```
from google.colab import drive
drive.mount('/content/gdrive', force_remount=True)
     Mounted at /content/gdrive
import cv2
import torch
import numpy as np
import pandas as pd
from tensorflow.keras.applications.resnet v2 import ResNet50V2,preprocess input
import matplotlib.pyplot as plt
from sklearn.model selection import train test split
from sklearn.metrics import classification report
from tqdm import tqdm
#locate the file path
im size = 224
train x = []
train y= []
val x = []
val y= []
dict label={}
import os
trainfolder list = os.listdir("/content/gdrive/MyDrive/FindCareer/FellowshipAI/imagewoof-320/train")
valfolder list = os.listdir("/content/gdrive/MyDrive/FindCareer/FellowshipAI/imagewoof-320/val")
i=0
for folder in trainfolder_list:
  dict_label[folder] = i
  i+=1
#read training data
for folder in tqdm(trainfolder_list):
  for filename in os.listdir('/content/gdrive/MyDrive/FindCareer/FellowshipAI/imagewoof-320/train/'+folder):
    img = cv2.resize(cv2.imread('/content/gdrive/MyDrive/FindCareer/FellowshipAI/imagewoof-320/train/'+folder+'/'+filename,cv2.IMREAD_
    img_array = preprocess_input(np.expand_dims(np.array(img[...,::-1].astype(np.float32)).copy(), axis=0))
    train_x.append(img_array.reshape(3,im_size,im_size))
    train_y.append(dict_label[folder])
```

```
100%
           10/10 [02:03<00:00, 12.33s/it]
#read validation data
for folder in tqdm(valfolder_list):
  for filename in os.listdir('/content/gdrive/MyDrive/FindCareer/FellowshipAI/imagewoof-320/val/'+folder):
   img = cv2.resize(cv2.imread('/content/gdrive/MyDrive/FindCareer/FellowshipAI/imagewoof-320/val/'+folder+'/'+filename,cv2.IMREAD CO
   img_array = preprocess_input(np.expand_dims(np.array(img[...,::-1].astype(np.float32)).copy(), axis=0))
   val_x.append(img_array.reshape(3,im_size,im_size))
   val_y.append(dict_label[folder])
    100%
           10/10 [00:03<00:00, 2.93it/s]
train x, test x, train y, test y = train test split(train x, train y, test size=0.2, random state=42)
#just checking the data
plt.imshow(train x[150].reshape(224,224,3))
plt.show()
print(train y[150])
print(dict label)
print("images-size:", train x[0].shape)
print(len(train y))
```

print(len(val\_y))
print(len(test\_y))

