## Paths

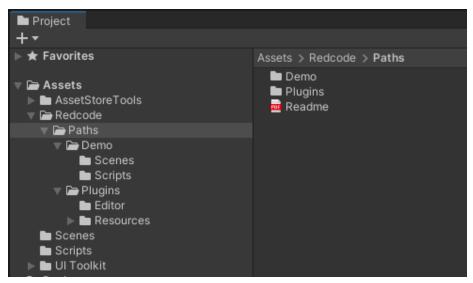
Paths is a library written in pure C# for creating and editing waypoint systems in Unity. Paths uses the Catmull-Rom curve algorithm.

# Supported versions of Unity

This Asset supports Unity version from 2021.2 and above.

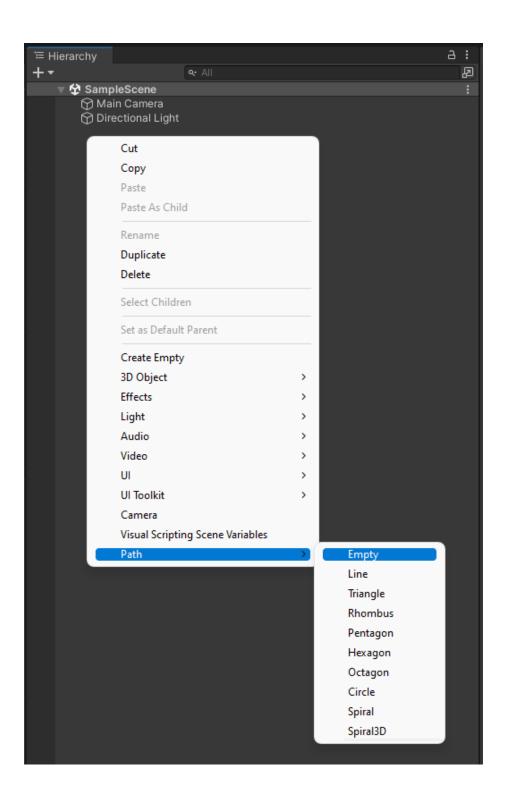
## Installation

All you need to do is import the unity-package into your project. Technically, the Paths library is just a Plugins/Numba/Paths folder with some scripts and other files.



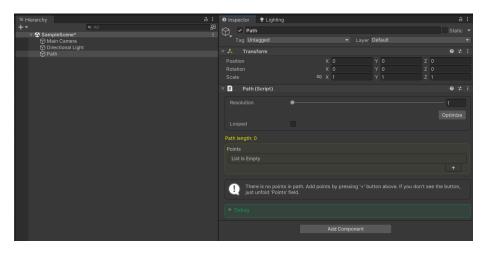
# Creating paths in the editor

To create a path in the editor in the Hierarchy tab, call the context menu and select Path > Empty.

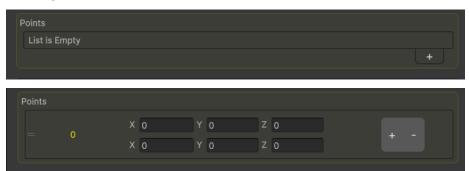


This will create a blank object and add the Path script to it. Of course, you can create a blank and add the Path script through the components menu manually, but a ready-made menu is more convenient for this. In addition to the empty path you can create ready-made ones (line, triangle and others) but we'll come back to them a little later.

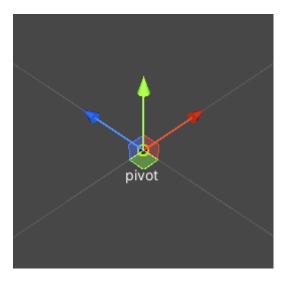
## Setting the path in the editor



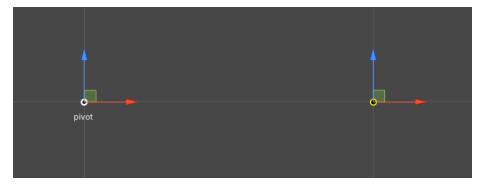
The script consists of several blocks. First of all, we are interested in the block of dots (yellow), it is currently empty. To add a point, click the + icon in the lower right corner of the block.



As you can see there is now one point in the path. The yellow number on the left side is the position of the point in the whole list. Then there are two Vector3 fields. The upper field is the position of the point, and the lower field is the rotation in the form of Euler angles. The position and rotation of the point are calculated relative to the game object to which the Path script is attached. So now point 0 coincides with the position of the parent object. This is also visible in the scene window.



The pivot text indicates the position of the parent object. Change the point position in the inspector to [1, 0, 0] and switch the scene window camera to top view to make it easier to observe. You will see that the point and the pivot of the object are now in different places.

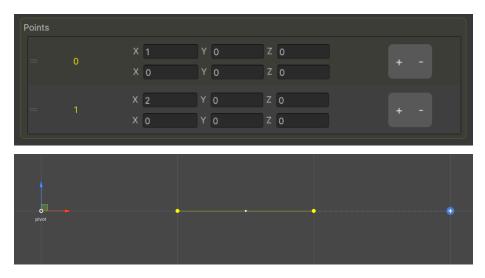


By moving, rotating and scaling the object to which the Path script is attached, you also move all its points.

