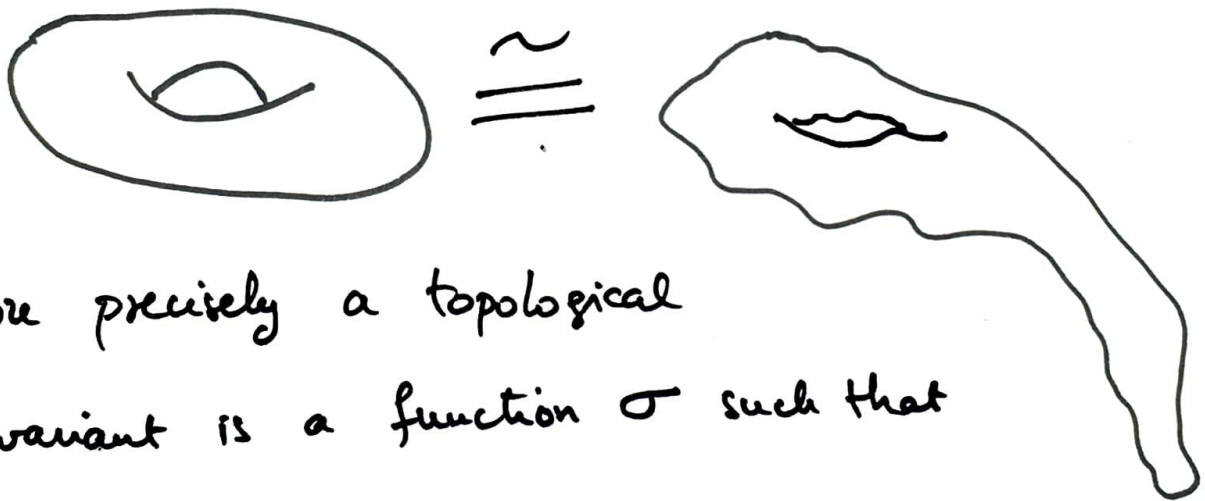


TOPOLOGICAL INVARIANTS

HOMOTOPY

We want to study properties of X that remain if we deform X by a homeomorphism.



More precisely a topological invariant is a function σ such that

if X is homeomorphic to Y

then $\sigma(X) = \sigma(Y)$.

Example: classify capital letters of the latin alphabet.

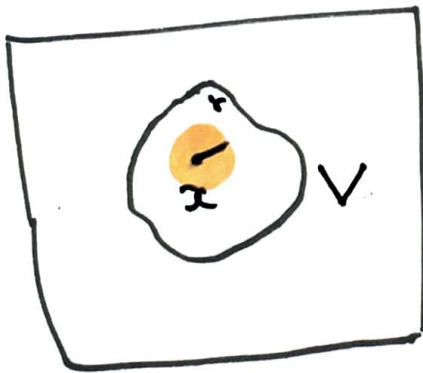
$I \sim L \not\sim P \dots$

Def. An n -vertex in a subset L of a topological (metric) space S is an element $v \in L$ such that there is a neighborhood $N_0 \subseteq S$ with $v \in N_0$ such that all neighborhoods $v \in N \subseteq N_0$ satisfy:

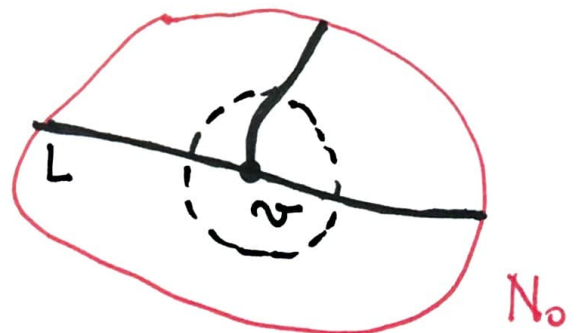
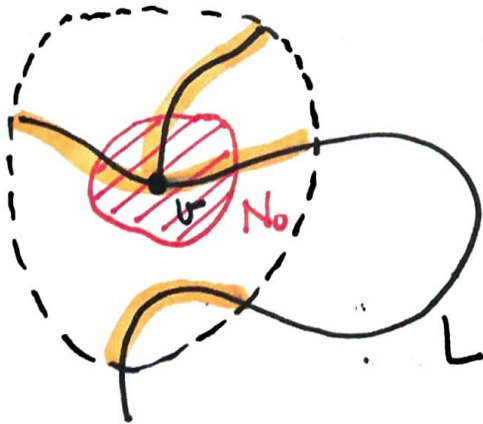
- $N \cap L$ is connected
- $N \cap L \setminus \{v\}$ has exactly n connected components.

