

Task: get the b-a curve of values such that there exists the optimal period 4 sink somewhere near the location of the stable-unstable manifold tangency.

Given two starting b, and corresponding a for period 4 sink along with the point p_xy, I am able to calculate all the remaining points on the curve b-a for the optimal period 4 sink, ie trace of $DF^4(p_{xy})$ is numerically zero (my average is around the order of 10^{-9} , however if I run the program slower to a higher accuracy, it can get to 10^{-14}).

My method works similar to the previous one I used for calculating the manifold tangencies, where I used a linear approximation of the previous two parameters to calculate the next initial guess. In the code, it looked like this:

```
slope_a = np.double((a_4sink[i-1] - a_4sink[i-2]) / (b_i[i-1] - b_i[i-2]))
slope_px = np.double((px_4sink[i-1] - px_4sink[i-2]) / (b_i[i-1] - b_i[i-2]))
slope_py = np.double((py_4sink[i-1] - py_4sink[i-2]) / (b_i[i-1] - b_i[i-2]))

a_guess = a_4sink[i-1] + slope_a*(b_i[i] - b_i[i-1])
px_guess = px_4sink[i-1] + slope_px*(b_i[i] - b_i[i-1])
py_guess = py_4sink[i-1] + slope_py*(b_i[i] - b_i[i-1])
```

The main difference in the program is that afterwards, I also take advantage of the fact we are working with a sink, and to improve accuracy, I use Newton's Method again with points px_better, py_better, which take the given p_x, p_y I obtained with the first root-solver, and then iterate with the Henon map 10,000 times by period 4, or 40,000 times total. This looks like this:

```
sink4_i = optimize.fsolve(F_sink, [a_guess, px_guess, py_guess, dx_4sink[i-1], dy_4sink[i-1]], xtol = 0.1)
better_p = NhMap_n(sink4_i[0], b_val, sink4_i[1], sink4_i[2], 4, 10000)
sink4_i = optimize.fsolve(F_sink, [sink4_i[0], better_p[0], better_p[1], sink4_i[3], sink4_i[4]], xtol = 0.1)
```

This method of correction increases the precision of the root-solver, which I verify by observing the relative error of the initial guess inputted into the Newton Method, and the outputted root. For the second newton method with the better p-values, the relative error is 1/10 or 1/100 of the first.

Furthermore, I verify the quality of my method by taking the final p-value, iterating it 10,000 times, and calculating the distance of the two values. It is never more than 10^{-10} . What's more, the trace of DF^4 of both values is not more than about 10^{-9} . Here is a sample result.

```

...
b: -0.34979999999999994
a: 1.1366654951793924
dx: -8744601338.01051
dy: 1523375629913.158
p: 1.3925187422889855 , -0.01305465693820011
4p: (1.3925187422856329, -0.01305465690311669)
4*10,000p: [1.3925187422868166, -0.013054656913321083]
^Trace DF4: 1.1212298346718885e-09
p-F Error: [array([-3.34399175e-12]), array([3.50184708e-11]), 3.3526514897630477e-12, -3.5083418808978806e-11, -4.5
97945253703717e-10]
10,000 4p-Error: [array([4.21884749e-15]), array([-2.15383267e-14]), 2.220446049250313e-16, -1.6653345369377348e-15,
1.1212298346718885e-09]
p sink diff error: 2.4973389749644544e-11
-----

```

The Error arrays above are from putting in the obtained root into F_{sink} , my error function I wanted to minimize in R^5 .