Now add one more point by pressing the + button near the point in the inspector window.

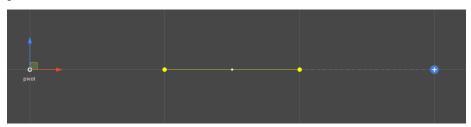


This will create another point right after the current one. Set it to position [2, 0, 0]. Our path now looks like this.



The yellow line between the two points is the path line. Later, we will figure out how to make an object move along this line. To delete a point, you can click the – button in the inspector window opposite to the point you want.

To see the point number in the scene window, just put the cursor on the desired point.

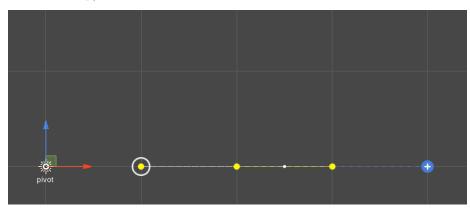


As you can see, navigating with points in the scene window is not difficult. You can also add a new point directly in the scene window. To do that, press the blue + button. This will create a new point at that location and connect it to the previous one.

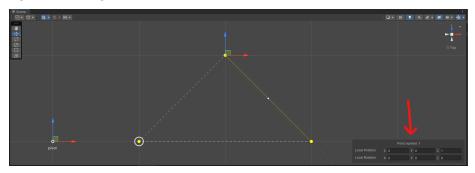


Now the path looks a little unclear, let's move the point 1 up. You can do this directly in the scene window, to do it, click on point 1 to select it, turn on the move tool (hotkey W) and move the point up to position 1 on the z-axis (use

### CTRL to snap).

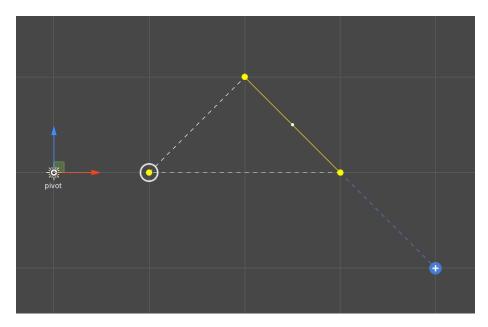


When a point is selected, a quick edit box for that point appears at the bottom right of the Stage window.



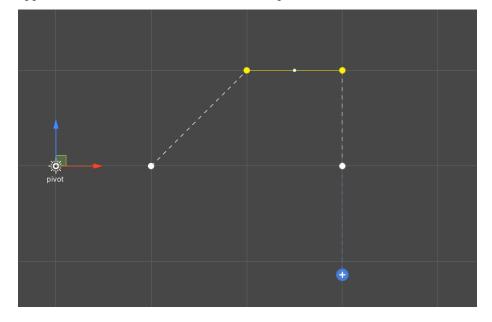
This block essentially just duplicates the point fields that are displayed in the inspector window. You can use it, or you can simply drag the point to the desired location using the gizmo tools.

You can add new points between the existing ones by moving the cursor over the small white circle between the two yellow points and a blue + button will appear, click on it to add a point.



Now the path consists of 4 dots. About the difference between the white dots and yellow dots, as well as between the dotted line and yellow line we will talk a little later, now we just need to learn how to edit the lines.

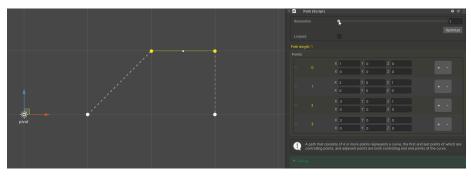
You can also delete unselected points directly in the scene window, move the cursor just above the point itself, a delete point button with an  ${\tt x}$  sign will appear and double click on it to remove the point.



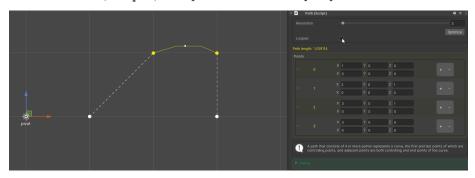
Undo the last action (deleting a point) by pressing CTRL+Z. Paths fully supports the undo/redo system built into Unity.

Working with points in the scene window is quite comfortable, but some parameters are only configurable in the inspector. The first block of the Path script in the inspector has 2 fields: Resolution and Looped.

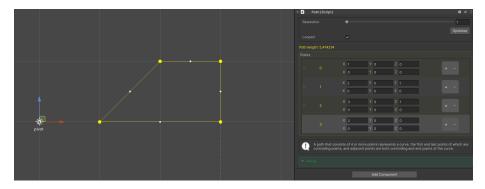
The Resolution - path resolution, that is, this parameter is responsible for how many broken lines should be created between two points. When Resolution is 1, one line is drawn between two points, so the whole path is a broken line. Increasing the resolution value will make the line curve. The higher the resolution, the smoother the line becomes.



