Class: Final Year (Computer Science and Engineering)

**Year:** 2022-23 **Semester:** 1

**Course:** High Performance Computing Lab

**Practical No. 10** 

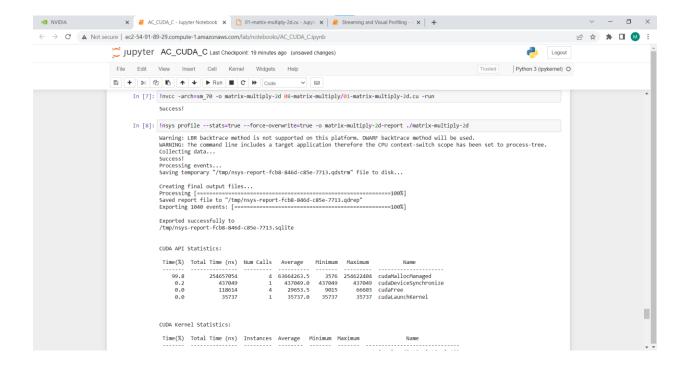
Exam Seat No: 2019BTECS00064

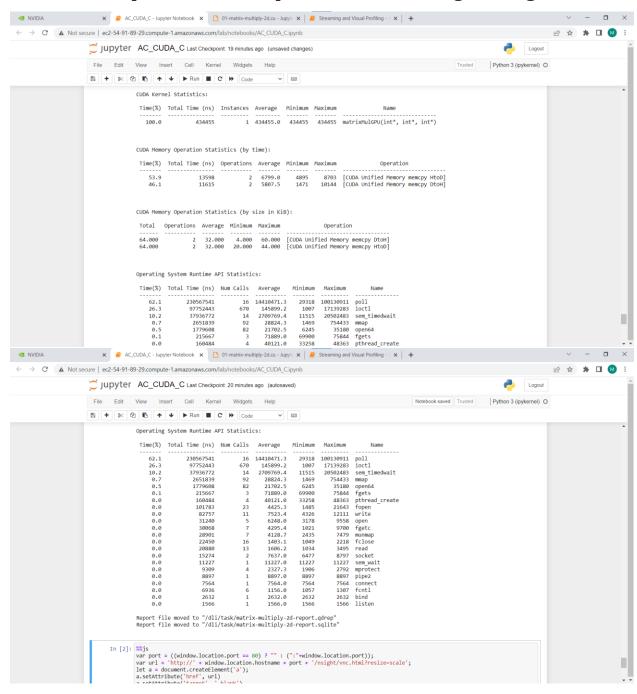
Name - Kunal Santosh Kadam

#### **Problem Statement 1:**

Implement Matrix-matrix Multiplication using global memory in CUDA C. Analyze and tune the program for getting maximum speed up. Do Profiling and state what part of the code takes the huge amount of time to execute

#### Screenshot #:





#### Information #:

```
#include <stdio.h>
#define N 64
__global__ void matrixMulGPU( int * a, int * b, int * c )
      int val = 0;
      int row = blockIdx.x * blockDim.x + threadIdx.x;
      int col = blockIdx.y * blockDim.y + threadIdx.y;
      if (row < N \&\& col < N)
             for ( int k = 0; k < N; ++k )
                    val += a[row * N + k] * b[k * N + col];
             c[row * N + col] = val;
      }
}
void matrixMulCPU( int * a, int * b, int * c )
      int val = 0;
      for( int row = 0; row < N; ++row )
             for( int col = 0; col < N; ++col )
             {
                    val = 0;
                    for ( int k = 0; k < N; ++k )
                           val += a[row * N + k] * b[k * N + col];
                    c[row * N + col] = val;
             }
}
```

```
int main()
{
      int *a, *b, *c cpu, *c gpu;
      int size = N * N * sizeof (int); // Number of bytes of an N x N matrix
      // Allocate memory
      cudaMallocManaged (&a, size);
      cudaMallocManaged (&b, size);
      cudaMallocManaged (&c_cpu, size);
      cudaMallocManaged (&c gpu, size);
      // Initialize memory
      for( int row = 0; row < N; ++row )
            for( int col = 0; col < N; ++col )
            {
                  a[row*N + col] = row;
                  b[row*N + col] = col+2;
                  c cpu[row*N + col] = 0;
                  c gpu[row*N + col] = 0;
            }
      dim3 threads per block (16, 16, 1); // A 16 x 16 block threads
      dim3 number of blocks ((N / threads per block.x) + 1, (N /
threads_per_block.y) + 1, 1);
      matrixMulGPU <<< number of blocks, threads per block >>> (a, b,
c_gpu );
      cudaDeviceSynchronize(); // Wait for the GPU to finish before
proceeding
      // Call the CPU version to check our work
```