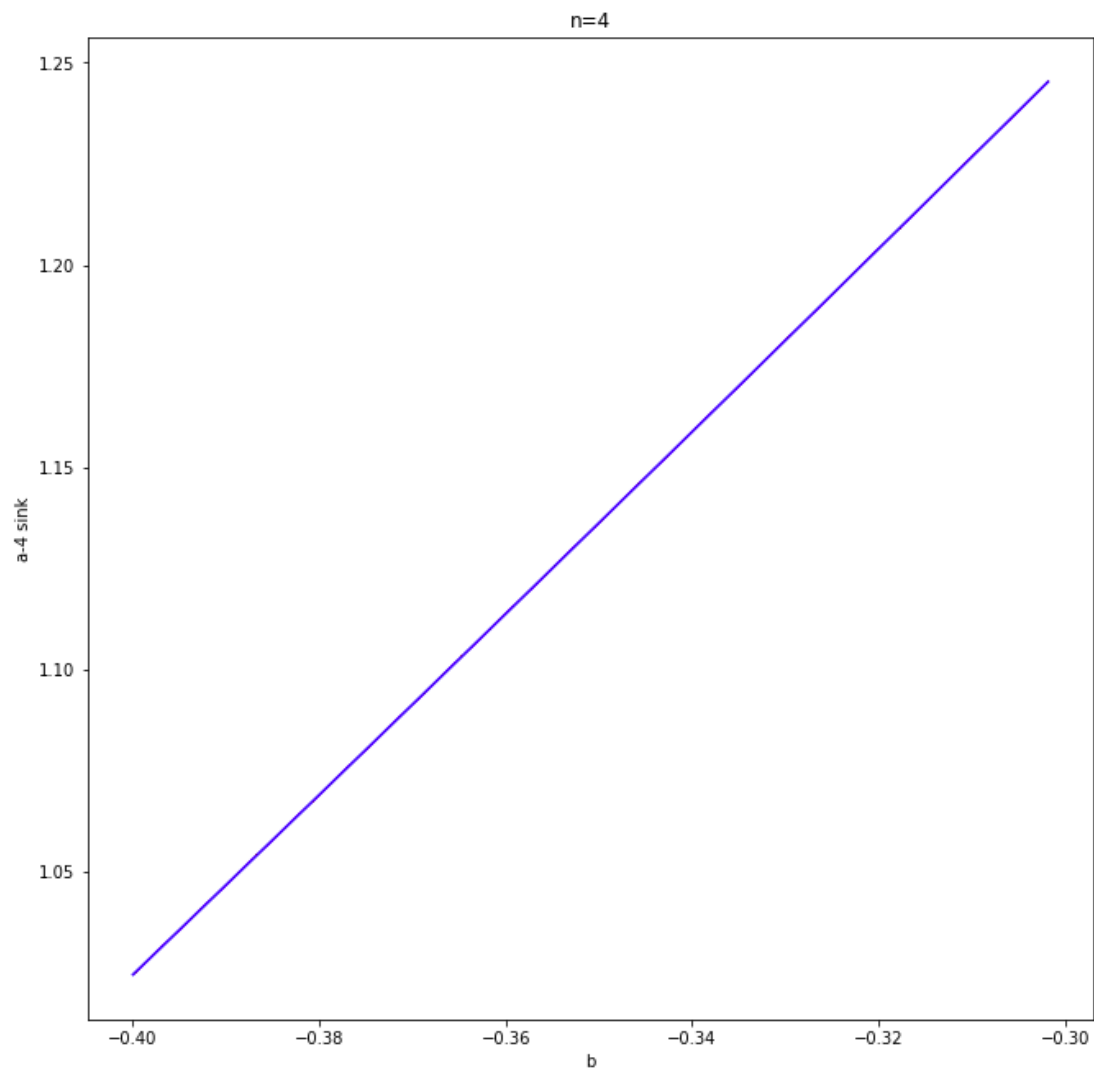
I also verified the points I was getting are in fact prime period 4. For some arbitrary point 1.3959993191801434 , -0.013172686175069824 with corresponding sink parameters (b,a) as (-0.35179999999999995, 1.13216811838981), the orbit of the point goes as follows:

```

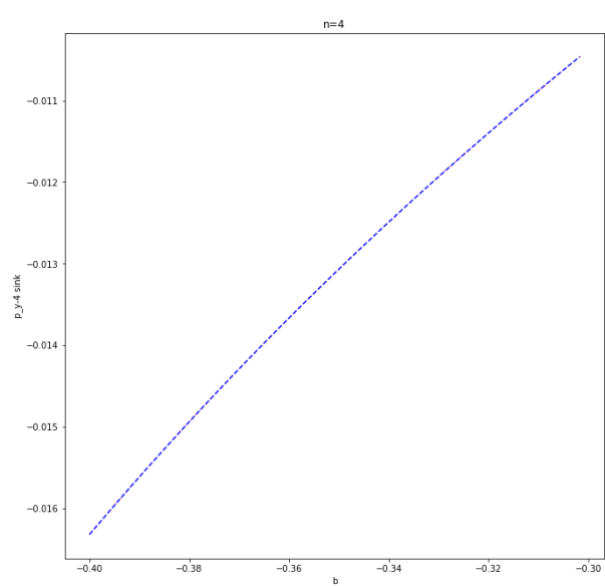