For us now: $S = \mathbb{R}^2$, $L = \text{some curve (typically a letter)}$

Recall that a neighborhood of a point $x \in S$ is a subset V that contains an open set that contains x .

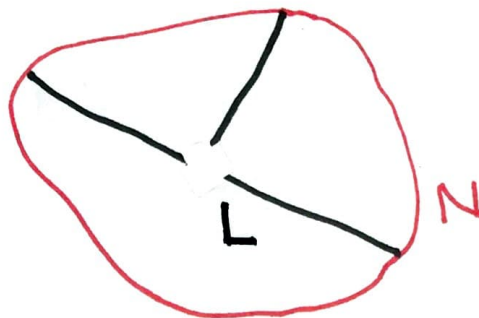


In a metric space, a neighborhood of x is a subset V that contains $B(x, r)$ for some $r > 0$.



$$N \cap L \setminus \{v\}$$

has 3 connected components.

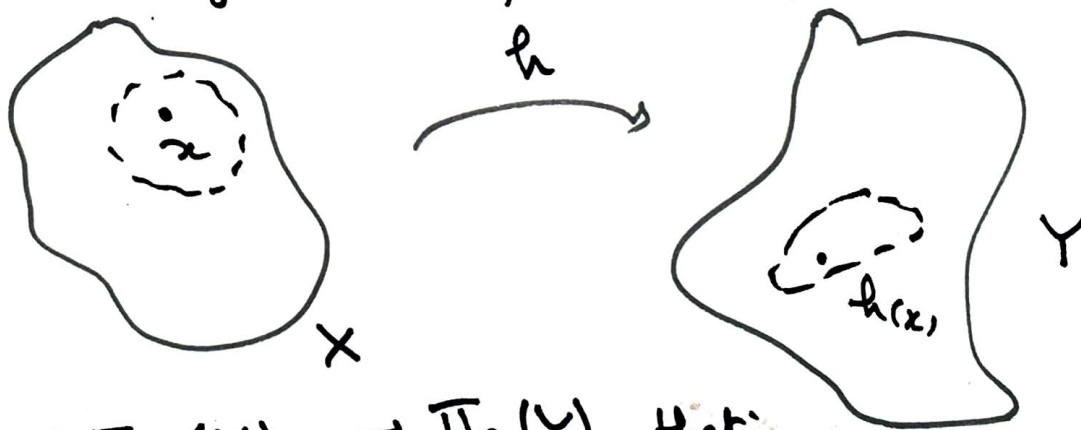


We see that v is a 3-vertex of L .

Observation: n -vertices are defined only in terms of neighborhoods and connected components.

If $h: X \xrightarrow{\sim} Y$ is a homeomorphism, then

$\rightarrow \forall x \in X$, h transforms a neighborhood of x into a neighborhood of $h(x)$.



