Comparing the two approaches

- Approach 1: Triangular Matrix
 - n = total number items
 - Count pair
 - Keep pair
 - **1**,2}, {1,3
 - Pair {i, j} is
 - Total numl
 - Triangular
- Approach : with count :

Problem is if we have too many items so the pairs do not fit into memory.

Can we do better?

but only for pairs

Beats Approach 1 if less than 1/3 of possible pairs actually occur

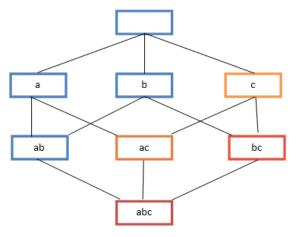
A-Priori Algorithm

A-Priori Algorithm – (1)

- A two-pass approach called A-Priori limits the need for main memory
- Key idea: monotonicity (单调性)
 - If a set of items *I* appears at least *s* times, so does every **subset** *J* of *I*
- Contrapositive for pairs:

If item i does not appear in s baskets, then no pair including i can appear in s baskets

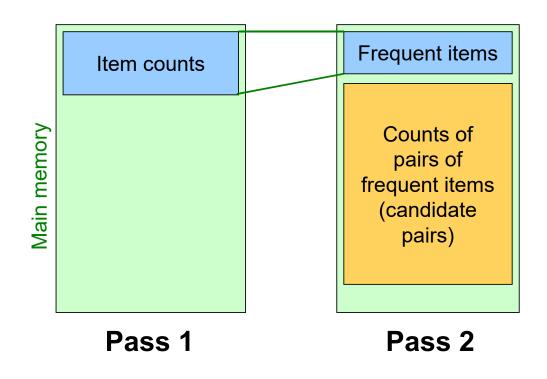
So, how does A-Priori find freq. pairs?



A-Priori Algorithm – (2)

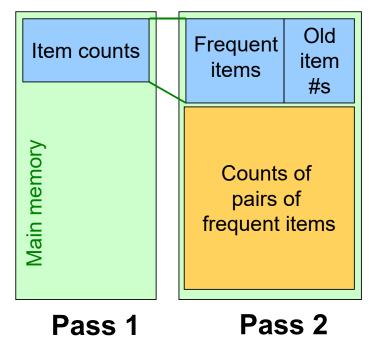
- Pass 1: Read baskets and count in main memory the occurrences of each individual item
 - Requires only memory proportional to #items
- Items that appear $\geq s$ times are the frequent items
- Pass 2: Read baskets again and count in main memory <u>only</u> those pairs where both elements are frequent (from Pass 1)
 - Requires memory proportional to square of frequent items only (for counts)
 - Plus a list of the frequent items (so you know what must be counted)

Main-Memory: Picture of A-Priori



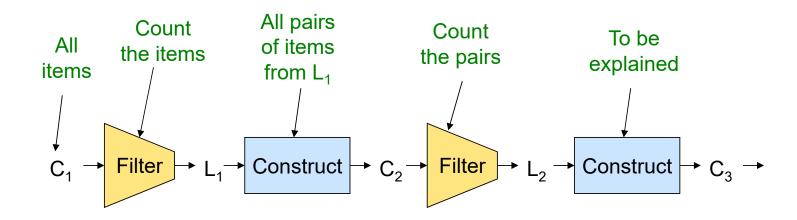
Detail for A-Priori

- You can use the triangular matrix method with n = number of frequent items
 - May save space compared with storing triples
- Trick: re-number frequent items 1,2,... and keep a table relating new numbers to original item numbers



Frequent Triples, Etc.

- For each k, we construct two sets of k-tuples (sets of size k):
 - $C_k = candidate \ k$ -tuples = those that might be frequent sets (support \geq s) based on information from the pass for k-1
 - L_k = the set of truly frequent k-tuples



Example

Hypothetical steps of the A-Priori algorithm

- $C_1 = \{ \{b\}, \{c\}, \{j\}, \{m\}, \{n\}, \{p\} \} \}$
- Count the support of itemsets in C₁
- Prune non-frequent: L₁ = { b, c, j, m }
- Generate C₂ = { {b,c}, {b,j}, {b,m},{c,j},{c,m},{j,m} }
- Count the support of itemsets in C₂
- Prune non-frequent: L₂ = { {b,c}, {b,m}, {c,m}, {c,j} }
- Generate $C_3 = \{\{b,c,j\}, \{b,c,m\}, \{b,m,j\}, \{c,m,j\}\}$
- Count the support of itemsets in C₃
- Prune non-frequent: L₃ = { {b,c,m} }

** Note here we generate new candidates by generating C_k from L_{k-1} and L_1 . But that one can be more careful with candidate generation. For example, in C_3 we know {b,m,j} cannot be frequent since {m,j} is not frequent

A-Priori for All Frequent Itemsets

- One pass for each k (itemset size)
- Needs room in main memory to count each candidate k-tuple
- For typical market-basket data and reasonable support (e.g., 1%), k = 2 requires the most memory
- What if A-Priori runs out of memory for k = 2?

