

Quick Overview:Week05

- Introduction to Communication/Network
- 5-0 Circuit Bending Workshop
- 5-1 Sharing Sensor Data over the Internet
- 5-2 Motion Tracking using Kinnect

5-0 Circuit Bending Exercise

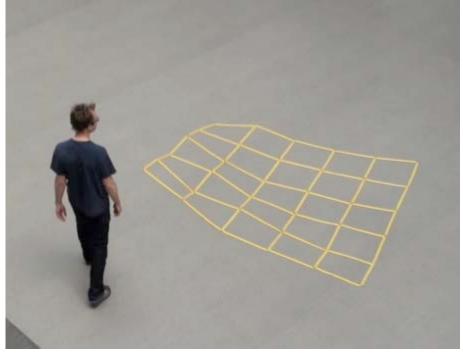
- 1. Identify the operating voltage of the device. (battery/ AC adaptor)
 - Find out Power/GND lines, how they are routed.
 - Solder+Extend them into the power rows of BreadBoard.
- 2. List up INPUTs/OUTPUTs and their functions of the device.
 - INPUT: Buttons, Switches, microphone etc...
 - OUTPUT: Displays, LED, Speaker, motor, etc...
 - Function: alarm, warning, trigger gun shot etc...
- 3. Solder + Extend INPUT/OUTPUT signals to the bread board.
- 4. Try if those INPUT/OUTPUT can be triggered from other signals (POWER/GND etc...).
- 5. Check if the machine can be operatable by arduino 5v power out.
 - IF yes -> use arduino input/output to control those signal.

DON'T BE AFRAID OF BRAKING THE DEVICE!

Internet of the things

- Tele-Present Water (David Bowen)
 http://www.dwbowen.com/tele water.html
- Tele-Present Wind (David Bowen)
 http://www.dwbowen.com/telewind.html



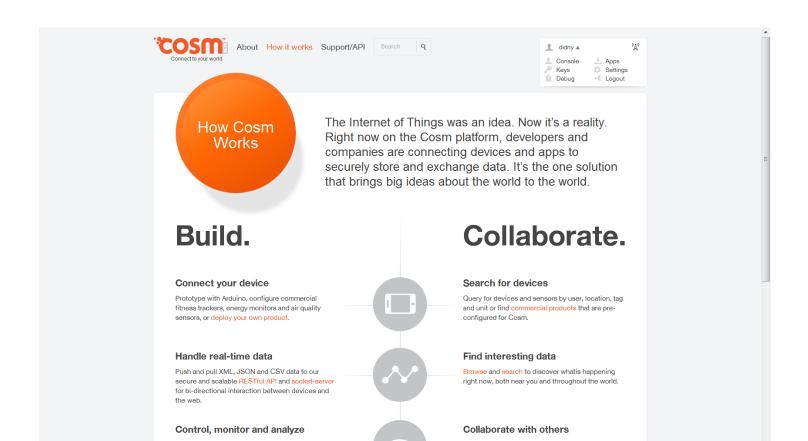


5-1 Arduino <-> Internet

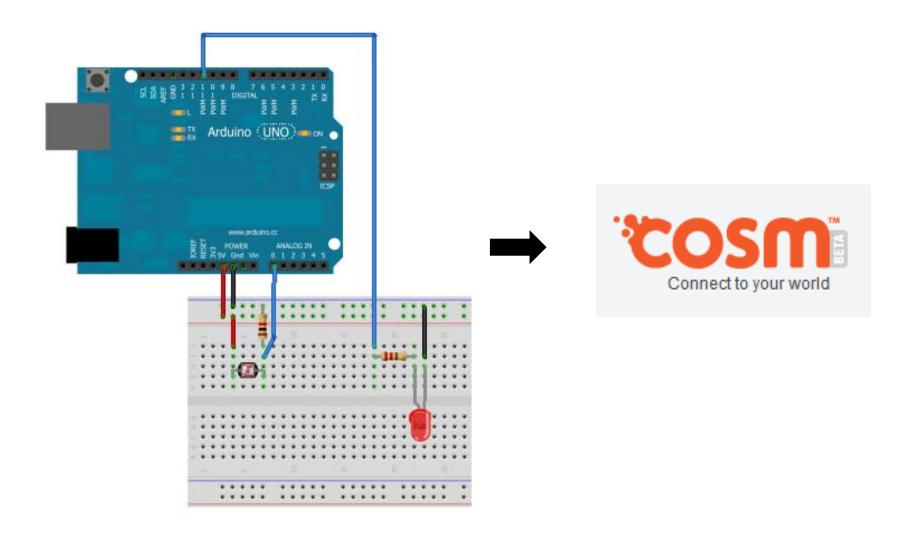
Sharing Sensor data over COSM: https://cosm.com/