### **Department of Computer Science and Engineering**

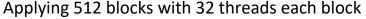
```
matrixMulCPU( a, b, c_cpu );
// Compare the two answers to make sure they are equal
bool error = false;
for( int row = 0; row < N && !error; ++row )
      for( int col = 0; col < N && !error; ++col )
            if (c cpu[row * N + col] != c gpu[row * N + col])
            {
                   printf("FOUND ERROR at c[%d][%d]\n", row, col);
                   error = true;
                   break;
            }
if (!error)
      printf("Success!\n");
// Free all our allocated memory
cudaFree(a);
cudaFree(b);
cudaFree( c_cpu );
cudaFree( c_gpu );
```

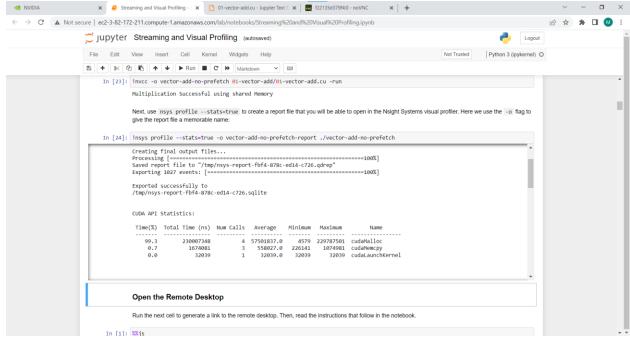
}

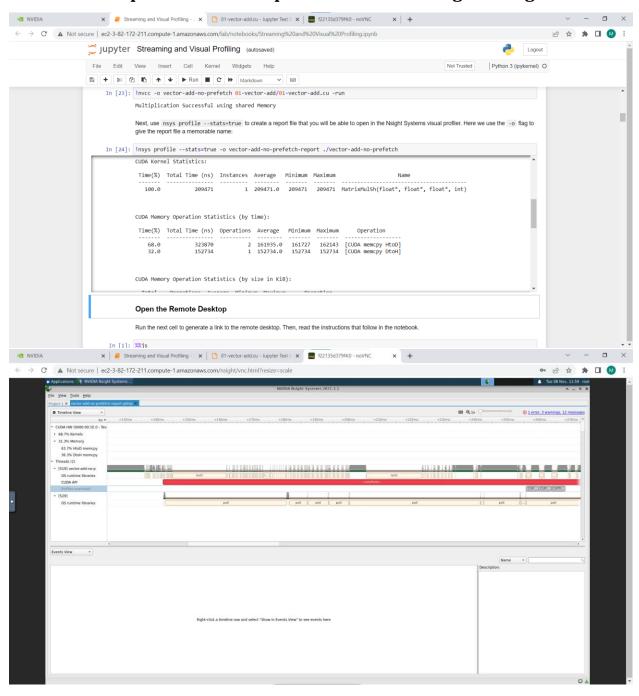
#### **Problem Statement 2:**

Implement Matrix-Matrix Multiplication using shared memory in CUDA C. Analyze and tune the program for getting maximum speed up. Do Profiling and state what part of the code takes the huge amount of time to execute.