The second field, Looped, is responsible for the looped path.

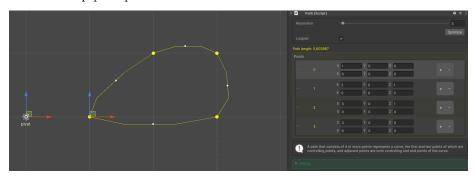


You can find the optimal resolution for the path by clicking the Optimize button under the Resolution field.

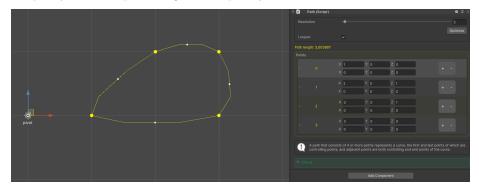


Immediately below the Looped field there is information about how long the path is (yellow lines).

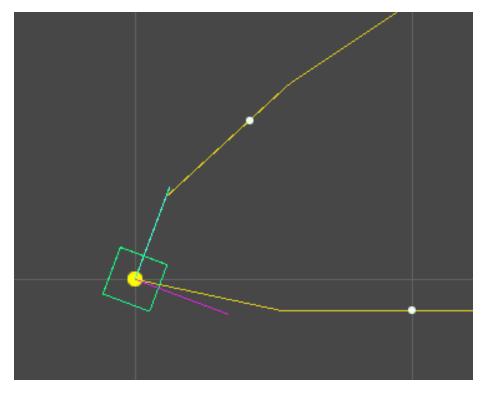
You can swap path points.



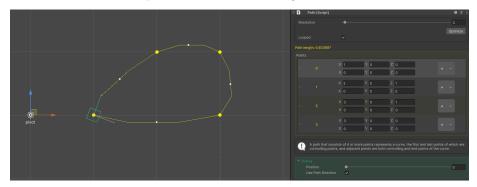
When the path is fully configured, you can see how the object will move along it. To do this, open the debug block (green), the scene will show the green edges of the imaginary cube, which will be at point 0. You can move the Position slider to specify on what percentage of the path you want this cube to be located.



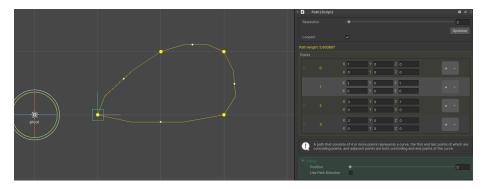
By default, when debugging, the face of the cube is always directed according to the path vector.



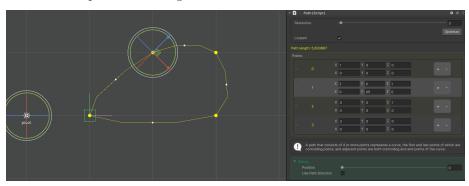
However, you can change this behavior by turning off the Use Path Direction field. In this case the cube will match the rotations of the points. In our example, we didn't change the rotations of the points (only their positions), so the rotations of all the points coincide with the global axes.



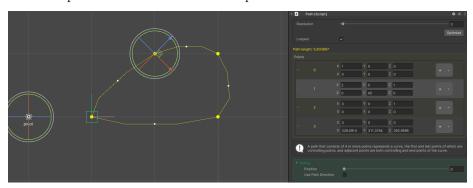
To work with point rotations, turn on the rotate tool (hotkey E). You can set the desired point rotations in the points list in the Inspector.



Or rotate the point with the gizmo in the scene window.

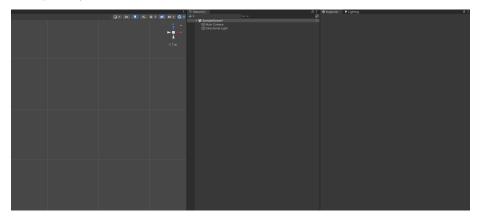


To make it easier to understand the rotation of a point, the local axes of the point are displayed inside the **rotation** tool gizmo. Once all the desired points are rotated, you can debug the path, i.e. see how the special cube will behave as it traverses that path. Passing through the points, the rotation of the cube will correspond to the rotations of these points.

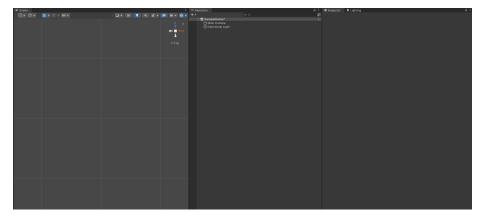


## Creating ready-made path templates

In addition to an empty path, you can create paths with points already in them. To do this, use the context menu Path > ... in the hierarchy window. For example, if you want to create a circle, use Path > Circle.



Or for example, you want a 3D spiral.



