



DIGITAL IMAGE PROCESSING

Single Image Haze Removal Using Dark Channel Prior

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CONTENT



INTRODUCTION



PRINCIPLE



RESULT



IMPROVEMENT



Background

- Deteriorated environment: Sandstorm, Dust and Haze
- Aerial surveying and mapping, Photography, Traffic information system and so on

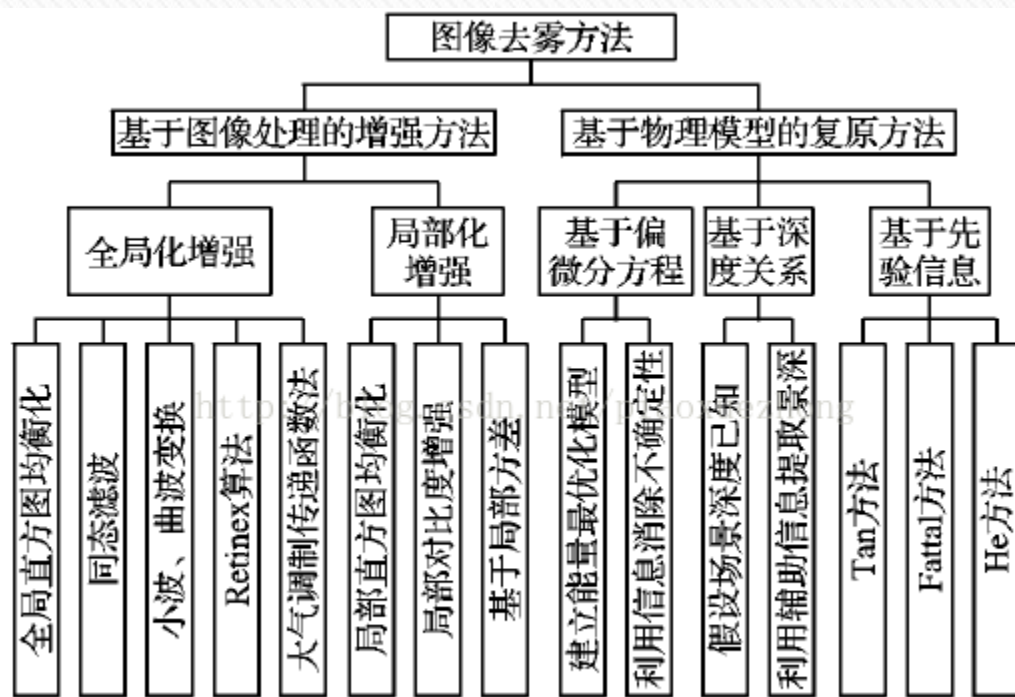


图1 主要去雾方法分类

PRINCIPLE

Dark Channel Prior: $J^{\text{dark}} \rightarrow 0$

$$J^{\text{dark}}(\mathbf{x}) = \min_{\mathbf{y} \in \Omega(\mathbf{x})} \left(\min_{c \in \{r, g, b\}} J^c(\mathbf{y}) \right)$$

A model widely used in a hazy image:

$$\mathbf{I}(\mathbf{x}) = \mathbf{J}(\mathbf{x})t(\mathbf{x}) + \mathbf{A}(1 - t(\mathbf{x}))$$

I: the observed intensity

J: the scene radiance

A: the global atmospheric light

t: the medium transmission

$$\min_{\mathbf{y} \in \Omega(\mathbf{x})} \left(\min_c \frac{I^c(\mathbf{y})}{A^c} \right) = \tilde{t}(\mathbf{x}) \min_{\mathbf{y} \in \Omega(\mathbf{x})} \left(\min_c \frac{J^c(\mathbf{y})}{A^c} \right) + 1 - \tilde{t}(\mathbf{x})$$