#### Screenshot #:

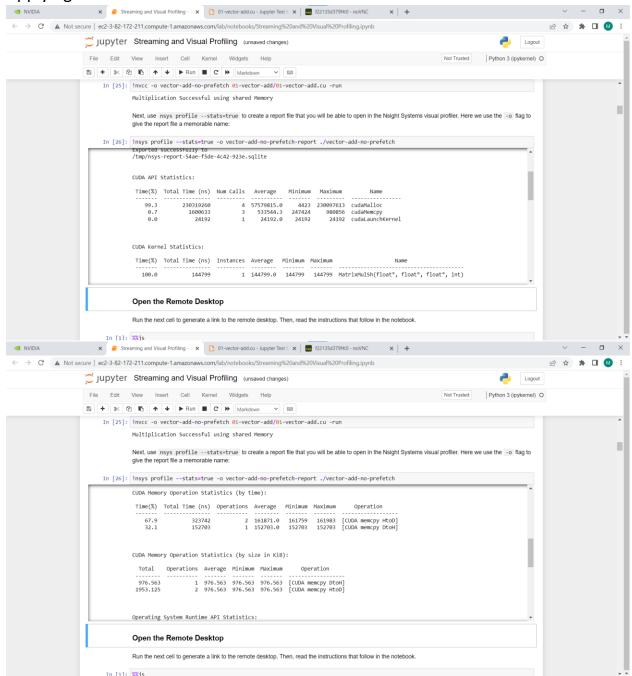






### **Department of Computer Science and Engineering**

Applying 256 blocks with 16 threads each block



#### Information #:

```
#include <stdio.h>
#include <math.h>
#define TILE WIDTH 2
/*matrix multiplication kernels*/
// shared
global void
MatrixMulSh(float *Md, float *Nd, float *Pd, const int WIDTH)
{
      //Taking shared array to break the MAtrix in Tile widht and fatch
them in that array per ele
      shared float Mds [TILE WIDTH][TILE WIDTH];
      __shared__ float Nds [TILE_WIDTH][TILE_WIDTH];
      // calculate thread id
      unsigned int col = TILE WIDTH*blockIdx.x + threadIdx.x;
      unsigned int row = TILE WIDTH*blockldx.y + threadIdx.y;
      for (int m = 0; m<WIDTH/TILE WIDTH; m++) // m indicate number
of phase
      {
            Mds[threadIdx.y][threadIdx.x] = Md[row*WIDTH +
(m*TILE_WIDTH + threadIdx.x)];
            Nds[threadIdx.y][threadIdx.x] = Nd[(m*TILE WIDTH+
threadIdx.y) * WIDTH + col];
            syncthreads(); // for syncronizeing the threads
           // Do for tile
```

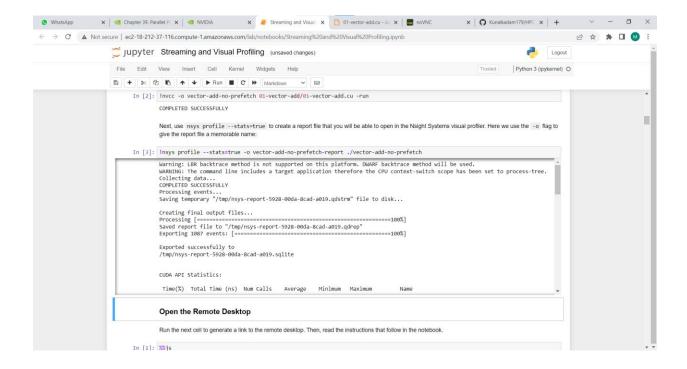
```
for (int k = 0; k < TILE WIDTH; k++)
                  Pd[row*WIDTH + col]+= Mds[threadIdx.x][k] *
Nds[k][threadIdx.y];
            __syncthreads(); // for syncronizeing the threads
      }
}
// main routine
int main ()
{
      const int WIDTH = 500;
      float array1_h[WIDTH][WIDTH], array2_h[WIDTH][WIDTH],
M result array h[WIDTH][WIDTH];
      float *array1 d, *array2 d, *result array d, *M result array d; //
device array
      int i, j;
      //input in host array
      for (i = 0; i < WIDTH; i++)
      {
            for (j = 0; j < WIDTH; j++)
            {
                  array1 h[i][j] = (i + 2*j) \%500;
                  array2_h[i][j] = (i + 3*j) %500;
            }
      }
      //create device array cudaMalloc ( (void **)&array name,
sizeofmatrixinbytes);
      cudaMalloc((void **) &array1 d , WIDTH*WIDTH*sizeof (int) );
      cudaMalloc((void **) &array2 d , WIDTH*WIDTH*sizeof (int) );
```