# Path special cases

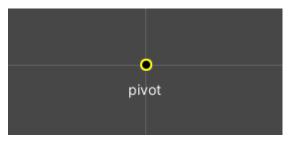
Now that you know how to control lines in the editor, it is necessary to deal with special cases of path construction, namely when the path consists of 0, 1, 2, 3 and more than 3 points. The point is that the Catmull-Rome algorithm knows how to work with at least 4 points, with the first and last being the controlling ones, and those in the middle - between them will draw the line.

### Path of 0 points.

In this case the path is nothing. Calling methods (we'll talk about them later) to retrieve data on the path will result in an exception.

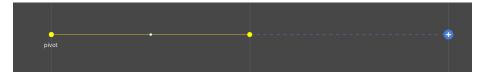
### Path from 1 point

A path from 1 point will always return a value at that point when calling methods to get data on the path, whether the path is looped or not. This single point is used as 4 points in this location.



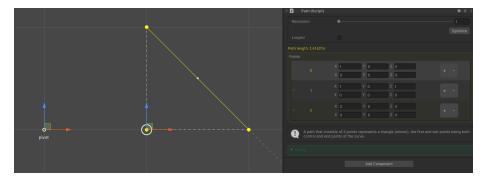
### Path from 2 points

The Catmull-Rom algorithm for 2 points can only construct a straight line, so regardless of the value of the Resolution field between two points will always be a straight line. If the path is looped, it will consist of two segments, the first from point 0 to point 1, and the second vice versa. This is because each point is both a controlling point and an end point (that is, the total will be 4 points).

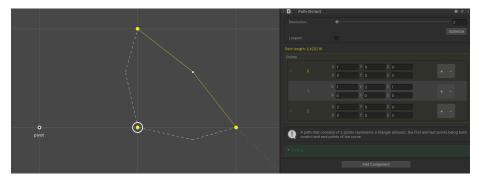


### Path of 3 points

Three points allow you to describe one segment of a curved line. Point 0 in this case is the controlling point for points 1 and 2, and points 1 and 2 are the end points, i.e. the ones between which the path is drawn. The Resolution field affects the smoothness of this line. The first point is both the controlling and the end point, which again together with the other two gives 4 points.



At the same time the path can be looped.

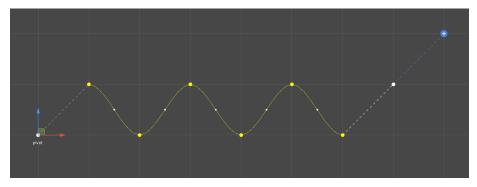


# A path of 4 or more points

When a path consists of 4 or more points, the first point (with the index 0) and the last one are controlling points and all other points are end points. You can control the line starting from point 1 separately thanks to the control point 0. It is the same with the penultimate point. The controlling points are drawn in white and connected by a white dotted line. These points do not participate in the traversed path, but only influence it. Moreover, with 4 points you can achieve the same result as with 1, 2 or 3 points.



And this is what a path of 7 points might look like.



### API

To work with paths via code, a convenient API has been developed. To access the necessary classes use the namespace Redcode.Paths.

#### Path creation

To create a path use the static method Path.Create(). It will create a game object named "Path" at position zero, add a Path component to it and return it as a result. This method has 4 overloads:

- 1. Path Create()
- 2. Path Create(Vector3 pivotPosition)
- Path Create(Vector3 pivotPosition, bool useGlobal, params Vector3[] points)
- 4. Path Create(Vector3 pivotPosition, bool useGlobal, IEnumerable<Vector3> points)

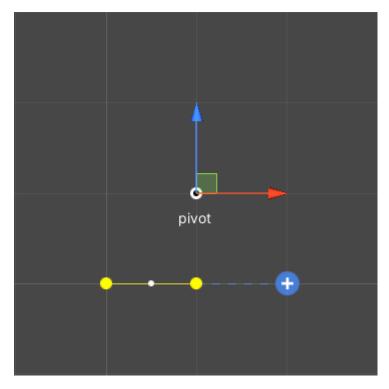
#### Where:

- pivotPosition path position.
- useGlobal specifies whether the points (parameter points) are transmitted in global (true) or local (false) space.
- points a collection of points.

#### For example:

```
var path = Path.Create(new Vector3(1f, 0f, 1f), true, Vector3.zero,
new Vector3(1f, 0f, 0f));
```

will create a new path located at position [1, 0, 1] with two points at the global positions [0, 0, 0] and [1, 0, 0].



You can also use the Path.CreatePolygon and Path.CreateSpiral methods.

The CreatePolygon creates a polygon path (triangle, rhombus, pentagon and others). There are 3 overloads available:

- 1. Path CreatePolygon(int sideCount, float radius)
- 2. Path CreatePolygon(Vector3 pivotPosition, int sideCount, float radius)
- 3. Path CreatePolygon(Vector3 pivotPosition, Vector3 normal, int sideCount, float radius)

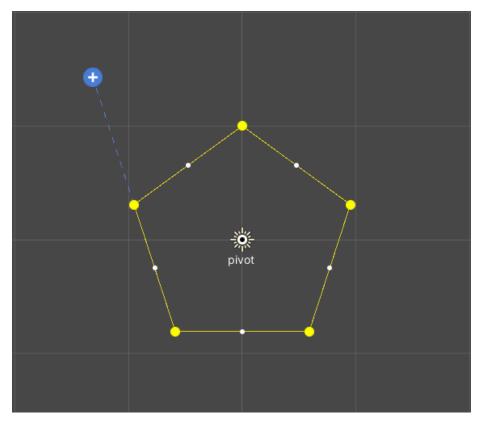
#### Where:

- sideCount the number of faces.
- radius distance from the center of the figure to any corner.
- $\bullet\,$  pivot Position - position of the path in space.
- normal the normal of the figure, that is a vector representing where the face of the figure is directed in space.
- up a vector representing the direction of the face of the figure when rotated towards normal.

#### For example:

```
var path = Path.CreatePolygon(5, 1f);
```

this code will create a pentagon with a radius of 1 meter.



CreateSpiral creates a path-spiral (Archimedean). There are 3 overloads:

- Path CreateSpiral(float offsetAngle, int coils, float step, int pointsCountPerCoil, bool use3D = false)
- 2. Path CreateSpiral(Vector3 pivotPosition, float offsetAngle, int coils, float step, int pointsCountPerCoil, bool use3D = false)
- 3. Path CreateSpiral(Vector3 pivotPosition, Vector3 normal, float offsetAngle, int coils, float step, int pointsCountPerCoil, bool use3D = false)

#### Where:

- offsetAngle angular displacement (in degrees) of the helix, i.e. rotation of the helix around its center.
- $\bullet\,$  coils number of coils of the spiral.
- step spiral pitch, i.e. the distance between two coils.
- PointsCountPerCoil number of generated points per coil.
- use3D Is it necessary to create a three-dimensional spiral?
- pivotPosition position of the path in space.
- normal the normal of the figure, that is, a vector representing where the

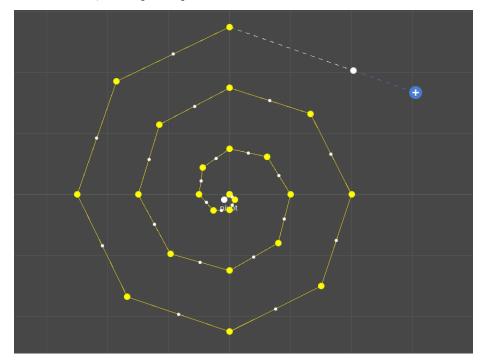
face of the figure is directed in space.

• up - a vector representing the direction of the face of the figure when rotated towards normal.

#### For example:

var path = Path.CreateSpiral(0f, 3, 1f, 8, true);

this code will create a 3D spiral with 0 degree offset, 3 turns, 1 meter distance between turns, and 8 points per turn.



The CreateArc creates a path-arc. There are 3 overloads:

- 1. Path CreateArc(float width, float height, int sideCount)
- 2. Path CreateArc(Vector3 pivotPosition, float width, float height, int sideCount)
- 3. Path CreateArc(Vector3 pivotPosition, Vector3 normal, Vector3 up, float width, float height, int sideCount)

#### Where:

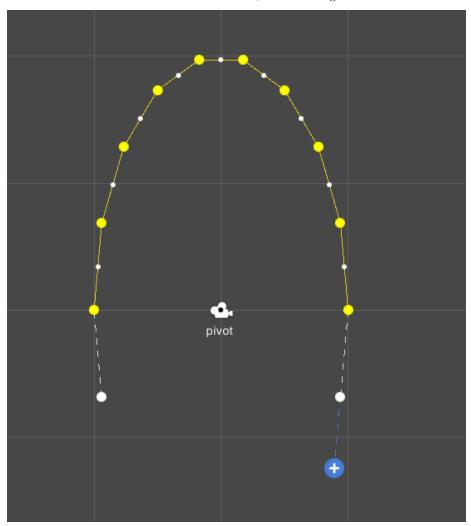
- width width of the arch in meters.
- height height of the arch in meters.
- sideCount number of sides in the arch (minimum 3).
- pivotPosition track position in space.
- normal the normal of the figure, that is a vector representing where the front side of the figure is directed in space.

• up - a vector representing the direction of the face of the figure when rotated towards normal.

For example:

var path = Path.CreateArc(2f, 4f, 8);

this code will create an arch 2 meters wide, 4 meters high and 8 sides.



