

Erasmus Mundus Joint Master Degree
in Image Processing and Computer
Vision (EMJMD-IPCV)



Applied Video Sequence Analysis

Lab 3 “Kalman filtering for object tracking”

Collaborative work (part II)

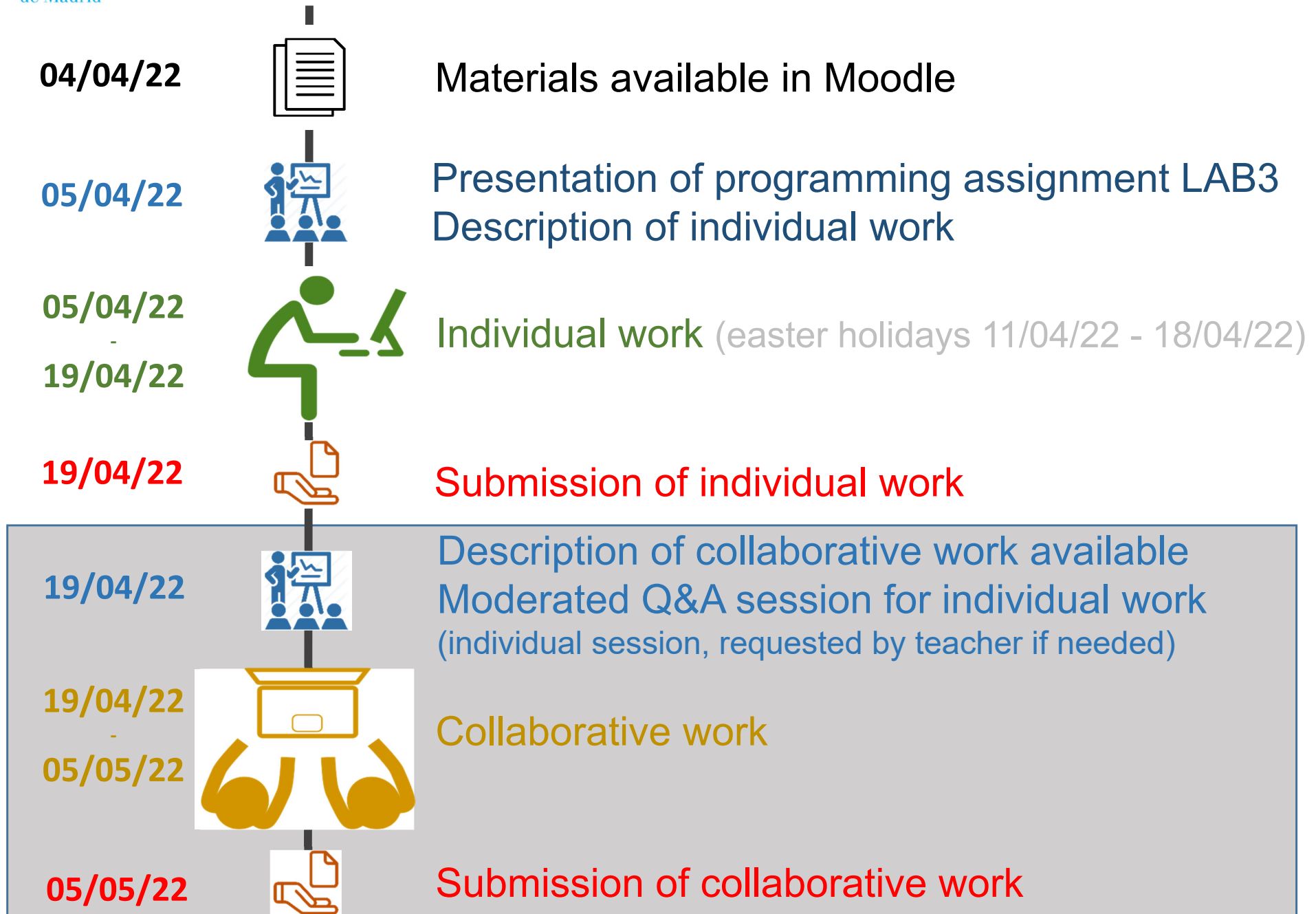
Instructor: Juan Carlos San Miguel (Juancarlos.Sanmiguel@uam.es)



PÁZMÁNY PÉTER
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- This lab assignment will be **graded with 10 points**

