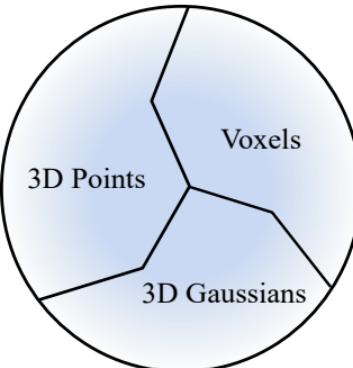
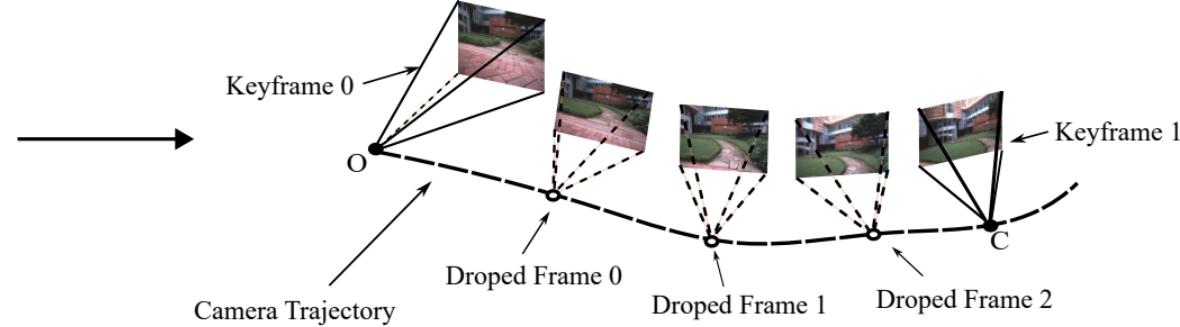


LiDAR Scan

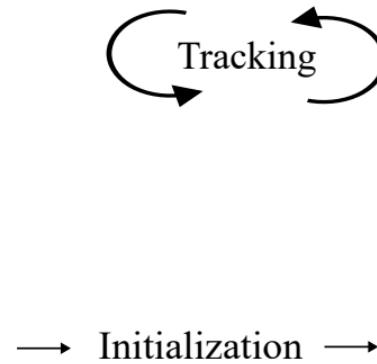
+ IMU Input +



RGB Input



Hyper Primitives



3D Gaussian Map

Render
Optimize