The  ${\tt CreateWave}$  creates a path-wave. There are 3 overloads available:

- 1. Path CreateWave(float height, float frequency, int repeat, bool startToUp = true)
- 2. Path CreateWave(Vector3 pivotPosition, float height, float frequency, int repeat, bool startToUp = true)

3. Path CreateWave(Vector3 pivotPosition, Vector3 normal, Vector3 up, float height, float frequency, int repeat, bool startToUp = true)

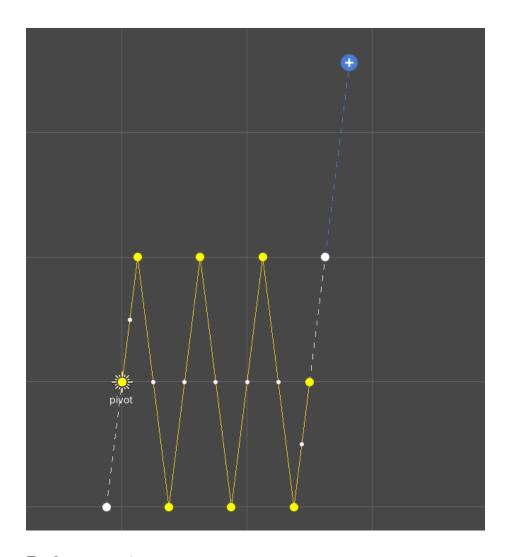
#### Where:

- height wave height in meters.
- frequency frequency of the wave per 1 meter.
- repeat the number of repetitions of the wave.
- startToUp in which direction the wave starts, up (true) or down (false).
- pivotPosition position of the path in space.
- normal the normal of the figure, i.e. a vector representing where the face of the figure is directed in space.
- up a vector representing the direction of the face of the figure when rotated towards normal.

#### For example:

```
var path = Path.CreateWave(1f, 2f, 3);
```

this code will create a wave with a height of 1 meter, a frequency of 2 waves per meter and repeat it 3 times.



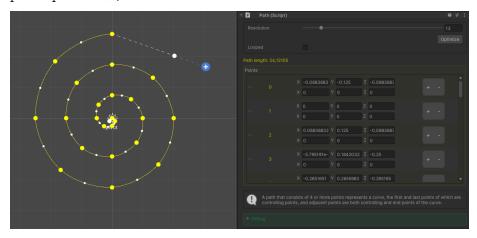
## Path properties

- $\bullet\,$  PointsCount total number of points in the path
- SegmentsCount number of segments in the path. A segment is a curve between two points. In a looped path, the number of segments is always equal to the number of points.
- Resolution path resolution. Affects all segments.
- Looped is the path looped?
- Length total length of the path (sum of lengths of all segments).

## Path optimization

You can use the Optimize method to optimize a path. The algorithm will find the most appropriate value for the Resolution field, such that the path looks moderately smoothed.

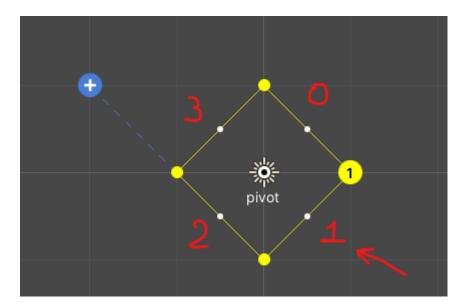
var path = Path.CreateSpiral(0f, 3, 1f, 8, true);
path.Optimize();



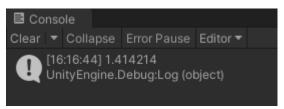
## Segment length

Use the float GetSegmentLength(int segment) method to get the length of a particular path segment.

```
var path = Path.CreatePolygon(4, 1f);
var segment1Length = path.GetSegmentLength(1);
Debug.Log(segment1Length);
```



In the figure above, the indexes of the segments formed by the dots are shown in red. Below you can see the result of calling the GetSegmentLength method.



# Point type

To work with points through code, there is a data type Point. It is a structure with properties Position and Rotation. You can create a point using the default constructor or an overloaded version that takes the position and rotation of the point in space. All points inside a Path object are calculated locally, but as you'll see later, almost all methods allow you to work with points globally as well if you want to.

var point1 = new Point(); // Create a point at position [0, 0, 0] and with zero rotation.
point1.Position = new Vector3(1f, 2f, 3f); // Set the position of this point to [1, 2, 3].
point1.Rotation = Quaternion.Euler(0f, 90f, 0f); // Set the rotation of this point in the diagram.

var point2 = new Point(1f, 2f, 3f, Quaternion.Euler(0f, 90f, 0f)); // Do the same thing, but

### PointData type

This type is an extended version of the Point structure, which in addition to the Position and Rotation properties contains also Direction. The Direction is the direction in space that corresponds to the movement along the path at the point Position, that is, it is a vector representing the direction of movement along the path. You don't have to create PointData structure objects manually, instead the methods that we'll explore later in this documentation will calculate this direction themselves and return PointData to you instead of Point where it makes sense.

### Operations on points

#### Adding to the end

- void AddPoint(float x, float y, float z, bool useGlobal = true) creates a new point with specified position and adds it to the end of the path.
- void AddPoint(Vector3 position, bool useGlobal = true) creates a new point with the specified position and adds it to the end of the path.
- void AddPoint(Point point, bool useGlobal = true) adds a point to the end of the path.