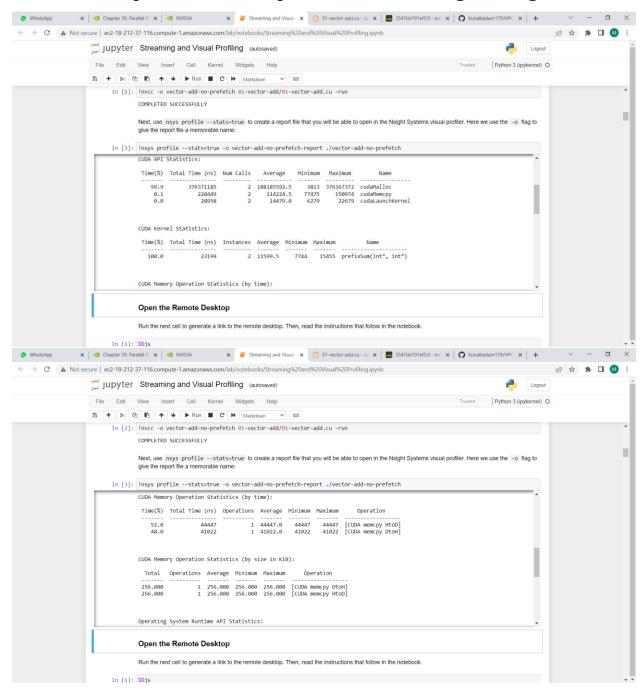
```
//copy host array to device array; cudaMemcpy ( dest , source ,
WIDTH, direction)
     cudaMemcpy ( array1 d , array1 h , WIDTH*WIDTH*sizeof (int) ,
cudaMemcpyHostToDevice );
     cudaMemcpy ( array2_d , array2_h , WIDTH*WIDTH*sizeof (int) ,
cudaMemcpyHostToDevice);
     //allocating memory for resultent device array
     cudaMalloc((void **) &result array d, WIDTH*WIDTH*sizeof (int));
     cudaMalloc((void **) &M result array d, WIDTH*WIDTH*sizeof
(int));
     MatrixMulSh<<<512,32>>> (array1 d, array2 d, M result array d,
WIDTH);
     // all gpu function blocked till kernel is working
     //copy back result_array_d to result_array_h
     cudaMemcpy(M result array h, M result array d,
WIDTH*WIDTH*sizeof(int), cudaMemcpyDeviceToHost);
  printf("Multiplication Successful using shared Memory");
}
```