Type	Concept evaluated	TASK	Max. Score	Criteria evaluated
Individual (35%)	Source Code	Task 3.1	2.5	Code: Functional requirements (60%) Code: Design & structure & Style (40%)
	Report	Task 3.1	1	Report: Introduction & methods (40%) Report: Analysis & discussion (60%)
Collaborative (65%)	Source Code	Task 3.2	1	Code: Functional requirements (60%) Code: Design & structure & Style (40%)
	Report	Task 3.3	2.5	Report: Experimental methodology (40%) Report: Analysis & discussion (60%)
		Task 3.4	2.5	Report: Experimental methodology (40%) Report: Analysis & discussion (60%)
		Task 3.5	0.5	Report: Analysis & discussion of team dynamics. Teamwork log. (100%)
		TOTAL	10	

- Delivery not following requirements: -0.5 points
(e.g., submission without makefile or without three directories; report not using the course format)
- Late delivery after the remaining days of the late policy (remember 4-days in total)
 - -25% (one day), -50% (two days), -75% (three days), -100%(>= four days)

- Methodology based on pair programming¹
 - Two programmers/students do a combined effort to develop software using the same computer (either remotely or physically in the same place)
 - Roles:
 - Driver: develops and writes code, controls the inputs (mouse, keyboard)
 - Navigator: checks written code, suggests alternatives, looks for errors, asks for clarifications,...
 - Roles are exchanged periodically
 - Methodology frequently applied in the software and tech industry and (to a lesser extent) for university teaching in programming courses
 - Further documentation and **guidelines are provided in Moodle**

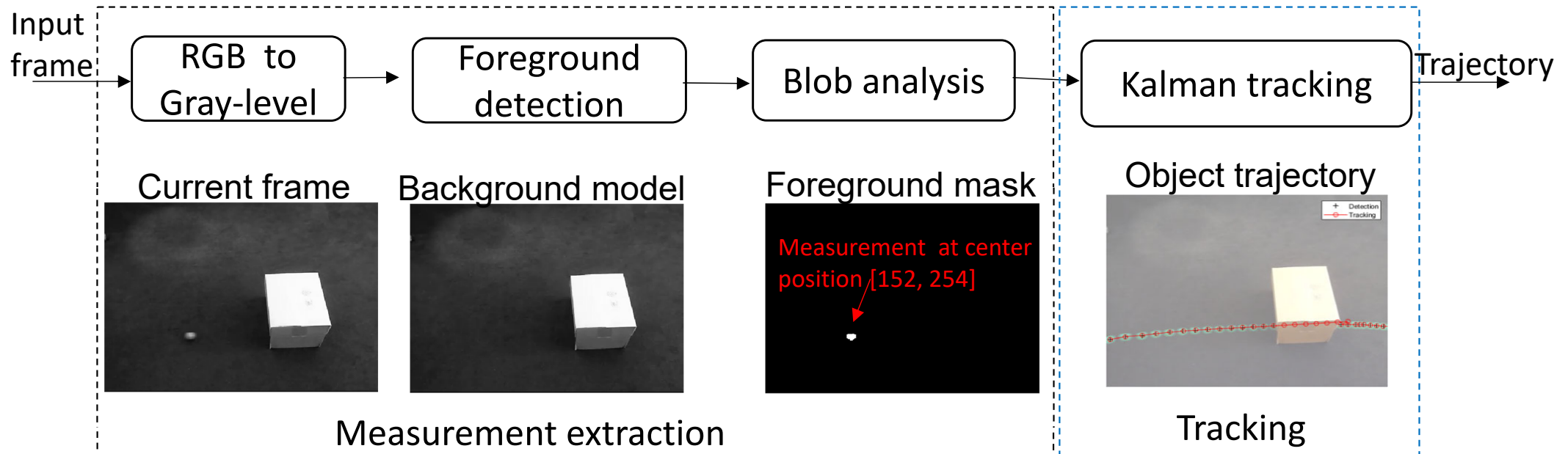


Source: Wikimedia.commons.org

¹Bevan, J. et al. "Guidelines for the use of pair programming in a freshman programming class". In IEEE CSEE&T, 2000.

3.1 Based on Background Subtraction: code implementation

Objective: implement a single-object tracker based on background subtraction and Kalman filtering like the one described in lectures



**TASK ALREADY COMPLETED WITH INDIVIDUAL WORK,
BUT YOU MUST MERGE INDIVIDUAL CODES OF TASK 3.1a & TASK 3.1b**

3.1 Based on Background Subtraction: code implementation

3.2 Based on Background Subtraction: analysis of toy data

Objective: based on task 3.1, analyze the effect of Kalman components for toy video sequences while keeping fixed measurement extraction

Task: change the parameters of the Kalman Filter (KF) for each sequence. You **must keep fixed the values of the MOG-based Extraction of the Object Measurement (EOM) for all test video sequences**. You may change EOM params, but a justification is needed in the report.