#### Insertion by index

- void InsertPoint(int index, float x, float y, float z, bool useGlobal = true) creates a new point with the specified position and inserts it into the path at the specified index.
- void InsertPoint(int index, Vector3 position, bool useGlobal = true) creates a new point with the specified position and inserts it into the path at the specified index.
- void InsertPoint(int index, Point point, bool useGlobal = true) inserts a point into the path at the specified index.

#### check for content

- bool ContainsPoint(float x, float y, float z, bool useGlobal = true) checks if there is a point with the specified position in the path.
- bool ContainsPoint(Vector3 position, bool useGlobal = true) checks if there is a point with the specified position in the path.
- bool ContainsPoint(Point point, bool useGlobal = true) checks if there is a point in the path.

#### Index search

- int IndexOfPoint(float x, float y, float z, bool useGlobal = true) finds point with specified position in the path and returns its index
- int IndexOfPoint(Vector3 position, bool useGlobal = true) finds point with specified position in the path and returns its index
- int IndexOfPoint(Point point, bool useGlobal = true) finds a point in the path and returns its index

#### Remove from the path

- bool RemovePoint(float x, float y, float z, bool useGlobal = true) removes a point with the specified position from the path. Returns true if the point has been removed.
- bool RemovePoint(Vector3 position, bool useGlobal = true) removes the point with the specified position from the path. Returns true if the point has been removed.
- bool RemovePoint(Point point, bool useGlobal = true) removes the point from the path. Returns true if point has been deleted.

#### Remove by index

• void RemovePointAt(int index) - removes a point from the path at the specified index.

#### Complete clearing.

• void ClearPoints() - removes all points from the path.

#### Example of using these methods.

Almost all of the methods described above have a useGlobal parameter, which tells the method in which space (local? or global?) the position and/or rotation are passed to it. A value of true means that the data is passed in global space.

```
var path = Path.Create();
path.AddPoint(Vector3.zero);
path.AddPoint(1f, 0f, 0f);

var point = new Point(2f, 0f, 0f, Quaternion.identity);
path.InsertPoint(0, point);
Debug.Log(path.ContainsPoint(point));

var index = path.IndexOfPoint(Vector3.zero);
Debug.Log(index);
```

```
path.RemovePoint(point);
path.RemovePointAt(index);
```

Debug.Log(path.PointsCount);



## Read and change points

To read point values, use the PointData GetPointByIndex(int index, bool useGlobal = true) method. This method will return you a PointData object representing the point and its direction in the path.

var path = Path.CreatePolygon(4, 1f);
print(path.GetPointByIndex(0));



The second line reads the value of point 0. The figure shows that the direction

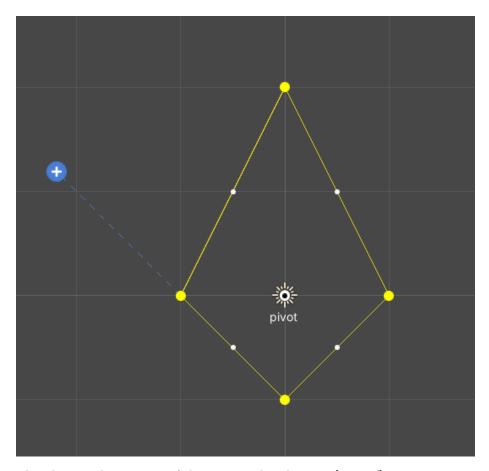
of movement from point 0 to point 1 (to the right and below it) in global space is [1, 0, -1], if we normalize this value, we get [0.71, 0, -0.71], as we see in the 'Debug' tab in the second screenshot.

Use one of the overloaded variants of the SetPoint method to write points:

- void SetPoint(int index, float x, float y, float z, bool useGlobal = true) change point position by index index.
- void SetPoint(int index, Vector3 position, bool useGlobal = true) change point position by index index.
- void SetPoint(int index, Quaternion rotation, bool useGlobal = true) change point rotation by index index.
- void SetPoint(int index, float x, float y, float z, Quaternion rotation, bool useGlobal = true) change position and rotation of the point by index index.
- void SetPoint(int index, Vector3 position, Quaternion rotation, bool useGlobal = true) change position and rotation of the point by index index.
- "void SetPoint(int index, Point point, bool useGlobal = true)- change point by indexindex'.

#### For example:

```
var path = Path.CreatePolygon(4, 1f);
path.SetPoint(0, 0f, 0f, 2f);
```



This changes the position of the point with index 0 to [0, 0, 2f].

# Calculate a point on a path

Use method GetPointOnPathByIndex if you need to calculate a point on the path (on the yellow line).

• PointData Calculate(int index, bool useGlobal = true) - calculates point on the path by index. As opposed to GetPointByIndex, this method only takes into account the points that lie on the path (the yellow line in the editor). With the useGlobal parameter you can specify in which space you want to calculate the point, if you pass true value, the calculation will take place in the global space.