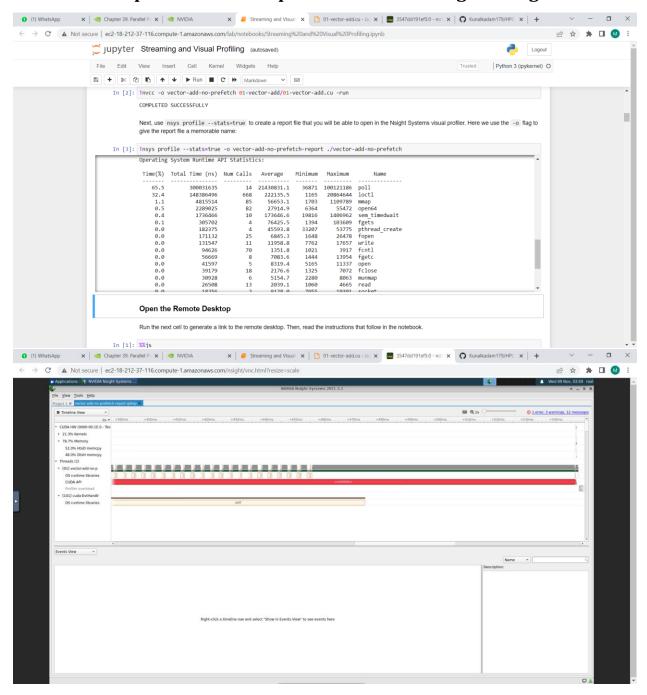
#### **Problem Statement 3:**

Implement Prefix sum using CUDA C. Analyze and tune the program for getting maximum speed up. Do Profiling and state what part of the code takes the huge amount of time to execute.

#### Screenshot #:







#### Information #:

```
// This program computes prefix sum with warp divergence
#include <bits/stdc++.h>
using std::accumulate;
using std::generate;
using std::cout;
using std::vector;
#define SHMEM SIZE 256
global void prefixSum(int *v, int *v r) {
  // Allocate shared memory
  shared int partial sum[SHMEM SIZE];
  // Calculate thread ID
  int tid = blockIdx.x * blockDim.x + threadIdx.x;
  // Load elements into shared memory
  partial sum[threadIdx.x] = v[tid];
  __syncthreads();
  // Iterate of log base 2 the block dimension
  for (int s = 1; s < blockDim.x; s *= 2) {
    // Reduce the threads performing work by half previous the previous
    // iteration each cycle
    if (threadIdx.x \% (2 * s) == 0) {
      partial sum[threadIdx.x] += partial sum[threadIdx.x + s];
    }
      _syncthreads();