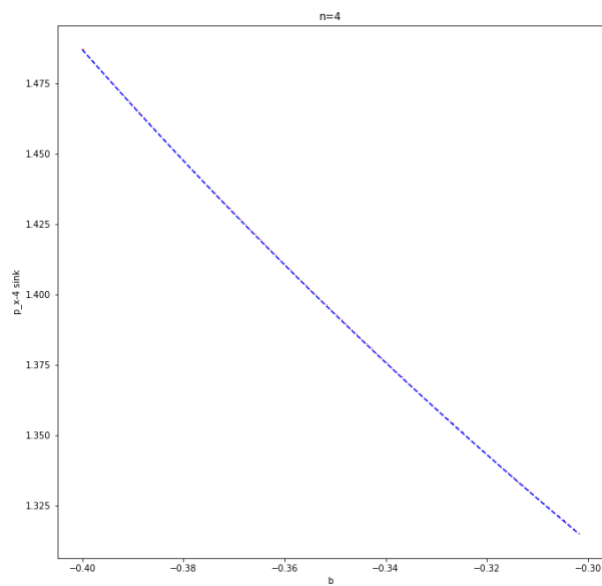
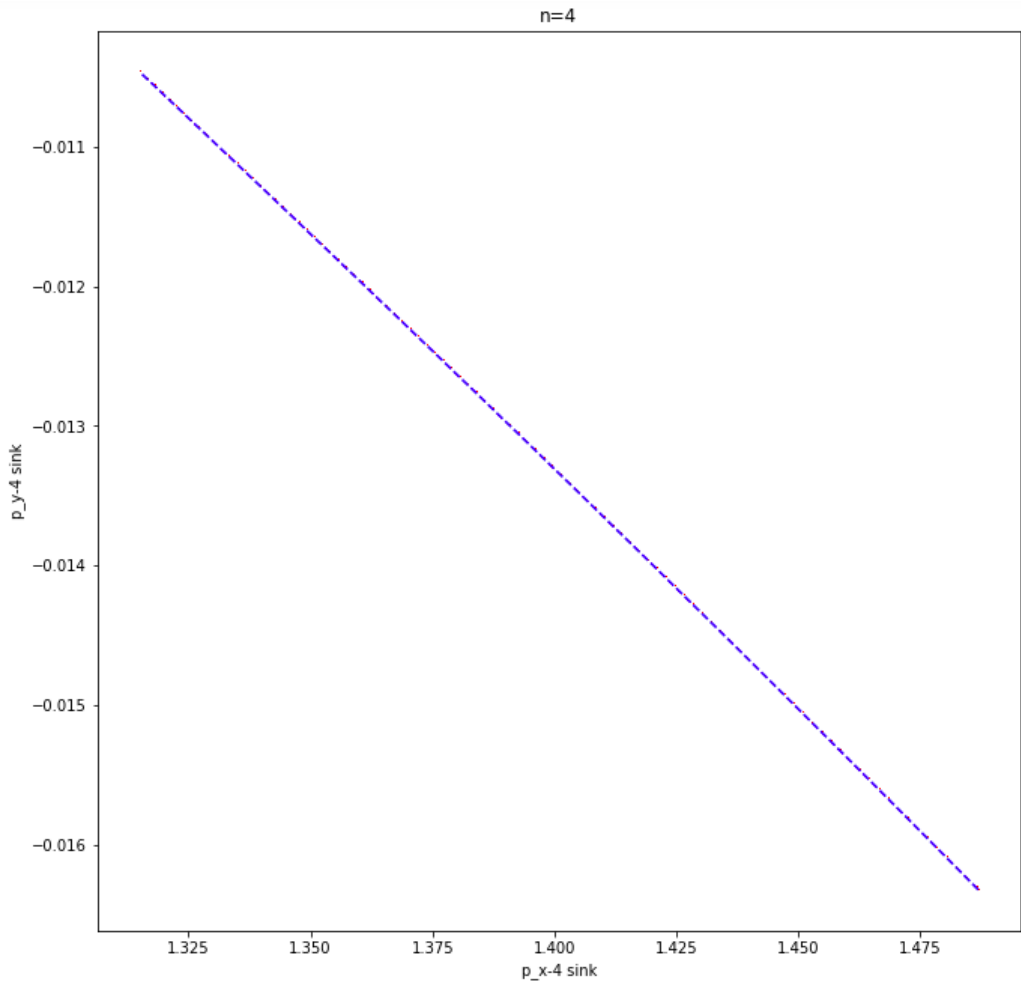
0 : (1.3959993191801434, -0.013172686175069824)
1 : (-1.2017510407314107, 1.3959993191801434)
2 : (-1.1261960563352322, -1.2017510407314107)
3 : (-0.013172686245485232, -1.1261960563352322)
4 : (1.3959993191884605, -0.013172686245485232)