(suggested MOG parameters: learning_rate=0.001, varThreshold=16 and history=50; parameters for Opening: size=3x3, type=MORPH_RECT; parameters for blob extraction: min width=50, min height=50)

Test sequences: “video2.mp4”, “video3.mp4”, “video5.mp4” and “video6.mp4”

Submission:

- Source code with the best param settings for “video2.mp4”
- Report: experimental methodology, analysis and discussion of results, and a selection of visual examples for good/bad cases.

3.1 Based on Background Subtraction: code implementation

3.2 Based on Background Subtraction: analysis of toy data

Objective: based on task 3.1, analyze the effect of Kalman components for toy video sequences while keeping fixed measurement extraction

Suggestions: explore Kalman parameters starting from the result of task 3.1, explore differences in tracking performance (i.e. how good is the estimated trajectory)...

- 1) ...between the constant velocity and acceleration models.
- 2) ...when initial Prior Covariance (P_0 matrix) changes from the default value seen in lectures.
- 3) ...when measurement noise covariance (R matrix) changes from the default value seen in lectures.

No performance evaluation metrics are needed to be computed , just identify visually which parameter setting performs better

3.1 Based on Background Subtraction: code implementation

3.2 Based on Background Subtraction: analysis of toy data

3.3 Based on Background Subtraction: analysis of real data

Objective: analyze and tune the tracker implemented in task 3.1 for real video sequences from changedetection.net

Task: for each sequence, you can change the parameters for the MOG-based Extraction of the Object Measurement (EOM) and the Kalman Filter (KF). The task here is to adjust SOME (OR ALL, IF NEEDED) parameters for each sequence.

Test sequences: “boats_6950_7900_clip.mp4”, “pedestrians_800_1025_clip.mp4”, “abandonedBox_600_1000_clip.mp4” and “streetCornerAtNight_0_100_clip.mp4”

Submission:

- Source code with the best param settings for “abandonedBox_600_1000_clip.mp4”
- Report: experimental methodology, analysis and discussion of results, and visual examples of good/bad cases.

3.1 Based on Background Subtraction: code implementation

3.2 Based on Background Subtraction: analysis of toy data

3.3 Based on Background Subtraction: analysis of real data

Objective: analyze and tune the tracker implemented in task 3.1 for real video sequences from changedetection.net

Suggestions:

- 1) Analyze the tracking problems that exist for each sequence
- 2) You may keep fixed the KF params for all sequences and adjust EOM params for each sequence. Must justify any changes from default values of KF params
- 3) You may keep fixed the EOM params for all sequences and adjust KF params for each sequence. Must justify any changes from default values of EOM params
- 4) Or you can change both EOM and KF parameters simultaneously

No performance evaluation metrics are needed to be computed , just identify visually which parameter setting performs better

- 3.1 Based on Background Subtraction: code implementation
- 3.2 Based on Background Subtraction: analysis of toy data
- 3.3 Based on Background Subtraction: analysis of real data
- 3.4 Reflection on the collaboration and individual work**

You must include in the report an appendix with the following information
(it does not count towards the max page limit of the report):

- 1) Difficulties found during the individual work stage
- 2) Modifications or fixes of individual codes when combining these codes collaboratively for building the pipeline for task 3.1
- 3) Time log for collaborative work with time/data of each session, the student roles and main objective of the session (keep in mind that it does not need to be very detailed)
- 4) Overall impression of the hybrid pair programming methodology for LAB3

- Expected workload for each student (~15 hours total):
 - ~0h face-to-face (in classroom)
 - ~15h non-presential

TASK	Expected hours	Type of work
-	0.5 (~5%)	Lecturer presentation of the lab3 – Part II
-	2 (10%)	Integration of individual work from task 3.1
Task 3.2	6 (~40%)	Running experiments, adjusting params & Description/analysis in the report
Task 3.3	6 (~40%)	Running experiments, adjusting params & Description/analysis in the report
Task 3.4	0.5 (~5%)	Collaborative log. Reflection on the individual and collaborative work.
TOTAL	15 (100%)	

1. Assignment available on Moodle to submit your material

→ LAB3 – Collaborative work (**deadline 05/05/22 10AM**)

– The material must be submitted as a **ZIP file** with the following format ***Surname1name1_Surname2name2_lab3.zip***

– The submitted ZIP file will contain

- Report in PDF format following the template
(max 6 pages, task 3.4 does not count for the limit)
- Three directories “T31”, “T32” & “T33” containing :
 - *Makefile* to compile and link the program by simply running *make*
 - “src” directory with all source files (.h, .hpp, .c and .cpp) necessary for compiling and executing the corresponding program in Linux
 - **Please do not submit configuration files of Eclipse**

Each pair must submit the work only once