print(val\_y)

```
Clipping input data to the valid range for imshow with RGB data ([0..1] for floats or [0..255] for integers).
      25
      50
      75
     100
from torch.utils.data import Dataset, DataLoader, ConcatDataset
batchSize = 32
dataset=list(zip(train x, train y))
trainloader = DataLoader(dataset, batch_size = batchSize, shuffle=True)
validataset=list(zip(val x, val y))
valiloader = DataLoader(validataset, batch size = batchSize, shuffle=True)
     1mages-size: (3, 224, 224)
testset=list(zip(test x, test y))
testloader = DataLoader(testset, batch size = batchSize, shuffle=True)
    from torchvision import *
device = torch.device('cuda:0' if torch.cuda.is available() else 'cpu')
net = models.resnet18(pretrained=True)
net = net.cuda() if device else net
net
    ResNet(
      (conv1): Conv2d(3, 64, kernel_size=(7, 7), stride=(2, 2), padding=(3, 3), bias=False)
      (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
      (relu): ReLU(inplace=True)
      (maxpool): MaxPool2d(kernel_size=3, stride=2, padding=1, dilation=1, ceil_mode=False)
      (layer1): Sequential(
        (0): BasicBlock(
          (conv1): Conv2d(64, 64, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
          (relu): ReLU(inplace=True)
          (conv2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
          (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
        (1): BasicBlock(
          (conv1): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
          (bn1): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
```

```
(relu): ReLU(inplace=True)
    (conv2): Conv2d(64, 64, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
    (bn2): BatchNorm2d(64, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
)
(layer2): Sequential(
  (0): BasicBlock(
    (conv1): Conv2d(64, 128, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), bias=False)
    (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track_running_stats=True)
    (relu): ReLU(inplace=True)
    (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
    (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (downsample): Sequential(
      (0): Conv2d(64, 128, kernel size=(1, 1), stride=(2, 2), bias=False)
      (1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (1): BasicBlock(
    (conv1): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
    (bn1): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (relu): ReLU(inplace=True)
    (conv2): Conv2d(128, 128, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
    (bn2): BatchNorm2d(128, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
(layer3): Sequential(
  (0): BasicBlock(
    (conv1): Conv2d(128, 256, kernel size=(3, 3), stride=(2, 2), padding=(1, 1), bias=False)
    (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (relu): ReLU(inplace=True)
    (conv2): Conv2d(256, 256, kernel_size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
    (bn2): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (downsample): Sequential(
      (0): Conv2d(128, 256, kernel size=(1, 1), stride=(2, 2), bias=False)
      (1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
  (1): BasicBlock(
    (conv1): Conv2d(256, 256, kernel size=(3, 3), stride=(1, 1), padding=(1, 1), bias=False)
    (bn1): BatchNorm2d(256, eps=1e-05, momentum=0.1, affine=True, track running stats=True)
    (relu): ReLU(inplace=True)
```

```
import torch.nn as nn
import torch.optim as optim
criterion = nn.CrossEntropyLoss()
optimizer = optim.SGD(net.parameters(), lr=0.0001, momentum=0.9)
```

```
def accuracy(out, labels):
  _,pred = torch.max(out, dim=1)
  return torch.sum(pred==labels).item()
num_ftrs = net.fc.in_features
net.fc = nn.Linear(num_ftrs, 128)
net.fc = net.fc.cuda() if torch.cuda.is available() else net.fc
n = 50
print every = 10
valid loss min = np.Inf
val loss = []
val acc = []
train loss = []
train acc = []
total step = len(trainloader)
for epoch in range(1, n epochs+1):
  running loss = 0.0
  correct = 0
  total=0
  print(f'Epoch {epoch}\n')
  for batch_idx, (data_, target_) in enumerate(trainloader):
    data_, target_ = data_.to(device), target_.to(device)
    optimizer.zero_grad() # zero the parameter gradients
    outputs = net(data_) # forward
    loss = criterion(outputs, target )
    loss.backward() #backward
    optimizer.step() #optimize
    running loss += loss.item()
    ,pred = torch.max(outputs, dim=1) # result of train
    correct += torch.sum(pred==target ).item()
    total += target .size(0)
    if (batch idx) % 20 == 0:
      print ('Epoch [{}/{}], Step [{}/{}], Loss: {:.4f}'
              .format(epoch, n epochs, batch idx, total step, loss.item()))
  train_acc.append(100 * correct / total)
  train_loss.append(running_loss/total_step)
  print(f'\ntrain-loss: {np.mean(train_loss):.4f}, train-acc: {(100 * correct/total):.4f}')
  batch_loss = 0
  total_t=0
  correct_t=0
  with torch.no_grad():
```

