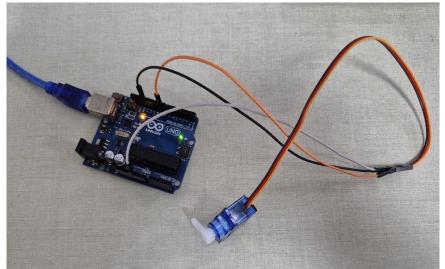
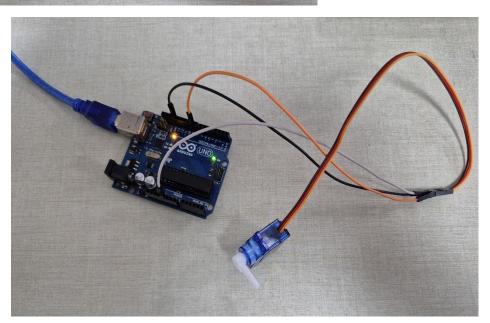
```
SERVO_MOTOR_1.ino
   1
       #include <Servo.h>
   2
   3
       Servo myservo; // create servo object to control a servo
       int pos = 0;  // variable to store the servo position
   4
   5
   6
       void setup() {
   7
       myservo.attach(9); // attaches the servo on pin 9 to the servo object
   8
   9
  10
       void loop() {
         for (pos = 0; pos <= 180; pos += 1) { // goes from 0 degrees to 180 degrees
  11
  12
           myservo.write(pos);
                                                // tell servo to go to position in variable 'pos'
  13
         delay(15);
                                                // waits 15ms for the servo to reach the position
  14
         for (pos = 180; pos >= 0; pos -= 1) { // goes from 180 degrees to 0 degrees
  15
                                               // tell servo to go to position in variable 'pos'
  16
           myservo.write(pos);
                                               // waits 15ms for the servo to reach the position
  17
         delay(15);
  18
  19
  20
```

```
SERVO_MOTOR_2.ino
       #include <Servo.h>
   1
   2
   3
       Servo myservo; // create servo object to control a servo
   4
   5
       void setup() {
   6
         Serial.begin(9600);
   7
          myservo.attach(9); // attaches the servo on pin 9 to the servo object
   8
   9
  10
       void loop() {
  11
          int val;
  12
          while (Serial.available() > 0) {
  13
            val = Serial.parseInt();
  14
            if (val != 0) {
  15
             Serial.println(val);
             myservo.write(val);
  16
  17
  18
            delay(15);
  19
  20
```



Output Serial Monitor X

Message (Enter to send message to 'Ardu



```
LCD_SCREEN_1.ino

1  #include <LiquidCrystal.h>
2  LiquidCrystal lcd(12, 11, 10, 9, 8, 7);
3  void setup() {
4   lcd.begin(16, 2);
5   // you can now interact with the LCD, e.g.
6   lcd.print("Hello World!");
7  }
8  void loop() {
9 }
```

LCD_SCREEN_2.ino

```
LCD_SCREEN_USING_I2C_MODULE.ino
```

```
#include <LiquidCrystal.h>
     LiquidCrystal lcd(7, 8, 9, 10, 11, 12);
2
 3
     void setup() {
4
       lcd.begin(16, 2);
 5
       lcd.setCursor(0, 1);
6
       lcd.write("LIGHT: ");
7
8
     void loop() {
9
       int sensorValue = analogRead(A0);
10
       lcd.print("Room: ");
11
       if (sensorValue > 700) {
12
       lcd.print("Light!");
13
       } else {
14
         lcd.print("Dark ");
15
16
       delay(100);
17
18
```

```
#include <Wire.h>
     #include <LiquidCrystal I2C.h>
 2
 3
    // Set the LCD I2C address (often 0x27 or 0x3F)
 4
    LiquidCrystal_I2C lcd(0x27, 16, 2);
 5
 6
     void setup() {
       lcd.init();
                             // Initialize the LCD
 8
       lcd.backlight();
9
                             // Turn on backlight
       lcd.print("Hello, World!");
10
11
12
13
     void loop() {
      // Nothing here for now
14
15
```

