Experimentation

· Tried implementing a basic KAN for MNIST dataset

Note: Since the proposed pykan library is a Python wrapper for working with knowledge graphs and structured data, it is not useful for our purpose, forcing us to look for alternatives.

• Implemented Quanvolutional Neural Networks for comparison with our original approach.

Note: Since the MNIST dataset consists of basic visual images, the accuracy of all methods is expected to be quite similar.

- Implementation of SineKANS, Multi-Layer Perceptrons for comparision. SineKANs are expected to produce the best result according to the paper [4].
- Lastly, the goal of the project is to explore the extension of KANs to QKANs and further investigate potential applications in LHC-related research. I have explained this aspect in detail in my proposal.

1. KAN for MNIST dataset

A. Implentation of splines by directly using BSpline functionality from SciPy.

```
import torch
import os
import torch.nn as nn
import torch.optim as optim
import torch.nn.functional as F
from torch.autograd import Function
from scipy.interpolate import BSpline #One of the few libraries for implementing B-Splines
import numpy as np
from torchvision import datasets, transforms
from torch.utils.data import DataLoader
import matplotlib.pyplot as plt
class BSplineActivation(Function):
   @staticmethod #Static throughout training and testing
   def forward(ctx, input, knots, coeffs, degree):
       ctx.save_for_backward(input, knots, coeffs) #Save input tensors
       ctx.degree = degree
        input_np = input.detach().cpu().numpy()
        knots_np = knots.detach().cpu().numpy()
       coeffs_np = coeffs.detach().cpu().numpy()
        #Define B-Spline
        spline = BSpline(knots_np, coeffs_np, degree)
       output = torch.tensor(spline(input_np), dtype=torch.float32).to(input.device)
        return output
   @staticmethod
   def backward(ctx, grad_output):
       input, knots, coeffs = ctx.saved_tensors
        degree = ctx.degree
        #Computing B-Spline derivative
        knots_np = knots.detach().cpu().numpy()
        coeffs_np = coeffs.detach().cpu().numpy()
        spline = BSpline(knots_np, coeffs_np, degree)
       deriv_spline = spline.derivative()
        input_np = input.detach().cpu().numpy()
       grad_input = torch.tensor(deriv_spline(input_np), dtype=torch.float32).to(input.device) * grad_output
        return grad_input, None, None, None #No grad calc for inputs, knots, coeffs
class KAN(nn.Module):
   def __init__(self, input_dim, hidden_dim, output_dim, spline_degree=3, num_knots=10):
        super(KAN, self).__init__()
```

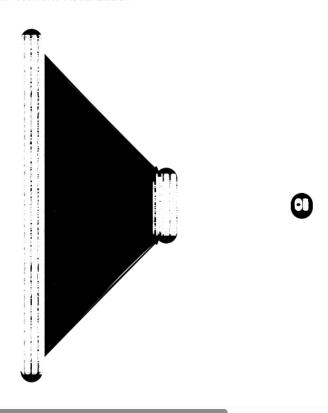
```
self.fc1 = nn.Linear(input_dim, hidden_dim)
        self.fc2 = nn.Linear(hidden dim, output dim)
        # Learnable B-Spline parameters
        self.knots = nn.Parameter(torch.linspace(-1, 1, num_knots))
        self.coeffs = nn.Parameter(torch.randn(num_knots))
        self.spline_degree = spline_degree
    def forward(self, x):
        x = self.fc1(x)
        x = BSplineActivation.apply(x, self.knots, self.coeffs, self.spline_degree) # KAN activations are placed on edges and not nodes, un
        x = self.fc2(x)
        return x
# Loading MNIST dataset
transform = transforms.Compose([
    transforms.ToTensor(),
    transforms.Normalize((0.1307,), (0.3081,)) # MNIST mean/std
])
train_dataset = datasets.MNIST(root='./data', train=True, transform=transform, download=True)
test_dataset = datasets.MNIST(root='./data', train=False, transform=transform, download=True)
train_loader = DataLoader(train_dataset, batch_size=64, shuffle=True)
test_loader = DataLoader(test_dataset, batch_size=1000, shuffle=False)
#Instantiate the model, device, loss type and optimizer
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
model = KAN(input_dim=28*28, hidden_dim=128, output_dim=10).to(device)
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(), lr=0.0005)
save_dir = "training_loss_images"
os.makedirs(save_dir, exist_ok=True)
# Training Loop
epochs = 60
epoch_train_losses=[]
for epoch in range(epochs):
    model.train()
    train_losses=0.0
    for images, labels in train_loader:
        images = images.view(images.size(0), -1).to(device) # Flatten images
        labels = labels.to(device)
        optimizer.zero_grad()
        output = model(images)
        loss = criterion(output, labels)
        loss.backward()
        optimizer.step()
        train_losses += loss.item()
    avg_loss = train_losses / len(train_loader)
    epoch_train_losses.append(avg_loss) # Store the loss for plotting
    plt.figure()
    plt.plot(range(epoch + 1), [train_losses / len(train_loader) for epoch in range(epoch + 1)], label="Train Loss")
    plt.xlabel('Epoch')
    plt.ylabel('Loss')
    plt.title(f'Epoch {epoch + 1}/{epochs}')
    plt.legend()
    plt.savefig(f"{save dir}/epoch {epoch + 1}.png")
    plt.close()
    print(f"Epoch {epoch+1}/{epochs}, Loss: {train_losses / len(train_loader):.4f}")
# Evaluate Model
model.eval()
correct = 0
total = 0
epoch_test_losses = []
test losses=0.0
with torch.no_grad():
    for images, labels in test_loader:
        images = images.view(images.size(0), -1).to(device)
        labels = labels.to(device)
        outputs = model(images)
```

```
loss = criterion(outputs, labels) # Compute loss
        test losses += loss.item() # Accumulate loss
        _, predicted = torch.max(outputs, 1)
        total += labels.size(0)
        correct += (predicted == labels).sum().item()
   avg_loss_t=test_losses/len(test_loader)
   epoch_test_losses.append(avg_loss_t)
print(f"Test Accuracy: {100 * correct / total:.2f}%")
Epoch 4/60, Loss: 0.3755
     Epoch 5/60, Loss: 0.5134
     Epoch 6/60, Loss: 0.3888
     Epoch 7/60, Loss: 0.2496
     Epoch 8/60, Loss: 0.7703
     Epoch 9/60, Loss: 0.2163
     Epoch 10/60, Loss: 0.4059
     Epoch 11/60, Loss: 0.4355
     Epoch 12/60, Loss: 0.5213
     Epoch 13/60, Loss: 0.2938
     Epoch 14/60, Loss: 0.5935
     Epoch 15/60, Loss: 0.3874
     Epoch 16/60, Loss: 0.3595
     Epoch 17/60, Loss: 0.5784
     Epoch 18/60, Loss: 0.3475
     Epoch 19/60, Loss: 0.5121
     Epoch 20/60, Loss: 0.4963
     Epoch 21/60, Loss: 0.3350
     Epoch 22/60, Loss: 0.6306
     Epoch 23/60, Loss: 0.3411
     Epoch 24/60, Loss: 0.7612
     Epoch 25/60, Loss: 0.5438
     Epoch 26/60, Loss: 0.4499
     Epoch 27/60, Loss: 0.5460
     Epoch 28/60, Loss: 0.4262
     Epoch 29/60, Loss: 0.6974
     Epoch 30/60, Loss: 0.5206
     Epoch 31/60, Loss: 0.6578
     Epoch 32/60, Loss: 0.5642
     Epoch 33/60, Loss: 0.4833
     Epoch 34/60, Loss: 0.7785
     Epoch 35/60, Loss: 0.5020
     Epoch 36/60, Loss: 0.6313
     Epoch 37/60, Loss: 0.7022
     Epoch 38/60, Loss: 0.6897
     Epoch 39/60, Loss: 0.8176
     Epoch 40/60, Loss: 0.6815
     Epoch 41/60, Loss: 0.6452
     Epoch 42/60, Loss: 0.7640
     Epoch 43/60, Loss: 0.7229
     Epoch 44/60, Loss: 0.7098
     Epoch 45/60, Loss: 1.0493
     Epoch 46/60, Loss: 0.8276
     Epoch 47/60, Loss: 0.8740
     Epoch 48/60, Loss: 0.8977
     Epoch 49/60, Loss: 0.8853
     Epoch 50/60, Loss: 0.8466
     Epoch 51/60, Loss: 0.9949
     Epoch 52/60, Loss: 1.0410
     Epoch 53/60, Loss: 1.0361
     Epoch 54/60, Loss: 1.0284
     Epoch 55/60, Loss: 1.1861
     Epoch 56/60, Loss: 1.1984
     Epoch 57/60, Loss: 0.9220
     Epoch 58/60, Loss: 1.4596
     Epoch 59/60, Loss: 1.1105
     Epoch 60/60, Loss: 1.0231
     Test Accuracy: 95.02%
import torch
import networkx as nx
import matplotlib.pyplot as plt
import numpy as np
# Extract model weights
fc1_weights = model.fc1.weight.detach().cpu().numpy()
fc2_weights = model.fc2.weight.detach().cpu().numpy()
# Define nodes
input_nodes = [f"X{i}" for i in range(fc1_weights.shape[1])] # Input layer
```

```
hidden\_nodes = [f"H{i}" for i in range(fc1\_weights.shape[0])] # Hidden layer
output_nodes = [f"O{i}" for i in range(fc2_weights.shape[0])] # Output layer
# Create graph
G = nx.DiGraph()
# Add nodes
G.add_nodes_from(input_nodes, layer=0)
G.add_nodes_from(hidden_nodes, layer=1)
G.add_nodes_from(output_nodes, layer=2)
# Add edges with weights
for i, h in enumerate(hidden_nodes):
    for j, x in enumerate(input_nodes):
        if abs(fc1\_weights[i, j]) > 0.1: # Only draw significant weights
            G.add_edge(x, h, weight=fc1_weights[i, j])
for i, o in enumerate(output_nodes):
    for j, h in enumerate(hidden_nodes):
        if abs(fc2_weights[i, j]) > 0.1:
            G.add_edge(h, o, weight=fc2_weights[i, j])
# Draw the network
pos = nx.multipartite_layout(G, subset_key="layer")
plt.figure(figsize=(8, 6))
nx.draw(G, pos, with_labels=True, node_color="black", font_color="white", node_size=500, edge_color="black")
plt.title("KAN Network Visualization")
plt.show()
```