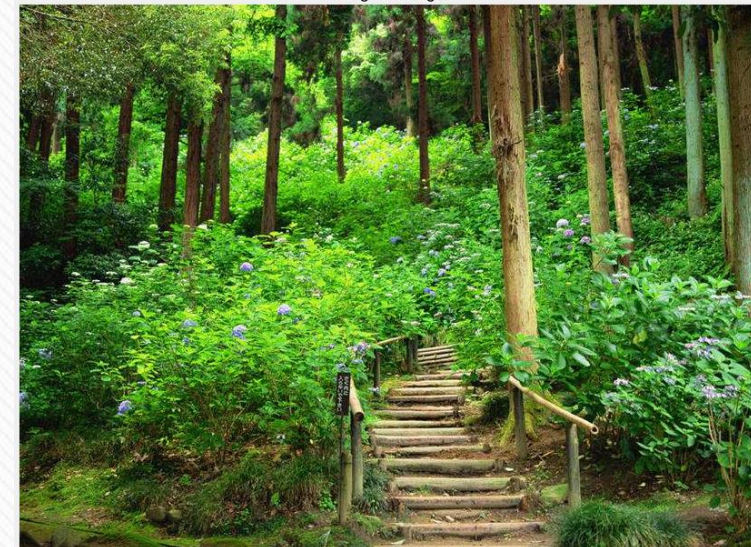
$$\tilde{t}(\mathbf{x}) = 1 - \min_{\mathbf{y} \in \Omega(\mathbf{x})} \left(\min_c \frac{I^c(\mathbf{y})}{A^c} \right)$$

A

Original Image



Original Image



Dark Channel



Dark Channel





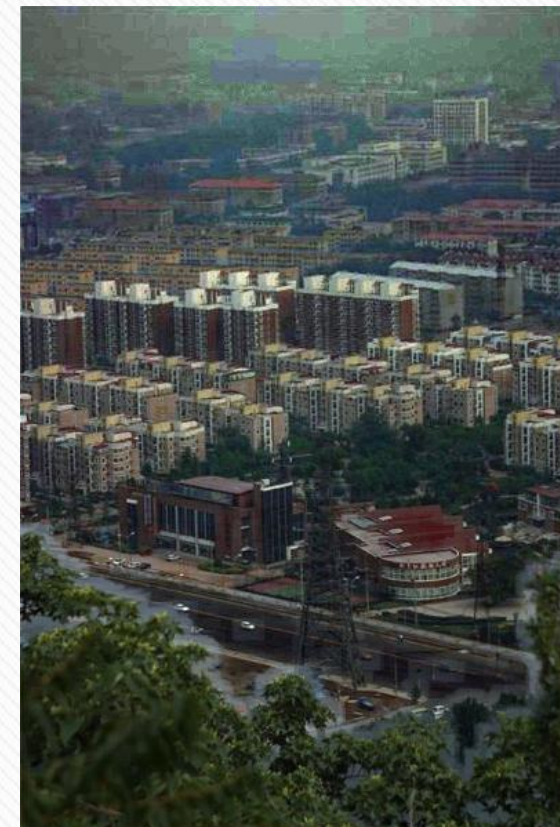
Original Image



Dark Channel Prior



Transmission



Haze Removed Image

IMPROVEMENT

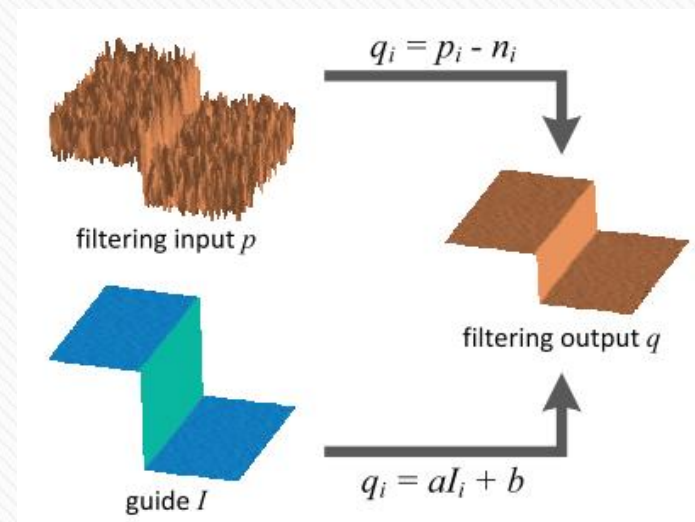
Edge-preserving filter: Guided filter



Transmission



Transmission



Algorithm 1. Guided Filter.

Input: filtering input image p , guidance image I , radius r , regularization ϵ

Output: filtering output q .

