

Allgemein

Formeln

$$u = R \cdot i \quad i = G \cdot u$$

$$R = \frac{u}{i} \quad G = \frac{i}{u}$$

$$P = R \cdot i^2 \quad P = G \cdot u^2$$

Parallel Serie

$$u_1 = u_2 \quad u_1 + u_2$$

$$i_1 + i_2 \quad i_1 = i_2$$

$$R_1 || R_2 \quad R_1 + R_2$$

$$G_1 + G_2 \quad G_1 || G_2$$

Sp.-Teiler
Serie

$$u_1 = \frac{R_1}{R_1 + R_2} \cdot u_g$$

$$u_1 = \frac{G_2}{G_1 + G_2} \cdot u_g$$

Stv.-Teiler
Parallel

$$i_1 = \frac{G_1}{G_1 + G_2} \cdot i_g$$

$$i_1 = \frac{R_2}{R_1 + R_2} \cdot i_g$$

Diöden

Ideal pn

$$u < 0, i = 0$$

$$u = 0, i > 0$$

$$i_d = I_s \cdot (e^{u/u_T} - 1)$$

$$u_d = u_T \cdot \ln\left(\frac{i_d}{I_s} + 1\right)$$

KS-LL

$u', i' = \text{Quelle}$
 $u, i = \text{Last}$

LL KS

$$i = 0 \quad u = 0$$

$$\phi = 0$$

$$a || b = \frac{a \cdot b}{a + b}$$

Dualwandlung: $i^d = \frac{u}{R_d}$ $u^d = R_d \cdot i$

Schalter $\begin{cases} 1, \text{Zu, KS} \\ 0, \text{auf, LL} \end{cases}$ $Q\text{-frei} = (0, 0)$

Generell

$i = \sum \text{Str.} = \text{Par. St. \&}$
 $u = \sum \text{Sp.} = \text{Ser. Sp. \&}$

Lin. Quellen

$$i' = G \cdot (u' - u_0)$$

$$= G \cdot u' - i_0$$

Ableitungsregeln

$$(\sin(x))' = \cos(x) \quad (\cos(x))' = -\sin(x)$$

$$(f(x) \cdot g(x))' = f(x)' \cdot g(x) + g(x)' \cdot f(x)$$

$$(f(x) \pm g(x))' = f(x)' \pm g(x)'$$

$$\left(\frac{f(x)}{g(x)}\right)' = \frac{f(x)' \cdot g(x) - f(x) \cdot g(x)'}{g(x)^2}$$

$$(e^x)' = e^x$$

$$x' = 1$$

$$k^x = \ln(k) \cdot k^x$$

$$k' = 0$$

$$(x^n)' = n \cdot x^{n-1}$$

$$\ln(x)' = \frac{1}{x}$$

$$\text{Inv. Matrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$\det = ad - bc$$

$$A^{-1} = \frac{1}{\det} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$\text{Steigung}$$

$$\text{Rise}$$

$$\text{Run}$$

Eintore

Konvexer Widerstand

$$(G, u)$$

$$(R, u)$$

Konvexer Widerstand

$$(R, u)$$

$$(G, u)$$

Ap finden

$$Q^x = Q(u, -i)$$

$$Q^x = Q(u, -i)$$

Umpolung

$$g_F'(u') = -g_F(-u')$$

$$v_F'(i') = -v_F(-i')$$

Quellwandlung

$$u_0 = \frac{u}{R}$$

$$i = \frac{u}{R}$$

Linearisierung

$$u_{lin} = \frac{\delta u}{\delta i} \bigg|_{i=I} \cdot (-i - I) + u$$

$$i_{lin} = \frac{\delta i}{\delta u} \bigg|_{u=U} \cdot (u - U) + I$$

$$u_{lin} = \frac{\delta u}{\delta i} \bigg|_{i=I} \cdot (-i - I) + u$$

$$i_{lin} = \frac{\delta i}{\delta u} \bigg|_{u=U} \cdot (u - U) + I$$

$$u_{lin} = \frac{\delta u}{\delta i} \bigg|_{i=I} \cdot (-i - I) + u$$

$$i_{lin} = \frac{\delta i}{\delta u} \bigg|_{u=U} \cdot (u - U) + I$$

Zweiteore

str. lin. & Q. frei

- 2 lin. un. Messungen

- Kennbach. immer

- Bildbesch. \rightarrow 2 Mess.

lin. & Q. frei

- str. lin. 2-Tor + lin. Q.

$$F = [M, N] \cdot \begin{bmatrix} u - u_0 \\ i - i_0 \end{bmatrix}$$

$$\begin{bmatrix} u \\ i \end{bmatrix} = \begin{bmatrix} u_0 \\ i_0 \end{bmatrix} + \begin{bmatrix} u - u_0 \\ i - i_0 \end{bmatrix}$$