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KAN Network Visualization



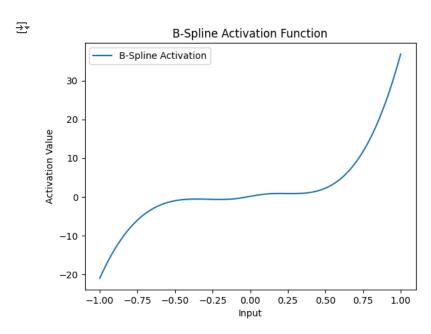
```
import numpy as np
import matplotlib.pyplot as plt
from scipy.interpolate import BSpline

# Get current knots & coefficients after training
knots_np = model.knots.detach().cpu().numpy()
coeffs_np = model.coeffs.detach().cpu().numpy()
spline_degree = model.spline_degree

# Create a B-Spline curve
x_vals = np.linspace(-1, 1, 100)
spline = BSpline(knots_np, coeffs_np, spline_degree) #k,c,t
```

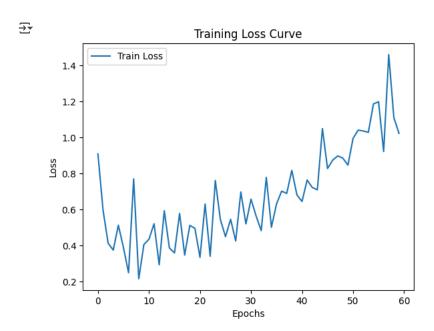
```
y_vals = spline(x_vals)

# Plot
plt.plot(x_vals, y_vals, label="B-Spline Activation")
plt.xlabel("Input")
plt.ylabel("Activation Value")
plt.title("B-Spline Activation Function")
plt.legend()
plt.show()
```



import matplotlib.pyplot as plt

```
# Example loss tracking (assuming losses are stored in lists during training)
plt.plot(epoch_train_losses, label='Train Loss')
plt.xlabel("Epochs")
plt.ylabel("Loss")
plt.legend()
plt.title("Training Loss Curve")
plt.show()
```



We ended up overshooting! This was because of setting the epochs = 60. Setting the number of epochs between [15,30] works well.

B. Alternate Implementation of splines without the manual SciPy use (Ref [5]).

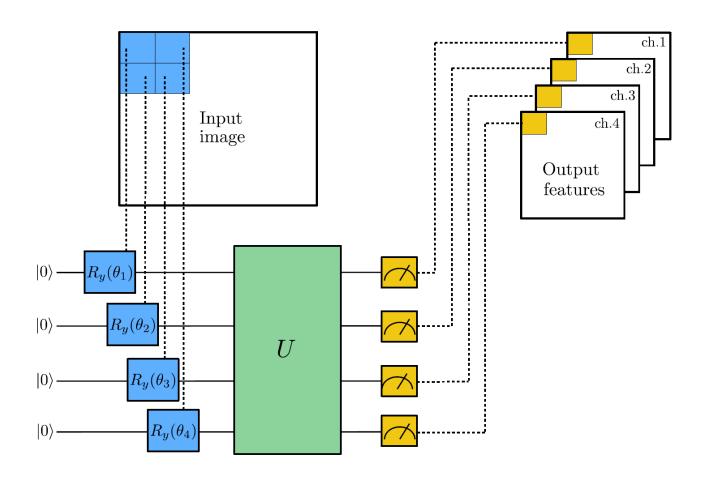
```
import torch
import torch.nn as nn
import torch.nn.functional as F
import torchvision
import torchvision.transforms as transforms
from torch.utils.data import DataLoader
import numpy as np
import time
# Function to precompute B-spline basis functions
def precompute_bspline_basis(num_splines, degree, num_points=100):
   knots = np.linspace(0, 1, num_splines + degree + 1)
   x = np.linspace(0, 1, num_points)
   basis = np.zeros((num_points, num_splines))
   def cox_de_boor(x, k, d, knots):
           return np.where((knots[k] \leftarrow x) & (x \leftarrow knots[k+1]), 1.0, 0.0)
            a = (x - knots[k]) / (knots[k+d] - knots[k] + 1e-8)
            b = (knots[k+d+1] - x) / (knots[k+d+1] - knots[k+1] + 1e-8)
            return a * cox_de_boor(x, k, d-1, knots) + b * cox_de_boor(x, k+1, d-1, knots)
    for i in range(num_splines):
       basis[:, i] = cox_de_boor(x, i, degree, knots)
   return torch.tensor(basis, dtype=torch.float32)
# Precompute basis functions
num_splines = 10
degree = 3
basis = precompute_bspline_basis(num_splines, degree).to('cuda') # Move the precomputed basis to GPU
# Define the PrecomputedB_Spline class
class PrecomputedB_Spline(nn.Module):
   def __init__(self, precomputed_basis):
        super(PrecomputedB_Spline, self).__init__()
        self.precomputed_basis = precomputed_basis
        self.coefficients = nn.Parameter(torch.randn(precomputed_basis.size(1)) * 0.1).to('cuda') # Initialize coefficients
        self.w = nn.Parameter(torch.ones(1).to('cuda'))
    def forward(self, x):
        idx = (x * (self.precomputed_basis.size(0) - 1)).long()
        idx = torch.clamp(idx, 0, self.precomputed_basis.size(0) - 1)
       basis = self.precomputed_basis[idx]
        spline = torch.matmul(basis, self.coefficients)
        b = x / (1 + torch.exp(-x)) # Silu function
        return self.w * (b + spline)
class KANLayer(nn.Module):
   def __init__(self, in_features, out_features, precomputed_basis):
        super(KANLayer, self).__init__()
        self.in_features = in_features
        self.out_features = out_features
        self.b_splines = nn.ModuleList(
            [PrecomputedB_Spline(precomputed_basis) for _ in range(out_features)]
        self.weights = nn.Parameter(torch.randn(out_features, in_features) * 0.1).to('cuda')
        self.bias = nn.Parameter(torch.zeros(out_features)).to('cuda')
        self.batch_norm = nn.BatchNorm1d(out_features)
    def forward(self, x):
        batch_size = x.size(0)
        activation_output = []
        for i in range(self.out_features):
            activation = self.b_splines[i]
            linear_combination = torch.matmul(x, self.weights[i]) + self.bias[i]
            activation_output.append(activation(linear_combination).unsqueeze(1))
        output = torch.cat(activation_output, dim=1)
        return self.batch_norm(output)
# Define the KANModel class
```

```
class KANModel(nn.Module):
    def __init__(self, precomputed_basis):
        super(KANModel, self).__init__()
        self.layer1 = KANLayer(784, 1024, precomputed_basis)
        self.layer2 = KANLayer(1024, 512, precomputed_basis)
        self.layer3 = KANLayer(512, 256, precomputed_basis)
        self.layer4 = KANLayer(256, 10, precomputed_basis)
    def forward(self, x):
        x = x.view(-1, 784)
       x = self.layer1(x)
       x = self.layer2(x)
        x = self.layer3(x)
        x = self.layer4(x)
        return x
# Load the MNIST dataset
print("Loading MNIST dataset...")
transform = transforms.Compose([transforms.ToTensor(), transforms.Normalize((0.5,), (0.5,))])
trainset = torchvision.datasets.MNIST(root='./data', train=True, download=True, transform=transform)
trainloader = DataLoader(trainset, batch_size=256, shuffle=True)
testset = torchvision.datasets.MNIST(root='./data', train=False, download=True, transform=transform)
testloader = DataLoader(testset, batch_size=256, shuffle=False)
print("MNIST dataset loaded.")
# Define the model, loss function, and optimizer
print("Initializing model...")
model = KANModel(basis).to('cuda')
criterion = nn.CrossEntropyLoss()
optimizer = torch.optim.Adam(model.parameters(), lr=0.0167, betas=(0.577, .839))
scheduler = torch.optim.lr_scheduler.StepLR(optimizer, step_size=5, gamma=0.1)
print("Model initialized.")
# Train the model
print("Starting training...")
start_time = time.time()
for epoch in range(10): # Increased number of epochs for example
    running_loss = 0.0
    for i, data in enumerate(trainloader, 0):
        inputs, labels = data
        inputs, labels = inputs.to('cuda'), labels.to('cuda')
        optimizer.zero_grad()
        outputs = model(inputs)
        loss = criterion(outputs, labels)
        loss.backward()
        optimizer.step()
        running_loss += loss.item()
        if i % 100 == 99:
                            # Print every 100 mini-batches
            print(f'[Epoch {epoch + 1}, Batch {i + 1}] loss: {running_loss / 100:.3f}')
            running_loss = 0.0
    scheduler.step()
    print(f'Finished epoch {epoch + 1} loss: {running_loss / 100:.3f}')
end time = time.time()
training_time = end_time - start_time
print(f'Total training time: {training_time:.2f} seconds')
print('Finished Training')
# Evaluate the model
print("Evaluating model...")
start_eval_time = time.time()
correct = 0
total = 0
with torch.no_grad():
    for data in testloader:
        images, labels = data
        images, labels = images.to('cuda'), labels.to('cuda')
        outputs = model(images)
        _, predicted = torch.max(outputs.data, 1)
        total += labels.size(0)
        correct += (predicted == labels).sum().item()
```

```
end eval time = time.time()
evaluation_time = end_eval_time - start_eval_time
print(f'Accuracy of the network on the 10000 test images: {100 * correct / total}%')
print(f'Total evaluation time: {evaluation_time:.2f} seconds')
→ Loading MNIST dataset...
                      9.91M/9.91M [00:00<00:00, 16.6MB/s]
     100%
                      28.9k/28.9k [00:00<00:00, 494kB/s]
     100%
                      1.65M/1.65M [00:00<00:00, 4.61MB/s]
     100%
                    | 4.54k/4.54k [00:00<00:00, 7.77MB/s]
     MNIST dataset loaded.
     Initializing model...
     Model initialized.
     Starting training...
     [Epoch 1, Batch 100] loss: 1.149
     [Epoch 1, Batch 200] loss: 0.441
     Finished epoch 1 loss: 0.131
     Total training time: 352.83 seconds
     Finished Training
     Evaluating model...
     Accuracy of the network on the 10000 test images: 89.47%
     Total evaluation time: 20.81 seconds
```