$\rightarrow h_*: \pi_0(X) \rightarrow \pi_0(Y)$, that is,

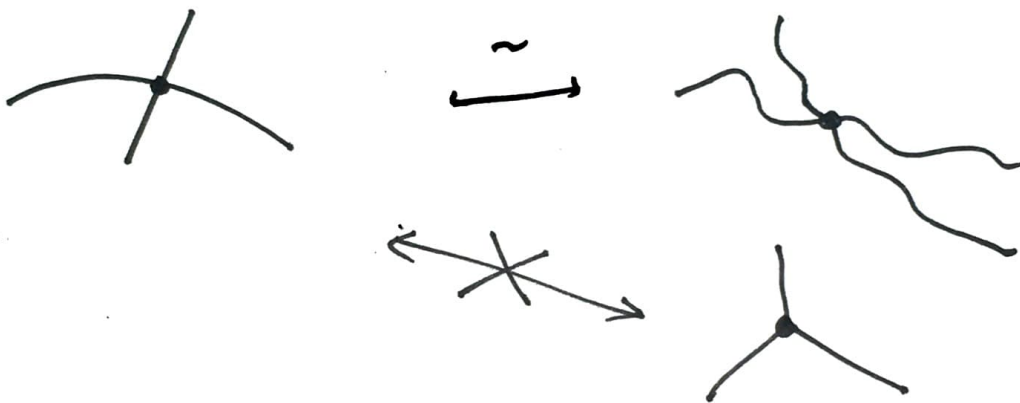
h preserves the number of connected components.

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Th. If $h: X \xrightarrow{\sim} Y$ is a homeomorphism,
It sends any m -vertex to an m -vertex.

In other words, the number of m -vertices is a
topological invariant!

Note: every point on a curve is a 2-vertex.



An issue in classifying letters:

- I $\not\sim$ F because I has no 3-vertex.
F has a 3-vertex.



- Can we compare I and \bigcirc ?

→ How do we formulate the fact that \bigcirc
has a hole?

Observe: let x be a point on $|$ or \bigcirc .

$| \setminus \{x\} = |$ is disconnected

$\bigcirc \setminus \{x\} = \bigcirc$ is still connected!

To classify letters, we may count holes, 3 vertices and h -vertices.

E, F, T, Y are all homeomorphic.

$E \rightsquigarrow \{ \rightsquigarrow |$

$F \rightsquigarrow \text{hooked F} \rightsquigarrow |$ (0, 1, 0)

$T \rightsquigarrow |$ (rotation)

$Y \rightsquigarrow T \rightsquigarrow |$



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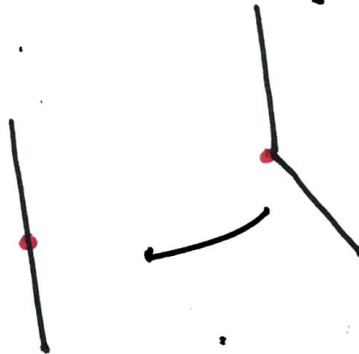