```

Now I will show graphs of my results. This is the b-a curve for the n=4 sink:

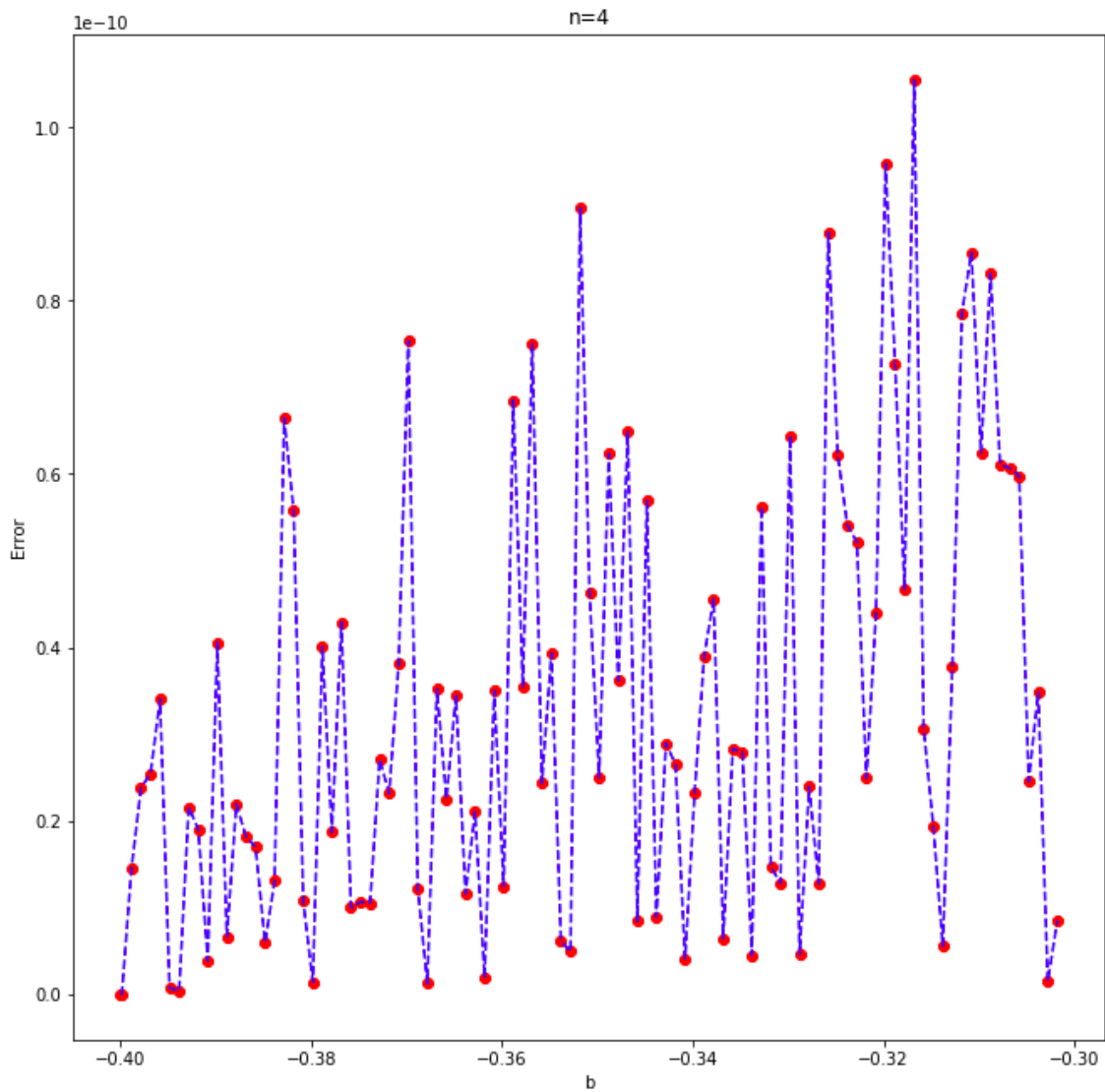


Here is how the period 4 point p_{xy} changes while varying b , along with the individual coordinates with b as an axis next.

