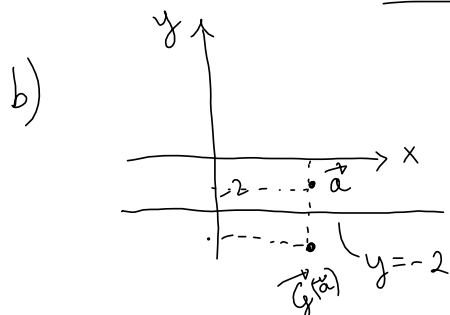


$$\begin{array}{c} \underline{\begin{bmatrix} 6 \\ 1 \end{bmatrix}} = \vec{F}(0, 1) = A \begin{bmatrix} 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 6 \\ 0 \end{bmatrix} = \underline{\begin{bmatrix} a_{12} + 6 \\ a_{22} + 0 \end{bmatrix}} \\ \text{Figur} \quad \text{affin} \end{array}$$

$$\begin{array}{l} a_{12} + 6 = 6 \\ a_{22} = 1 \end{array} \Rightarrow \begin{array}{l} a_{12} = 0 \\ a_{22} = 1 \end{array}$$

$$\Rightarrow A = \underline{\underline{\begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}}} \quad (\vec{b} = \begin{bmatrix} 6 \\ 0 \end{bmatrix})$$



2.7: Kjemeregelen

$$2) f(u, v) = u e^{-v}, \quad g(x, y, z) = 2xy + z, \quad h(x, y, z) = 2y(z+x)$$

$$k(x, y, z) = f(\underbrace{g(x, y, z)}_{\text{"spiller rollen som } u"}, \underbrace{h(x, y, z)}_{\text{"spiller rollen som } v"})$$

$$\begin{aligned} \frac{\partial k}{\partial x} &= \frac{\partial f}{\partial u} \frac{\partial g}{\partial x} + \frac{\partial f}{\partial v} \frac{\partial h}{\partial x} = e^{-2y(z+x)} 2y - (2xy+z) e^{-2y(z+x)} 2y \\ &= 2y e^{-2y(z+x)} \underline{\underline{(1 - (2xy+z))}} \end{aligned}$$

Kjemeregel på komponentform

$$\begin{aligned}\frac{\partial k}{\partial y} &= \frac{\partial f}{\partial u} \frac{\partial g}{\partial y} + \frac{\partial f}{\partial v} \frac{\partial h}{\partial y} = e^{-2y(z+x)} (2x - (2xy+z)) e^{-2y(z+x)} \\ &= e^{-2y(z+x)} (2x - 2(2xy+z)(z+x))\end{aligned}$$

8) $T = f(x, y)$, $x = r \cos \theta$, $y = r \sin \theta$
 $T(r, \theta) = f(r \cos \theta, r \sin \theta)$

a) $\frac{\partial T}{\partial r} = \frac{\partial f}{\partial x} \frac{\partial x(r, \theta)}{\partial r} + \frac{\partial f}{\partial y} \frac{\partial y(r, \theta)}{\partial r}$

Kjennregel
på komponentform

$$= \frac{\partial f}{\partial x} \cos \theta + \frac{\partial f}{\partial y} \sin \theta$$

$$\frac{\partial T}{\partial \theta} = \frac{\partial f}{\partial x} \frac{\partial x(r, \theta)}{\partial \theta} + \frac{\partial f}{\partial y} \frac{\partial y(r, \theta)}{\partial \theta} = \frac{\partial f}{\partial x} r \sin \theta + \frac{\partial f}{\partial y} r \cos \theta$$

b) $r = g(t)$, $\theta = h(t)$;

$$T'(t) = \frac{\partial T}{\partial r} \underbrace{\frac{\partial r}{\partial t}}_{r'(t)} + \frac{\partial T}{\partial \theta} \underbrace{\frac{\partial \theta}{\partial t}}_{\theta'(t)} = \left(\frac{\partial f}{\partial x} \cos \theta + \frac{\partial f}{\partial y} \sin \theta \right) g'(t) + \left(-\frac{\partial f}{\partial x} r \sin \theta + \frac{\partial f}{\partial y} r \cos \theta \right) h'(t)$$

2.8: Linearisering

2) $\vec{F}(x, y) = \begin{bmatrix} x \sin(xy) \\ x e^y \\ 2x^3 + y \end{bmatrix}$, $\vec{a} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$

$$\vec{T}_{\vec{a}} \vec{F}(\vec{x}) = \vec{F}(\vec{a}) + \vec{F}'(\vec{a})(\vec{x} - \vec{a}) = \begin{bmatrix} 0 \\ 2 \\ 16 \end{bmatrix} + \begin{bmatrix} 0 & 4 \\ 1 & 2 \\ 24 & 1 \end{bmatrix} (\vec{x} - \vec{a})$$

$$\vec{F}'(x,y) = \begin{bmatrix} \sin(xy) + x \cos(xy)y & x^2 \cos(xy) \\ e^y & x e^y \\ 6x^2 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 \\ 2 \\ 16 \end{bmatrix} + \begin{bmatrix} 0 & 4 \\ 1 & 2 \\ 24 & 1 \end{bmatrix} \begin{bmatrix} x-2 \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 16 \end{bmatrix} + \begin{bmatrix} 4y \\ x-2+2y \\ 24x-48+y \end{bmatrix}$$

$$= \begin{bmatrix} 4y \\ x+2y \\ 24x-32+y \end{bmatrix}$$