remove point



2 components

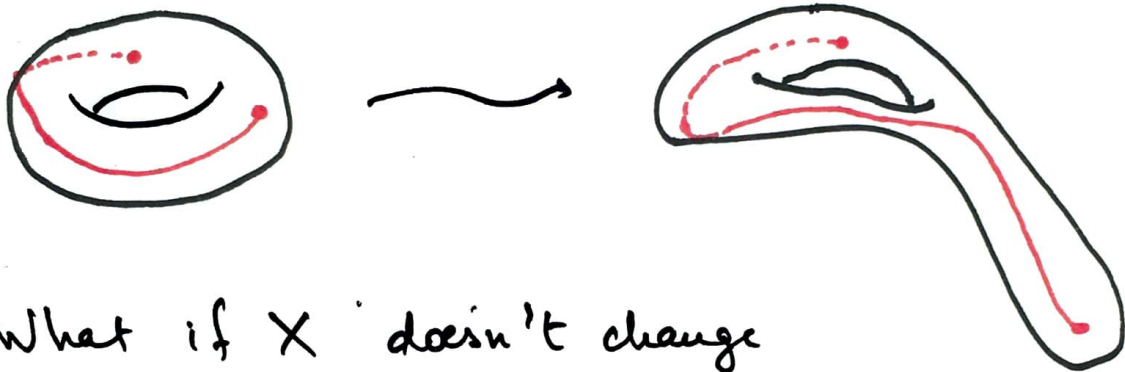
2 components

 \cong 

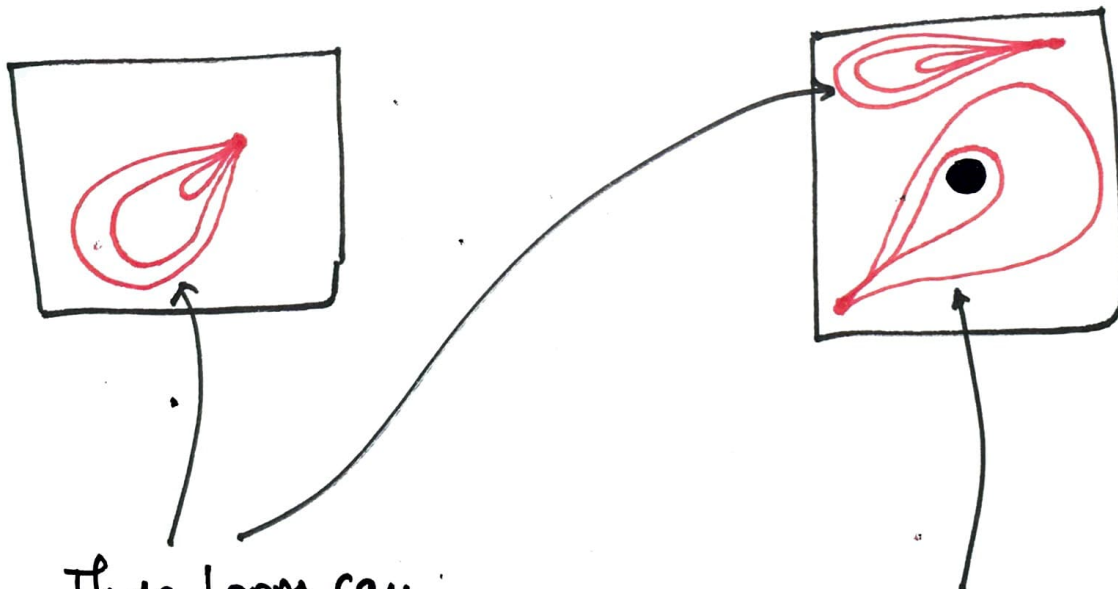
Note: These successive transformations are continuous and reversible, that is, they are homeomorphisms.

Homotopy

Idea: if X is deformed into something homeomorphic, or at least continuous, the curves on X are deformed too:

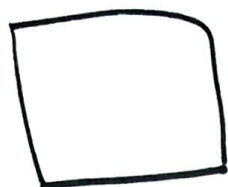


→ What if X doesn't change and we try to deform curves on X ?

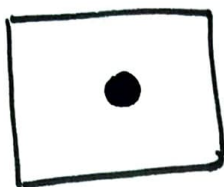


These loops can be deformed to a single point in a continuous way.

This one cannot

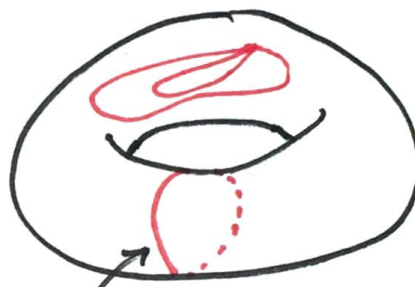
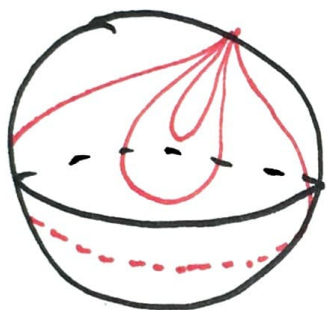


X



Y

- Every loop in X can be contracted continuously to a single point.
- Not in Y : only loops that do not enclose the hole can be contracted.



cannot be contracted.

Def Let X, Y be metric space and $f, g: X \rightarrow Y$ two continuous maps. We say f and g are homotopic if there is a continuous map

$$H: [0, 1] \times X \longrightarrow Y$$

such that $H(0, \cdot) = f$ and $H(1, \cdot) = g$
 H is called a homotopy between f and g .

