



## INTRODUCTION

Deep Neural Networks

Session 02

Pramod Sharma

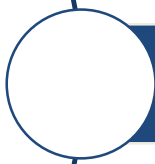
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2

## Agenda



Perceptron



Single Layer Neural Network



Overview of back propagation of errors

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3

## Solution to Equation of Perceptron

Its is as simple as  $y = mx + c$  !



Frank Rosenblatt

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4

## To play or not to play...

id	Rains	Temp	Homework	Team Members	Equipment	Ground	Played
1	0	38	1	15	0	600	1
2	0	25	1	15	1	800	1
3	0	26	1	15	1	1000	1
4	5	27	1	10	1	600	0
5	20	23	0	8	1	1800	0
6	30	22	0	6	0	600	0

### □ Features:

- ❖ Rains in millimeter
- ❖ Temperature in ° C
- ❖ Homework completed? – 0 : No; 1: Yes
- ❖ Team members : How many team members are ready to play?
- ❖ Is cricket equipment available?
- ❖ Ground: per hour rent in Rupees/hour

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5

## Weights

- ❑ Each of the feature has different importance
- ❑ To assign importance to each of the feature, we use weights!
- ❑ Values of each features are in different order of magnitude
  - ❖ Summation is not going to work
  - ❖ Scale the features between 0 and 1

id	Rains	Temp	Homework	Team Members	Equipment	Ground	Played
1	0	38	1	15	0	600	1
2	0	25	1	15	1	800	1
3	0	26	1	15	1	1000	1
4	5	27	1	10	1	600	0
5	20	23	0	8	1	1800	0
6	30	22	0	6	0	600	0

- ❑ Note:
  - ❖ Variation in features have different bearing on the results
  - ❖ Team members → higher the better
  - ❖ Ground cost → lower the better

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6

## Perceptron

- ❑ In MP Neuron Model,
  - ❖ All inputs had same weights
  - ❖ Threshold ' $w_0$ ' could take limited values
  - ❖ Every feature needed to be [0,1]
- ❑ Perceptron model introduced different weights to different inputs features
- ❑ Real values are also accepted
  - ❖ Temperatures are in tens and ground rent is in hundreds.
  - ❖ Min – Max – Scaler to compensate for huge difference in values
- ❑ Threshold ' $w_0$ ' can take any value
- ❑ Outputs are still [ 0, 1 ]

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## Perceptron

### □ Loss Function:

- ❖ A correction is applied on the outputs
- ❖ To adjust values of ' $w_i$ ' to reach right results
- ❖ It would also give us indications of what weights to be fixed to arrive at the solution

### □ Activation function $g(x)$ is applied as follows:

- ❖ If  $\sum x_i \cdot w_i \geq w_0 \Rightarrow \hat{y} = 1$
- ❖ If  $\sum x_i \cdot w_i < w_0 \Rightarrow \hat{y} = 0$

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## Perceptron – Data Preprocessing

- Lets consider “Ground” and “Team Members” as features and its associated weights to arrive at the solution.

id	Rains	Temp	Homework	Team Members	Equipment	Ground	Played
1	0	38	1	15	0	600	1
2	0	25	1	15	1	800	1
3	0	26	1	15	1	1000	1
4	5	27	1	10	1	600	0
5	20	23	0	8	1	1800	0
6	30	22	0	6	0	600	0

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## Perceptron – Data Preprocessing

- Scaled Data ( all columns to be between 0 and 1)

id	Rains	Temp	Homework	Team Members	Equipment	Ground	Played
1	0.00	0.00	1.00	1.00	0.00	1.00	1
2	0.00	0.81	1.00	1.00	1.00	0.83	1
3	0.00	0.75	1.00	1.00	1.00	0.67	1
4	-0.17	0.69	1.00	0.44	1.00	1.00	0
5	-0.67	0.94	0.00	0.22	1.00	0.00	0
6	-1.00	1.00	0.00	0.00	0.00	1.00	0

- What about reverse correlation
- Two option to address reverse correlation
  - ❖ Take negative of values
  - ❖ Use negative weight

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10

## Perceptron – Weights

- Weights – consider importance of each of the feature

id	Threshold	Team Members		Ground		Calculations	Likely	Played	Loss
	w0	x1	w1	x2	w2	$w0+x1*w1+x2*w2$	(y_hat)	(y)	(y-y_hat)^2
1	-1.00	1.00	1.10	1.00	1.00	1.10	1	1	0
2	-1.00	1.00	1.10	0.83	1.00	0.93	1	1	0
3	-1.00	1.00	1.10	0.67	1.00	0.77	1	1	0
4	-1.00	0.44	1.10	1.00	1.00	0.49	1	0	1
5	-1.00	0.22	1.10	0.00	1.00	-0.76	0	0	0
6	-1.00	0.00	1.10	1.00	1.00	0.00	1	0	1

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11

## Perceptron – Weights and Loss

- Our best solution would be where ground truth and predicted values are same
- Loss is some function of ground truth and predicted values
- And we want it to be cumulative, Square of difference looks promising
  - ❖  $\ell(\hat{y}, y) = (y - \hat{y})^2$
  - ❖ Our overall loss was 2.
- By adjusting weights ( $w_1, w_2$ ) and threshold ( $w_0$ ) we can bring the loss to minimum (zero in this case)

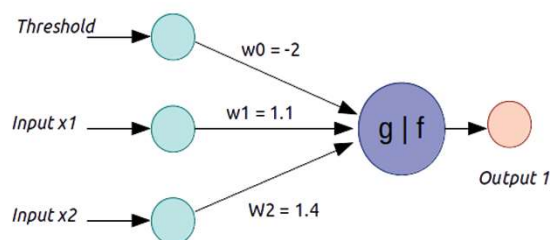
id	Threshold	Team Members		Ground		Calculations	Likely	Played	Loss
	w0	x1	w1	x2	w2	$w_0 + x_1 * w_1 + x_2 * w_2$	(y_hat)	(y)	$(y - y\_hat)^2$
1	-2.00	1.00	1.10	1.00	1.40	0.50	1	1	0
2	-2.00	1.00	1.10	0.83	1.40	0.27	1	1	0
3	-2.00	1.00	1.10	0.67	1.40	0.03	1	1	0
4	-2.00	0.44	1.10	1.00	1.40	-0.11	0	0	0
5	-2.00	0.22	1.10	0.00	1.40	-1.76	0	0	0
6	-2.00	0.00	1.10	1.00	1.40	-0.60	0	0	0