- 1: $\text{mean}_I = f_{\text{mean}}(I)$
 $\text{mean}_p = f_{\text{mean}}(p)$
 $\text{corr}_I = f_{\text{mean}}(I \cdot I)$
 $\text{corr}_{Ip} = f_{\text{mean}}(I \cdot p)$
- 2: $\text{var}_I = \text{corr}_I - \text{mean}_I \cdot \text{mean}_I$
 $\text{cov}_{Ip} = \text{corr}_{Ip} - \text{mean}_I \cdot \text{mean}_p$
- 3: $a = \text{cov}_{Ip} / (\text{var}_I + \epsilon)$
 $b = \text{mean}_p - a \cdot \text{mean}_I$
- 4: $\text{mean}_a = f_{\text{mean}}(a)$
 $\text{mean}_b = f_{\text{mean}}(b)$
- 5: $q = \text{mean}_a \cdot I + \text{mean}_b$

/ f_{mean} is a mean filter with a wide variety of $O(N)$ time methods. */*

IMPROVEMENT

Edge-preserving filter: Guided filter



Original Image



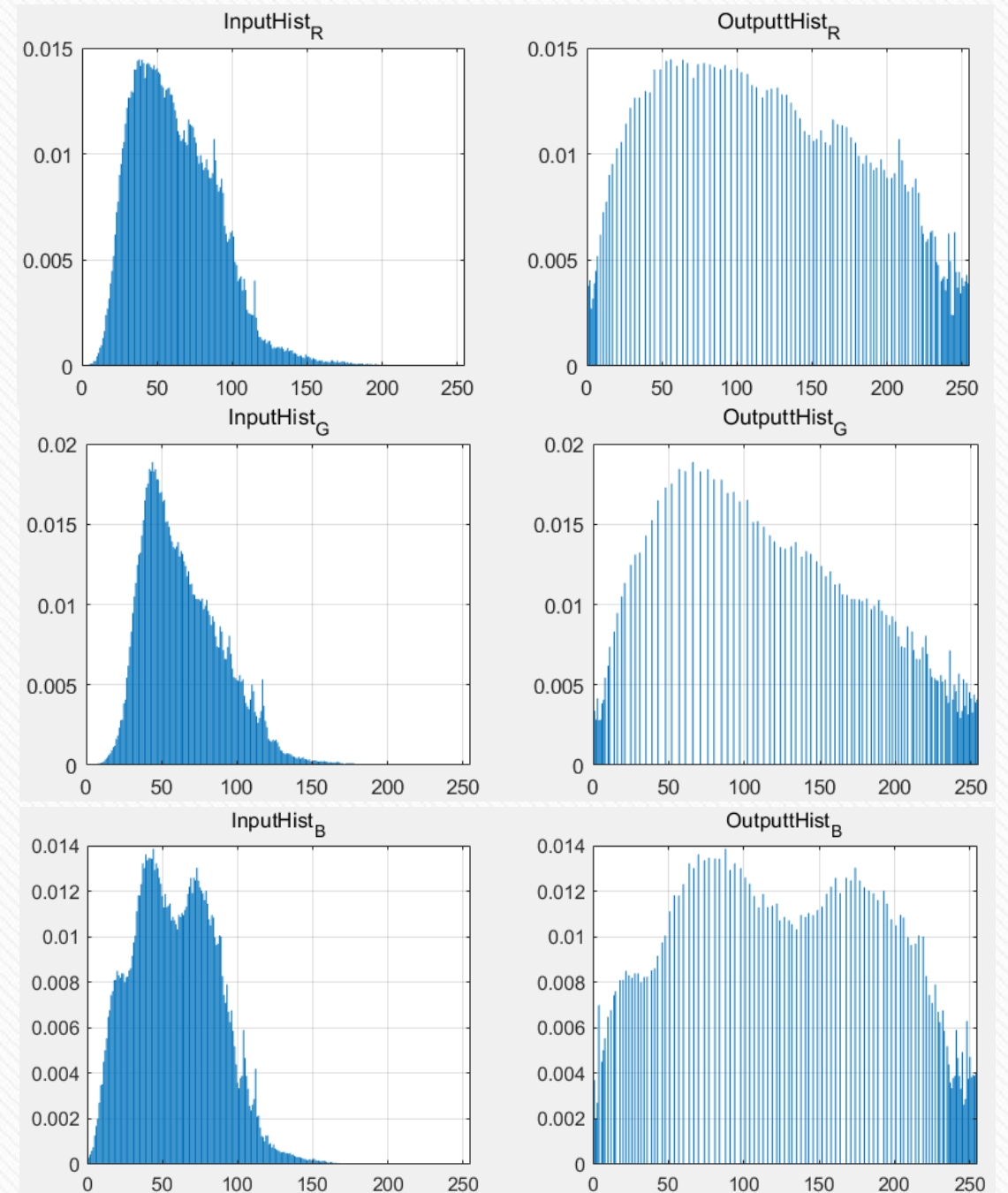
Without Filtering



Guided Filtering

IMPROVEMENT

Brightness Adjustment: Histogram Equalization



IMPROVEMENT

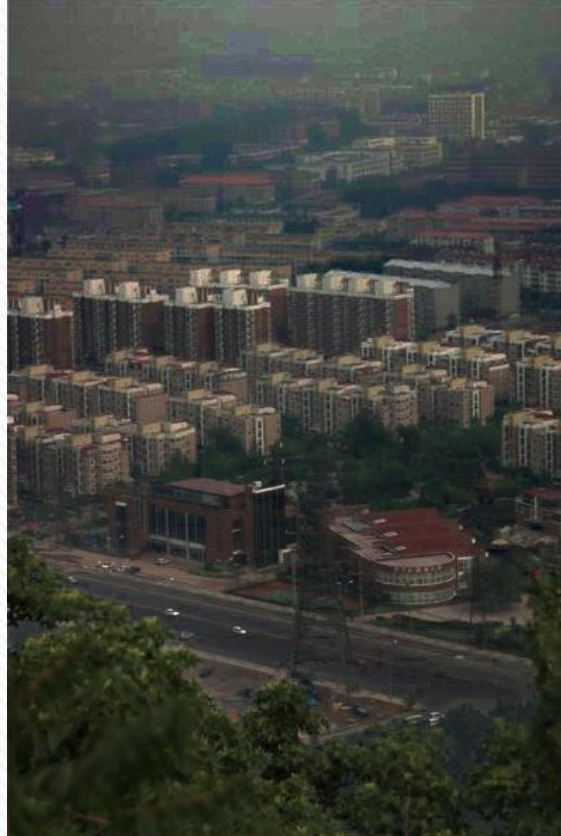
Brightness Adjustment:
Auto Color Gradation and Auto Contrast

```
if R0(i,j)<minR
    R(i,j) = 0;
elseif R0(i,j)>maxR
    R(i,j) = 255;
else
    R(i,j) = (R0(i,j)-minR)/(maxR-minR)*255;
end
```

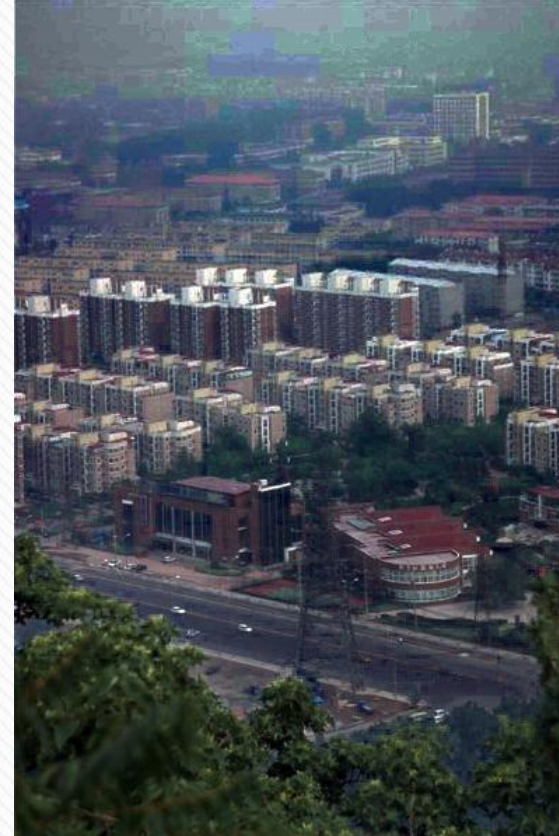
$MIN = \min([minR, minG, minB]);$
 $MAX = \max([maxR, maxG, maxB]);$