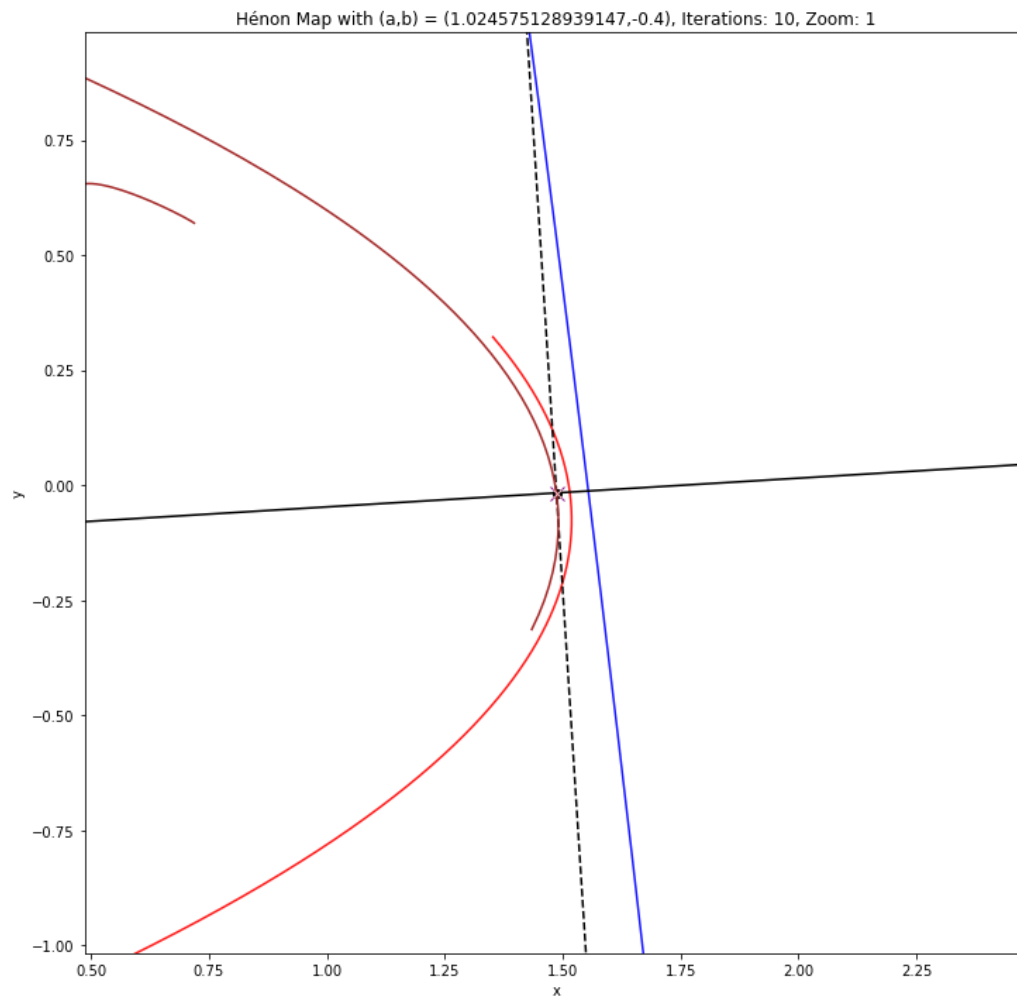


And here is the error I described above by calculating the difference between the final point and the 40,000th iterate of it. The average is on top.