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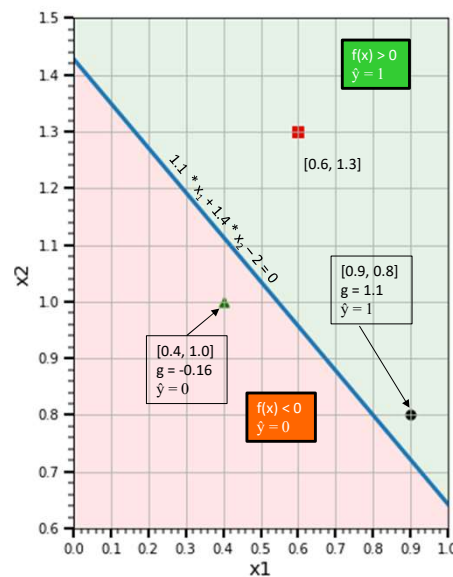
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13

## Perceptron



- We can represent :  $g = w_0 + x_1 * w_1 + x_2 * w_2$ 
  - ❖ As  $g = [x_1, x_2] \cdot \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} + w_0$
- Given:  $W = \begin{bmatrix} 1.1 \\ 1.4 \end{bmatrix}$  and  $w_0 = -2$ 
  - ❖  $g = [x_1, x_2] \cdot \begin{bmatrix} 1.1 \\ 1.4 \end{bmatrix} - 2$
  - ❖  $g = 1.1 * x_1 + 1.4 * x_2 - 2$



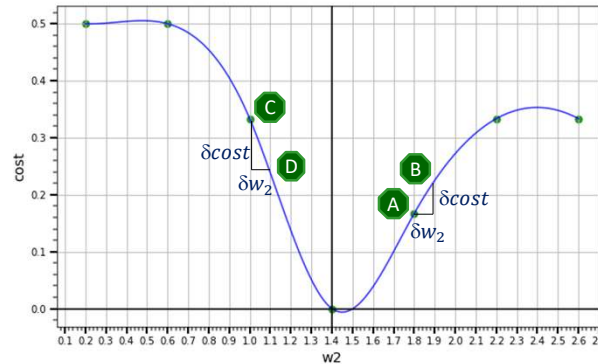
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14

## Perceptron – Gradient Descent

- $w_0, w_1, w_2$  need to be adjusted to arrive at most optimal solution i.e. lowest point on the graph.
- Assume that  $w_0$  is fixed at -2, and  $w_1$  at 1.1 and  $w_2$  varies from 0 to 3 (only one variable considered to make plotting simple)
- From point A to B, slope is positive hence  $w_2$  value needs to be decreased
- From point C to D slope is negative hence  $w_2$  needs to be increased.



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## Perceptron – Activation Function

- So we based our entire calculations on:

$$z = w_0 + x_1 * w_1 + x_2 * w_2$$



But that's an equation of straight line! 😊  
What happened to all those 'inhibitory' features?

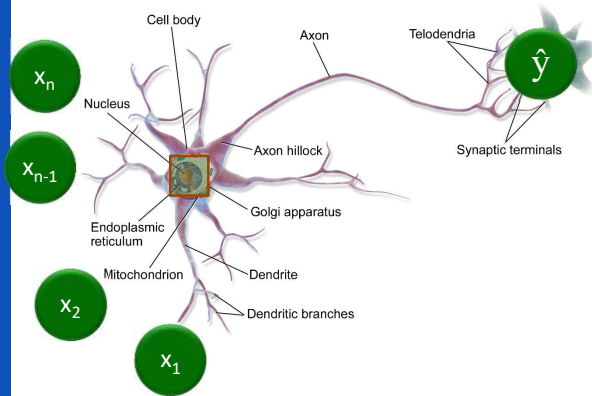


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16

## Non Linear Activation function



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Non-linear Activation function

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$$\hat{y} = \sigma(\sum X * W + b)$$

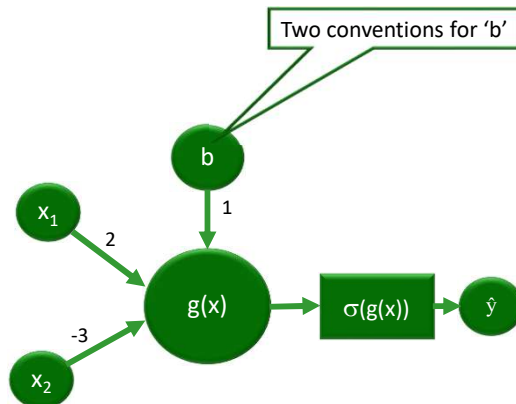
Some function of sum of 'weights' times 'input value' plus 'bias'

$$u_k = \sum_{j=1}^m x_j w_{kj}$$

$$y_k = \sigma(u_k + b_k)$$

17

## Perceptron with non-linear activation function



□ Given:

$$\diamond W = \begin{bmatrix} 2 \\ -3 \end{bmatrix} \text{ and } b = 1$$

$$\diamond \hat{y} = \sigma([x_1, x_2] \cdot \begin{bmatrix} 2 \\ -3 \end{bmatrix} + 1)$$

$$\diamond \hat{y} = \sigma(1 + 2 * x_1 - 3 * x_2)$$

$\underbrace{\hspace{10em}}_z$

$$\square \hat{y} = \sigma(z);$$

□ Lets use sigmoid function for  $\sigma$ .

$$\diamond \hat{y} = \frac{1}{(1+e^{-z})}$$

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18

## Perceptron with non-linear activation function

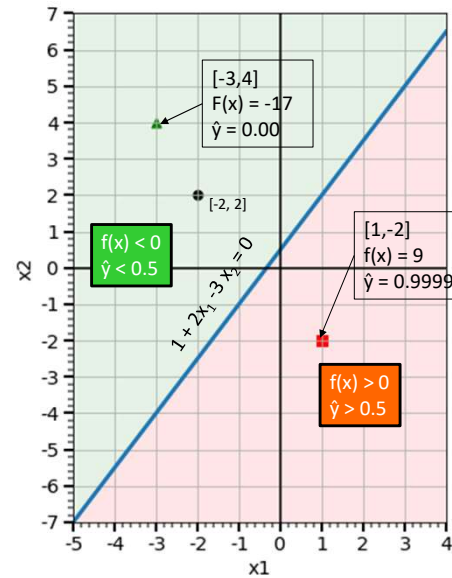
$$\hat{y} = \sigma(1 + 2 * x_1 - 3 * x_2)$$

