

1a.  $T(x[n]) = e^{x[n]} + 1$

① Assume:  $|x[n]| \leq B_x < \infty$

Then:  $|y[n]| \leq |e^{x[n]} + 1| \leq e^{B_x} + 1 = B_y < \infty$

Is Stable

② Is causal bc it only depends on current values

③ Define:  $x_3[n] = a_1 x_1[n] + a_2 x_2[n]$

$y_3[n] = T\{x_3[n]\} = e^{a_1 x_1[n] + a_2 x_2[n]} + 1 \neq a_1 (e^{x_1[n]} + 1) + a_2 (e^{x_2[n]} + 1)$

Not Linear

④  $x[n] \rightarrow y[n]$

$x_1[n] = x[n - n_d]$

$y_1[n] = e^{x_1[n]} + 1 = e^{x[n - n_d]} + 1 = y[n - n_d]$

Is time invariant

⑤ Its memoryless since it only depends on current values

1b.  $T(x[n]) = b + n^2 x[n]$ ,  $b \neq 0$

① Assume:  $|x[n]| \leq B_x < \infty$

Then:  $|y[n]| \leq |b + n^2 x[n]| \leq b + n^2 B_x = B_y < \infty$

Is stable

② Is causal bc it only depends on current values

③  $x_3[n] = a_1 x_1[n] + a_2 x_2[n]$

$y_3[n] = b + n^2 (a_1 x_1[n] + a_2 x_2[n]) \neq a_1 (b + n^2 x_1[n]) + a_2 (b + n^2 x_2[n])$

Not Linear

④  $x[n] \rightarrow y[n]$

$x_1[n] = x[n - n_d]$

$y_1[n] = b + n^2 x_1[n] = b + n^2 x[n - n_d] \neq y[n - n_d]$

Not time invariant

⑤ Its memoryless bc it only depends on current values

2a.  $x[n] = \sin\left(\frac{\pi n}{8} + 2\pi\right) + \cos\left(\frac{\pi n}{4} + 3\pi\right)$

$$\omega_0 = \frac{\pi}{8}$$

$$\Rightarrow \frac{\pi}{8}n = 2\pi k$$

Periodic
$N = 16$

2b.  $x[n] = e^{jn}$

$$\omega_0 = 1$$

$$\omega_0 N = 2\pi k \Rightarrow N = 2\pi \rightarrow \text{rational}$$

Not periodic

2c.  $x[n] = 2 \cos\left(\frac{\pi n}{6} + \frac{\pi}{4}\right) + \pi e^{j\frac{\pi n}{8}} + 5$

$$\omega_0 = \frac{\pi}{6}$$

$$\Downarrow$$

$$N_0 = 12$$

$$\omega_1 = \frac{\pi}{8}$$

$$\Downarrow$$

$$N_1 = 16$$

Periodic  $N = \text{lcm}(12, 16) = 48$

3a.  $y[n] = x[n] e^{-j\omega_0 n} * h[n]$   
 $= \sum_{k=-\infty}^{\infty} e^{-j\omega_0 k} x[k] h[n-k]$

Let  $x_3[n] = a_1 x_1[n] + a_2 x_2[n]$

$$\begin{aligned} y_3[n] &= \sum_{k=-\infty}^{\infty} e^{-j\omega_0 k} (a_1 x_1[k] + a_2 x_2[k]) h[n-k] \\ &= a_1 \sum_{k=-\infty}^{\infty} e^{-j\omega_0 k} x_1[k] h[n-k] + a_2 \sum_{k=-\infty}^{\infty} e^{-j\omega_0 k} x_2[k] h[n-k] \\ &= a_1 y_1[n] + a_2 y_2[n] \end{aligned}$$

Its linear

3b. Let  $x_1[n] = x[n - n_0]$

$$\begin{aligned} y_1[n] &= \sum_{k=-\infty}^{\infty} e^{-j\omega_0(k-n)} x_1[k] h[n-k] \\ &= \sum_{k=-\infty}^{\infty} e^{-j\omega_0(k-n)} x_1[n-k] h[k] \\ &= \sum_{k=-\infty}^{\infty} e^{-j\omega_0(k-n)} x[n-n_0-k] h[k] \\ &\neq y[n-n_0] \end{aligned}$$

Not time invariant

3c. Assume  $x[n] \leq B_x < \infty$

Then  $y[n] = e^{-j\omega_0 n} x[n] * h[n] \leq x[n] * h[n] \leq B_x * h[n] \leq B_x$

Stable bc  $h[n]$  is stable and  $e^{-j\omega_0 n}$  is bounded by 1



3d. S:  $Y[n] = \sum_{-\infty}^{\infty} e^{-j\omega_0 k} x[k] h[n-k]$

$$\begin{aligned}
 & X[n] * (h[n] e^{j\omega_0 n}) \rightarrow [c] \rightarrow \sum_{-\infty}^{\infty} e^{-j\omega_0 k} x[k] h[n-k] \\
 & = \sum_{-\infty}^{\infty} x[k] h[n-k] e^{-j\omega_0 (n-k)} \\
 & = \sum_{-\infty}^{\infty} e^{-j\omega_0 n} e^{j\omega_0 k} x[k] h[n-k] \\
 & = \underbrace{e^{-j\omega_0 n}}_{\text{C}} \sum_{-\infty}^{\infty} e^{j\omega_0 k} x[k] h[n-k]
 \end{aligned}$$

