

Kunal Yede

✉ kunaloff2000@gmail.com ☎ 9112343877 📍 New Sanghvi, Pune in kunal-yede 🌐 kunal-yede

PROFILE

A fresher software developer looking forward for challenging opportunities to strategical & operational goal of the company & to implement the knowledge & skills to contribute to the success of the organization as well as to enhance my knowledge.

PROFESSIONAL EXPERIENCE

Java Development Intern, CodeClause 2023/07 – 2023/08
Basic Projects :- Folder Locker using Java
Timer & Stopwatch using Java

EDUCATION

Bachelor Of Engineering, Sant Gadge Baba Amravati university 2018/08 – 2022/06
Mechanical Engineering Amravati
75.55%

HSC, G.B.M.M. Jr. College 2017/06 – 2018/03
81.69% Hinganghat, India

TECHNICAL SKILLS

Core Java, SQL ((RDBMS, Joins, Good Knowledge of writing Queries)),
Advance Java ((Multithreading, JDBC, hibernate)), **Microsoft Excel, Troubleshooting, Debugging,**
Web Development Technologies : (Html, Css, JavaScript),
Framework : (ReactJs, Spring Core, Spring Hibernate, Spring MVC, Spring Boot),
Data structure and algorithm

SOFT SKILLS

- Adaptability
- Effective Communication
- Team work
- Problem solving
- Ability to collaborate
- management Skills

COURSES

Full Stack Java Development, Qspiders Software testing and Developemnt institute 2022/09 – 2023/04
Pune, India

PROJECTS

Weather App

- users can enter any city name to get the 5-day weather forecast.
- Including temperature, wind speed, humidity, and more.

Full Stack E-commerce Website

- Product search, add to cart and payment Options are available
- Used Strapi Headless CMS
- CRUD Operations in Strapi
- Used Stripe payment gateway

ACADEMIC PROJECTS

Automated Guided Vehicle:- 2022/02 – 2022/05

Description: - An automated guided vehicle (AGV), different from an autonomous mobile robot (AMR), is a portable robot follows along marked long lines or wires on the floor, or uses radio waves, vision cameras, magnets, or lasers for navigation.

Key responsibilities:

Understanding the requirements and functionality of AGV's.
Use Embedded System to run the AGV according to sensors.