For  $X = [-3, 4]$

$$\begin{aligned} \hat{y} &= \sigma(1 + 2 * (-3) - 3 * 4) \\ \hat{y} &= \sigma(1 - 6 - 12) \\ \hat{y} &= \sigma(-17) \\ \hat{y} &= 0.0 \end{aligned}$$

Similarly, for  $X = [1, -2]$

$$\begin{aligned} \hat{y} &= \sigma(1 + 2 * 1 - 3 * (-2)) \\ \hat{y} &= \sigma(1 + 2 - 6) \\ \hat{y} &= \sigma(9) \\ \hat{y} &= 1.0 \end{aligned}$$



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19

## Perceptron with non-linear activation function

$$\begin{aligned} \hat{y} &= \sigma(1 + 2 * x_1 - 3 * x_2) \\ \text{For } X &= [-3, 4] \\ \hat{y} &= \sigma(1 + 2 * (-3) - 3 * 4) \\ \hat{y} &= \sigma(1 - 6 - 12) \\ \hat{y} &= \sigma(-17) \\ \hat{y} &= 0.0 \end{aligned}$$

Are we there yet!

Lets learn some math too!!

Yeehaw!!!

$$\begin{aligned} f(x) &> 0 \\ \hat{y} &> 0.5 \end{aligned}$$

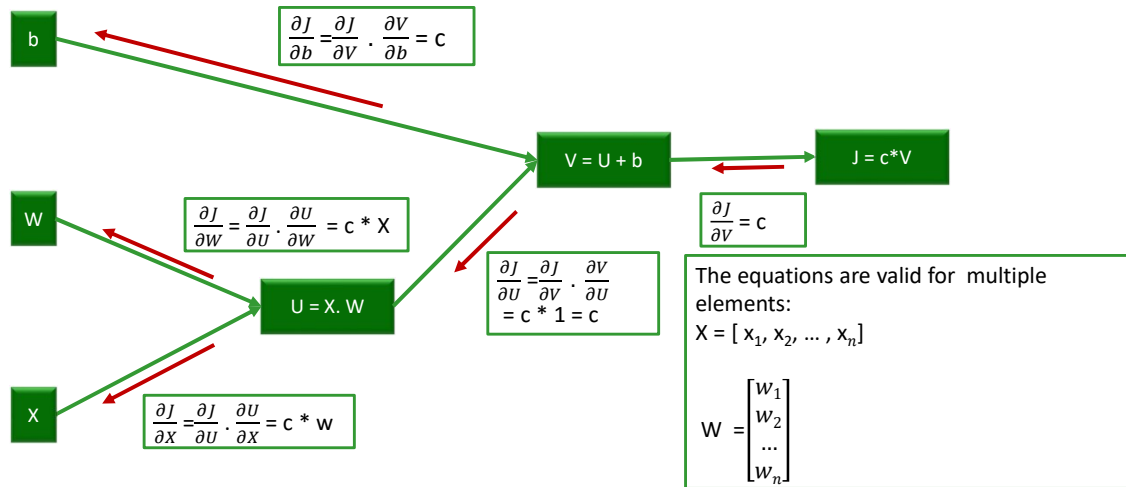
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20

## Computational Graph

□ Consider following hypothetical case, basic equation for single neuron :

❖  $\hat{y} = X \cdot W + b$  and Cost is some constant times  $\hat{y}$ ;  $J = c * \hat{y}$



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21

## Exercise 2 : Computational Graph

□ Given a Cost Function J

❖  $J(w, x, b) = 3 * (b + x * w)$

□ Calculate  $\frac{\partial J}{\partial w}$ ,  $\frac{\partial J}{\partial x}$  and  $\frac{\partial J}{\partial b}$

□ Calculate slope at point :

❖  $b = 6$

❖  $w = 3$

❖  $x = 2$



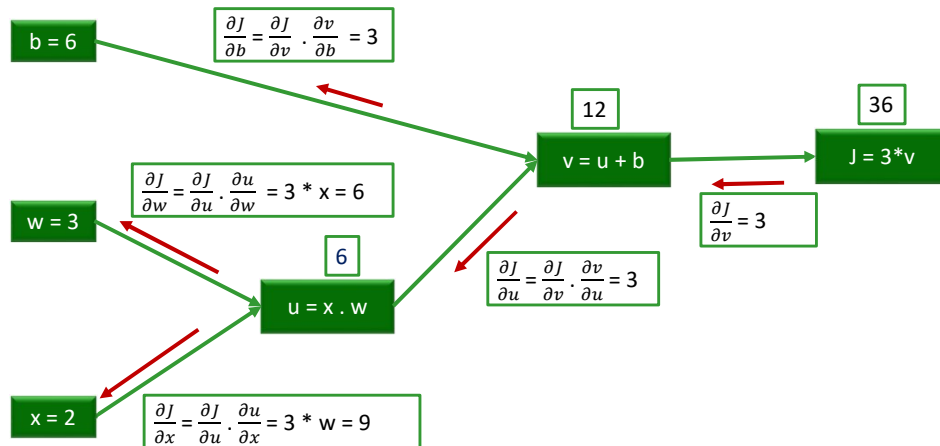
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## Exercise - Solution

- Given a Cost Function  $J(w, x, b) = 3 * (b + w * x)$



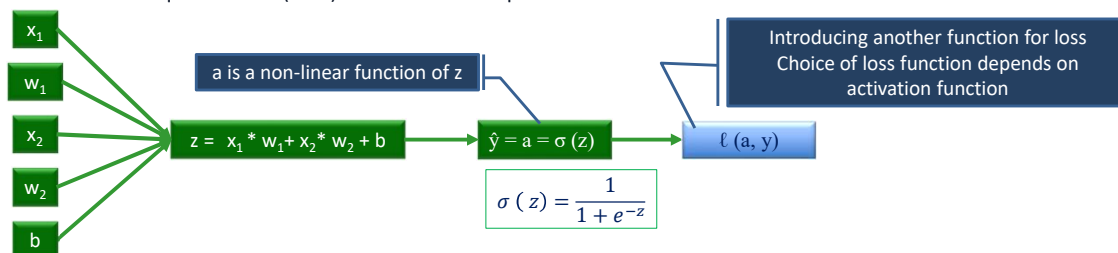
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## Consider Single Path... MLE

- Maximum likelihood estimation, or MLE, is a framework for inference for finding the best statistical estimates of parameters from historical training data
  - ❖ Exactly what we are trying to do with the neural network
- In Classification, output is probability of it belonging to a class
  - ❖ Maximum likelihood estimation, seeks a set of model weights that minimize the difference between the predicted probability distribution and the Ground Truth [cross-entropy]
- In Regression problems:
  - ❖ Use the mean squared error (MSE) loss function or equivalent.



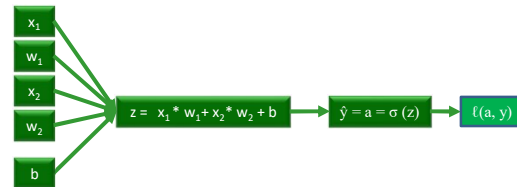
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## Consider Single Path... Loss Function

- ❑ A function used to evaluate a candidate solution
- ❑ Helps to maximize or minimize the objective function
- ❑ Estimates how closely the distribution of predictions made by a model matches the ground truth (maximum likelihood)
- ❑ Under maximum likelihood framework, the error between two probability distributions is measured using cross-entropy
  - ❖ Hence  $\ell(\hat{y}, y) = -[y * \log(\hat{y}) + (1 - y) * \log(1 - \hat{y})]$



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25

## Cost Function

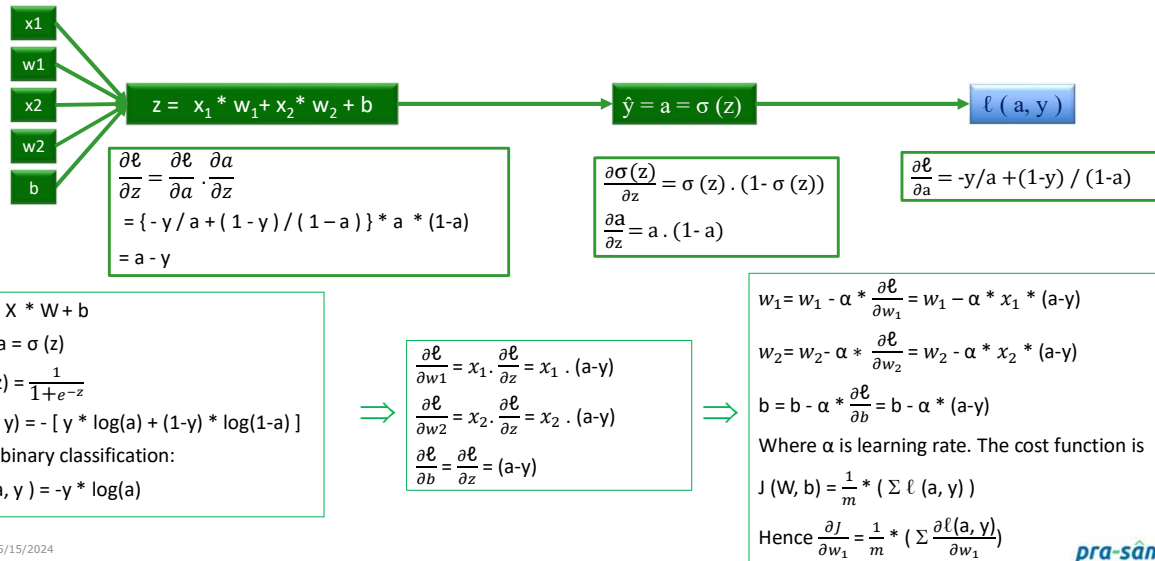
- ❑  $\hat{y} = \sigma(\sum W * X + b)$
- ❑ Where  $\sigma(z) = \frac{1}{1+e^{-z}}$
- ❑ Loss function:
  - ❖ A parameter which defines how good our outputs are i.e.
  - ❖ How far our predicted values ' $\hat{y}$ ' (y hat) were from ground truth 'y'
- ❑ For logistic regression
  - ❖  $\text{Loss}(\hat{y}, y) = -(y \cdot \log \hat{y} + (1 - y) \cdot \log(1 - \hat{y}))$
  - ❖ Loss function is for an instance
  - ❖ In case of binary classification,  $\text{Loss}(\hat{y}, y) = -y \cdot \log \hat{y}$
- ❑ Cost Function: Its a sum of losses for all instances
  - ❖  $J(W, b) = \frac{1}{m} (\sum \text{Loss}(\hat{y}, y))$
  - ❖  $= -\frac{1}{m} (\sum (y \cdot \log \hat{y} + (1 - y) \cdot \log(1 - \hat{y})))$
- ❑ For binary classification:
  - ❖  $J(W, b) = \frac{1}{m} (\sum \text{Loss}(\hat{y}, y))$
  - ❖  $= -\frac{1}{m} (\sum (y \cdot \log \hat{y}))$

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26

## Forward and Back Propagation



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27

So where are the hidden layers!!!

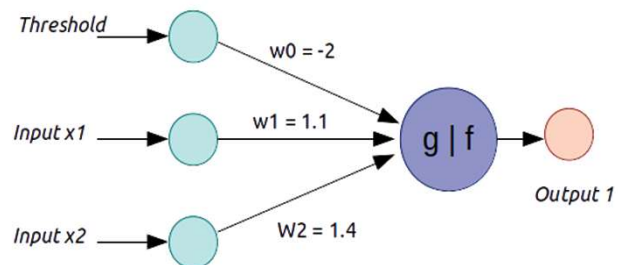
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28

## Hidden Layers

id	Threshold	Team Members		Ground	
	x0	x1	w1	x2	w2
1	-2.00	1.00	1.10	1.00	1.40
2	-2.00	1.00	1.10	0.83	1.40
3	-2.00	1.00	1.10	0.67	1.40
4	-2.00	0.44	1.10	1.00	1.40
5	-2.00	0.22	1.10	0.00	1.40
6	-2.00	0.00	1.10	1.00	1.40



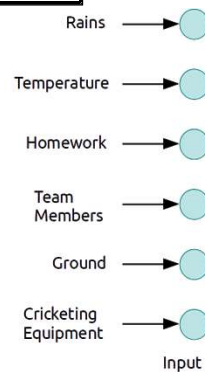
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29

## Hidden Layers

id	Rains	Temp	Homework	Team Members	Equipment	Ground	Played
1	0.00	0.00	1.00	1.00	0.00	1.00	1
2	0.00	0.81	1.00	1.00	1.00	0.83	1
3	0.00	0.75	1.00	1.00	1.00	0.67	1
4	-0.17	0.69	1.00	0.44	1.00	1.00	0
5	-0.67	0.94	0.00	0.22	1.00	0.00	0
6	-1.00	1.00	0.00	0.00	0.00	1.00	0



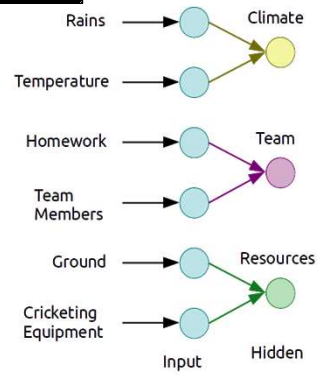
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30

## Hidden Layers

id	Rains	Temp	Homework	Team Members	Equipment	Ground	Played
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2	0.00	0.81	1.00	1.00	1.00	0.83	1
3	0.00	0.75	1.00	1.00	1.00	0.67	1
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6	-1.00	1.00	0.00	0.00	0.00	1.00	0



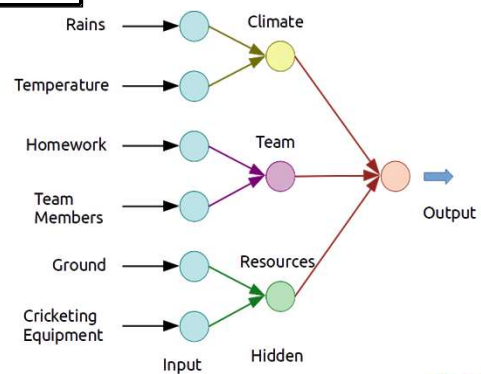
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31

## Hidden Layers

id	Rains	Temp	Homework	Team Members	Equipment	Ground	Played
1	0.00	0.00	1.00	1.00	0.00	1.00	1
2	0.00	0.81	1.00	1.00	1.00	0.83	1
3	0.00	0.75	1.00	1.00	1.00	0.67	1
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5	-0.67	0.94	0.00	0.22	1.00	0.00	0
6	-1.00	1.00	0.00	0.00	0.00	1.00	0

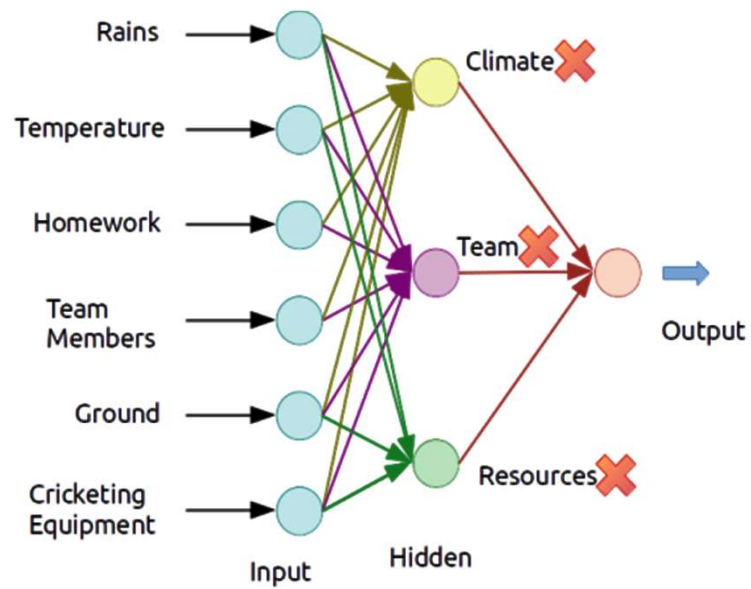


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32

## Hidden Layers



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33

## Hidden Layers



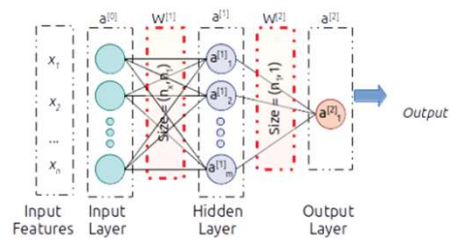
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34

## Two Major Conventions

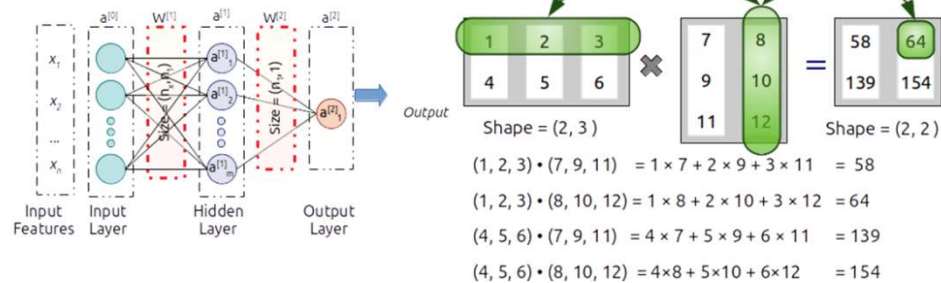


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35

## Two Major Conventions

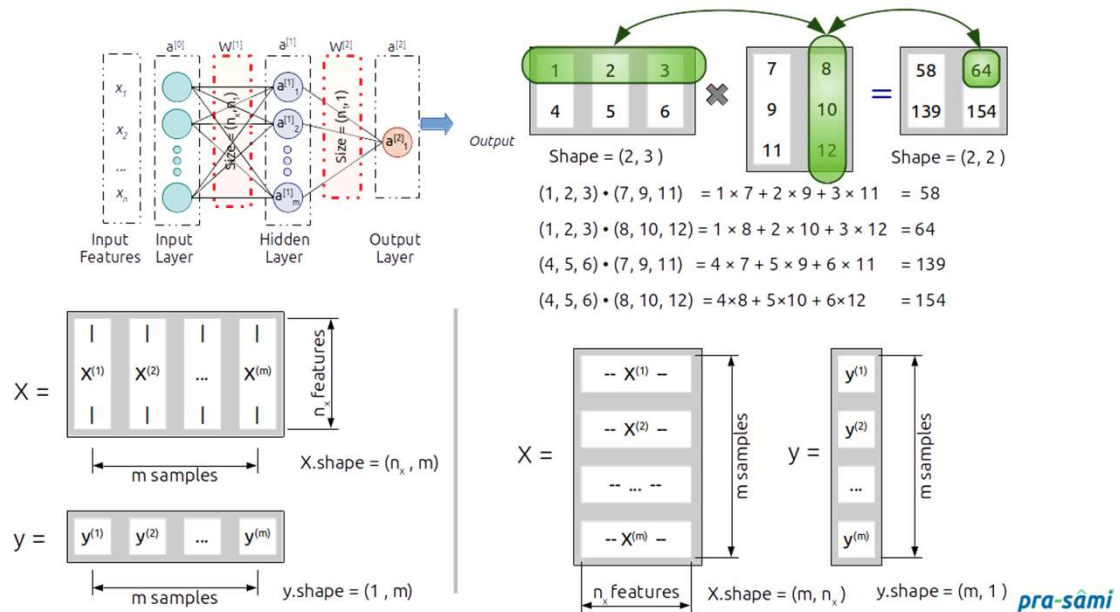


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36

## Two Major Conventions



37

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38

## Reflect...

❑ How many type of layers Deep Learning Algorithms have?

