

2-) Probability & Random Variables

- $h(x_i) = f_i/n \rightarrow$ relative frequency
- $h(x_i) = f_i/n * (c_i - c_{i-1}) \rightarrow$ density height
- f_i : frequency
- n : sample size
 - $P(A) \geq 0$
 - $P(S) = 1$
 - Mutually Exclusive Events
 - $P(A1 \cup A2 \cup \dots) = P(A1) + P(A2) + \dots$
- $nPr = n! / (n-r)!$
- $nCr = n! / r! * (n-r)!$
- MR (Multiplication Rule)
 - $P(A \cap B) = P(A | B) \times P(B)$
 - $P(A \cap B) = P(B | A) \times P(A)$
- EMR
 - $P(A \cap B \cap C) = P((A \cap B) | C) \times P(C | (A \cap B)) \times P(A \cap B)$
 - $P(A \cap B) = P(B | A) \times P(A)$
 - $P(A \cap B \cap C) = P((A \cap B) | C) \times P(C | (A \cap B)) \times P(B | A) \times P(A)$
- VENN
 - $\frac{P(A_1 \cap B) \cup P(A_2 \cap B) \cup \dots P(A_k \cap B)}{P(B)}$
- ME
 - $\frac{P(A_1 \cap B) + P(A_2 \cap B) + \dots P(A_k \cap B)}{P(B)}$
- CP
 - $P(A_1 | B) + P(A_2 | B) + \dots P(A_k | B)$
- Independent Events
 - $P(A \cap B) = P(A) \times P(B)$
- Conditional Probability
 - $P(T^+ | D) = \frac{N(T^+ \cap D)/N(S)}{N(D)/N(S)}$
 - $P(T^+ | D) \neq P(D | T^+)$
 - $P(A | B) = \frac{P(A \cap B)}{P(B)}$
- Hyper Geometric Distribution
 - $P(X = x) = f(x) = \frac{\binom{m}{x} \binom{N-m}{n-x}}{\binom{N}{n}}$
 - select n items without replacement from a set of N items
 - m of the items are of one type
 - and $N - m$ of the items are of a second type
- Expected Value & Variance & Standard Deviation
 - $E(X) = 3(0.3) + 4(0.4) + 5(0.3) = 4$
 - $E(Y) = 1(0.4) + 2(0.1) + 6(0.3) + 8(0.2) = 4$
 - $\sigma = E(\mu(x)) = E((X - \mu)^2) \rightarrow$ Standard Deviation
 - $\sigma^2 = E(\mu(x)) = E((X - \mu)^2) \rightarrow$ Variance = $\sqrt{\sigma^2}$

3-) Bayes & Naïve Bayes

- Bayesian Rule
$$P(c | x) = \frac{p(x | c) p(c)}{p(x)} = \text{Posterior} = \frac{\text{likelihood} \times \text{prior}}{\text{evidence}} = \frac{\text{joint}}{\text{normalizer}}$$
 - Updates the probability of an event
 - Based new evidence
 - Run Out Of Space & Time
 - Tons Of Data
 - Learning Joint Probability is infeasible
- Posterior Probability ($P(w_j | x)$)
 - hypothesis is true or not in the light of relevant observations
- Joint Probability
 - $x = (x_1, x_2), P(x) = P(x_1, x_2)$
 - $P(x_1, x_2) = P(x_2 | x_1) P(x_1) = P(x_1 | x_2) P(x_2)$
 - $P(C, x) = P(x | C) P(C) \rightarrow$ Joint Probability
 - $P(\neg C, x) = P(x | \neg C) P(\neg C) \rightarrow$ Joint Probability
 - Sensitivity: “ ”, Specificity: “ \neg ”
- Normalized Histogram (3-1 Page 21, 3-2 Page 8)
 - $P(x) = P(C, x) + P(\neg C, x)$
 - Total or Evidence
- Posterior
 - $P(C | x) = \frac{P(C, x)}{\text{Normalizer}}$
 - $P(\neg C | x) = \frac{P(\neg C, x)}{\text{Normalizer}}$
 - $P(C) \rightarrow$ Prior
 - $P(Pos | C) \rightarrow$ Sensitivity
 - $P(Neg | \neg C) \rightarrow$ Specificity

➤ Naïve Bayes Normal Distribution

$$\hat{P}(x_j | c_i) = \frac{1}{\sqrt{2\pi}\sigma_{ji}} \exp\left(-\frac{(x_j - \mu_{ji})^2}{2\sigma_{ji}^2}\right)$$

μ_{ji} : mean (average) of feature values x_j of examples for which $c = c_i$

σ_{ji} : standard deviation of feature values x_j of examples for which $c = c_i$

$$\mu = \frac{1}{N} \sum_{n=1}^N x_n, \quad \sigma^2 = \frac{1}{N} \sum_{n=1}^N (x_n - \mu)^2$$

4-) KNN & Regression

$$L_p(x, y) = \left(\sum_{i=1}^d |x_i - y_i|^p \right)^{1/p} \quad L_2(x, y) = \left(\sum_{i=1}^d |x_i - y_i|^2 \right)^{1/2} \quad L_1(x, y) = \sum_{i=1}^d |x_i - y_i|$$

- L_p Norm (Minkowski), Euclidian Distance, Manhattan Distance
- $y = mx + b$ ($y \rightarrow$ dependent & $x \rightarrow$ independent)
- $y = mx * b_1 + b_0$
- $Q = \sum_{i=1}^n y_i - y_i'$
- Regression Line
- $\hat{y} = b_0 + b_1 x$
- Sum of Squared Errors
- $SSE = \sum_{i=1}^n (y_i - \hat{y}_i)^2 = \sum_{i=1}^n (y - b_0 - b_1 x)^2$
- $n = 10$
 - $\sum x = 564$ $\sum x^2 = 32604$
 - $\sum y = 14365$ $\sum xy = 818755$
- $b_1 = \frac{n \sum xy - \sum x \sum y}{n \sum x^2 - (\sum x)^2} = 10.8$
- $b_0 = 1436.5 - 10.8(56.4) = 828$
- $b_0 = \frac{\hat{y}}{n} - b_1 \frac{x}{n}$
- $cov(x, y) = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{n-1}$
- $r = \frac{cov\ variance(x, y)}{\sqrt{var\ x} \sqrt{var\ y}} = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2} \sqrt{\sum_{i=1}^n (y_i - \bar{y})^2}}$
- $\hat{r} = \frac{cov\ variance(x, y)}{\sqrt{var\ x} \sqrt{var\ y}} = \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\frac{\sum_{i=1}^n (x_i - \bar{x})^2}{n-1}} \sqrt{\frac{\sum_{i=1}^n (y_i - \bar{y})^2}{n-1}}}$
- $\hat{\beta} = \frac{Cov(x, y)}{Var(x)}$
- Intercept = Calculate: $\bar{\alpha} = \bar{y} - \hat{\beta} \bar{x}$
- $\hat{r} = \hat{\beta} \frac{SD_x}{SD_y}$
- $e_i = Y_i - \hat{Y}_i \rightarrow$ Residual = Observed – Predicted
- Observed = Real Dot (Ground Root)
- Predicted = Value of Y in Line Correspond to X
- $S_{y.x}^2 = \frac{1}{n-2} \sum e_i^2 = \frac{1}{n-2} \sum (y_i - \hat{y}_i)^2$

5-) Clustering & PCA

- Euclidian, Manhattan, Infinity

$$d(x, y) = \sqrt{\sum_{i=1}^d (x_i - y_i)^2} \quad d(x, y) = |x - y| = \sum_{i=1}^d |x_i - y_i| \quad d(x, y) = \max_{1 \leq i \leq d} |x_i - y_i|$$

- K-Means : Initial Centre – Distance Matrix – Object Clustering – Distance Matrix – Object Clustering – Recompute Until No Change

6-) Decision Tree & Linear Classification

- $Entropy(S) = -p_+ \log_2 p_+ - p_- \log_2 p_-$
- $H(Y) = -\sum_{i=1}^k P(Y = y_i) \log_2 P(Y = y_i)$
- $H(Y | X) = -\sum_{j=1}^v P(X = x_j) \sum_{i=1}^k P(Y = y_i | X = x_j) \log_2 P(Y = y_i | X = x_j)$
- $IG(X_i) = H(Y) - H(Y | X_i)$
- $\text{argmax } IG(X_i) = \text{argmax } H(Y) - H(Y | X_i)$
- $H(Y | X : t) = P(X < t) H(Y | X < t) + P(X \geq t) H(Y | X \geq t)$
- $IG(Y | X : t) = H(Y) - H(Y | X : t)$
- $IG^*(Y | X) = \max_t IG(Y | X : t)$
- $E = \frac{1}{2} (y - f(\sum w_i x_i))^2$
- $w_j^r(\text{new}) = w_j^r(\text{old}) - \mu \sum_{i=1}^N \frac{\partial \varepsilon(i)}{\partial w_j^r}$ where $\frac{\partial \varepsilon(i)}{\partial w_j^r} = \delta_j^r(i) y^{r-1}(i) = \text{Batch Learning}$
- $w_j^r(\text{new}) = w_j^r(\text{old}) - \mu \frac{\partial \varepsilon(i)}{\partial w_j^r}$ where $\frac{\partial \varepsilon(i)}{\partial w_j^r} = \delta_j^r(i) y^{r-1}(i) = \text{Online Learning}$