2. Quanvolutional Neural Networks

Let us try comparing the results of ths classical KAN with quanvolutional neural networsk by benchmarking accuracy similarly on the MNIST dataset.



```
!pip install pennylane
import pennylane as qml
from pennylane import numpy as np
from pennylane.templates import RandomLayers
import tensorflow as tf
from tensorflow import keras
import matplotlib.pyplot as plt
```

```
→ Collecting pennylane

       Downloading PennyLane-0.40.0-py3-none-any.whl.metadata (10 kB)
     Requirement already satisfied: numpy<2.1 in /usr/local/lib/python3.11/dist-packages (from pennylane) (2.0.2)
     Requirement already satisfied: scipy in /usr/local/lib/python3.11/dist-packages (from pennylane) (1.14.1)
     Requirement already satisfied: networkx in /usr/local/lib/python3.11/dist-packages (from pennylane) (3.4.2)
     Collecting rustworkx>=0.14.0 (from pennylane)
       Downloading rustworkx-0.16.0-cp39-abi3-manylinux_2_17_x86_64.manylinux2014_x86_64.whl.metadata (10 kB)
     Requirement already satisfied: autograd in /usr/local/lib/python3.11/dist-packages (from pennylane) (1.7.0)
     Collecting tomlkit (from pennylane)
       Downloading tomlkit-0.13.2-py3-none-any.whl.metadata (2.7 kB)
     Collecting appdirs (from pennylane)
       Downloading appdirs-1.4.4-py2.py3-none-any.whl.metadata (9.0 kB)
     Collecting autoray>=0.6.11 (from pennylane)
       Downloading autoray-0.7.1-py3-none-any.whl.metadata (5.8 kB)
     Requirement already satisfied: cachetools in /usr/local/lib/python3.11/dist-packages (from pennylane) (5.5.2)
     Collecting pennylane-lightning>=0.40 (from pennylane)
       Downloading PennyLane_Lightning-0.40.0-cp311-cp311-manylinux_2_28_x86_64.whl.metadata (27 kB)
     Requirement already satisfied: requests in /usr/local/lib/python3.11/dist-packages (from pennylane) (2.32.3)
     Requirement already satisfied: typing-extensions in /usr/local/lib/python3.11/dist-packages (from pennylane) (4.12.2)
     Requirement already satisfied: packaging in /usr/local/lib/python3.11/dist-packages (from pennylane) (24.2)
     Collecting diastatic-malt (from pennylane)
       Downloading diastatic_malt-2.15.2-py3-none-any.whl.metadata (2.6 kB)
     Collecting scipy-openblas32>=0.3.26 (from pennylane-lightning>=0.40->pennylane)
       Downloading scipy_openblas32-0.3.29.0.0-py3-none-manylinux_2_17_x86_64.manylinux2014_x86_64.whl.metadata (56 kB)
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     Requirement already satisfied: astunparse in /usr/local/lib/python3.11/dist-packages (from diastatic-malt->pennylane) (1.6.3)
     Requirement already satisfied: gast in /usr/local/lib/python3.11/dist-packages (from diastatic-malt->pennylane) (0.6.0)
     Requirement already satisfied: termcolor in /usr/local/lib/python3.11/dist-packages (from diastatic-malt->pennylane) (2.5.0)
     Requirement already satisfied: charset-normalizer<4,>=2 in /usr/local/lib/python3.11/dist-packages (from requests->pennylane) (3.4.1)
     Requirement already satisfied: idna<4,>=2.5 in /usr/local/lib/python3.11/dist-packages (from requests->pennylane) (3.10)
     Requirement already satisfied: urllib3<3,>=1.21.1 in /usr/local/lib/python3.11/dist-packages (from requests->pennylane) (2.3.0)
     Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.11/dist-packages (from requests->pennylane) (2025.1.31)
     Requirement already satisfied: wheel<1.0,>=0.23.0 in /usr/local/lib/python3.11/dist-packages (from astunparse->diastatic-malt->pennylane
     Requirement already satisfied: six<2.0,>=1.6.1 in /usr/local/lib/python3.11/dist-packages (from astunparse->diastatic-malt->pennylane) (
     Downloading PennyLane-0.40.0-py3-none-any.whl (2.0 MB)
                                                - 2.0/2.0 MB 13.9 MB/s eta 0:00:00
     Downloading autoray-0.7.1-py3-none-any.whl (930 kB)
                                                930.8/930.8 kB 20.7 MB/s eta 0:00:00
     Downloading PennyLane_Lightning-0.40.0-cp311-cp311-manylinux_2_28_x86_64.whl (2.4 MB)
                                                · 2.4/2.4 MB 25.8 MB/s eta 0:00:00
     Downloading rustworkx-0.16.0-cp39-abi3-manylinux_2_17_x86_64.manylinux2014_x86_64.whl (2.1 MB)
                                                - 2.1/2.1 MB 25.3 MB/s eta 0:00:00
     Downloading appdirs-1.4.4-py2.py3-none-any.whl (9.6 kB)
     Downloading diastatic_malt-2.15.2-py3-none-any.whl (167 kB)
                                                - 167.9/167.9 kB 6.6 MB/s eta 0:00:00
     Downloading tomlkit-0.13.2-py3-none-any.whl (37 kB)
     Downloading scipy_openblas32-0.3.29.0.0-py3-none-manylinux_2_17_x86_64.manylinux2014_x86_64.whl (8.6 MB)
                                                - 8.6/8.6 MB 27.3 MB/s eta 0:00:00
     Installing collected packages: appdirs, tomlkit, scipy-openblas32, rustworkx, autoray, diastatic-malt, pennylane-lightning, pennylane
     Successfully installed appdirs-1.4.4 autoray-0.7.1 diastatic-malt-2.15.2 pennylane-0.40.0 pennylane-lightning-0.40.0 rustworkx-0.16.0 sc
n_epochs = 60  # Number of optimization epochs
               # Number of random layers
n_layers = 1
n train = 50
              # Size of the train dataset
n_{\text{test}} = 30
               # Size of the test dataset
SAVE_PATH = "../_static/demonstration_assets/quanvolution/" # Data saving folder
PREPROCESS = True
np.random.seed(0)
tf.random.set_seed(0)
mnist dataset = keras.datasets.mnist
(train_images, train_labels), (test_images, test_labels) = mnist_dataset.load_data()
# Reduce dataset size
train_images = train_images[:n_train]
train_labels = train_labels[:n_train]
test_images = test_images[:n_test]
test_labels = test_labels[:n_test]
# Normalize pixel values within 0 and 1
train_images = train_images / 255
test_images = test_images / 255
# Add extra dimension for convolution channels
train_images = np.array(train_images[..., tf.newaxis], requires_grad=False)
test_images = np.array(test_images[..., tf.newaxis], requires_grad=False)
```

```
Downloading data from <a href="https://storage.googleapis.com/tensorflow/tf-keras-datasets/mnist.npz">https://storage.googleapis.com/tensorflow/tf-keras-datasets/mnist.npz</a>
     11490434/11490434 -
                                             1s Ous/step
dev = qml.device("default.qubit", wires=4)
rand_params = np.random.uniform(high=2 * np.pi, size=(n_layers, 4))
@qml.qnode(dev)
def circuit(phi):
    # Encoding of 4 classical input values
    for j in range(4):
        qml.RY(np.pi * phi[j], wires=j)
    # Random quantum circuit
    RandomLayers(rand_params, wires=list(range(4)))
    # Measurement producing 4 classical output values
    return [qml.expval(qml.PauliZ(j)) for j in range(4)]
np.shape(train_images[0])
→ (28, 28, 1)
def quanv(image):
      "Convolves the input image with many applications of the same quantum circuit."""
    out = np.zeros((14, 14, 4))
    for j in range(0, 28, 2):
        for k in range(0, 28, 2):
            q_results = circuit(
                [
                     image[j, k, 0],
                    image[j, k + 1, 0],
                    image[j + 1, k, 0],
                    image[j + 1, k + 1, 0]
                ]
            # Assign expectation values to different channels of the output pixel (j/2, k/2)
            for c in range(4):
                out[j // 2, k // 2, c] = q_results[c]
    return out
PREPROCESS=True
if PREPROCESS == True:
    q_train_images = []
    print("Quantum pre-processing of train images:")
    for idx, img in enumerate(train_images):
                             ".format(idx + 1, n_train), end="\r")
        print("{}/{}
        q_train_images.append(quanv(img))
    q_train_images = np.asarray(q_train_images)
    q_test_images = []
    print("\nQuantum pre-processing of test images:")
    for idx, img in enumerate(test_images):
        print("{}/{}
                             ".format(idx + 1, n_test), end="\r")
        q_test_images.append(quanv(img))
    q_test_images = np.asarray(q_test_images)
    # Create the directory if it doesn't exist
    os.makedirs(SAVE_PATH, exist_ok=True)
    # Save pre-processed images
    np.save(os.path.join(SAVE_PATH, "q_train_images.npy"), q_train_images)
    np.save(os.path.join(SAVE_PATH, "q_test_images.npy"), q_test_images)
# Load pre-processed images
q_train_images = np.load(os.path.join(SAVE_PATH, "q_train_images.npy"))
q_test_images = np.load(os.path.join(SAVE_PATH, "q_test_images.npy"))
Quantum pre-processing of train images:
```