- ❖ A. 2
- ❖ B. 3
- ❖ C. 4
- ❖ D. 5

❑ Answer : B

❑ The first layer is called the?

- ❖ A. Input Layer
- ❖ B. Output Layer
- ❖ C. Hidden Layer
- ❖ D. None of The Above

❑ Answer : A

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❑ Which of the following is/are Limitations of deep learning?

- ❖ A. Data labeling
- ❖ B. Obtain huge training datasets
- ❖ C. Both A and B
- ❖ D. None of the above

❑ Answer : C

❑ Deep learning algorithms are \_\_\_\_\_ more accurate than machine learning algorithm in image classification.

- ❖ A. 33%
- ❖ B. 37%
- ❖ C. 40%
- ❖ D. 41%

❑ Answer : D

39

## Reflect...

❑ In which of the following applications can we use deep learning to solve the problem

- ❖ A. Protein structure prediction
- ❖ B. Prediction of chemical reactions
- ❖ C. Detection of exotic particles
- ❖ D. All of the above

❑ Answer : D

❑ The number of nodes in the input layer is 10 and the hidden layer is 5. The maximum number of connections from the input layer to the hidden layer are:

- ❖ A. 50
- ❖ B. less than 50
- ❖ C. more than 50
- ❖ D. It is an arbitrary value

❑ Answer : A

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❑ What is a perceptron?

- ❖ A. A type of neural network
- ❖ B. A reinforcement learning algorithm
- ❖ C. A clustering algorithm
- ❖ D. A regression algorithm

❑ Answer : A

❑ Who is credited with the invention of the perceptron?

- ❖ A. Geoffrey Hinton
- ❖ B. Yann LeCun
- ❖ C. Frank Rosenblatt
- ❖ D. Andrew Ng

❑ Answer : C

40

## Reflect...

❑ What is the basic building block of a perceptron?

- ❖ A. Neuron
- ❖ B. Weight
- ❖ C. Activation function
- ❖ D. Bias

❑ Answer: A

❑ In a perceptron, what is the purpose of the activation function?

- ❖ A. To compute the weighted sum of inputs
- ❖ B. To introduce non-linearity
- ❖ C. To adjust the weights during training
- ❖ D. To add a bias to the output

❑ Answer: B

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❑ What is the primary purpose of training a perceptron?

- ❖ A. To optimize the activation function
- ❖ B. To minimize the error in the output
- ❖ C. To increase the number of neurons
- ❖ D. To add more layers to the network

❑ Answer: B

❑ In a binary classification problem, what is the output of a perceptron?

- ❖ A. Real number
- ❖ B. Probability
- ❖ C. Binary value (0 or 1)
- ❖ D. Vector

❑ Answer: C

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41

## Reflect...

❑ What is the perceptron learning rule used for?

- ❖ A. Updating weights to reduce prediction error
- ❖ B. Adjusting the learning rate during training
- ❖ C. Initializing weights in the network
- ❖ D. Selecting the appropriate activation function

❑ Answer: A

❑ What happens if a perceptron is unable to learn a linearly separable function?

- ❖ A. It converges quickly
- ❖ B. It converges slowly
- ❖ C. It never converges
- ❖ D. It always converges

❑ Answer: C

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❑ Which of the following statements about the perceptron is true?

- ❖ A. It can only be used for linearly separable problems
- ❖ B. It is suitable for any type of problem
- ❖ C. It can only have one layer
- ❖ D. It has no weights

❑ Answer: A

❑ What is the main limitation of a single-layer perceptron?

- ❖ A. It cannot learn non-linearly separable functions
- ❖ B. It requires a large amount of training data
- ❖ C. It is computationally expensive
- ❖ D. It is not suitable for classification tasks

❑ Answer: A

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42

## Reflect...

- ❑ What is a deep neural network?
  - ❖ A) A neural network with a single layer
  - ❖ B) A neural network with more than one layer
  - ❖ C) A neural network with no layers
  - ❖ D) A neural network with only input and output layers

❑ Answer: B

- ❑ What is the purpose of the backpropagation algorithm in training deep neural networks?
  - ❖ A) To compute the gradient of the loss function with respect to the weights
  - ❖ B) To initialize the weights of the network
  - ❖ C) To regularize the network
  - ❖ D) To activate neurons in the network

❑ Answer: A

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- ❑ What is the primary function of the input layer in a deep neural network?
  - ❖ A) Extracting features from the input data
  - ❖ B) Normalizing the input data
  - ❖ C) Propagating the output to the next layer
  - ❖ D) Receiving input data and passing it to the hidden layers

❑ Answer: D) Receiving input data and passing it to the hidden layers

- ❑ Which term refers to the number of neurons in the hidden layer of a neural network?
  - ❖ A) Depth
  - ❖ B) Width
  - ❖ C) Length
  - ❖ D) Breadth

❑ Answer: B) Width

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43

## Reflect...

- ❑ What does the term "backpropagation" refer to in the context of neural networks?
  - ❖ A) The process of adjusting the weights of the network based on the prediction error
  - ❖ B) The process of training the network using labeled data
  - ❖ C) The process of selecting the optimal hyperparameters for the network
  - ❖ D) The process of initializing the weights of the network

❑ Answer: A) The process of adjusting the weights of the network based on the prediction error

- ❑ What is the primary purpose of using multiple hidden layers in a deep neural network?
  - ❖ A) To increase the computational efficiency
  - ❖ B) To decrease the complexity of the network
  - ❖ C) To learn hierarchical features from the input data
  - ❖ D) To reduce the training time

❑ Answer: C) To learn hierarchical features from the input data

- ❑ Which type of neural network architecture is commonly used for image recognition tasks?
  - ❖ A) Recurrent Neural Network (RNN)
  - ❖ B) Convolutional Neural Network (CNN)
  - ❖ C) Feedforward Neural Network (FNN)
  - ❖ D) Long Short-Term Memory (LSTM)

❑ Answer: B) Convolutional Neural Network (CNN)

