

Plenum 26/4-16

4.10: 5a

4.11: 1, 10

5.1: 1de, 4

5.2: 1

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4.10:

$$5.) a) \quad c_1 \vec{u}_1 + c_2 \vec{u}_2 + c_3 \vec{u}_3 + c_4 \vec{u}_4 = \vec{x}$$

$$\begin{bmatrix} \vec{u}_1 & \vec{u}_2 & \vec{u}_3 & \vec{u}_4 \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \end{bmatrix} = \vec{x}$$

$$\underbrace{U}_{\text{lijnt}} \underbrace{\vec{c}}_{?} = \underbrace{\vec{x}}_{\text{lijnt}}$$

Fra MATLAB;

$$\vec{x} = (-1,9 - 2,4i) \vec{u}_1 + (-1,9 + 2,4i) \vec{u}_2 + 1,4 \vec{u}_3 + 3,9 \vec{u}_4$$

1. egenvektor

4.11:

$$1) \quad x_{n+1} = x_n + 3y_n, \quad x_0 = 5, \quad y_0 = -5$$

$$y_{n+1} = 2x_n + 2y_n$$

Matriseform:

$$\begin{bmatrix} x_{n+1} \\ y_{n+1} \end{bmatrix} = \overbrace{\begin{bmatrix} 1 & 3 \\ 2 & 2 \end{bmatrix}}^{:= A} \begin{bmatrix} x_n \\ y_n \end{bmatrix}$$

$$\det(\lambda I - A) = \begin{vmatrix} \lambda - 1 & -3 \\ -2 & \lambda - 2 \end{vmatrix} = (\lambda - 1)(\lambda - 2) - 6$$

$$= \lambda^2 - 3\lambda - 4 = 0$$

$\Downarrow$  (2. gradsformel)

$$\underline{\lambda_1 = -1} \text{ og } \underline{\lambda_2 = 4}$$

$$\vec{v}_1: A\vec{v}_1 = \lambda_1 \vec{v}_1$$

$$(\lambda_1 I - A)\vec{v}_1 = 0$$

$$-I - A = \begin{bmatrix} -2 & -3 \\ -2 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & \frac{3}{2} \\ 0 & 0 \end{bmatrix} \Rightarrow \vec{v}_1 = \begin{bmatrix} -3 \\ 2 \end{bmatrix}$$

Velger  $y=2$

$$\vec{v}_2: 4I - A = \begin{bmatrix} 3 & -3 \\ -2 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} \Rightarrow \vec{v}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Skriv  $(x_0, y_0) = (5, -5)$  som lin. komb. af  $\vec{v}_1$  og  $\vec{v}_2$ :

$$\begin{bmatrix} -3 & 1 & 5 \\ 2 & 1 & -5 \end{bmatrix} \sim \begin{bmatrix} 1 & -\frac{1}{3} & -\frac{5}{3} \\ 2 & 1 & -5 \end{bmatrix} \sim \begin{bmatrix} 1 & -\frac{1}{3} & -\frac{5}{3} \\ 0 & \frac{5}{3} & -\frac{5}{3} \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & -\frac{1}{3} & -\frac{5}{3} \\ 0 & 1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} 5 \\ -5 \end{bmatrix} = -2 \begin{bmatrix} -3 \\ 2 \end{bmatrix} - \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\Rightarrow \begin{bmatrix} x_n \\ y_n \end{bmatrix} = -2(-1)^n \begin{bmatrix} -3 \\ 2 \end{bmatrix} - 4^n \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$= \underline{\underline{\begin{bmatrix} 6(-1)^n - 4^n \\ (-4)(-1)^n - 4^n \end{bmatrix}}}$$

Hvorfor?

$$\begin{bmatrix} x_n \\ y_n \end{bmatrix} = A \begin{bmatrix} x_{n-1} \\ y_{n-1} \end{bmatrix}$$

$$= A A \begin{bmatrix} x_{n-2} \\ y_{n-2} \end{bmatrix}$$

$$= A^2 \begin{bmatrix} x_{n-2} \\ y_{n-2} \end{bmatrix}$$

$$= \dots = A^n \begin{bmatrix} x_{n-n} \\ y_{n-n} \end{bmatrix}$$

$$= A^n \begin{bmatrix} x_0 \\ y_0 \end{bmatrix}$$

$$= A^n (c_1 \vec{v}_1 + c_2 \vec{v}_2)$$

$$= c_1 (A^n \vec{v}_1) + c_2 (A^n \vec{v}_2)$$

$$= \underline{\underline{c_1 \lambda_1^n \vec{v}_1 + c_2 \lambda_2^n \vec{v}_2}}$$

10.)  $x(t) = \text{row}$ ,  $y(t) = \text{byte}$   
 $x(0) = 500$ ,  $y(0) = 1000$

a) (\*) 
$$\begin{cases} x'(t) = x(t) + y(t) \\ y'(t) = -x(t) + y(t) \end{cases}$$

$$\vec{r}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

Fra (\*): 
$$\vec{r}'(t) = \underbrace{\begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}}_{:=A} \vec{r}(t)$$

Eigenwert:

$$\det(\lambda I - A) = \begin{vmatrix} \lambda - 1 & -1 \\ 1 & \lambda - 1 \end{vmatrix} = (\lambda - 1)^2 + 1 = \lambda^2 - 2\lambda + 2$$

$$\lambda = \frac{2 \pm \sqrt{4 - 8}}{2} = \frac{2 \pm \sqrt{-4}}{2} = \frac{2 \pm 2i}{2} = 1 \pm i = \begin{cases} 1+i & \swarrow \lambda_1 \\ 1-i & \nwarrow \lambda_2 \end{cases}$$

Eigenvektoren:

$$\lambda_1 I - A = \begin{bmatrix} i & -1 \\ 1 & i \end{bmatrix} \sim \begin{bmatrix} 1 & i \\ i & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & i \\ 0 & 0 \end{bmatrix} \Rightarrow \vec{v}_1 = \begin{bmatrix} -i \\ 1 \end{bmatrix} \quad (y=1)$$

Fra Set. 4.10.8: 
$$\vec{v}_2 = \begin{bmatrix} i \\ 1 \end{bmatrix}$$

Fra argument s. 387: Setz

$$\vec{r}(t) = c_1(t) \vec{v}_1 + c_2(t) \vec{v}_2 \quad (\square)$$

$$\downarrow$$

$$c_1'(t) = \lambda_1 c_1(t) \quad \text{og} \quad c_2'(t) = \lambda_2 c_2(t)$$

$$c_1(t) = C_1 e^{(1+i)t} \quad \text{og} \quad c_2(t) = C_2 e^{(1-i)t}$$

Startbedingung:

$$\vec{r}(0) = \begin{bmatrix} 500 \\ 1000 \end{bmatrix} \stackrel{(\text{D})}{=} C_1 \vec{v}_1 + C_2 \vec{v}_2 = \begin{bmatrix} -C_1 i + C_2 i \\ C_1 + C_2 \end{bmatrix}$$

$$\Rightarrow C_1 = 1000 - C_2 \quad \text{og} \quad -(1000 - C_2)i + C_2 i = 500$$

$$C_1 = \underline{500 + 250i}$$

$$\Leftarrow C_2 = \underline{500 - 250i}$$

Fra (7):

$$x(t) = \underbrace{-(500 + 250i)e^t (\cos t + i \sin t)}_{c_1(t)} i + \underbrace{(500 - 250i)e^t (\cos t - i \sin t)}_{c_2(t)} i$$

$e^{(1+i)t} = e^t (\cos t + i \sin t)$   
 $e^{(1-i)t} = e^t (\cos t - i \sin t)$   
 $e^{(1+i)t} = e^t e^{i t} = e^t (\cos t + i \sin t)$   
 $e^{(1-i)t} = e^t e^{-i t} = e^t (\cos t - i \sin t)$

$$= \dots = e^t (1000 \sin t + 500 \cos t)$$

$$y(t) = (500 + 250i)e^t (\cos t + i \sin t) + (500 - 250i)e^t (\cos t - i \sin t)$$

$$= e^t (1000 \cos t - 500 \sin t)$$

$$b) \begin{cases} x'(t) = -2x(t) + 4y(t) \\ y'(t) = x(t) - 2y(t) \end{cases}$$

$$\vec{r}'(t) = A \vec{r}(t) \text{ der } A = \begin{bmatrix} -2 & 4 \\ 1 & -2 \end{bmatrix}$$

Egenvektorer &amp; egenverdier:

$$\det(\lambda I - A) = \begin{vmatrix} \lambda + 2 & -4 \\ -1 & \lambda + 2 \end{vmatrix} = (\lambda + 2)^2 - 4 = \lambda(\lambda + 4) = 0$$

$$\Rightarrow \lambda_1 = 0 \text{ og } \lambda_2 = -4$$

$$\vec{v}_1: \lambda_1 I - A = -A = \begin{bmatrix} 2 & -4 \\ -1 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & -2 \\ 0 & 0 \end{bmatrix} \Rightarrow \vec{v}_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\vec{v}_2: \lambda_2 I - A = \begin{bmatrix} -2 & -4 \\ -1 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} \Rightarrow \vec{v}_2 = \begin{bmatrix} -2 \\ 1 \end{bmatrix}$$

 $\vec{v}_1$  og  $\vec{v}_2$  lin. uavh; så basis!

$$\text{Fra opg. 387: } \vec{r}(t) = c_1(t) \vec{v}_1 + c_2(t) \vec{v}_2 \quad (\Delta)$$

$$\text{der } c_1(t) = C_1 e^{\lambda_1 t} \text{ og } c_2(t) = C_2 e^{\lambda_2 t}$$

$$= C_1 e^0 = C_1$$

$$= C_2 e^{-4t}$$

Startbetingelse:

$$\begin{aligned} \underline{\begin{bmatrix} 500 \\ 1000 \end{bmatrix}} &= \underset{(\Delta)}{\vec{r}(0)} = C_1 \underbrace{\begin{bmatrix} 2 \\ 1 \end{bmatrix}}_{\vec{v}_1} + C_2 e^{-4 \cdot 0} \underbrace{\begin{bmatrix} -2 \\ 1 \end{bmatrix}}_{\vec{v}_2} \\ &= \underline{\begin{bmatrix} 2C_1 - 2C_2 \\ C_1 + C_2 \end{bmatrix}} \end{aligned}$$

$$\Rightarrow C_1 = 1000 - C_2 \quad \text{og} \quad 2(1000 - C_2) - 2C_2 = 500$$

$$\underline{C_1 = 625}$$

$$4C_2 = 1500$$

$$\leftarrow \underline{C_2 = 375}$$

$$\begin{aligned} \text{Så fra } (\Delta): \quad \underline{\vec{r}(t)} = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} &= \underbrace{625}_{C_1(t)} \begin{bmatrix} 2 \\ 1 \end{bmatrix} + \underbrace{375 e^{-4t}}_{C_2(t)} \begin{bmatrix} -2 \\ 1 \end{bmatrix} \\ &= \underline{\underline{\begin{bmatrix} 1250 - 750 e^{-4t} \\ 625 + 375 e^{-4t} \end{bmatrix}}} \end{aligned}$$

c) Ikke flere byttedyr!

Modell a):  $y(t) = 0$  ?  $y(t)$  er 0 når

$$1000 \cos t - 500 \sin t = 0$$

$$2 \cos t = \sin t$$

$$\tan(t) = 2$$

Hvor mange måneder for dette skjer?  $\arctan(\tan t) = \arctan(2)$   
 $t \approx 1,1$

Så etter 1,1 år (ca 13 mnd.) er det ingen byttedyr i modell a).

$$\text{Modell b): } \lim_{t \rightarrow \infty} y(t) = \lim_{t \rightarrow \infty} 625 + 375 e^{-4t} = \underline{625}$$

PASSER  
BRA!

(b)  
 $y(t) = 625 + 375 e^{-4t} \neq 0$ ; Er alltid pos.  
 antall byttedyr i  
modell b).

PASSER  
DÄRLIG!