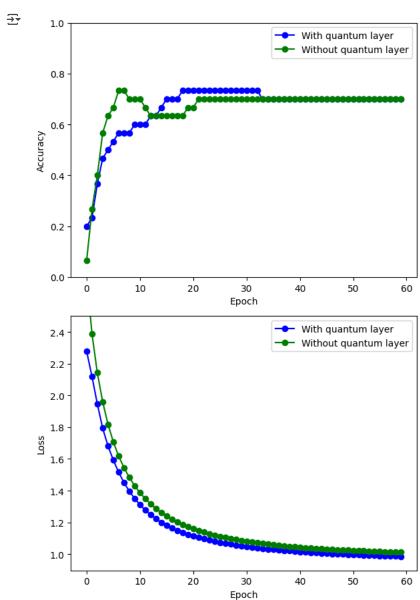
Quantum pre-processing of test images:

```
n_samples = 4
n_{channels} = 4
fig, axes = plt.subplots(1 + n_channels, n_samples, figsize=(10, 10))
for k in range(n_samples):
    axes[0, 0].set_ylabel("Input")
    axes[0, k].imshow(train_images[k, :, :, 0], cmap="gray")
    # Plot all output channels
    for c in range(n_channels):
        axes[c + 1, 0].set_ylabel("Output [ch. {}]".format(c))
        axes[c + 1, k].imshow(q_train_images[k, :, :, c], cmap="gray")
plt.tight_layout()
plt.show()
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      Output [ch. 1]
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      Output [ch. 3]
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def model():
 model=keras.models.Sequential([
      keras.layers.Flatten(),
      keras.layers.Dense(20, activation="softmax")
 ])
```

```
model.compile(
     optimizer='adam',
     loss="sparse_categorical_crossentropy";
     metrics=["accuracy"],
 return model
q_model = model()
q_history = q_model.fit(
   q_train_images,
   train labels.
   validation_data=(q_test_images, test_labels),
   batch size=4,
   epochs=n_epochs,
   verbose=2,
)
Epoch 32/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0764 - val_accuracy: 0.7333 - val_loss: 1.0436
    Epoch 33/60
    13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0725 - val accuracy: 0.7333 - val loss: 1.0397
    Epoch 34/60
    13/13 - 0s - 13ms/step - accuracy: 1.0000 - loss: 0.0690 - val_accuracy: 0.7000 - val_loss: 1.0359
    Epoch 35/60
    13/13 - 0s - 20ms/step - accuracy: 1.0000 - loss: 0.0657 - val_accuracy: 0.7000 - val_loss: 1.0324
    Epoch 36/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0627 - val_accuracy: 0.7000 - val_loss: 1.0291
    Epoch 37/60
    13/13 - 0s - 23ms/step - accuracy: 1.0000 - loss: 0.0599 - val_accuracy: 0.7000 - val_loss: 1.0260
    Epoch 38/60
    13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0572 - val accuracy: 0.7000 - val loss: 1.0231
    Epoch 39/60
    13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0548 - val_accuracy: 0.7000 - val_loss: 1.0204
    Epoch 40/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0525 - val_accuracy: 0.7000 - val_loss: 1.0177
    Epoch 41/60
    13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0504 - val_accuracy: 0.7000 - val_loss: 1.0153
    Epoch 42/60
    13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0484 - val_accuracy: 0.7000 - val_loss: 1.0129
    Epoch 43/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0465 - val_accuracy: 0.7000 - val_loss: 1.0107
    Epoch 44/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0448 - val_accuracy: 0.7000 - val_loss: 1.0086
    Epoch 45/60
    13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0431 - val accuracy: 0.7000 - val loss: 1.0066
    Epoch 46/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0416 - val_accuracy: 0.7000 - val_loss: 1.0047
    Epoch 47/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0401 - val_accuracy: 0.7000 - val_loss: 1.0029
    Epoch 48/60
    13/13 - 0s - 12ms/step - accuracy: 1.0000 - loss: 0.0387 - val_accuracy: 0.7000 - val_loss: 1.0011
    Epoch 49/60
    13/13 - 0s - 20ms/step - accuracy: 1.0000 - loss: 0.0374 - val_accuracy: 0.7000 - val_loss: 0.9995
    Epoch 50/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0362 - val accuracy: 0.7000 - val loss: 0.9979
    Epoch 51/60
    13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0350 - val_accuracy: 0.7000 - val_loss: 0.9964
    13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0339 - val accuracy: 0.7000 - val loss: 0.9950
    Epoch 53/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0328 - val_accuracy: 0.7000 - val_loss: 0.9936
    Epoch 54/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0318 - val_accuracy: 0.7000 - val_loss: 0.9923
    Epoch 55/60
    13/13 - 0s - 20ms/step - accuracy: 1.0000 - loss: 0.0308 - val_accuracy: 0.7000 - val_loss: 0.9911
    Epoch 56/60
    13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0299 - val_accuracy: 0.7000 - val_loss: 0.9898
    Epoch 57/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0290 - val accuracy: 0.7000 - val loss: 0.9887
    Epoch 58/60
    13/13 - 0s - 12ms/step - accuracy: 1.0000 - loss: 0.0282 - val_accuracy: 0.7000 - val_loss: 0.9876
    Epoch 59/60
    13/13 - 0s - 12ms/step - accuracy: 1.0000 - loss: 0.0274 - val_accuracy: 0.7000 - val_loss: 0.9865
    Epoch 60/60
    13/13 - 0s - 13ms/step - accuracy: 1.0000 - loss: 0.0266 - val_accuracy: 0.7000 - val_loss: 0.9855
c model = model()
```

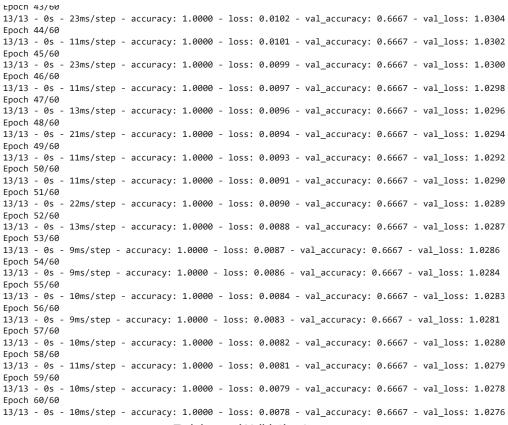
```
c_history = c_model.fit(
   train_images,
   train_labels,
   validation_data=(test_images, test_labels),
   batch size=4.
   epochs=n_epochs,
   verbose=2,
)
→ Epoch 32/60
    13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.1134 - val_accuracy: 0.7000 - val_loss: 1.0756
     Epoch 33/60
     13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.1078 - val accuracy: 0.7000 - val loss: 1.0710
     Epoch 34/60
     13/13 - 0s - 23ms/step - accuracy: 1.0000 - loss: 0.1026 - val_accuracy: 0.7000 - val_loss: 1.0667
     Epoch 35/60
     13/13 - 0s - 12ms/step - accuracy: 1.0000 - loss: 0.0978 - val_accuracy: 0.7000 - val_loss: 1.0627
     Epoch 36/60
     13/13 - 0s - 12ms/step - accuracy: 1.0000 - loss: 0.0934 - val_accuracy: 0.7000 - val_loss: 1.0590
     Epoch 37/60
     13/13 - 0s - 13ms/step - accuracy: 1.0000 - loss: 0.0893 - val_accuracy: 0.7000 - val_loss: 1.0555
     Epoch 38/60
     13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0854 - val_accuracy: 0.7000 - val_loss: 1.0522
     Epoch 39/60
     13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0818 - val_accuracy: 0.7000 - val_loss: 1.0491
     Epoch 40/60
     13/13 - 0s - 12ms/step - accuracy: 1.0000 - loss: 0.0784 - val accuracy: 0.7000 - val loss: 1.0462
     Epoch 41/60
     13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0753 - val_accuracy: 0.7000 - val_loss: 1.0435
     Epoch 42/60
     13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0723 - val_accuracy: 0.7000 - val_loss: 1.0409
     Epoch 43/60
     13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0696 - val_accuracy: 0.7000 - val_loss: 1.0385
     Epoch 44/60
     13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0670 - val_accuracy: 0.7000 - val_loss: 1.0362
     Epoch 45/60
     13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0645 - val accuracy: 0.7000 - val loss: 1.0340
     Epoch 46/60
     13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0622 - val_accuracy: 0.7000 - val_loss: 1.0320
     Epoch 47/60
     13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0600 - val accuracy: 0.7000 - val loss: 1.0300
     Epoch 48/60
     13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0579 - val_accuracy: 0.7000 - val_loss: 1.0282
     Epoch 49/60
     13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0560 - val_accuracy: 0.7000 - val_loss: 1.0265
     Epoch 50/60
     13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0541 - val_accuracy: 0.7000 - val_loss: 1.0248
     Epoch 51/60
     13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0523 - val_accuracy: 0.7000 - val_loss: 1.0233
     Epoch 52/60
     13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0507 - val accuracy: 0.7000 - val loss: 1.0218
     Epoch 53/60
     13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0491 - val_accuracy: 0.7000 - val_loss: 1.0204
     Epoch 54/60
     13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0476 - val accuracy: 0.7000 - val loss: 1.0190
     Epoch 55/60
     13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0461 - val_accuracy: 0.7000 - val_loss: 1.0178
     Epoch 56/60
     13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0448 - val_accuracy: 0.7000 - val_loss: 1.0165
     Epoch 57/60
     13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0434 - val_accuracy: 0.7000 - val_loss: 1.0154
     Epoch 58/60
     13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0422 - val_accuracy: 0.7000 - val_loss: 1.0143
     Epoch 59/60
     13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0410 - val accuracy: 0.7000 - val loss: 1.0133
     Epoch 60/60
     13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0399 - val_accuracy: 0.7000 - val_loss: 1.0123
import matplotlib.pyplot as plt
fig, (ax1, ax2) = plt.subplots(2, 1, figsize=(6, 9))
ax1.plot(q_history.history["val_accuracy"], "-ob", label="With quantum layer")
ax1.plot(c_history.history["val_accuracy"], "-og", label="Without quantum layer")
ax1.set_ylabel("Accuracy")
ax1.set_ylim([0, 1])
ax1.set_xlabel("Epoch")
ax1.legend()
ax2.plot(q_history.history["val_loss"], "-ob", label="With quantum layer")
ax2.plot(c_history.history["val_loss"], "-og", label="Without quantum layer")
ax2.set_ylabel("Loss")
```