KS-LL

$$x_{11} = \frac{1 \text{ gest.}}{1 \text{ st.}} \quad 1. \text{ st. } 0$$

$$x_{12} = \frac{1 \text{ gest.}}{2 \text{ st.}} \quad 1. \text{ st. } 0$$

$$\vdots$$

NIK

$$n = -1$$

$$n = +1$$

$$A = \begin{bmatrix} -k & 0 \\ 0 & \frac{1}{k} \end{bmatrix}$$

Nullor

$$\{ \} = \text{gest. Q.}$$

VCVS

$$H = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} \frac{1}{R} & 0 \\ 0 & 0 \end{bmatrix}$$

VCCS

$$G = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 0 & -\frac{1}{R} \\ 0 & 0 \end{bmatrix}$$

CCCS

$$H = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 0 & 0 \\ 0 & -\frac{1}{R} \end{bmatrix}$$

CCVS

$$R = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 0 & 0 \\ \frac{1}{R} & 0 \end{bmatrix}$$

Symmetrie

$$P = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$\text{symm. if}$$

$$M = P \cdot M \cdot P$$

Rec.

$$R \& G \rightarrow b = c$$

$$H \rightarrow b = -c$$

$$A \rightarrow \det = 1$$

$$u^T \cdot I - I^T \cdot u = 0$$

Verlustlos

$$u^T \cdot I + I^T \cdot u = 0$$

$$\sim \sim \sim \sim$$

Jacobus Mat.

$$J = \begin{bmatrix} \frac{\delta h_1(u_1, u_2)}{\delta u_1} & \frac{\delta h_1(u_1, u_2)}{\delta u_2} \\ \frac{\delta h_2(u_1, u_2)}{\delta u_1} & \frac{\delta h_2(u_1, u_2)}{\delta u_2} \end{bmatrix}$$

Dualw. 2-Tor

$$G^d = \frac{1}{R_d^2} \cdot R$$

$$R^d = R_d^2 \cdot G$$

Bild Besch.

$$\begin{bmatrix} u \\ i \end{bmatrix} = \begin{bmatrix} u_1 & u_2 \\ u_3 & u_4 \\ u_5 & u_6 \\ u_7 & u_8 \end{bmatrix} \cdot \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

Gvr.

$$R = -R^T$$

$$R = \begin{bmatrix} 0 & -R_d \\ R_d & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 0 & +R_d \\ \frac{1}{R_d} & 0 \end{bmatrix}$$

$$T_1 = T_2^d$$

Übertreger

$$\frac{1}{s} \cdot \frac{u}{i}$$

$$u^T \cdot I = 0$$

$$H = \begin{bmatrix} 0 & \ddot{u} \\ -\ddot{u} & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} \ddot{u} & 0 \\ 0 & -\ddot{u} \end{bmatrix}$$

Kleinsignalanalyse

$$\Delta i = i_{lin} - I_{AP} \quad \Delta u = u - U_{AP}$$

$$\text{Konst. } Q. = 0$$

$$i_{lin} = \frac{\partial g_1(u_1, u_2)}{\partial u_1} \bigg|_{u=U} (u_1 - U_1) + \frac{\partial g_1(u_1, u_2)}{\partial u_2} \bigg|_{u=U} (u_2 - U_2) + I_1$$

$$i_{lin} = \frac{\partial g_2(u_1, u_2)}{\partial u_1} \bigg|_{u=U} (u_1 - U_1) + \frac{\partial g_2(u_1, u_2)}{\partial u_2} \bigg|_{u=U} (u_2 - U_2) + I_2$$

| * | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
|----|----|----|----|----|----|----|----|----|----|-----|
| 1 | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| 2 | 2 | 4 | 6 | 8 | 10 | 12 | 14 | 16 | 18 | 20 |
| 3 | 3 | 6 | 9 | 12 | 15 | 18 | 21 | 24 | 27 | 30 |
| 4 | 4 | 8 | 12 | 16 | 20 | 24 | 28 | 32 | 36 | 40 |
| 5 | 5 | 10 | 15 | 20 | 25 | 30 | 35 | 40 | 45 | 50 |
| 6 | 6 | 12 | 18 | 24 | 30 | 36 | 42 | 48 | 54 | 60 |
| 7 | 7 | 14 | 21 | 28 | 35 | 42 | 49 | 56 | 63 | 70 |
| 8 | 8 | 16 | 24 | 32 | 40 | 48 | 56 | 64 | 72 | 80 |
| 9 | 9 | 18 | 27 | 36 | 45 | 54 | 63 | 72 | 81 | 90 |
| 10 | 10 | 20 | 30 | 40 | 50 | 60 | 70 | 80 | 90 | 100 |

$$\begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = G \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} + \begin{bmatrix} i_{G1} \\ i_{G2} \end{bmatrix}$$

$$\begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = R \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} + \begin{bmatrix} u_{R1} \\ u_{R2} \end{bmatrix}$$