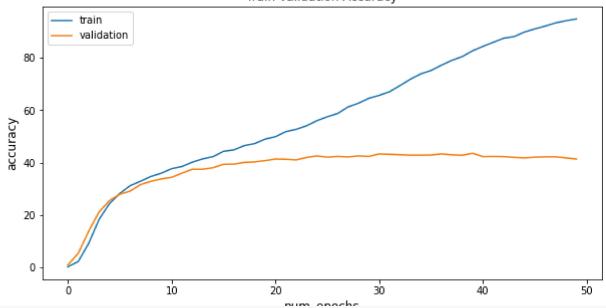
```
net.eval()
 for data_t, target_t in (testloader):
    data_t, target_t = data_t.to(device), target_t.to(device)
   outputs t = net(data t)
   loss t = criterion(outputs_t, target_t)
    batch loss += loss t.item()
   _,pred_t = torch.max(outputs_t, dim=1)
                                              # result of validation
   correct t += torch.sum(pred t==target t).item()
   total_t += target_t.size(0)
 val_acc.append(100 * correct_t/total_t)
 val loss.append(batch loss/len(testloader))
 network learned = batch loss < valid loss min</pre>
 print(f'validation loss: {np.mean(val loss):.4f}, validation acc: {(100 * correct t/total t):.4f}\n')
 if network learned:
   valid loss min = batch loss
   torch.save(net.state dict(), 'resnet.pt')
    print('Improvement-Detected, save-model')
net.train()
   Epoch 1
```

```
Epoch [1/50], Step [0/312], Loss: 5.2005
Epoch [1/50], Step [20/312], Loss: 5.0639
Epoch [1/50], Step [40/312], Loss: 5.2119
Epoch [1/50], Step [60/312], Loss: 5.0445
Epoch [1/50], Step [80/312], Loss: 4.8600
Epoch [1/50], Step [100/312], Loss: 5.0268
Epoch [1/50], Step [120/312], Loss: 5.1811
Epoch [1/50], Step [140/312], Loss: 5.0006
Epoch [1/50], Step [160/312], Loss: 4.9041
Epoch [1/50], Step [180/312], Loss: 5.1079
Epoch [1/50], Step [200/312], Loss: 4.9323
Epoch [1/50], Step [220/312], Loss: 4.8471
Epoch [1/50], Step [240/312], Loss: 5.0265
Epoch [1/50], Step [260/312], Loss: 5.0492
Epoch [1/50], Step [280/312], Loss: 5.0017
Epoch [1/50], Step [300/312], Loss: 5.1574
train-loss: 5.0641, train-acc: 0.2407
validation loss: 4.9505, validation acc: 0.9226
```

```
Epoch 2
     Epoch [2/50], Step [0/312], Loss: 4.8512
     Epoch [2/50], Step [20/312], Loss: 4.9664
     Epoch [2/50], Step [40/312], Loss: 5.1286
     Epoch [2/50], Step [60/312], Loss: 4.8805
     Epoch [2/50], Step [80/312], Loss: 4.7874
     Epoch [2/50], Step [100/312], Loss: 4.7970
     Epoch [2/50], Step [120/312], Loss: 4.9842
     Epoch [2/50], Step [140/312], Loss: 4.8065
     Epoch [2/50], Step [160/312], Loss: 4.9451
     Epoch [2/50], Step [180/312], Loss: 4.7618
     Epoch [2/50], Step [200/312], Loss: 4.8417
     Epoch [2/50], Step [220/312], Loss: 4.8299
     Epoch [2/50], Step [240/312], Loss: 4.6699
     Epoch [2/50], Step [260/312], Loss: 4.9697
     Epoch [2/50], Step [280/312], Loss: 4.6094
     Epoch [2/50], Step [300/312], Loss: 4.7161
     train-loss: 4.9608, train-acc: 2.2365
     validation loss: 4.8401, validation acc: 5.3751
     Improvement-Detected, save-model
     Epoch 3
     Epoch [3/50], Step [0/312], Loss: 4.7666
     Epoch [3/50], Step [20/312], Loss: 4.8541
     Epoch [3/50], Step [40/312], Loss: 5.1191
     Epoch [3/50], Step [60/312], Loss: 4.5958
     Epoch [3/50], Step [80/312], Loss: 4.9548
     Epoch [3/50], Step [100/312], Loss: 4.7945
     Epoch [3/50], Step [120/312], Loss: 4.6657
     Epoch [3/50], Step [140/312], Loss: 4.5556
     Epoch [3/50], Step [160/312], Loss: 4.6119
fig = plt.figure(figsize=(10,5))
plt.title("Train-Validation Accuracy")
plt.plot(train_acc, label='train')
plt.plot(val acc, label='validation')
plt.xlabel('num epochs', fontsize=12)
plt.ylabel('accuracy', fontsize=12)
plt.legend(loc='best')
```

Improvement-Detected, save-model

## Train-Validation Accuracy



```
correct = 0
total = 0
pred_list=[]
true_list=[]
# since we're not training, we don't need to calculate the gradients for our outputs
net.eval()
with torch.no grad():
 for data in valiloader:
   images, labels = data
   images, labels = images.cuda(), labels.cuda()
   # calculate outputs by running images through the network
   outputs = net(images)
   # the class with the highest energy is what we choose as prediction
   _, predicted = torch.max(outputs.data, 1)
   total += labels.size(0)
   correct += (predicted == labels).sum().item()
   pred_list.append(predicted.cpu().numpy())
   true_list.append(labels.cpu().numpy())
print(f'Accuracy of the network on the test images: {100 * correct // total} %')
```