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$$H: [0,1] \times X \longrightarrow Y$$

$$(t, x) \longmapsto H(t, x)$$

$$t \in [0,1]$$

$$x \in X$$

For every $t_0 \in [0,1]$, consider:

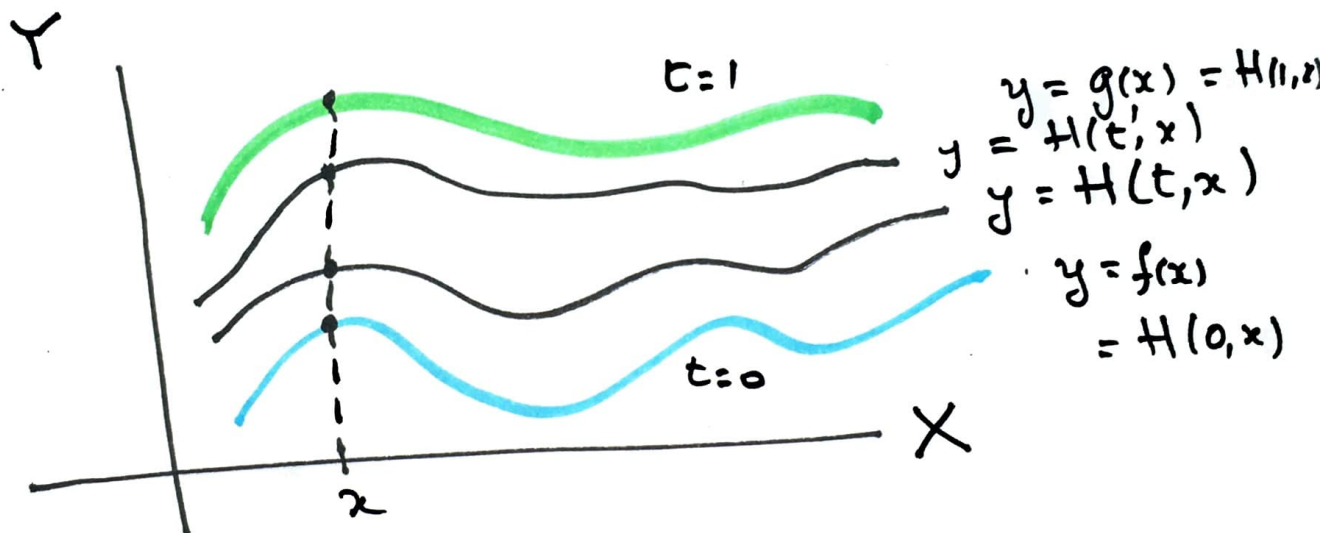
$$H(t_0, \cdot): X \longrightarrow Y$$

$$x \longmapsto H(t_0, x)$$

Saying that H is a homotopy is saying:

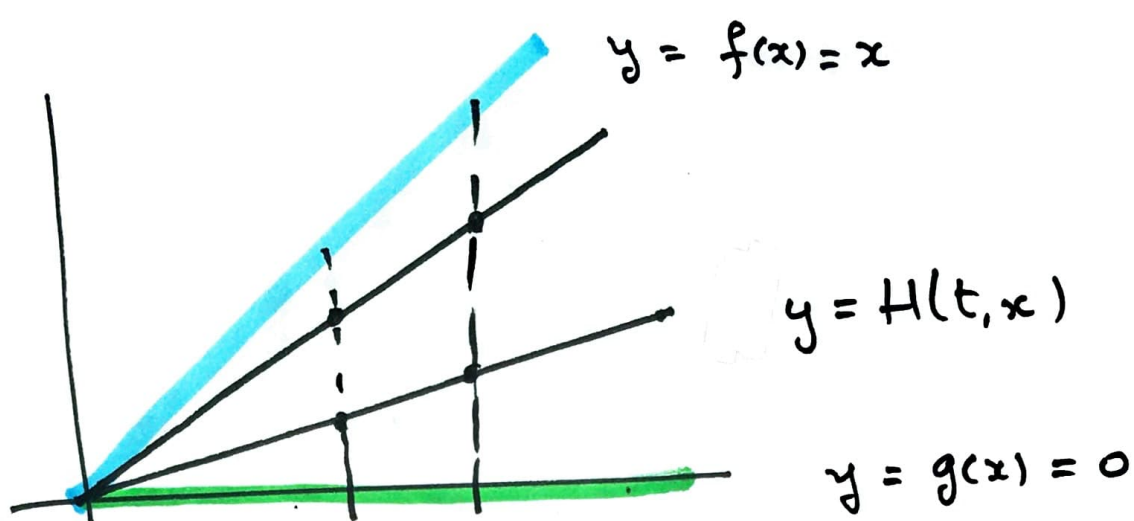
$$\forall x \in X, \quad H(0, x) = f(x)$$