ax2.set_ylim(top=2.5)
ax2.set_xlabel("Epoch")
ax2.legend()
plt.tight_layout()
plt.show()

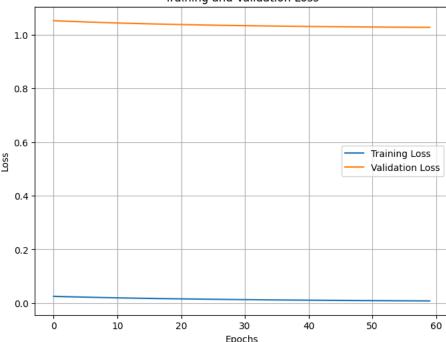


```
import matplotlib.pyplot as plt
# Fit the model and store the training history
history = q_model.fit(
    q_train_images,
    train_labels,
    validation_data=(q_test_images, test_labels),
    batch_size=4,
    epochs=n_epochs,
    verbose=2,
)
# Plot the loss
plt.figure(figsize=(8, 6))
plt.plot(history.history['loss'], label='Training Loss')
plt.plot(history.history['val_loss'], label='Validation Loss')
plt.title('Training and Validation Loss')
plt.xlabel('Epochs')
plt.ylabel('Loss')
plt.legend()
plt.grid(True)
plt.show()
```

```
→ Epoch 1/60
    13/13 - 0s - 16ms/step - accuracy: 1.0000 - loss: 0.0249 - val_accuracy: 0.6333 - val_loss: 1.0524
    Epoch 2/60
    13/13 - 0s - 18ms/step - accuracy: 1.0000 - loss: 0.0243 - val_accuracy: 0.6333 - val_loss: 1.0514
    Epoch 3/60
    13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0236 - val_accuracy: 0.6333 - val_loss: 1.0505
    Epoch 4/60
    13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0230 - val_accuracy: 0.6333 - val_loss: 1.0495
    Epoch 5/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0224 - val_accuracy: 0.6333 - val_loss: 1.0486
    Epoch 6/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0219 - val_accuracy: 0.6333 - val_loss: 1.0478
    Epoch 7/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0213 - val_accuracy: 0.6333 - val_loss: 1.0469
    Epoch 8/60
    13/13 - 0s - 12ms/step - accuracy: 1.0000 - loss: 0.0208 - val_accuracy: 0.6333 - val_loss: 1.0461
    Enoch 9/60
    13/13 - 0s - 24ms/step - accuracy: 1.0000 - loss: 0.0203 - val_accuracy: 0.6333 - val_loss: 1.0454
    Epoch 10/60
    13/13 - 0s - 23ms/step - accuracy: 1.0000 - loss: 0.0198 - val_accuracy: 0.6333 - val_loss: 1.0446
    Epoch 11/60
    13/13 - 0s - 19ms/step - accuracy: 1.0000 - loss: 0.0193 - val_accuracy: 0.6333 - val_loss: 1.0439
    Epoch 12/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0189 - val_accuracy: 0.6333 - val_loss: 1.0432
    Epoch 13/60
    13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0185 - val_accuracy: 0.6333 - val_loss: 1.0425
    Epoch 14/60
    13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0180 - val_accuracy: 0.6333 - val_loss: 1.0419
    Epoch 15/60
    13/13 - 0s - 13ms/step - accuracy: 1.0000 - loss: 0.0176 - val_accuracy: 0.6333 - val_loss: 1.0413
    Epoch 16/60
    13/13 - 0s - 23ms/step - accuracy: 1.0000 - loss: 0.0173 - val_accuracy: 0.6333 - val_loss: 1.0407
    Epoch 17/60
    13/13 - 0s - 24ms/step - accuracy: 1.0000 - loss: 0.0169 - val_accuracy: 0.6333 - val_loss: 1.0401
    Epoch 18/60
    13/13 - 0s - 13ms/step - accuracy: 1.0000 - loss: 0.0165 - val_accuracy: 0.6333 - val_loss: 1.0396
    Epoch 19/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0162 - val_accuracy: 0.6667 - val_loss: 1.0390
    Epoch 20/60
    13/13 - 0s - 25ms/step - accuracy: 1.0000 - loss: 0.0158 - val_accuracy: 0.6667 - val_loss: 1.0385
    Epoch 21/60
    13/13 - 0s - 24ms/step - accuracy: 1.0000 - loss: 0.0155 - val_accuracy: 0.6667 - val_loss: 1.0380
    Epoch 22/60
    13/13 - 0s - 21ms/step - accuracy: 1.0000 - loss: 0.0152 - val_accuracy: 0.6667 - val_loss: 1.0375
    Epoch 23/60
    13/13 - 0s - 12ms/step - accuracy: 1.0000 - loss: 0.0149 - val_accuracy: 0.6667 - val_loss: 1.0370
    Epoch 24/60
    13/13 - 0s - 24ms/step - accuracy: 1.0000 - loss: 0.0146 - val accuracy: 0.6667 - val loss: 1.0366
    Epoch 25/60
    13/13 - 0s - 23ms/step - accuracy: 1.0000 - loss: 0.0143 - val_accuracy: 0.6667 - val_loss: 1.0362
    Epoch 26/60
    13/13 - 0s - 15ms/step - accuracy: 1.0000 - loss: 0.0140 - val_accuracy: 0.6667 - val_loss: 1.0357
    Epoch 27/60
    13/13 - 0s - 14ms/step - accuracy: 1.0000 - loss: 0.0137 - val_accuracy: 0.6667 - val_loss: 1.0353
    Epoch 28/60
    13/13 - 0s - 24ms/step - accuracy: 1.0000 - loss: 0.0135 - val_accuracy: 0.6667 - val_loss: 1.0349
    Epoch 29/60
    13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0132 - val_accuracy: 0.6667 - val_loss: 1.0346
    Epoch 30/60
    13/13 - 0s - 12ms/step - accuracy: 1.0000 - loss: 0.0129 - val_accuracy: 0.6667 - val_loss: 1.0342
    Epoch 31/60
    13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0127 - val_accuracy: 0.6667 - val_loss: 1.0338
    Epoch 32/60
    13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0125 - val_accuracy: 0.6667 - val_loss: 1.0335
    Epoch 33/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0122 - val_accuracy: 0.6667 - val_loss: 1.0332
    Epoch 34/60
    13/13 - 0s - 10ms/step - accuracy: 1.0000 - loss: 0.0120 - val_accuracy: 0.6667 - val_loss: 1.0328
    Epoch 35/60
    13/13 - 0s - 9ms/step - accuracy: 1.0000 - loss: 0.0118 - val_accuracy: 0.6667 - val_loss: 1.0325
    Epoch 36/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0116 - val_accuracy: 0.6667 - val_loss: 1.0322
    Epoch 37/60
    13/13 - 0s - 12ms/step - accuracy: 1.0000 - loss: 0.0114 - val_accuracy: 0.6667 - val_loss: 1.0320
    Epoch 38/60
    13/13 - 0s - 22ms/step - accuracy: 1.0000 - loss: 0.0112 - val_accuracy: 0.6667 - val_loss: 1.0317
    Epoch 39/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0110 - val_accuracy: 0.6667 - val_loss: 1.0314
    Epoch 40/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0108 - val_accuracy: 0.6667 - val_loss: 1.0312
    Epoch 41/60
    13/13 - 0s - 24ms/step - accuracy: 1.0000 - loss: 0.0106 - val_accuracy: 0.6667 - val_loss: 1.0309
    Epoch 42/60
    13/13 - 0s - 11ms/step - accuracy: 1.0000 - loss: 0.0104 - val_accuracy: 0.6667 - val_loss: 1.0307
```