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44

## Reflect...

- ❑ What is the purpose of regularization techniques in deep neural networks?
    - ❖ A) To increase the complexity of the model
    - ❖ B) To reduce the computational cost of training
    - ❖ C) To prevent overfitting
    - ❖ D) To speed up the convergence of the training process
  - ❑ Answer: C) To prevent overfitting
  - ❑ Which term describes the process of evaluating the performance of a neural network on unseen data?
    - ❖ A) Training
    - ❖ B) Testing
    - ❖ C) Validation
    - ❖ D) Optimization
  - ❑ Answer: B) Testing
- ❑ What is the primary disadvantage of using deep neural networks?
    - ❖ A) They require large amounts of labeled data for training
    - ❖ B) They are computationally expensive to train
    - ❖ C) They are prone to overfitting
    - ❖ D) They are difficult to interpret
  - ❑ Answer: B) They are computationally expensive to train

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45

Next Session - Coding Perceptron Model in Python

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46



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EXTRA MATERIAL

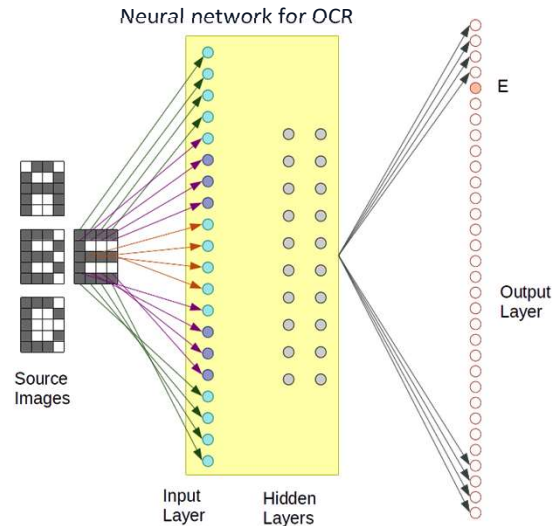
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Applications

48

## Applications

- The properties of neural networks define where they are useful
- Typical Network
  - ❖ Can learn complex mappings from inputs to outputs, based solely on samples
  - ❖ Difficult to analyse
  - ❖ Firm predictions about neural network behaviour difficult;
    - Unsuitable for safety-critical applications.
  - ❖ Require limited understanding from trainer, who can be guided by heuristics



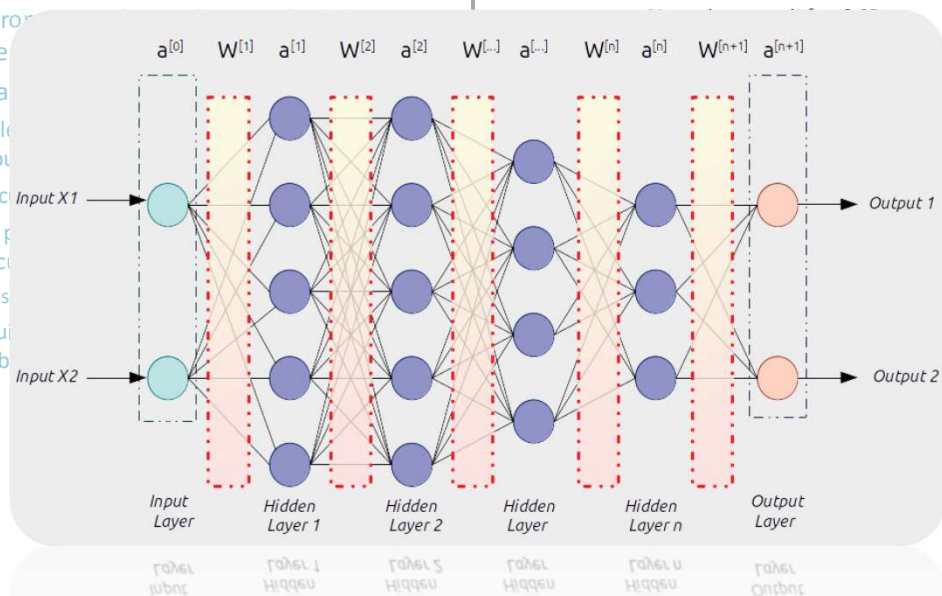
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49

## Applications

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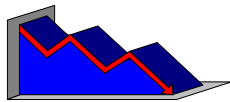


50

## Applications

### □ Stock market prediction

- ❖ “Technical trading” refers to trading based solely on known statistical parameters; e.g. previous price
- ❖ Neural networks have been used to attempt to predict changes in prices.
- ❖ Difficult to assess success or otherwise
  - Since companies using these techniques are reluctant to disclose information.



### □ Mortgage assessment

- ❖ Assess risk of lending to an individual
- ❖ Difficult to decide on marginal cases
- ❖ Neural networks have been trained to make decisions, based upon the opinions of expert underwriters
- ❖ Neural network produced a 12% reduction in delinquencies compared with human experts



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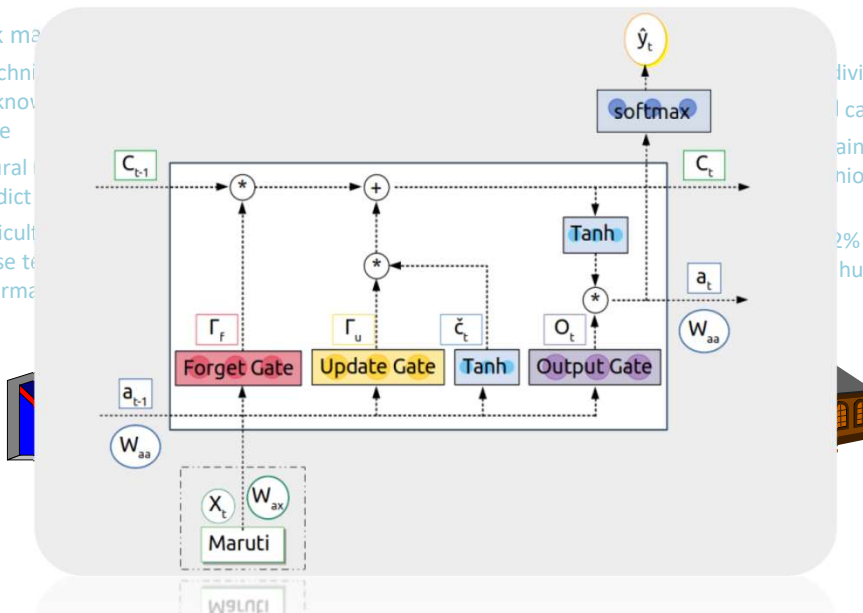
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51

