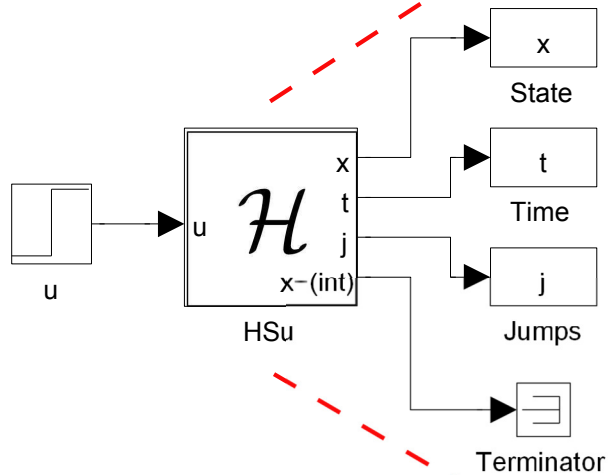


This model simulates a hybrid system with input

Double Click
to Initialize

Double Click to
Plot Solutions



1
 u_1

x
 u
 \dot{x}
 f
flow map f

x
 u
 v
 C
flow set C

x
 u
 g
 a
jump map g

\leq
 \leq
AND
 D

Integrator System

x
1
 x

t
2
 t

j
3
 j

x^-
4
 $x^-(int)$