3. SineKAN

```
import torch
import torch.nn.functional as F
import math
from typing import *
import numpy as np
import torch.nn as nn
import torch.optim as optim
import torchvision
import torchvision.transforms as transforms
from torch.utils.data import DataLoader
from tqdm import tqdm
def forward_step(i_n, grid_size, A, K, C):
       ratio = A * grid_size**(-K) + C
       i n1 = ratio * i n
       return i_n1
class SineKANLayer(torch.nn.Module):
       def __init__(self, input_dim, output_dim, device='cuda', grid_size=5, is_first=False, add_bias=True, norm_freq=True):
              super(SineKANLayer, self).__init__()
              self.grid_size = grid_size
              self.device = device
              self.is_first = is_first
              self.add_bias = add_bias
              self.input_dim = input_dim
              self.output_dim = output_dim
              self.A, self.K, self.C = 0.9724108095811765, 0.9884401790754128, 0.999449553483052
              self.grid_norm_factor = (torch.arange(grid_size) + 1)
              self.grid_norm_factor = self.grid_norm_factor.reshape(1, 1, grid_size)
              if is first:
                     self.amplitudes = torch.nn.Parameter(torch.empty(output_dim, input_dim, 1).normal_(0, .4) / output_dim / self.grid_norm_factor)
              else:
                      self.amplitudes = torch.nn.Parameter(torch.empty(output_dim, input_dim, 1).uniform_(-1, 1) / output_dim / self.grid_norm_factor
              grid_phase = torch.arange(1, grid_size + 1).reshape(1, 1, 1, grid_size) / (grid_size + 1)
              self.input_phase = torch.linspace(0, math.pi, input_dim).reshape(1, 1, input_dim, 1).to(device)
              phase = grid_phase.to(device) + self.input_phase
              if norm freq:
                     self.freq = torch.nn.Parameter(torch.arange(1, grid\_size + 1).float().reshape(1, 1, 1, grid\_size) / (grid\_size + 1)**(1 - is\_fired_size) / (grid\_size + 1)**(1 - is\_fired_size) / (grid\_size + 1)**(1 - is\_fired_size) / (grid\_size) / (grid\_s
              else:
                      self.freq = torch.nn.Parameter(torch.arange(1, grid_size + 1).float().reshape(1, 1, 1, grid_size))
               for i in range(1, self.grid_size):
                      phase = forward_step(phase, i, self.A, self.K, self.C)
              self.register_buffer('phase', phase)
              if self.add bias:
                      self.bias = torch.nn.Parameter(torch.ones(1, output_dim) / output_dim)
       def forward(self, x):
              x_shape = x.shape
              output_shape = x_shape[0:-1] + (self.output_dim,)
              x = torch.reshape(x, (-1, self.input_dim))
              x_reshaped = torch.reshape(x, (x.shape[0], 1, x.shape[1], 1))
              s = torch.sin(x_reshaped * self.freq + self.phase)
              y = torch.einsum('ijkl,jkl->ij', s, self.amplitudes)
              if self.add_bias:
                     y += self.bias
              y = torch.reshape(y, output_shape)
              return y
class SineKAN(torch.nn.Module):
       def __init__(
              self,
              layers_hidden: List[int],
              grid_size: int = 8,
              device: str = 'cuda',
       ) -> None:
              super().__init__()
```

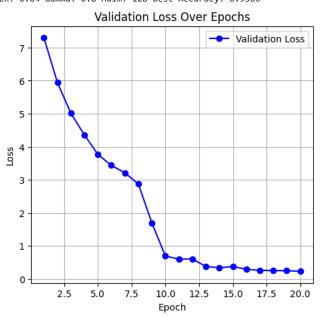
```
self.layers = torch.nn.ModuleList([
            SineKANLayer(
               in_dim, out_dim, device, grid_size=grid_size, is_first=True
            ) if i == 0 else SineKANLayer(
                in_dim, out_dim, device, grid_size=grid_size,
            ) for i, (in_dim, out_dim) in enumerate(zip(layers_hidden[:-1], layers_hidden[1:]))
        ])
    def forward(self, x):
        for layer in self.layers:
           x = layer(x)
        return x
transform = transforms.Compose(
    [transforms.ToTensor(), transforms.Normalize((0.1307,), (0.3081,))]
trainset = torchvision.datasets.MNIST(
    root="./data", train=True, download=True, transform=transform
)
valset = torchvision.datasets.MNIST(
    root="./data", train=False, download=True, transform=transform
train_loader = DataLoader(trainset, batch_size=64, num_workers=2, shuffle=True)
val_loader = DataLoader(valset, batch_size=64, num_workers=2, shuffle=False)
epochs = 5
lrs = [2e-4, 3e-3, 4e-2]
gammas = [0.8, 0.9]
hdims = [64, 128, 256]
best_accs = []
for lr in lrs:
    for gamma in gammas:
        for hdim in hdims:
            torch.manual_seed(42)
            best acc = 0
            # Define model
            model = SineKAN(layers_hidden=[28 * 28, hdim, 10], grid_size=8)
            device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
            model.to(device)
            # Define optimizer
            optimizer = optim.AdamW(model.parameters(), lr=lr)
            # Define learning rate scheduler
            scheduler = optim.lr_scheduler.ExponentialLR(optimizer, gamma=gamma)
            # Define loss
            criterion = nn.CrossEntropyLoss()
            for epoch in range(epochs): # Train
                model.train()
                with tqdm(train_loader) as pbar:
                    for i, (images, labels) in enumerate(pbar):
                        images = images.view(-1, 28 * 28).to(device)
                        optimizer.zero_grad()
                        output = model(images)
                        loss = criterion(output, labels.to(device))
                        loss.backward()
                        optimizer.step()
                        accuracy = (output.argmax(dim=1) == labels.to(device)).float().mean()
                        pbar.set\_postfix(loss=loss.item(), accuracy=accuracy.item(), lr=optimizer.param\_groups[0]['lr'])
                # Validation
                model.eval()
                val loss = 0
                val_accuracy = 0
                with torch.no_grad():
                    for images, labels in val_loader:
                        images = images.view(-1, 28 * 28).to(device)
                        output = model(images)
                        val_loss += criterion(output, labels.to(device)).item()
                        val_accuracy += (
                            (output.argmax(dim=1) == labels.to(device)).float().mean().item()
                val_loss /= len(val_loader)
                val_accuracy /= len(val_loader)
                if val_accuracy > best_acc:
                    best_acc = val_accuracy
```