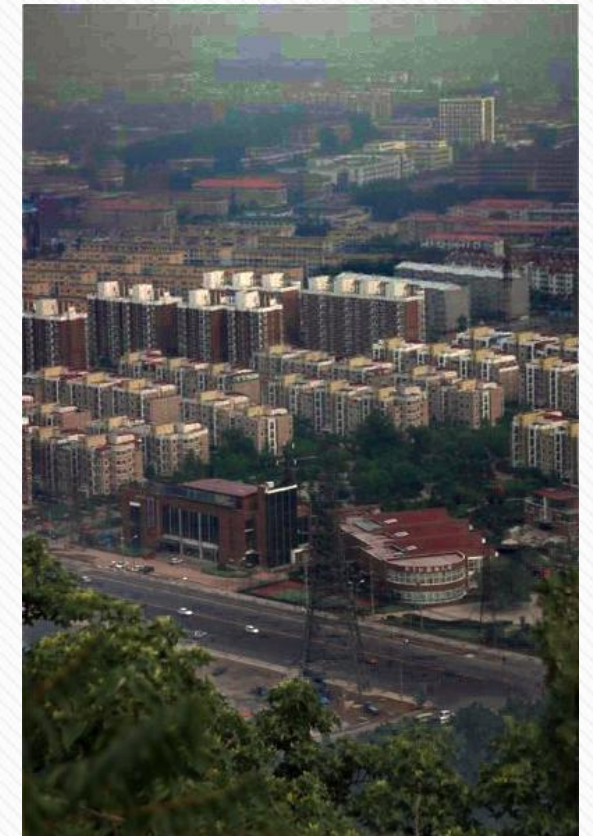
Original Image



Without Adjustment



Auto Color Gradation

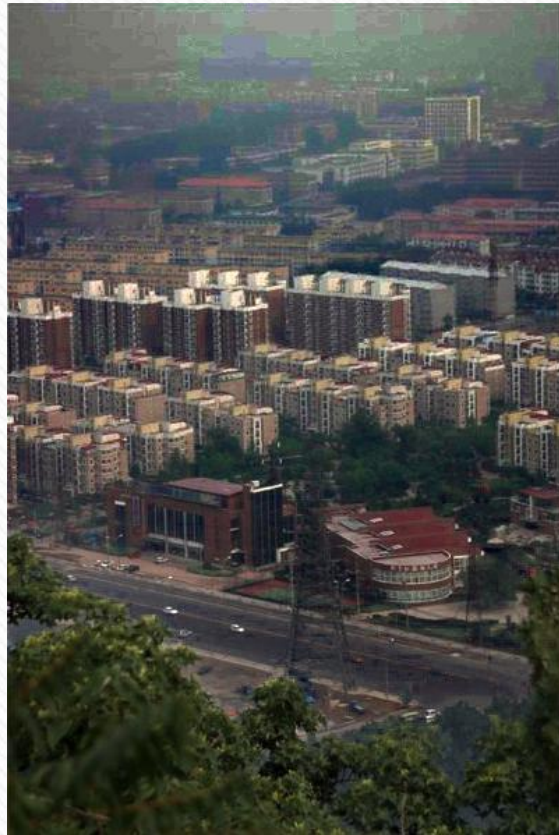


Auto Contrast

Sky Region Operation



Original Image



Auto Contrast



Sky Region Operation

$$J(x) = \frac{I(x) - A}{\max[t(x), t_0]} + A$$



$$J(x) = \frac{I(x) - A}{\min\left(\max\left(\frac{K}{|I(x) - A|}, 1\right) \cdot \max(t(x), t_0), 1\right)} + A$$

Comparison between $I(x)$ and A :
 $|I(x) - A| > K \rightarrow$ Normal Region
 $|I(x) - A| < K \rightarrow$ Sky Region



