1 & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix}$$

$$x = \epsilon$$

$$y = \epsilon$$

$$v_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

i) $\lambda = 3$

$$v_1 = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \Rightarrow S[0] = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\text{As } n \rightarrow \infty, \quad 3^n \begin{bmatrix} -1 \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} -\infty \\ \infty \end{bmatrix}$$

\therefore if $R[0] < 0$ and $J[0] > 0$,
then they continued in that
same feeling state but with
greater feelings. In other words,
Juliet likes Romeo.

if $R[0] > 0$ and $J[0] < 0$,
then Romeo likes Juliet as
 $n \rightarrow \infty$ but with greater
feelings.

$$2. j) \lambda = -1$$

$$V_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$s[0] = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{As } n \rightarrow \infty, (-1)^n \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

\therefore They oscillate between liking and disliking each other as $n \rightarrow \infty$.

3.

a) $S = H\hat{i} + w$.

Aim: Express \hat{i} in terms of H, S, w .

$$\therefore H\hat{i} = S - w$$

$$H^{-1}H\hat{i} = H^{-1}(S - w)$$

$$\hat{i} = H^{-1}(S - w)$$

b) Noise is scaled $\Rightarrow \hat{w} = H^{-1}w$.

Let $w = \alpha_1 b_1 + \dots + \alpha_n b_n$

w is represented as the
Eigenvectors of H^{-1} .

Change of base.

$$\hat{w} = H^{-1}(\alpha_1 b_1 + \dots + \alpha_n b_n)$$

$$= H^{-1}\alpha_1 b_1 + \dots + H^{-1}\alpha_n b_n$$

$$= \alpha_1 H^{-1}b_1 + \dots + \alpha_n H^{-1}b_n$$

$$= \alpha_1 \lambda_1 b_1 + \dots + \alpha_n \lambda_n b_n$$

* we multiply
the eigenvector
of a matrix with
the matrix to
get λb_1

For eigenvectors with larger Eigenvalues \Rightarrow Noise Signal
Amplified

For eigenvectors with smaller Eigenvalues \Rightarrow Noise Signal
Attenuated

c) Matrix H_1 performs best when recreating the image.

so that the noise
in the reconstructed
image is
Attenuated.

we want the eigenvalues of H^{-1} to be small.

This means that we want the eigenvalues
of H to be large.

↳ in ipynb, we are given H_1, \dots, H_3 .

↳ H_1 has the biggest Smallest Eval.

↳ H_3 has the smallest of Small Eval's.

∴ Inverse $\Rightarrow H_1 \Rightarrow$ Smaller.
 $\Rightarrow H_3 \Rightarrow$ Larger.

d) Prove: Show that if λ is an Eigenval of H , then
 $1/\lambda$ is an eigenval. of H^{-1} .

Proof: we know that $HV = \lambda V$.

$$H^{-1}HV = H^{-1}\lambda V$$

$$V = \lambda H^{-1}V$$

$$\frac{1}{\lambda}V = H^{-1}V$$

$$H^{-1}V = \frac{1}{\lambda}V$$

∴ Eigenvalue of H^{-1} is $\frac{1}{\lambda}$.

4 Cubic Polynomials

a) $p(t) = p_0 + p_1 t + p_2 t^2 + p_3 t^3$

Dimension $\Rightarrow 3+1 = 4$

b) $P(t) = C^T \phi(t)$

$$\downarrow$$
$$\begin{bmatrix} 1 \\ t \\ t^2 \\ t^3 \end{bmatrix}$$

$$C^T = [C_0 \ C_1 \ C_2 \ C_3]$$

Therefore
cannot represent
one terms of the
other.

$$C^T \cdot \phi(t) = [C_0 \ C_1 \ C_2 \ C_3] \begin{bmatrix} 1 \\ t \\ t^2 \\ t^3 \end{bmatrix}$$

$$= C_0 + C_1 t + C_2 t^2 + C_3 t^3$$

$$= p_0 + p_1 t + p_2 t^2 + p_3 t^3$$

$$C^T = [p_0 \ p_1 \ p_2 \ p_3]$$

$\Delta \therefore$ Linearly
Independent

c) To show that $\phi_k(t) = t^k$ for $k=1,2,3,0$ is a basis, show that they are linearly independent.

\therefore For any t^i , where $i \in \{0,1,2,3\}$, if we try to represent one base t^i in terms for the other bases, we get $\phi_i(t) = \alpha_0 t^0 + \alpha_1 t^1 + \alpha_2 t^2 + \alpha_3 t^3$. But we have coefficient α_i on one side and zero on the other

d) Basis Polynomials:

$$\phi_0(t) = 1 \Rightarrow \text{Denv.} = 0 \cdot 0$$

$$\phi_1(t) = t \Rightarrow \text{Denv.} = 1 \Rightarrow \phi_0(t)$$

$$\phi_2(t) = t^2 \Rightarrow \text{Denv.} = 2t \Rightarrow 2\phi_1(t)$$

$$\phi_3(t) = t^3 \Rightarrow \text{Denv.} = 3t^2 \Rightarrow 3\phi_2(t)$$

e) $P(t) = C_0 + C_1 t + C_2 t^2 + C_3 t^3$

$$\frac{dP}{dt} = C_1 + 2C_2 t + 3C_3 t^2 + 0 \cdot t^3$$

$$\Rightarrow [C_1 \quad 2C_2 \quad 3C_3 \quad 0]$$

$$\begin{bmatrix} 1 \\ t \\ t^2 \\ t^3 \end{bmatrix}$$

(DC)^T $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} C_0 \\ C_1 \\ C_2 \\ C_3 \end{bmatrix} = \begin{bmatrix} C_1 \\ 2C_2 \\ 3C_3 \\ 0 \end{bmatrix}$

Continued.

$$\therefore D \cdot \begin{bmatrix} c_0 \\ c_1 \\ c_2 \\ c_3 \end{bmatrix} = \begin{bmatrix} c_1 \\ 2c_2 \\ 3c_3 \\ 0 \end{bmatrix}$$

$$\therefore D = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

7. I worked on question 1 and 2 on Monday and question 3 and 4 on Wednesday. I worked alone but went to office hours on Wednesday and Friday to clarify some doubts.