Date: 18/08/2021

Lab 02 - Ultrasound distance sensor using Tinker CAD Arduino

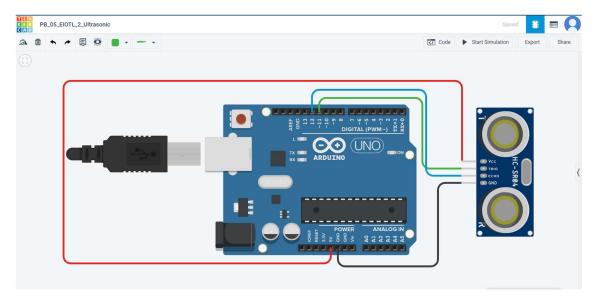
Aim: To Interface following sensors such as Temperature or Ultrasonic or Gas sensors with Raspberry-Pi/Beagle board/ TinkerCAD Arduino etc. and display readings on console.

Theory:

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	PB_05_Kustragua Suryawarshi. Batch (B1)
	EIOT-LAB-2 Ultrasonic distance sensor.
	din: To interface following sensors such as Temperature or Ultrasoric or yas sensors with Ardino and display readings on console.
	Theory:
k	List and state various servors used in 10T systems. Jemperature Humidity Pressure Proximity Accelerometers Lygroscope Lyas servors.
- 2. ·	What are other distance measurement sensors? Ultransonic IR pronimity kaver distance radar sensors.
	Describe the details of HC-SRO4 distance sensor. HC-SRO4 is an ultrasonic distance sensor. Main features:

BDARS GAR	Dr. Vishwanath Karad MIT WORLD PEAC UNIVERSITY PUNE 11 PRINTED TO BE TO THE PORT OF PRINTED A TOOL TOOL TOOL TOOL TOOL TOOL TOOL TO
	Main Parts: transmitter and receiver.
- 3	
	Jechnology used - non contact tech Operating voltage - 5 v.
	Operating Juguency - 4MHz.
	Sitellion range - 2cm to 400 cm.
420	Measuring anaple = 30°.
Marier.	Resolution - 3mm.
	Dimensions - 45×20×15 mm.
	The state of the s

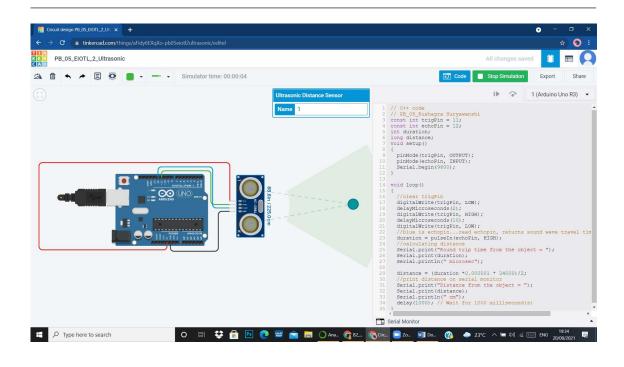
Ultrasonic distance sensor:



Explanation: In this experiment I have made a distance sensor circuit using an Arduino uno board, HC-SR04 Ultrasonic distance sensor. The VCC and GND pins of sensor are connected to Arduino's 5V supply and GND respectively. Input/Output of sensor, i.e, transmitter and receiver are connected to ports 11 and 12.

```
Code:
// C++ code
// PB 05 Kushagra Suryawanshi
//
const int trigPin = 11;
const int echoPin = 12;
int duration;
long distance;
void setup()
{
 pinMode(trigPin, OUTPUT);
 pinMode(echoPin, INPUT);
 Serial.begin(9600);
}
void loop()
{
 //clear trigPin
 digitalWrite(trigPin, LOW);
 delayMicroseconds(2);
 digitalWrite(trigPin, HIGH);
 delayMicroseconds(10);
 digitalWrite(trigPin, LOW);
 //blue is echopin...read echopin, returns sound wave travel time in microsecs
 duration = pulseIn(echoPin, HIGH);
 //calculating distance
 Serial.print("Round trip time from the object = ");
```

```
Serial.print(duration);
Serial.println(" microsec");
distance = (duration *0.000001 * 34000)/2;
//print distance on serial monitor
Serial.print("Distance from the object = ");
Serial.print(distance);
Serial.println(" cm");
delay(1000); // Wait for 1000 millisecond(s)
}
```



Conclusion: Thus, we learnt about Ultrasonic distance sensor and temperature sensor and how to interface them with Arduino uno board.

Simulation Link: https://www.tinkercad.com/things/aFidy6EXqXo-pb05eiotl2ultrasonic/editel?sharecode=PLZ1yBKLehd7loZLZPzMPj0WkiQwHja2 aD3eLsamxyg