Accuracy of the network on the 10000 test images: 37 %

```
pred_list=list(np.concatenate(pred_list).flat)
true list=list(np.concatenate(true list).flat)
print(pred list)
print(true list)
    [2, 5, 6, 9, 9, 3, 5, 8, 9, 6, 8, 4, 8, 0, 6, 7, 7, 3, 2, 8, 4, 6, 4, 0, 2, 5, 3, 7, 3, 8, 1, 2, 6, 1, 5, 4, 1, 9, 5, 2, 4, 7, 3,
    [4, 5, 1, 1, 9, 6, 5, 9, 3, 6, 8, 4, 8, 0, 4, 3, 0, 6, 4, 8, 5, 1, 1, 0, 2, 5, 8, 7, 8, 8, 1, 2, 6, 7, 2, 4, 1, 8, 5, 2, 6, 1, 3,
from sklearn.metrics import confusion matrix, classification report
array=confusion matrix(true list, pred list)
print(array)
    [[10 1 5 1 1 1 2 8 8 13]
     [120 2 4 8 1 4 5 2 3]
     [0 2 39 1 2 2 0 1
         2 3 16 5 4 3 7 4 6]
         6 10 2 13 0 5 1 6 7
         1 5 1 4 24 2
         3 0 10 5 4 14 6 5 3]
     [212 0 5 7 0 217 1 4]
         1 3 6 3 7 4 1 20 5
     [52319215616]]
#dummy classifier
from sklearn.dummy import DummyClassifier
X = true list
y = true list
dummy clf = DummyClassifier(strategy="most frequent") #or most frequent,stratified
dummy clf.fit(X, y)
print("dummy classifier result\n")
#print(dummy clf.score(X, y))
x dummy=dummy clf.predict(X)
print(classification report(true list, x dummy))
    dummy classifier result
                              recall f1-score
                 precision
                                               support
```

0

1

2

3

0.10

0.00

0.00

0.00

1.00

0.00

0.00

0.00

0.18

0.00

0.00

0.00

50

50

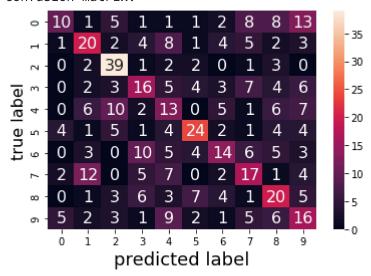
50

50

```
4
                        0.00
                                   0.00
                                             0.00
                                                         50
                5
                        0.00
                                   0.00
                                             0.00
                                                         50
                6
                        0.00
                                   0.00
                                             0.00
                                                         50
                7
                        0.00
                                   0.00
                                             0.00
                                                         50
                8
                        0.00
                                   0.00
                                             0.00
                                                         50
                9
                                   0.00
                        0.00
                                             0.00
                                                         50
                                             0.10
                                                        500
         accuracy
                                             0.02
        macro avg
                        0.01
                                   0.10
                                                        500
     weighted avg
                        0.01
                                   0.10
                                             0.02
                                                        500
     /usr/local/lib/python3.7/dist-packages/sklearn/metrics/_classification.py:1318: UndefinedMetricWarning: Precision and F-score are
       warn prf(average, modifier, msg start, len(result))
     /usr/local/lib/python3.7/dist-packages/sklearn/metrics/ classification.py:1318: UndefinedMetricWarning: Precision and F-score are
       _warn_prf(average, modifier, msg_start, len(result))
     /usr/local/lib/python3.7/dist-packages/sklearn/metrics/ classification.py:1318: UndefinedMetricWarning: Precision and F-score are
       warn prf(average, modifier, msg start, len(result))
#plot the confusion_matrix, and classification_report
import seaborn as sn
print("confusion matrix: ")
df_cm = pd.DataFrame(array, range(10), range(10))
sn.heatmap(df_cm, annot=True, annot_kws={"size": 16}, fmt='g')
plt.xlabel('predicted label', fontsize=18)
plt.ylabel('true label', fontsize=16)
plt.show()
```

print("\n\nclassification report:\n\n"+classification report(true list, pred list))

## confusion matrix:



## classification report:

	precision	recall	f1-score	support
0	0.45	0.20	0.28	50
1	0.40	0.40	0.40	50
2	0.56	0.78	0.65	50
3	0.34	0.32	0.33	50
4	0.23	0.26	0.24	50
5	0.53	0.48	0.51	50
6	0.38	0.28	0.32	50
7	0.33	0.34	0.33	50
8	0.34	0.40	0.37	50
9	0.26	0.32	0.29	50
accuracy			0.38	500
macro avg	0.38	0.38	0.37	500
weighted avg	0.38	0.38	0.37	500