## Applications

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52

## Applications

### ALVINN: Autonomous Land Vehicle In a Neural Network

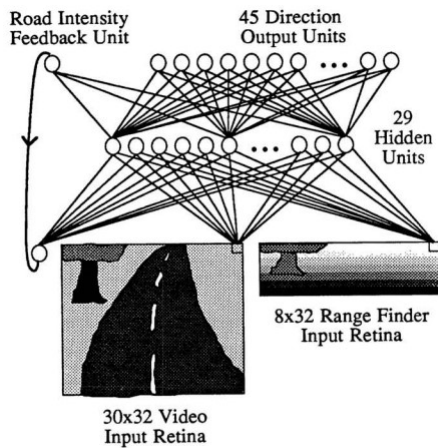
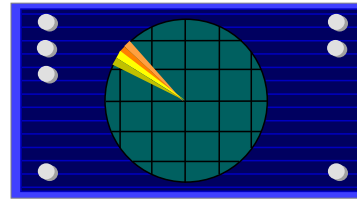


Figure 1: ALVINN Architecture

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### Sonar target recognition

- ❖ Distinguish mines from rocks on sea-bed
- ❖ The neural network is provided with a large number of parameters which are extracted from the sonar signal.
- ❖ The training set consists of sets of signals from rocks and mines.

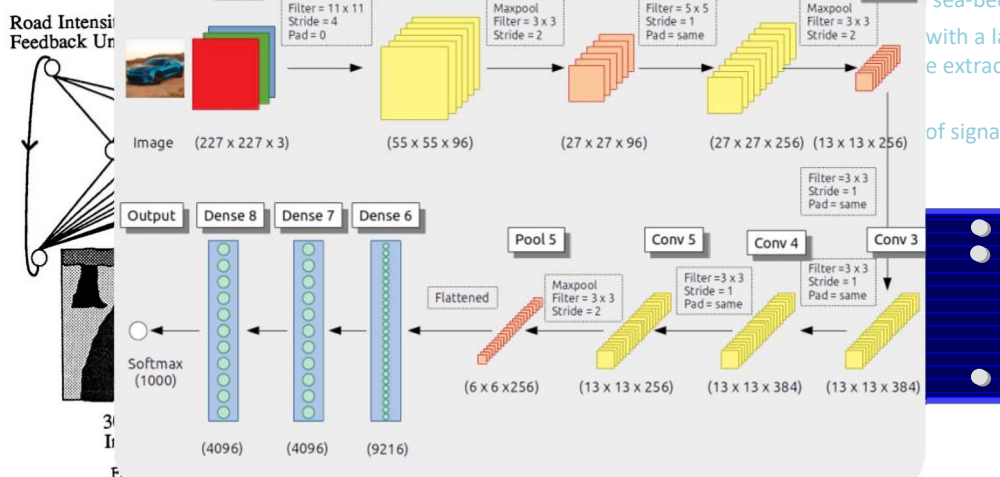


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53

## Applications

### ALVINN: Autonomous Land Vehicle In a Neural Network



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54

## Applications

### □ Engine management

- ❖ The behavior of a car engine is influenced by a large number of parameters
  - > temperature at various points
  - > fuel/air mixture
  - > lubricant viscosity.
- ❖ Major companies have used neural networks to dynamically tune an engine depending on current settings



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### □ Signature recognition

- ❖ Each person's signature is different.
- ❖ There are structural similarities which are difficult to quantify.
- ❖ Recognizes signatures to a high level of accuracy.
- ❖ Considers speed in addition to gross shape
- ❖ Makes forgery even more difficult.

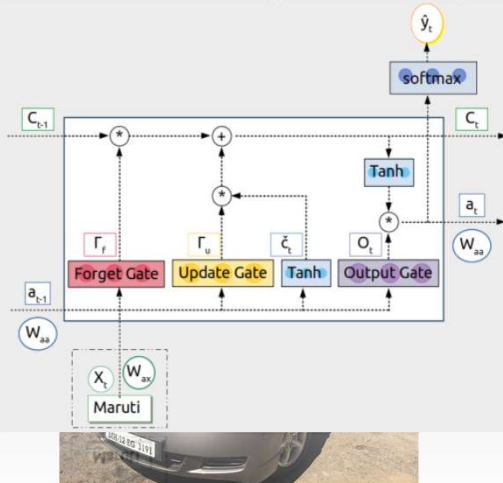
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55

## Applications

### □ Engine management

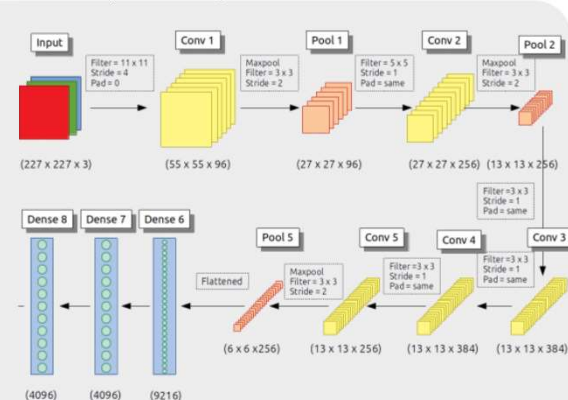
- ❖ The behavior of a car engine is influenced by a



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### □ Signature recognition

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## Derivation of Sigmoid

$$\begin{aligned}
 \partial a &= \partial \sigma(z) \\
 &= \frac{\partial}{\partial z} \left[ \frac{1}{1 + e^{-z}} \right] \\
 &= \frac{\partial}{\partial z} (1 + e^{-z})^{-1} \\
 &= -(1 + e^{-z})^{-2} (-e^{-z}) \\
 &= \frac{e^{-z}}{(1 + e^{-z})^2} \\
 &= \frac{1}{1 + e^{-z}} \circ \frac{e^{-z}}{1 + e^{-z}} \\
 &= \frac{1}{1 + e^{-z}} \circ \frac{(1 + e^{-z}) - 1}{1 + e^{-z}} \\
 &= \frac{1}{1 + e^{-z}} \circ \left[ \frac{1 + e^{-z}}{1 + e^{-z}} - \frac{1}{1 + e^{-z}} \right] \\
 &= \frac{1}{1 + e^{-z}} \circ \left[ 1 - \frac{1}{1 + e^{-z}} \right] \\
 &= \sigma(z) \circ (1 - \sigma(z)) \\
 &= a \circ (1 - a)
 \end{aligned}$$