  // Let the thread 0 for this block write it's result to main memory
```

```
// Result is inexed by this block
  if (threadIdx.x == 0) {
    v r[blockIdx.x] = partial sum[0];
 }
}
int main() {
 // Vector size
  int N = 1 << 16;
  size t bytes = N * sizeof(int);
 // Host data
 vector<int> h v(N);
 vector<int> h_v_r(N);
// Initialize the input data
 generate(begin(h_v), end(h_v), [](){ return rand() % 10; });
 // Allocate device memory
 int *d v, *d v r;
  cudaMalloc(&d v, bytes);
  cudaMalloc(&d_v_r, bytes);
 // Copy to device
  cudaMemcpy(d v, h v.data(), bytes, cudaMemcpyHostToDevice);
 // TB Size
  const int TB SIZE = 256;
 // Grid Size (No padding)
  int GRID_SIZE = N / TB_SIZE;
 // Call kernels
  prefixSum<<<GRID_SIZE, TB_SIZE>>>(d_v, d_v_r);
```

```
prefixSum<<<1, TB_SIZE>>> (d_v_r, d_v_r);

// Copy to host;
cudaMemcpy(h_v_r.data(), d_v_r, bytes, cudaMemcpyDeviceToHost);

// Print the result
assert(h_v_r[0] == std::accumulate(begin(h_v), end(h_v), 0));

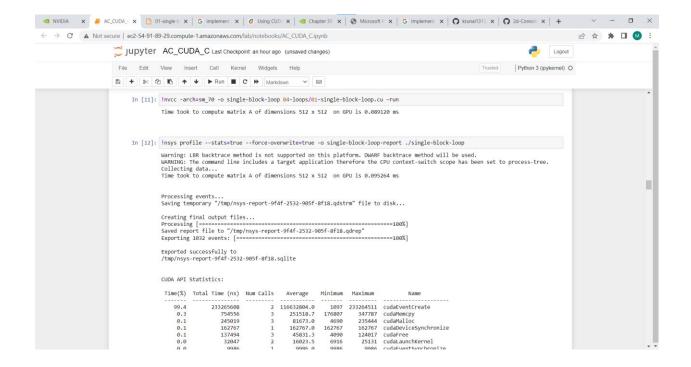
cout << "COMPLETED SUCCESSFULLY\n";

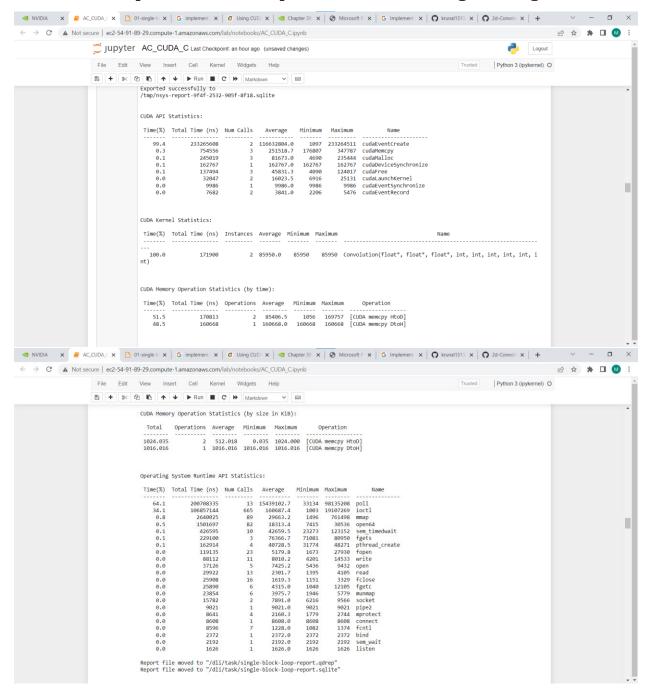
return 0;
}</pre>
```