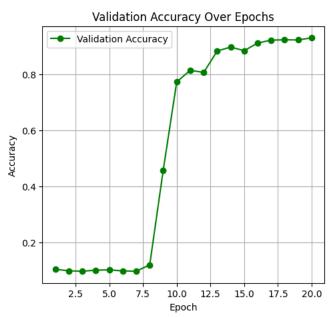
```
# Update learning rate
               scheduler.step()
               print(
                   f"Epoch {epoch + 1}, Val Loss: {val_loss}, Val Accuracy: {val_accuracy}"
           best_accs.append(best_acc)
           print(f"LR: {lr} Gamma: {gamma} Hdim: {hdim} Best Accuracy: {best acc}")
             938/938 [00:20<00:00, 44.68it/s, accuracy=0.938, loss=0.136, lr=0.0002]
    Epoch 1, Val Loss: 0.25346964880064793, Val Accuracy: 0.9266520700636943
    100%| 938/938 [00:15<00:00, 62.50it/s, accuracy=0.938, loss=0.297, lr=0.00016]
          2, Val Loss: 0.19701114199628497, Val Accuracy: 0.942078025477707
             938/938 [00:15<00:00, 61.28it/s, accuracy=0.938, loss=0.2, lr=0.000128]
    Epoch_3, Val Loss: 0.14599578013750397, Val Accuracy: 0.9561106687898089
             938/938 [00:19<00:00, 46.92it/s, accuracy=1, loss=0.0342, lr=0.000102]
    Epoch 4, Val Loss: 0.13135418584748249, Val Accuracy: 0.9593949044585988
    100%| 938/938 [00:15<00:00, 60.96it/s, accuracy=1, loss=0.0731, lr=8.19e-5]
    Epoch 5, Val Loss: 0.11268040606200364, Val Accuracy: 0.9650676751592356
    LR: 0.0002 Gamma: 0.8 Hdim: 64 Best Accuracy: 0.9650676751592356
    100%| 938/938 [00:15<00:00, 59.54it/s, accuracy=0.875, loss=0.274, lr=0.0002]
    Epoch 1, Val Loss: 0.20217574968530683, Val Accuracy: 0.9417794585987261
    100%| 938/938 [00:14<00:00, 63.32it/s, accuracy=1, loss=0.0719, lr=0.00016]
    Epoch 3, Val Loss: 0.11302672866079364, Val Accuracy: 0.9665605095541401
    100%| 938/938 [00:15<00:00, 60.74it/s, accuracy=1, loss=0.0345, lr=0.000102]
    Epoch 4, Val Loss: 0.1042141501315733, Val Accuracy: 0.9677547770700637
    100%| 938/938 [00:14<00:00, 63.16it/s, accuracy=0.969, loss=0.047, lr=8.19e-5]
    Epoch 5, Val Loss: 0.09780232257515216, Val Accuracy: 0.9707404458598726
    LR: 0.0002 Gamma: 0.8 Hdim: 128 Best Accuracy: 0.9707404458598726
    100%| 938/938 [00:15<00:00, 62.32it/s, accuracy=1, loss=0.0408, lr=0.0002]
    Epoch 1, Val Loss: 0.18200375050140224, Val Accuracy: 0.948546974522293
    100%| 938/938 [00:15<00:00, 58.76it/s, accuracy=0.875, loss=0.367, lr=0.00016]
    Epoch 2, Val Loss: 0.12366194087733176, Val Accuracy: 0.9625796178343949
    100%| | 938/938 [00:15<00:00, 62.17it/s, accuracy=1, loss=0.0248, lr=0.000128]
    Epoch 3, Val Loss: 0.09775582525232558, Val Accuracy: 0.9709394904458599
    100%| 938/938 [00:15<00:00, 62.40it/s, accuracy=0.969, loss=0.0793, lr=0.000102]
    Epoch 4, Val Loss: 0.08831097605077633, Val Accuracy: 0.971437101910828
    100%| | 938/938 [00:16<00:00, 58.47it/s, accuracy=1, loss=0.00568, lr=8.19e-5]
    Epoch 5, Val Loss: 0.08067609585642185, Val Accuracy: 0.9739251592356688
    LR: 0.0002 Gamma: 0.8 Hdim: 256 Best Accuracy: 0.9739251592356688
    100%| 938/938 [00:14<00:00, 62.57it/s, accuracy=0.938, loss=0.136, lr=0.0002]
    Epoch 1, Val Loss: 0.25346964880064793, Val Accuracy: 0.9266520700636943
               | 938/938 [00:15<00:00, 62.05it/s, accuracy=0.938, loss=0.289, lr=0.00018]
    Epoch 2, Val Loss: 0.19540891957700632, Val Accuracy: 0.9423765923566879
    100%| 938/938 [00:15<00:00, 60.78it/s, accuracy=0.938, loss=0.194, lr=0.000162]
    Epoch 3, Val Loss: 0.14697432232676608, Val Accuracy: 0.9563097133757962
                938/938 [00:15<00:00, 61.94it/s, accuracy=1, loss=0.023, lr=0.000146]
    Epoch 4, Val Loss: 0.12716912634368202, Val Accuracy: 0.9598925159235668
             938/938 [00:15<00:00, 61.06it/s, accuracy=1, loss=0.0529, lr=0.000131]
    Epoch 5, Val Loss: 0.1096566090935687, Val Accuracy: 0.9651671974522293
    LR: 0.0002 Gamma: 0.9 Hdim: 64 Best Accuracy: 0.9651671974522293
    100%| 938/938 [00:15<00:00, 61.85it/s, accuracy=0.875, loss=0.274, lr=0.0002]
    Epoch 1, Val Loss: 0.20217574968530683, Val Accuracy: 0.9417794585987261
    100%| 938/938 [00:15<00:00, 61.10it/s, accuracy=1, loss=0.0781, lr=0.00018]
    Epoch 2, Val Loss: 0.14685676535472844, Val Accuracy: 0.9575039808917197
    100%| 938/938 [00:15<00:00, 59.49it/s, accuracy=0.938, loss=0.116, lr=0.000162]
    Epoch 3, Val Loss: 0.1151969745498637, Val Accuracy: 0.9655652866242038
    100%| 938/938 [00:15<00:00, 61.70it/s, accuracy=0.969, loss=0.0552, lr=0.000146]
    Epoch 4, Val Loss: 0.1159010350772411, Val Accuracy: 0.9637738853503185
    100%| 938/938 [00:15<00:00, 62.39it/s, accuracy=1, loss=0.0434, lr=0.000131]
    Epoch 5, Val Loss: 0.10195070593232278, Val Accuracy: 0.9694466560509554
    LR: 0.0002 Gamma: 0.9 Hdim: 128 Best Accuracy: 0.9694466560509554
    Epoch 1, Val Loss: 0.18200375050140224, Val Accuracy: 0.948546974522293
    100%| 938/938 [00:16<00:00, 58.39it/s, accuracy=1, loss=0.0408, lr=0.0002]
              938/938 [00:15<00:00, 61.56it/s, accuracy=0.906, loss=0.349, lr=0.00018]
import matplotlib.pyplot as plt
epochs = 20
lrs = [4e-2]
gammas = [0.8]
hdims = [128]
best accs = []
for lr in lrs:
   for gamma in gammas:
       for hdim in hdims:
           torch.manual_seed(42)
           best acc = 0
```

```
# Define model
model = SineKAN(layers_hidden=[28 * 28, hdim, 10], grid_size=8)
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
model.to(device)
# Define optimizer
optimizer = optim.AdamW(model.parameters(), lr=lr)
# Define learning rate scheduler
scheduler = optim.lr_scheduler.ExponentialLR(optimizer, gamma=gamma)
# Define loss function
criterion = nn.CrossEntropyLoss()
# Lists to store validation loss and accuracy
val losses = []
val_accuracies = []
for epoch in range(epochs):
   model.train()
   with tqdm(train_loader) as pbar:
        for i, (images, labels) in enumerate(pbar):
           images = images.view(-1, 28 * 28).to(device)
            optimizer.zero_grad()
            output = model(images)
            loss = criterion(output, labels.to(device))
            loss.backward()
            optimizer.step()
            accuracy = (output.argmax(dim=1) == labels.to(device)).float().mean()
            pbar.set\_postfix(loss=loss.item(), accuracy=accuracy.item(), lr=optimizer.param\_groups[0]['lr'])
    # Validation
   model.eval()
   val loss = 0
   val_accuracy = 0
    with torch.no_grad():
        for images, labels in val_loader:
            images = images.view(-1, 28 * 28).to(device)
            output = model(images)
            val_loss += criterion(output, labels.to(device)).item()
            val_accuracy += (
                (output.argmax(dim=1) == labels.to(device)).float().mean().item()
    val_loss /= len(val_loader)
   val_accuracy /= len(val_loader)
    # Append values to lists
    val_losses.append(val_loss)
   val_accuracies.append(val_accuracy)
    if val_accuracy > best_acc:
        best_acc = val_accuracy
    # Update learning rate
    scheduler.step()
    print(f"Epoch {epoch + 1}, Val Loss: {val_loss:.4f}, Val Accuracy: {val_accuracy:.4f}")
best_accs.append(best_acc)
print(f"LR: {lr} Gamma: {gamma} Hdim: {hdim} Best Accuracy: {best_acc:.4f}")
# Plot Validation Loss and Accuracy
plt.figure(figsize=(12, 5))
# Plot Loss
plt.subplot(1, 2, 1)
plt.plot(range(1, epochs + 1), val_losses, marker='o', label='Validation Loss', color='blue')
plt.xlabel('Epoch')
plt.ylabel('Loss')
plt.title('Validation Loss Over Epochs')
plt.legend()
plt.grid()
# Plot Accuracy
plt.subplot(1, 2, 2)
plt.plot(range(1, epochs + 1), val_accuracies, marker='o', label='Validation Accuracy', color='green')
```

```
plt.xlabel('Epoch')
plt.ylabel('Accuracy')
plt.title('Validation Accuracy Over Epochs')
plt.legend()
plt.grid()
plt.show()
```

938/938 [00:15<00:00, 60.41it/s, accuracy=0.156, loss=5.72, lr=0.04] Epoch 1, Val Loss: 7.2959, Val Accuracy: 0.1052 938/938 [00:16<00:00, 55.40it/s, accuracy=0.0938, loss=6.2, lr=0.032] 100% Epoch 2, Val Loss: 5.9440, Val Accuracy: 0.0995 100%| 938/938 [00:15<00:00, 59.27it/s, accuracy=0.188, loss=4.77, lr=0.0256] Epoch 3, Val Loss: 5.0121, Val Accuracy: 0.0978 938/938 [00:15<00:00, 59.23it/s, accuracy=0.125, loss=4.89, lr=0.0205] Epoch 4, Val Loss: 4.3592, Val Accuracy: 0.1019 100%| 938/938 [00:15<00:00, 59.04it/s, accuracy=0.0625, loss=3.6, lr=0.0164] Epoch 5, Val Loss: 3.7688, Val Accuracy: 0.1031 938/938 [00:16<00:00, 57.79it/s, accuracy=0.0625, loss=4.06, lr=0.0131] Epoch 6, Val Loss: 3.4369, Val Accuracy: 0.0991 938/938 [00:16<00:00, 57.13it/s, accuracy=0.0625, loss=3.15, lr=0.0105] Epoch 7, Val Loss: 3.2133, Val Accuracy: 0.0980 100%| 938/938 [00:16<00:00, 58.50it/s, accuracy=0.0938, loss=2.68, lr=0.00839] Epoch 8, Val Loss: 2.8744, Val Accuracy: 0.1208 100% 938/938 [00:16<00:00, 55.47it/s, accuracy=0.562, loss=1.42, lr=0.00671] Epoch 9, Val Loss: 1.6969, Val Accuracy: 0.4583 938/938 [00:15<00:00, 59.72it/s, accuracy=0.719, loss=0.58, lr=0.00537] Epoch 10, Val Loss: 0.6985, Val Accuracy: 0.7732 100%| 938/938 [00:16<00:00, 58.37it/s, accuracy=0.875, loss=0.426, lr=0.00429] Epoch 11, Val Loss: 0.6025, Val Accuracy: 0.8149 938/938 [00:16<00:00, 58.08it/s, accuracy=0.812, loss=0.774, lr=0.00344] Epoch 12, Val Loss: 0.6071, Val Accuracy: 0.8071 100% 938/938 [00:16<00:00, 58.58it/s, accuracy=0.875, loss=0.301, lr=0.00275] Epoch 13, Val Loss: 0.3812, Val Accuracy: 0.8836 100%| 938/938 [00:16<00:00, 58.14it/s, accuracy=0.844, loss=0.497, lr=0.0022] Epoch 14, Val Loss: 0.3400, Val Accuracy: 0.8977 100%| 938/938 [00:15<00:00, 59.13it/s, accuracy=0.906, loss=0.185, lr=0.00176] Epoch 15, Val Loss: 0.3791, Val Accuracy: 0.8848 100% 938/938 [00:16<00:00, 56.28it/s, accuracy=1, loss=0.0994, lr=0.00141] Epoch 16, Val Loss: 0.2947, Val Accuracy: 0.9120 100%| 938/938 [00:15<00:00, 59.52it/s, accuracy=0.938, loss=0.114, lr=0.00113] Epoch 17, Val Loss: 0.2624, Val Accuracy: 0.9225 938/938 [00:16<00:00, 55.89it/s, accuracy=0.875, loss=0.334, lr=0.000901] 100% Epoch_18, Val Loss: 0.2577, Val Accuracy: 0.9237 100%| 938/938 [00:16<00:00, 58.60it/s, accuracy=0.969, loss=0.107, lr=0.000721] Epoch 19, Val Loss: 0.2503, Val Accuracy: 0.9231 100%| || | 938/938 [00:15<00:00, 59.19it/s, accuracy=0.875, loss=0.321, lr=0.000576] Epoch 20, Val Loss: 0.2342, Val Accuracy: 0.9306 LR: 0.04 Gamma: 0.8 Hdim: 128 Best Accuracy: 0.9306