Bio Media Art Workshop(Tama Art University: in JP):

http://yoppa.org/tau bmaw12

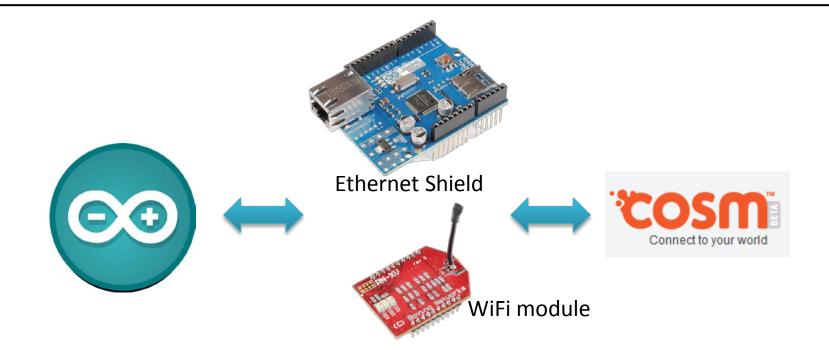


Sharing LightSensor(LDR) data over the Internet



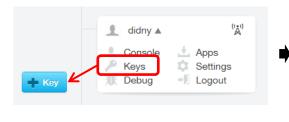
Various ways to share sensor data over the Internet

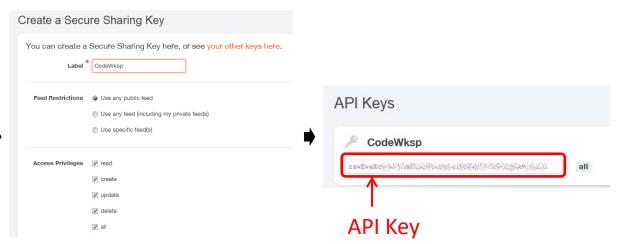




Uploading sensor feed to COSM

- Create an account on COSM & Log in
- 2. Create an API Key
 - Label: CodeWksp (or any name)
 - Feed Restrictions: Use any public feed
 - Access Privilege: All





3. Install Cosm-Processing-Library

https://github.com/jmsaavedra/Cosm-Processing-Library/blob/master/distribution/cosm-1/download/cosm.zip

Copy an unzipped folder into

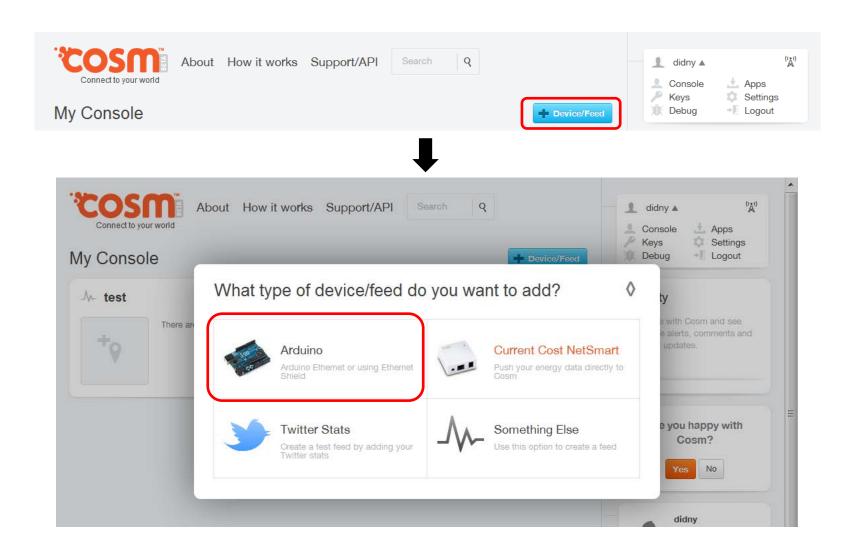
Windows:

\Documents\processing\libraries

Mac:

/Document/processing/libraries

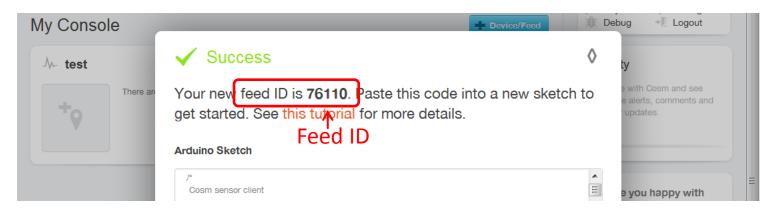
4. Create a sensor feed on COSM



4. Create a sensor feed on COSM



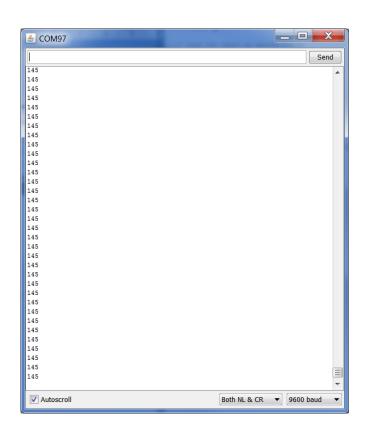




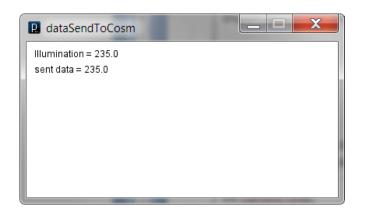
Arduino Code:

\01.dataSendToCosm\arduino\cosmSendReceive\

```
// an LED connected on Pin11.
int led = 11;
// the setup routine runs once when you press reset:
void setup() {
 // initialize the digital pin as an output.
 pinMode(led, OUTPUT);
 Serial.begin(9600);
// the loop routine runs over and over again forever:
void loop() {
 // Read the Sensor Input AO and send a value to the Serial Port.
 int sensorValue = analogRead(A0);
 // print out the value you read:
 Serial.println(sensorValue);
```



Processing Code



```
import cosm.*;
DataOut feed;
String apiKey = "YOUR_API_KEY";
String feedId = "YOUR FEED ID";
int sendInterval = 1000;
feed = new DataOut(this, apiKey, feedId);
void sendVal() {
 feed.setStream(0, illumination);
 sentData = illumination;
```

Retrieving data from COSM

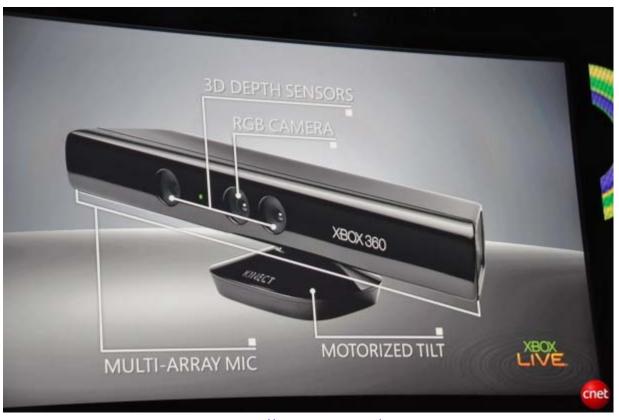
```
import cosm.*;
DataIn feed;
String apiKey = "YOUR API KEY";
String feedId = "YOUR FEED ID";
feed = new DataIn(this, apiKey, feedId);
void requestData() {
 feed.connect();
 feedValues[count] = feed.getValue(0);
 println(feedValues[count]);
 count = ++count % width;
```

Motion Tracking

Audience: http://random-international.com/work/audience/



Microsoft Kinnect



http://reviews.cnet.com/8301-21539 7-20007665-10391702.html

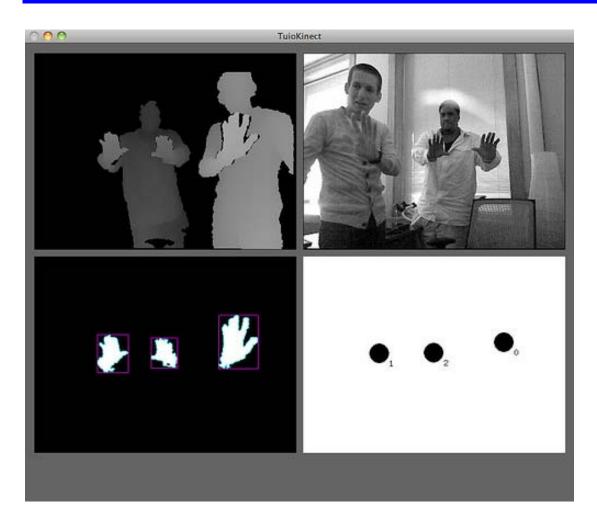
Kinnect Hack

http://www.engadget.com/2010/11/19/kinect-hack-creates-worlds-greatest-shadow-puppet-video/



TUIO Kinnect

http://code.google.com/p/tuiokinect/



http://vimeo.com/21525588t

Assignment Wk05

- 01: Attach a sensor(s) in your home/studio environment and record/share a daily activity over COSM.
 - (ex. Pressure sensor -> Chair = Chair Usage)
- 02: Create an object that respond to the value changes of a sensor feed on COSM.