Original Image



MATLAB Image



Haze Removed Image

MORE RESULTS

12



Original Image



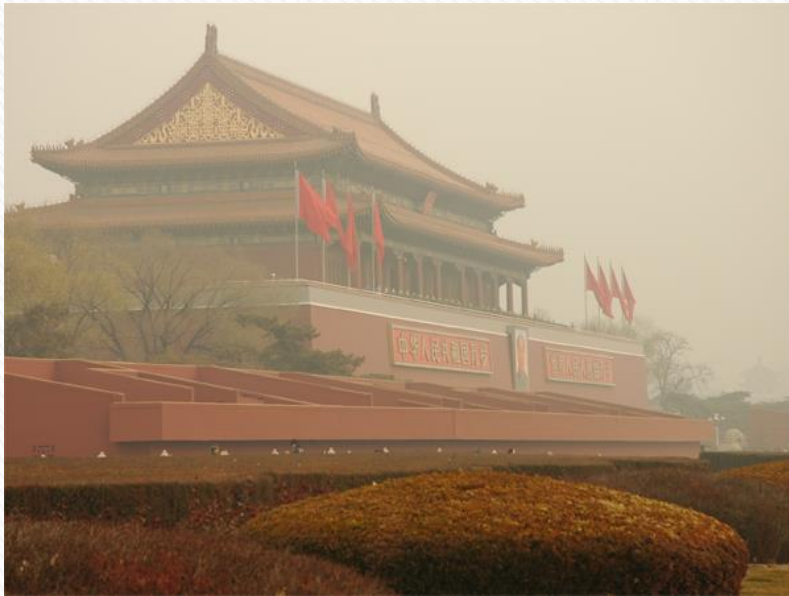
MATLAB Image



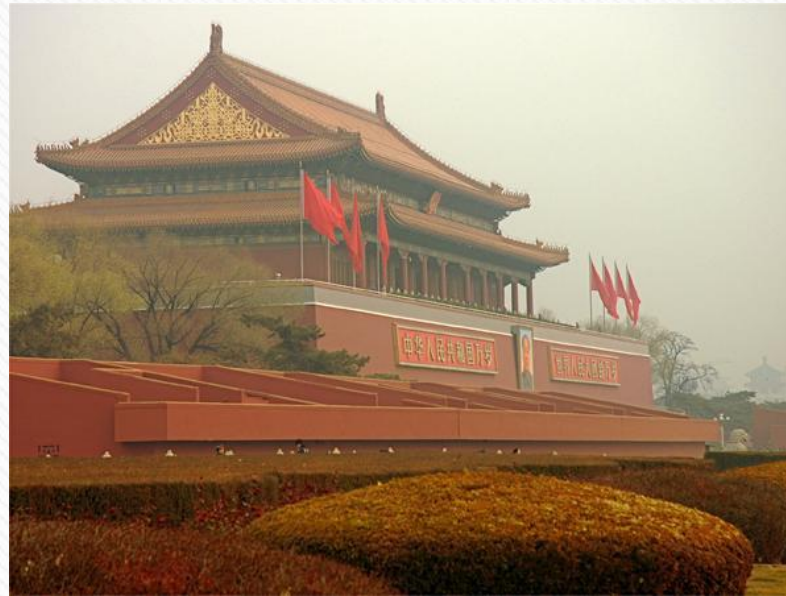
Haze Removed Image

MORE RESULTS

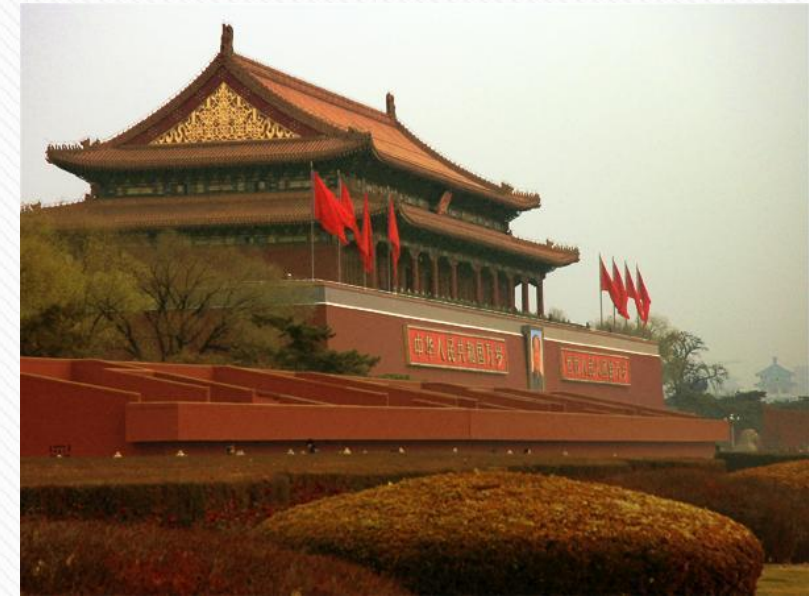
13



Original Image



MATLAB Image



Haze Removed Image

REFERENCE

- [1] Kaiming He, Jian Sun and Xiaoou Tang, "Single Image Haze Removal Using Dark Channel Prior", *IEEE Transactions on Pattern Analysis and Machine Intelligence*, vol. 33, no. 12, pp. 2341-2353, 2011.
- [2] Kaiming He, Jian Sun and Xiaoou Tang, "Guided Image Filtering", *IEEE Transactions on Pattern Analysis and Machine Intelligence*, vol. 35, no. 6, pp. 1397-1409, 2013.
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- [6] "局部自适应自动色阶/对比度算法在图像增强上的应用。 - Imageshop - 博客园", *Cnblogs.com*, 2018. [Online]. Available: <http://www.cnblogs.com/Imageshop/p/3395968.html>. [Accessed: 05- Jun- 2018].