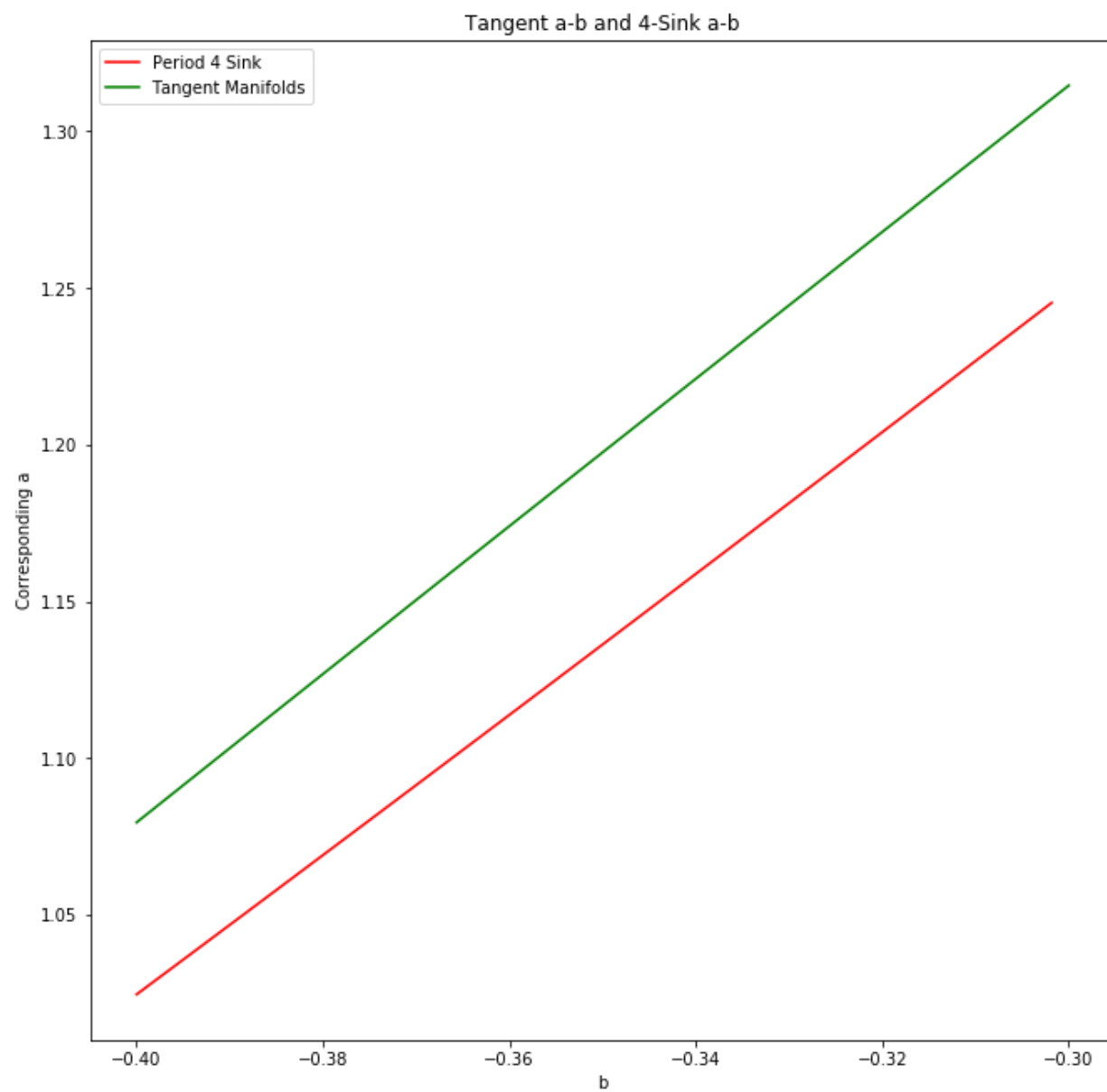
3.26081833322675e-11



Here is an image of what one of these points looks like geometrically, for $b = -0.4$, along with the stable manifold, the line with directions dx, dy obtained through the algorithm, the corresponding perpendicular line's image under the Henon 4-Map, and periodic point p itself.



Finally, I graph the tangent curve along with the period 4 sink.



I ran into a few problems while trying to do this, but was able to resolve them. First, there was a big issue with the point I obtained, p_{xy} , let's say 1.396 , -0.01317 converging to some fixed point around approximately (0.5, 0.5) after I iterated 40,000 times. This tended to happen if my a -value was too far off, which had to be resolved by taking the linear guess instead of the previous result, when my increase in b was too large. Furthermore, I found that using the p_{better} values and re-doing the Newton method helped too. Therefore for each iteration of b , I use root finding twice. However, with all the precautions I took to ensure accurate starting parameters, I was able to run the program to get the a values for $b=[-0.4,-0.3]$ in about 5 minutes.

Next, I am planning to do further work in the other tasks you've asked me to do, such as make an algorithm to find the most optimal starting guess a for an arbitrary period n . I will try this in the method we've discussed, first by trying the smarter bisection search. Then I will try to make my algorithm itself work for arbitrary n , for now I've only got it coded for $n=4$, but that shouldn't be a difficult thing to change.

Thank you for your time.