#### **Problem Statement 4:**

Implement 2D Convolution using shared memory using CUDA C. Analyze and tune the program for getting maximum speed up. Do Profiling and state what part of the code takes the huge amount of time to execute.

#### Screenshot #:





#### Information #:

```
#include <stdio.h>
#include <cstdlib>
#include <time.h>
#define BLOCK SIZE 32
#define WA 512
#define HA 512
#define HC 3
#define WC 3
#define WB (WA - WC + 1)
\#define HB (HA - HC + 1)
global void Convolution(float* A, float* B, float* C, int numARows, int
numACols, int numBRows, int numBCols, int numCRows, int numCCols)
{
      int col = blockIdx.x * (BLOCK SIZE - WC + 1) + threadIdx.x;
      int row = blockIdx.y * (BLOCK SIZE - WC + 1) + threadIdx.y;
      int row i = row - WC + 1;
      int col i = col - WC + 1;
      float tmp = 0;
      __shared__ float shm[BLOCK_SIZE][BLOCK_SIZE];
      if (row i < WA \&\& row i >= 0 \&\& col i < WA \&\& col i >= 0)
      {
            shm[threadIdx.y][threadIdx.x] = A[col i * WA + row i];
      else
      {
            shm[threadIdx.y][threadIdx.x] = 0;
```

```
}
      __syncthreads();
      if (threadIdx.y < (BLOCK SIZE - WC + 1) && threadIdx.x < (BLOCK SIZE
-WC + 1) && row < (WB - WC + 1) && col < (WB - WC + 1))
            for (int i = 0; i < WC;i++)
                   for (int j = 0;j < WC;j++)
                         tmp += shm[threadIdx.y + i][threadIdx.x + i] *
C[j*WC + i];
             B[col*WB + row] = tmp;
      }
}
void randomInit(float* data, int size)
{
      for (int i = 0; i < size; ++i)
            data[i] = rand() / (float)RAND MAX;
}
int main(int argc, char** argv)
{
      srand(2006);
      cudaError_t error;
      cudaEvent t start G, stop G;
      cudaEventCreate(&start G);
      cudaEventCreate(&stop G);
      unsigned int size A = WA * HA;
      unsigned int mem size A = sizeof(float) * size A;
      float* h_A = (float*)malloc(mem_size_A);
```

```
unsigned int size B = WB * HB;
      unsigned int mem size B = sizeof(float) * size B;
      float* h B = (float*)malloc(mem size B);
      unsigned int size C = WC * HC;
      unsigned int mem_size_C = sizeof(float) * size_C;
      float* h C = (float*)malloc(mem size C);
      randomInit(h A, size A);
      randomInit(h C, size C);
      float* d A;
      float* d B;
      float* d C;
      error = cudaMalloc((void**)&d A, mem size A);
      if (error != cudaSuccess)
      {
            fprintf(stderr, "GPUassert: %s in cudaMalloc for A\n",
cudaGetErrorString(error));
            return EXIT FAILURE;
      }
      error = cudaMalloc((void**)&d B, mem size B);
      if (error != cudaSuccess)
      {
            fprintf(stderr, "GPUassert: %s in cudaMalloc for B\n",
cudaGetErrorString(error));
            return EXIT FAILURE;
      }
      error = cudaMalloc((void**)&d C, mem size C);
      if (error != cudaSuccess)
```

```
{
            fprintf(stderr, "GPUassert: %s in cudaMalloc for C\n",
cudaGetErrorString(error));
            return EXIT FAILURE;
     }
     error = cudaMemcpy(d A, h A, mem size A,
cudaMemcpyHostToDevice);
     if (error != cudaSuccess)
     {
            fprintf(stderr, "GPUassert: %s in cudaMemcpy for A\n",
cudaGetErrorString(error));
            return EXIT FAILURE;
     }
     error = cudaMemcpy(d C, h C, mem size C,
cudaMemcpyHostToDevice);
     if (error != cudaSuccess)
     {
            fprintf(stderr, "GPUassert: %s in cudaMemcpy for C\n",
cudaGetErrorString(error));
            return EXIT FAILURE;
     }
      dim3 threads(BLOCK SIZE, BLOCK SIZE);
     dim3 grid((WB - 1) / (BLOCK SIZE - WC + 1), (WB - 1) / (BLOCK SIZE -
WC + 1));
     Convolution << < grid, threads >> >(d A, d B, d C, HA, WA, HB, WB,
HC, WC);
     cudaEventRecord(start G);
```

```
Convolution << < grid, threads >> >(d A, d B, d C, HA, WA, HB, WB,
HC, WC);
      error = cudaGetLastError();
      if (error != cudaSuccess)
            fprintf(stderr, "GPUassert: %s in launching kernel\n",
cudaGetErrorString(error));
            return EXIT FAILURE;
      }
      error = cudaDeviceSynchronize();
      if (error != cudaSuccess)
            fprintf(stderr, "GPUassert: %s in cudaDeviceSynchronize \n",
cudaGetErrorString(error));
            return EXIT FAILURE;
      }
      cudaEventRecord(stop_G);
      cudaEventSynchronize(stop G);
      error = cudaMemcpy(h B, d B, mem size B,
cudaMemcpyDeviceToHost);
      if (error != cudaSuccess)
      {
            fprintf(stderr, "GPUassert: %s in cudaMemcpy for B\n",
cudaGetErrorString(error));
            return EXIT_FAILURE;
      }
```

### **Department of Computer Science and Engineering**

```
float miliseconds = 0;
cudaEventElapsedTime(&miliseconds, start_G, stop_G);
printf("Time took to compute matrix A of dimensions %d x %d on GPU is %f ms \n \n \n", WA, HA, miliseconds);
```

```
//for (int i = 0; i < HB; i++)
      //{
      //
             for (int j = 0; j < WB; j++)
      //
             {
                   printf("%f", h_B[i*HB + j]);
      //
      //
             }
      //
             printf("\n");
      //}
      free(h A);
      free(h B);
      free(h C);
      cudaFree(d_A);
      cudaFree(d B);
      cudaFree(d_C);
      return EXIT SUCCESS;
}
```

#### **Github Link:**

https://github.com/Kunalkadam179/HPC-Assignment/tree/main/Assignment%20-%2010