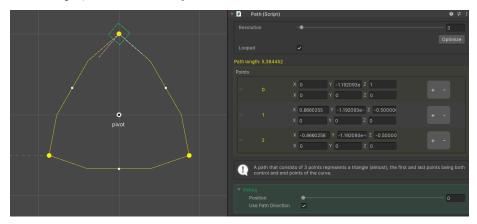
Use the method GetPointAtDistance if you need to calculate a point on a path. There are several overloads of this method.

• PointData GetPointAtDistance(int segment, float distance,

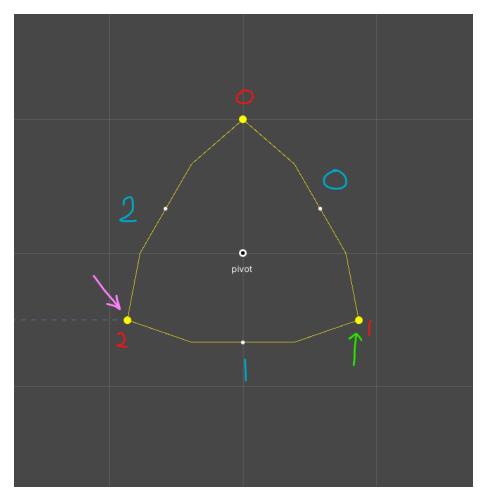
bool useNormalizedDistance = true, bool useGlobal = true) - calculates the point on the specified segment. If the useNormalizedDistance parameter is true, then the distance parameter will be used as a normalized value (that is, from 0 to 1), otherwise distance is treated as meters.

• PointData GetPointAtDistance(float distance, bool useNormalizedDistance = true, bool useGlobal = true) - calculates a point on the entire path. The parameters behave the same as in the previous method.

For example, we have this way.

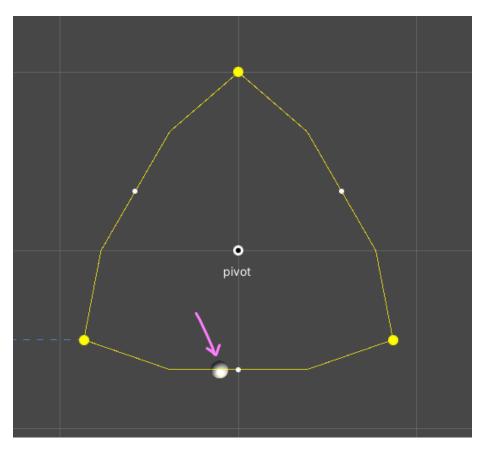


And we want to get a point that lies on a segment with the index 1. The point must be at a distance of 1 meter from the beginning of the segment. To understand how to solve this problem, let's first understand the segment indices.



In the figure above, point indices are marked in red, and segment indices are marked in blue. Segments always start at the first point of the path (the yellow point, not the white one). Note that the segment with index 1 is at the bottom of the triangular path. Its beginning is indicated by a green arrow, and its end by a pink one. According to the problem, we need to find a point lying on the path at a distance of 1 meter from the green toward the pink. The first overloaded method GetPointAtDistance from the list above is suitable for this purpose.

var data = \_path.GetPointAtDistance(1, 1f, false); // Calculate a point on the segment with
var sphere = GameObject.CreatePrimitive(PrimitiveType.Sphere).transform;
sphere.position = data.Position;
sphere.localScale \*= 0.1f;

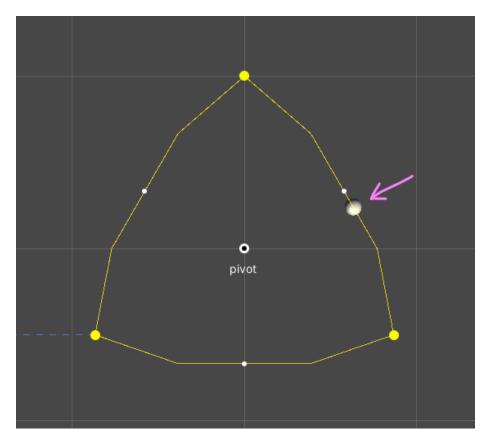


As you can see, the point has been successfully calculated.

If you need to calculate a point not on a particular segment, but on the whole path, just skip the segment index in the GetPointAtDistance method;

 $\ \ \text{var data = \_path.GetPointAtDistance(1f, false); // Calculate the point on the entire path, and the point of the entire path, and the entire path of the entire path, and the entire path of the entire path o$ 

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var sphere = GameObject.CreatePrimitive(PrimitiveType.Sphere).transform;
sphere.position = data.Position;
sphere.localScale *= 0.1f;
```



As you see now the point is calculated on the whole path. If the specified distance from the beginning is greater than the length of the path, the point will be bounded at the end of that path.

# Point Cycle

To create a point cycle you can use the PointsCount property and the GetPointAtDistance method.

for (int i = 0; i < \_path.PointsCount; i++)
 print(\_path.GetPointAtDistance(i));</pre>



Well, that's all for now! We hope you will find the PATH bibliography helpful. Good luck!