7-) SVM

- $f(x) = w^T x_i + w_0$, ($w_0 = \text{bias}$), bias corresponds to the output of an CNN when it has zero input
- Init $w = 0$
- Cycle Through $\{x, y\}$
- If x is misclassified $w \leftarrow w + \text{assign}(f(x))x$
- Continue Until Data is Correctly Classified
- Linear SVM
 - $f(x) = \sum_i \alpha_i x_i (x_i^T x) + b$
 - $r = \frac{wx_i + b}{\|w\|}$ where $\|w\| = \sqrt{w_1^2 + \dots + w_n^2}$
 - $\text{margin} = \frac{2}{\|w\|} \rightarrow$ minimize weight vector, it will maximize margin
 - $w x_i + b \geq 1$ if $y_i = +1$ $w x_i + b \leq -1$ if $y_i = -1$
 - $y_i (w x_i + b) \geq 1$ for all i
 - $\phi = \frac{1}{2} (w^T w)$, find unique minimum by using training data
 - $\frac{1}{2} w^T w + C \sum_{k=1}^R \epsilon_k$ C is the Slack Variables
 - Small C Allows constraints easily ignored \rightarrow Large Margin – Wider (Soft) ($C=1$ e.g.)
 - Large C Allows constraints hard to ignored \rightarrow Narrow Margin – Close to Hard ($C=100$)
 - Infinite C enforces all constraints \rightarrow Hard Margin ($C = \infty$)

7-) SVM

➤ Non-Linear SVM

- $\varphi(x_2^{x_1}) \rightarrow \begin{pmatrix} r \\ \theta \end{pmatrix} R^2 \rightarrow R^2$
- $\varphi(x_2^{x_1}) \rightarrow \begin{pmatrix} x_1^2 \\ x_2^2 \\ \sqrt{2}x_1x_2 \end{pmatrix} R^2 \rightarrow R^3$
- $f(x) = w^T x_i + w_0 \rightarrow f(x) = w^T \varphi(x) + b$
- Classifier : $f(x) = w^T \varphi(x) + b$
- RBF SVM
 - $f(x) = \sum_i \alpha_i y_i \exp(-\|x - x_i\|^2 / 2\sigma^2) + b$
 - $\sigma \rightarrow$ Seperate Data
 - Hyper Parameter for Slack Variable
 - Decide our data by C & σ
 - Decrease σ , it moves towards NN Classifier

9-) Deep Learning

➤ $f(x, W) = Wx$

➤ $L_i = \sum_{j \neq y_i} \max(0, s_j - s_{y_i} + 1)$

- $s_j \rightarrow Others$
- $s_{y_i} \rightarrow Target$

➤ $L_i = \frac{1}{N} \sum_{i=1}^N L_i$

➤ MSE, Quadratic, $L2 = \frac{\sum_{i=1}^n (y_i - \hat{y}_i)^2}{n}$

➤ Mean Absolute Error, $L1 = \frac{\sum_{i=1}^n |y_i - \hat{y}_i|}{n}$

➤ Mean Bias Error = $\frac{\sum_{i=1}^n (y_i - \hat{y}_i)}{n}$

➤ Cross Entropy Loss = $-(y_i \log(\hat{y}_i) + (1 - y_i) \log(1 - \hat{y}_i))$

➤ Activations Functions: Sigmoid, tanh, ReLU, LReLU, Maxout, ELU

- $\sigma(x) = \frac{1}{1 + e^{-x}}$
- $\tanh(x)$
- $\max(0, x)$
- $\max(0.1x, x)$
- $\max(w_1^T x + b_1, w_2^T x + b_2)$
- $\begin{cases} \mathbf{x} & \mathbf{x} \geq \mathbf{0} \\ \alpha(e^{\mathbf{x}} - 1) & \mathbf{x} < \mathbf{0} \end{cases} \rightarrow \text{Exponential Linear Unit}$

➤ $f[n, m] * h[n, m] = \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} f[k, l] h[n - k, m - l]$

➤ Details of CNN

- Output Size:
 - $O: (N-F)/\text{Stride} + 1$
 - N – Input Size
 - F – Frame Size
 - The O value can't be float.
- Generally, Output Sizes
 - Stride: 1
 - Filters: $F \times F$
 - Zero Padding: $(F-1)/2$
 - Will preserve size stability
- Output Volume Size:
 - $OVS: (N-2*P-F)/\text{Stride} + 1$
 - 2 is double sided padding coefficient
- Output Volume:
 - $OV: OVS \times OVS \times \text{Feature_Size}$
- Number of Parameters:
 - Parameters: $F * F * \text{Input_Depth} + \text{Bias}$
 - NOP: Parameters * Feature_Size
 - Bias : 0 or +1
 - Pooling Layers doesn't consist parameters
- Summary
 - $W_1 * H_1 * D_1$
 - K: Number of Filter
 - F: Spatial Extent
 - S: Stride
 - P: Amount of Zero Padding
 - $W_2 * H_2 * D_2$
 - $W_2 = (W_1 - F + 2P)/S + 1$
 - $H_2 = (H_1 - F + 2P)/S + 1$
 - $D_2 = K$