#Weight Decay Regularization

```
wds = [0.01, 0.1, 0.25, 0.5, 0.75, 1.]
wd_accs = np.empty((6, epochs))
for h, wd in enumerate(wds):
   torch.manual_seed(42)
   best acc = 0
   # Define model
   model = SineKAN(layers_hidden=[28 * 28, hdim, 10], grid_size=8)
   device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
   model.to(device)
   # Define optimizer
   optimizer = optim.AdamW(model.parameters(), lr=4e-4, weight_decay=wd)
   # Define learning rate scheduler
   scheduler = optim.lr_scheduler.ExponentialLR(optimizer, gamma=gamma)
   # Define loss
   criterion = nn.CrossEntropyLoss()
   for epoch in range(epochs):
        # Train
       model.train()
        with tqdm(train loader) as pbar:
            for i, (images, labels) in enumerate(pbar):
                images = images.view(-1, 28 * 28).to(device)
                optimizer.zero_grad()
                output = model(images)
                loss = criterion(output, labels.to(device))
                loss.backward()
                optimizer.step()
                accuracy = (output.argmax(dim=1) == labels.to(device)).float().mean()
                pbar.set\_postfix(loss=loss.item(), accuracy=accuracy.item(), lr=optimizer.param\_groups[0]['lr'])
        # Validation
        model.eval()
        val_loss = 0
        val_accuracy = 0
        with torch.no grad():
            for images, labels in val_loader:
               images = images.view(-1, 28 * 28).to(device)
                output = model(images)
                val_loss += criterion(output, labels.to(device)).item()
                val_accuracy += (
                    (output.argmax(dim=1) == labels.to(device)).float().mean().item()
                )
        val_loss /= len(val_loader)
        val_accuracy /= len(val_loader)
        wd_accs[h, epoch] = val_accuracy
        # Update learning rate
        scheduler.step()
        print(
            f"Epoch {epoch + 1}, Val Loss: {val_loss}, Val Accuracy: {val_accuracy}"
# Checking best dims
epochs = 5
hdims = [16, 32, 64, 128, 256, 512]
hdim_accs = np.empty((6, epochs))
for h, hdim in enumerate(hdims):
   torch.manual seed(42)
   # Define model
   model = SineKAN(layers_hidden=[28 * 28, hdim, 10], grid_size=8)
   device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
   model.to(device)
   # Define optimizer
   optimizer = optim.AdamW(model.parameters(), lr=4e-4, weight_decay=.5)
   # Define learning rate scheduler
   scheduler = optim.lr_scheduler.ExponentialLR(optimizer, gamma=0.9)
   # Define loss
   criterion = nn.CrossEntropyLoss()
   for epoch in range(epochs):
        # Train
       model.train()
       with tqdm(train loader) as pbar:
```

```
for i, (images, labels) in enumerate(pbar):
                images = images.view(-1, 28 * 28).to(device)
                optimizer.zero_grad()
                output = model(images)
                loss = criterion(output, labels.to(device))
                loss.backward()
                optimizer.step()
                accuracy = (output.argmax(dim=1) == labels.to(device)).float().mean()
                pbar.set\_postfix(loss=loss.item(), accuracy=accuracy.item(), lr=optimizer.param\_groups[0]['lr'])
        # Validation
        model.eval()
        val_loss = 0
        val_accuracy = 0
        with torch.no_grad():
            for images, labels in val_loader:
                images = images.view(-1, 28 * 28).to(device)
                output = model(images)
                val_loss += criterion(output, labels.to(device)).item()
                val_accuracy += (
                    (output.argmax(dim=1) == labels.to(device)).float().mean().item()
               )
        val_loss /= len(val_loader)
        val_accuracy /= len(val_loader)
        hdim_accs[h, epoch] = val_accuracy
        # Update learning rate
        scheduler.step()
        print(
            f"Epoch {epoch + 1}, Val Loss: {val_loss}, Val Accuracy: {val_accuracy}"
# Checking best hidden layers
epochs = 5
n_{ayers} = [1, 2, 3, 4]
layer_accs = np.empty((4, epochs))
for h, n_layer in enumerate(n_layers):
   torch.manual_seed(42)
   # Define model
   model = SineKAN(layers_hidden=[28 * 28] + [128]*n_layer + [10], grid_size=8)
   device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
   model.to(device)
   # Define optimizer
   optimizer = optim.AdamW(model.parameters(), lr=4e-4, weight_decay=.5)
   # Define learning rate scheduler
   scheduler = optim.lr_scheduler.ExponentialLR(optimizer, gamma=0.9)
   # Define loss
   criterion = nn.CrossEntropyLoss()
    for epoch in range(epochs):
        # Train
       model.train()
       with tqdm(train_loader) as pbar:
            for i, (images, labels) in enumerate(pbar):
                images = images.view(-1, 28 * 28).to(device)
                optimizer.zero_grad()
                output = model(images)
                loss = criterion(output, labels.to(device))
                loss.backward()
                optimizer.step()
                accuracy = (output.argmax(dim=1) == labels.to(device)).float().mean()
                pbar.set\_postfix(loss=loss.item(), accuracy=accuracy.item(), lr=optimizer.param\_groups[0]['lr'])
        # Validation
        model.eval()
        val_loss = 0
        val accuracy = 0
        with torch.no_grad():
            for images, labels in val_loader:
                images = images.view(-1, 28 * 28).to(device)
                output = model(images)
                val_loss += criterion(output, labels.to(device)).item()
                val_accuracy += (
```

```
(output.argmax(dim=1) == labels.to(device)).float().mean().item()
)
val_loss /= len(val_loader)
val_accuracy /= len(val_loader)
layer_accs[h, epoch] = val_accuracy

# Update learning rate
scheduler.step()
print(
    f"Epoch {epoch + 1}, Val Loss: {val_loss}, Val Accuracy: {val_accuracy}"
)
```

4. Convolutional Neural Network

```
import torch
import torch.nn as nn
import torch.optim as optim
import torchvision
import torchvision.transforms as transforms
from torch.utils.data import DataLoader
# Define device
device = torch.device("cuda" if torch.cuda.is available() else "cpu")
# Transformations
transform = transforms.Compose([
    transforms.ToTensor(),
    transforms.Normalize((0.1307,), (0.3081,)) # Normalization for MNIST
])
# Datasets
train_dataset = torchvision.datasets.MNIST(root="./data", train=True, download=True, transform=transform)
test_dataset = torchvision.datasets.MNIST(root="./data", train=False, download=True, transform=transform)
# Dataloaders
train_loader= DataLoader(dataset= train_dataset, batch_size=64, shuffle=True)
test_loader= DataLoader(dataset= test_dataset, batch_size=64, shuffle=False)
# CNN Module
class CNN(nn.Module):
 def __init__(self):
    super(CNN, self).__init__()
    self.conv1= nn.Conv2d(in_channels=1, out_channels=32, kernel_size=2, stride=1, padding=1)
    self.conv2= nn.Conv2d(in_channels=32, out_channels=64, kernel_size=2, stride=1, padding=1)
    self.pool= nn.MaxPool2d(kernel_size=2, stride=2)
    self.fc1= nn.Linear(in_features=64*7*7, out_features=128)
    self.fc2 = nn.Linear(in_features=128, out_features=10)
    self.relu = nn.ReLU()
    self.dropout = nn.Dropout(p=0.4)
  def forward(self, x):
      x= self.pool(self.relu(self.conv1(x)))
      x= self.pool(self.relu(self.conv2(x)))
      x = x.view(-1, 64*7*7)
      x=self.relu(self.fc1(x))
      x= self.dropout(x)
      x = self.fc2(x)
      return x
model= CNN().to(device)
criterion = nn.CrossEntropyLoss()
optimizer = optim.Adam(model.parameters(), lr=0.001)
    100%
                      9.91M/9.91M [00:00<00:00, 16.3MB/s]
     100%
                      28.9k/28.9k [00:00<00:00, 482kB/s]
     100%
                      1.65M/1.65M [00:00<00:00, 4.43MB/s]
                  4.54k/4.54k [00:00<00:00, 8.64MB/s]
#Training Loop & Testing Loop
epochs= 10
train_losses= []
```