$$H(1, x) = g(x)$$



Ex: $f(x) = x$ on \mathbb{R}_+
 $g(x) = 0$ on \mathbb{R}_+
 $H(t, x) = (1-t)x$

1. Draw graphs of $f, g, H(\frac{1}{2}, \cdot), H(\frac{3}{4}, \cdot)$
2. Show H is a homotopy between f and g .



If t is fixed, $H(t, \cdot) : \mathbb{R}_+ \longrightarrow \mathbb{R}$
 $x \longmapsto (1-t)x$

$H(t, \cdot)$ is the linear map with slope $1-t$.

$t=0$: slope $= 1-0 = 1$

$$H(0, x) = x = f(x)$$

$t=1$

$$H(1, x) = 0 \cdot x = g(x)$$

$H(t, x)$ is polynomial, hence continuous.

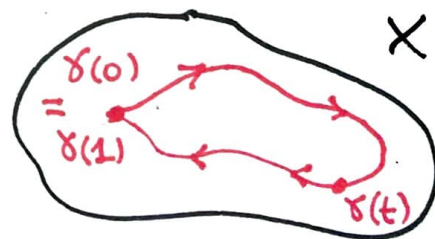
Of special interest: homotopies of loops.

Reminder: a path on X metric is a continuous

function $\gamma : [0, 1] \longrightarrow X$

A loop on X is a path $\gamma : [0, 1] \longrightarrow X$ with

$$\gamma(0) = \gamma(1)$$

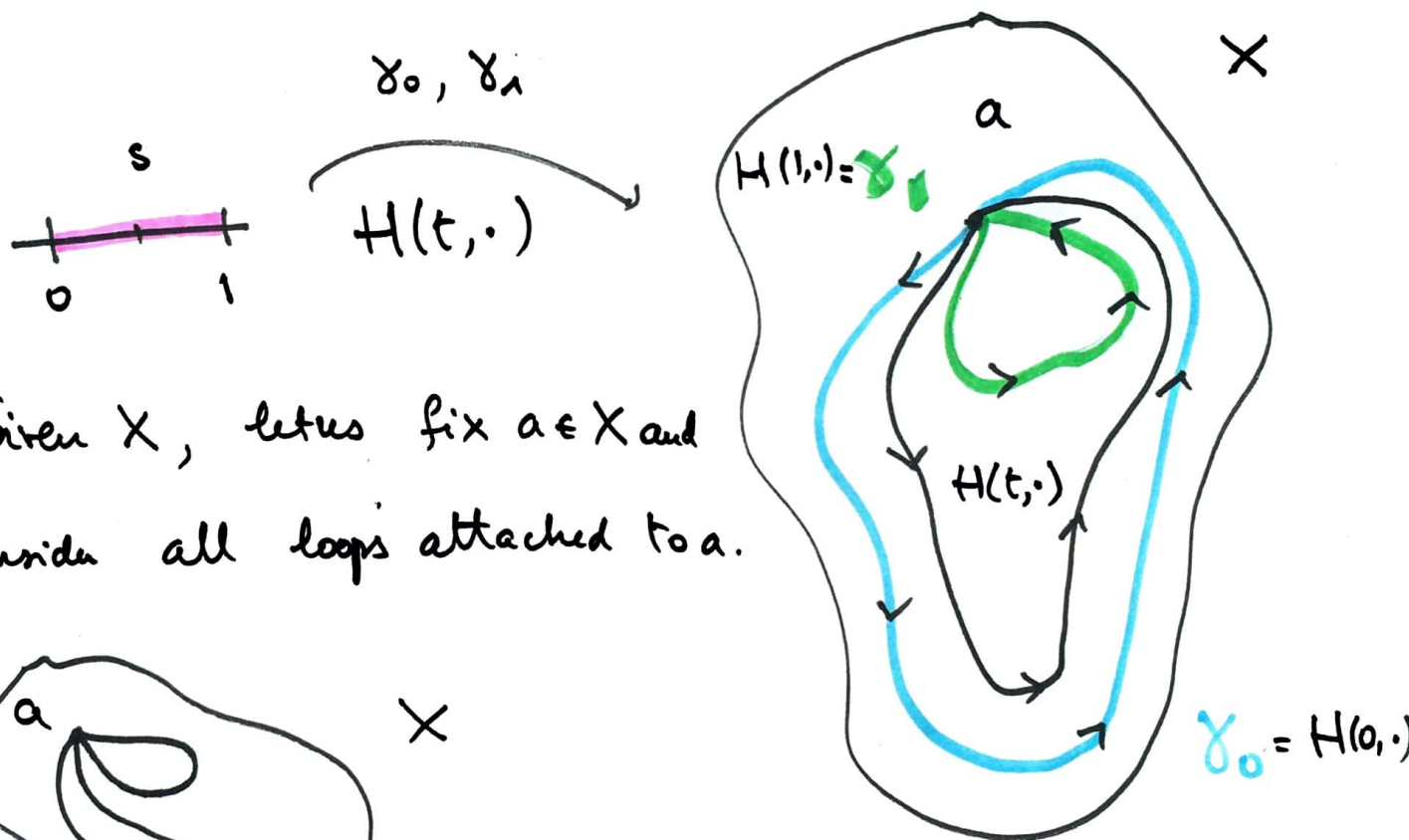


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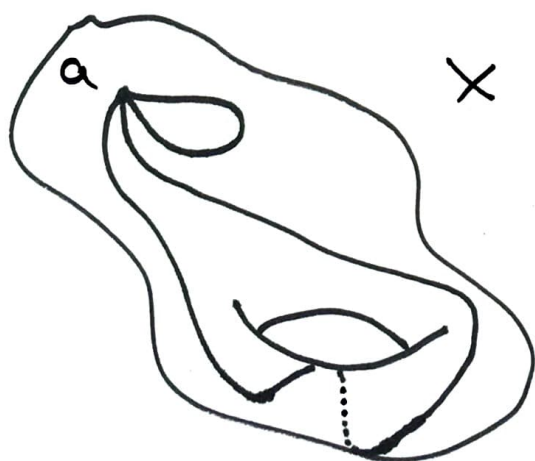
We say that two loops γ_0 and γ_1 are homotopic if $\gamma_0(0) = \gamma_1(0) = \gamma_0(1) = \gamma_1(1) = a$ and there is a homotopy

$H: [0,1] \times [0,1] \longrightarrow X$
between γ_0 and γ_1 , s. t.

$$\forall t \in [0,1], \quad H(t,0) = H(t,1) = a$$

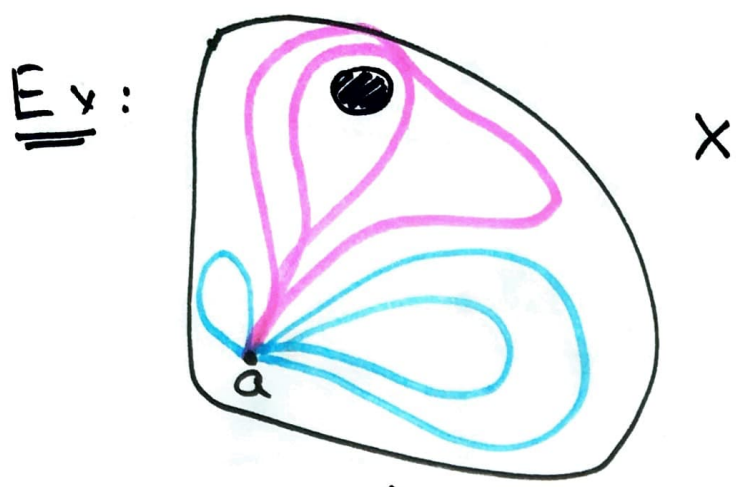


Given X , let us fix $a \in X$ and consider all loops attached to a .