C should be a multiplication by  $e^{j\omega_0 n}$

4a.  $e^{j5\omega n}$  can be an eigenfunction because it is an LTI system

4b.  $e^{2j\omega n} + e^{j3\omega n}$  cannot be an eigenfunction because the function is not linear

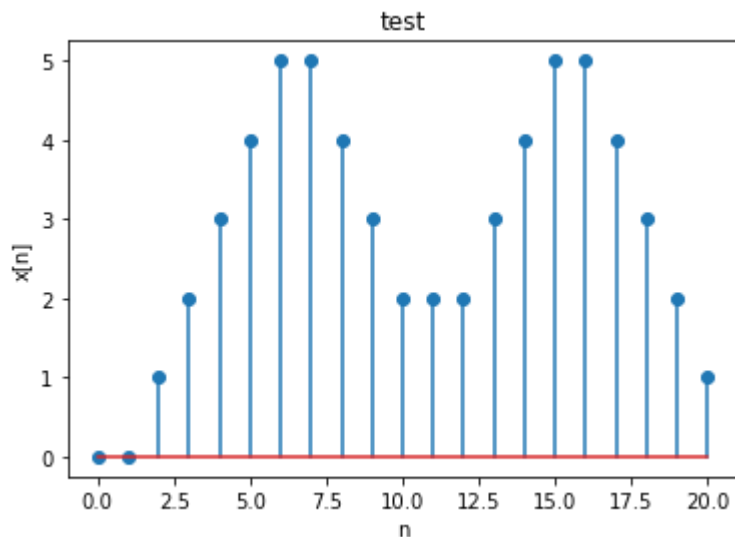
4c.  $2^n u[n]$  cannot be an eigenfunction because it is not stable.

```
In [5]: import numpy as np
import matplotlib.pyplot as plt
from scipy import signal

arr=np.convolve([1,1,1,1,1], [0,0,1,1,1,1,1,1,0,0,0,1,1,1,1,1,1])
plt.xlabel('n')
plt.ylabel('x[n]')
plt.title('test')
n=np.arange(21)
plt.stem(n, arr)
plt.show()
```

<ipython-input-5-c955eab66fa0>:10: UserWarning: In Matplotlib 3.3 individual lines on a stem plot will be added as a LineCollection instead of individual lines. This significantly improves the performance of a stem plot. To remove this warning and switch to the new behaviour, set the "use\_line\_collection" keyword argument to True.

```
plt.stem(n, arr)
```



```

In [6]: numerator=[.008,-.033,.05,-.033,.008]
denominator=[1,2.37,2.7,1.6,.41]
w,h=signal.freqz(numerator,denominator)
fig = plt.figure()
plt.title('Digital filter frequency response')
ax1 = fig.add_subplot(111)

plt.plot(w, 20 * np.log10(abs(h)), 'b')
plt.ylabel('Amplitude [dB]', color='b')
plt.xlabel('Frequency [rad/sample]')

ax2 = ax1.twinx()
angles = np.unwrap(np.angle(h))
plt.plot(w, angles, 'g')
plt.ylabel('Angle (radians)', color='g')
plt.grid()
plt.axis('tight')
plt.show()

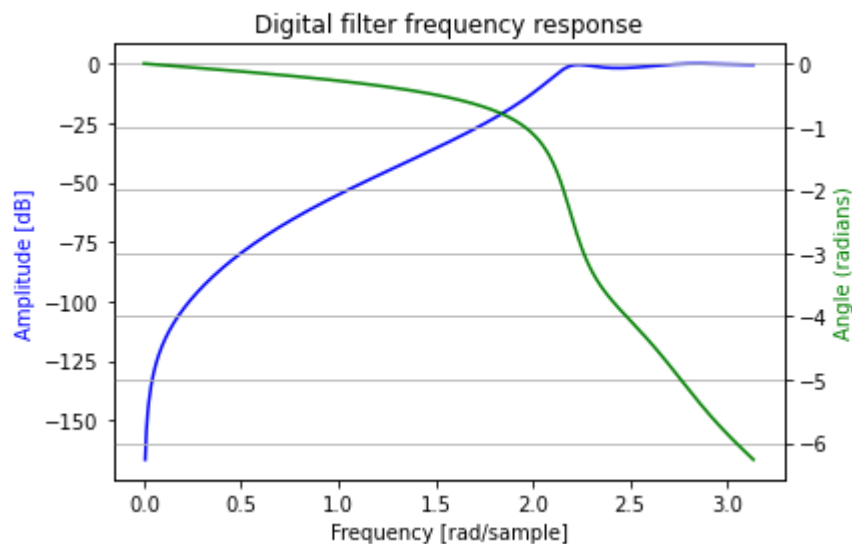
```

<ipython-input-6-73261741e4e8>:6: MatplotlibDeprecationWarning: Adding an axes using the same arguments as a previous axes currently reuses the earlier instance. In a future version, a new instance will always be created and returned. Meanwhile, this warning can be suppressed, and the future behavior ensured, by passing a unique label to each axes instance.

```

ax1 = fig.add_subplot(111)
<ipython-input-6-73261741e4e8>:8: RuntimeWarning: divide by zero encountered in log10
plt.plot(w, 20 * np.log10(abs(h)), 'b')

```



In [ ]: