

UNIVERSITY OF OSLO

CONTROL OF MOBILE ROBOTS

UNIK4490

An Unnecessarily Extra Long Convoluted Academic Title That Makes Little Sense

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Some Heading

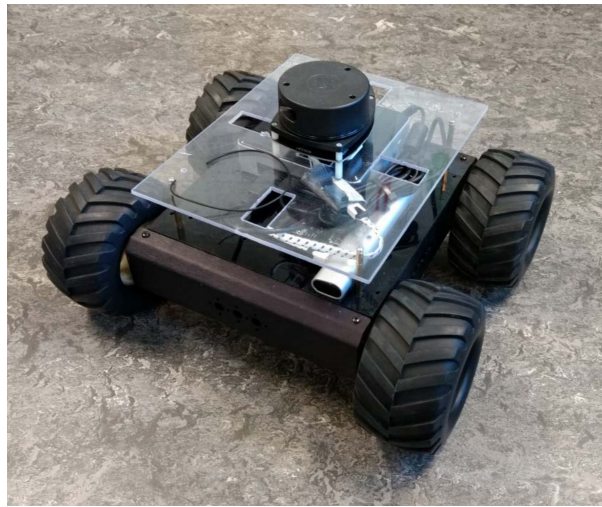


Figure 1: 4 by 4 Rover

Tasks

1. Move the robot to a pose
2. Implement odometric localization
3. Implement motor control for each wheel
4. Implement posture regulation motion control