Some loops in X are homotopic, some may not be. Write $\gamma \sim_h \gamma'$ if γ and γ' are homotopic.

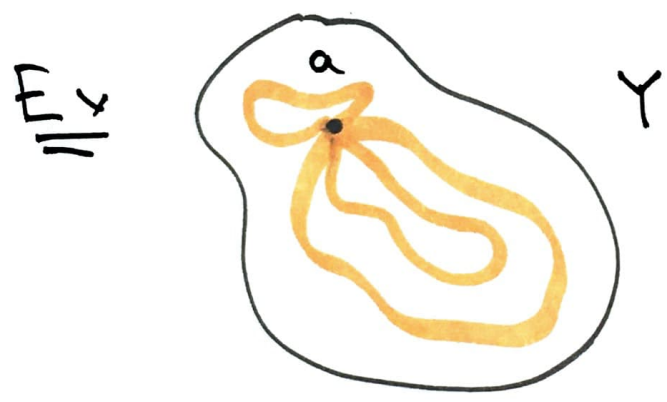
$$\pi_1(X) = \{ \text{classes of loops} \}.$$



$$\pi_1(X) = \{ \mathbb{O}, \mathbb{I} \}$$

$\mathbb{O} = \{ \text{all loops that do not enclose the hole} \}$

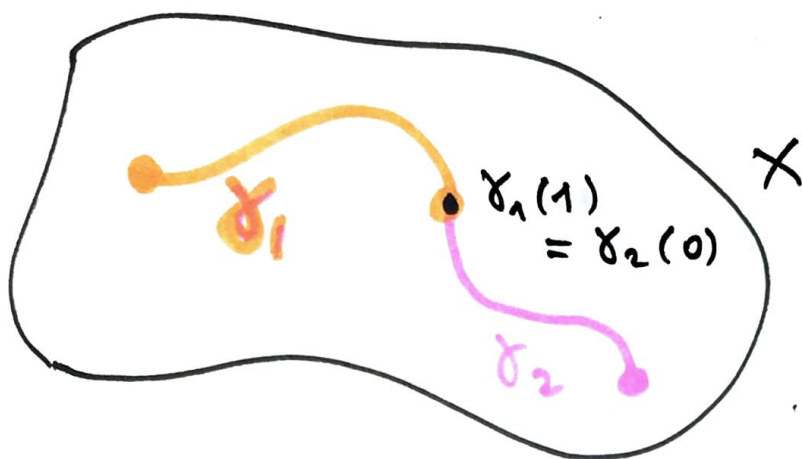
$\mathbb{I} = \{ \text{all loops around the hole} \}$



$$\pi_1(Y) = \{ \mathbb{O} \}$$

all loops in Y are homotopic to each other
and to the constant loop $\gamma(t) = a$
(for all t).

In fact, $\pi_1(X)$ is a group, for path composition:



If γ_1, γ_2 are paths on X with

$$\gamma_1(1) = \gamma_2(0)$$

then we can join them:

$$\gamma_1 * \gamma_2 : [0, 1] \longrightarrow X$$

$$t \longmapsto \gamma_1(2t) \text{ if } 0 \leq t \leq \frac{1}{2}$$

$$t \longmapsto \gamma_2(2t-1) \text{ if } \frac{1}{2} \leq t \leq 1$$

$$\begin{aligned} \text{if } t = \frac{1}{2}, \quad \gamma_1 * \gamma_2\left(\frac{1}{2}\right) &= \gamma_1\left(2 \times \frac{1}{2}\right) = \gamma_1(1) \\ &= \gamma_2\left(2 \times \frac{1}{2} - 1\right) = \gamma_2(0) \end{aligned}$$

$(\pi_1(X), *)$ is a group, called

the fundamental group of X .