| | R | G | H | H' | A | A' |
|----|---|---|---|--|---|--|
| R | $\begin{bmatrix} r_{11} & r_{12} \\ r_{21} & r_{22} \end{bmatrix}$ | $\frac{1}{\det G} \begin{bmatrix} g_{22} & -g_{12} \\ -g_{21} & g_{11} \end{bmatrix}$ | $\frac{1}{h_{22}} \begin{bmatrix} \det H & h_{12} \\ -h_{21} & 1 \end{bmatrix}$ | $\frac{1}{h_{11}} \begin{bmatrix} 1 & -h_{12} \\ h_{21} & \det H' \end{bmatrix}$ | $\frac{1}{a_{21}} \begin{bmatrix} a_{11} & \det A \\ 1 & a_{22} \end{bmatrix}$ | $\frac{1}{a_{11}} \begin{bmatrix} a_{22} & 1 \\ \det A' & a_{11} \end{bmatrix}$ |
| G | $\frac{1}{\det R} \begin{bmatrix} r_{22} & -r_{12} \\ -r_{21} & r_{11} \end{bmatrix}$ | $\begin{bmatrix} g_{11} & g_{12} \\ g_{21} & g_{22} \end{bmatrix}$ | $\frac{1}{h_{11}} \begin{bmatrix} 1 & -h_{12} \\ h_{21} & \det H \end{bmatrix}$ | $\frac{1}{h_{22}} \begin{bmatrix} \det H' & h_{12} \\ -h_{21} & 1 \end{bmatrix}$ | $\frac{1}{a_{12}} \begin{bmatrix} a_{22} & -\det A \\ -1 & a_{11} \end{bmatrix}$ | $\frac{1}{a_{12}} \begin{bmatrix} a_{11} & -1 \\ -\det A' & a_{22} \end{bmatrix}$ |
| H | $\frac{1}{r_{22}} \begin{bmatrix} \det R & r_{12} \\ -r_{21} & 1 \end{bmatrix}$ | $\frac{1}{g_{11}} \begin{bmatrix} 1 & -g_{12} \\ g_{21} & \det G \end{bmatrix}$ | $\begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix}$ | $\frac{1}{\det H'} \begin{bmatrix} h_{22} & -h_{12} \\ -h_{21} & h_{11} \end{bmatrix}$ | $\frac{1}{a_{22}} \begin{bmatrix} a_{12} & \det A \\ -1 & a_{21} \end{bmatrix}$ | $\frac{1}{a_{11}} \begin{bmatrix} a_{12} & 1 \\ -\det A' & a_{21} \end{bmatrix}$ |
| H' | $\frac{1}{r_{11}} \begin{bmatrix} 1 & -r_{12} \\ r_{21} & \det R \end{bmatrix}$ | $\frac{1}{g_{22}} \begin{bmatrix} \det G & g_{12} \\ -g_{21} & 1 \end{bmatrix}$ | $\frac{1}{h_{22}} \begin{bmatrix} h_{22} & -h_{12} \\ -h_{21} & h_{11} \end{bmatrix}$ | $\begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix}$ | $\frac{1}{a_{11}} \begin{bmatrix} a_{21} & -\det A \\ 1 & a_{12} \end{bmatrix}$ | $\frac{1}{a_{22}} \begin{bmatrix} a_{21} & -1 \\ \det A' & a_{12} \end{bmatrix}$ |
| A | $\frac{1}{r_{11}} \begin{bmatrix} r_{11} & \det R \\ 1 & r_{22} \end{bmatrix}$ | $\frac{1}{g_{21}} \begin{bmatrix} -g_{22} & -1 \\ -\det G & -g_{11} \end{bmatrix}$ | $\frac{1}{h_{21}} \begin{bmatrix} -\det H & -h_{11} \\ -h_{22} & -1 \end{bmatrix}$ | $\frac{1}{h_{11}} \begin{bmatrix} 1 & h_{22} \\ h_{11} & \det H' \end{bmatrix}$ | $\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$ | $\frac{1}{\det A'} \begin{bmatrix} a_{22} & a_{12} \\ a_{21} & a_{11} \end{bmatrix}$ |
| A' | $\frac{1}{r_{12}} \begin{bmatrix} r_{22} & \det R \\ 1 & r_{11} \end{bmatrix}$ | $\frac{1}{g_{12}} \begin{bmatrix} -g_{11} & -1 \\ -\det G & -g_{22} \end{bmatrix}$ | $\frac{1}{h_{12}} \begin{bmatrix} 1 & h_{11} \\ h_{22} & \det H \end{bmatrix}$ | $\frac{1}{h_{12}} \begin{bmatrix} -\det H' & -h_{22} \\ -h_{11} & -1 \end{bmatrix}$ | $\frac{1}{\det A} \begin{bmatrix} a_{22} & a_{12} \\ a_{21} & a_{11} \end{bmatrix}$ | $\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$ |