PCY (Park-Chen-Yu) Algorithm

PCY (Park-Chen-Yu) Algorithm

- Observation: In pass 1 of A-Priori, most memory is idle
 - We store only individual item counts
 - Can we use the idle memory to reduce memory required in pass 2?
- Pass 1 of PCY: In addition to item counts, maintain a hash table with as many buckets as fit in memory
 - Keep a count for each bucket into which pairs of items are hashed
 - For each bucket just keep the count, not the actual pairs that hash to the bucket!

PCY Algorithm – First Pass

Few things to note:

- Pairs of items need to be generated from the input file; they are not present in the file
- We are not just interested in the presence of a pair, but we need to see whether it is present at least s (support) times

Observations about Buckets

- Observation: If a bucket contains a frequent pair, then the bucket is surely frequent
- However, even without any frequent pair, a bucket can still be frequent ☺
 - So, we cannot use the hash to eliminate any member (pair) of a "frequent" bucket
- But, for a bucket with total count less than s, none of its pairs can be frequent ©
 - Pairs that hash to this bucket can be eliminated as candidates (even if the pair consists of 2 frequent items)
- Pass 2: Only count pairs that hash to frequent buckets

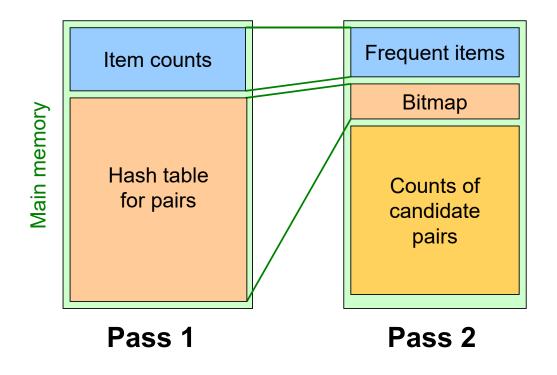
PCY Algorithm – Between Passes

- Replace the buckets by a bit-vector:
 - 1 means the bucket count exceeded the support s (call it a frequent bucket); 0 means it did not
- 4-byte integer counts are replaced by bits, so the bit-vector requires 1/32 of memory
- Also, decide which items are frequent and list them for the second pass

PCY Algorithm – Pass 2

- Count all pairs {i, j} that meet the conditions for being a candidate pair:
 - 1) Both i and j are frequent items
 - 2) The pair {i, j} hashes to a bucket whose bit in the bit vector is 1 (i.e., a frequent bucket)
 - Both conditions are necessary for the pair to have a chance of being frequent

Main-Memory: Picture of PCY



Main-Memory Details

- Buckets require a few bytes each:
 - Note: we do not have to count past s
 - #buckets is O(main-memory size)
- On second pass, a table of (item, item, count) triples is essential (we cannot use triangular matrix approach, why?)
 - Thus, hash table must eliminate approx. 2/3 of the candidate pairs for PCY to beat A-Priori

Refinement: Multistage Algorithm & Multihash

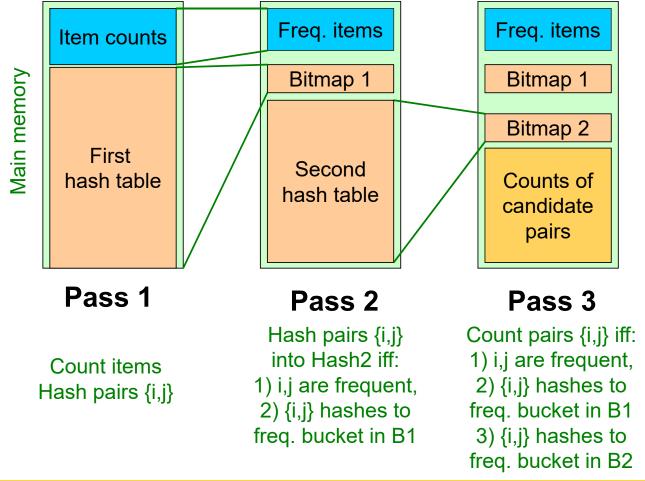
Refinement: Multistage Algorithm

- Limit the number of candidates to be counted
 - Remember: Memory is the bottleneck
 - Still need to generate all the itemsets but we only want to count/keep track of the ones that are frequent
- Key idea: After Pass 1 of PCY, rehash only those pairs that qualify for Pass 2 of PCY
 - 1) i and j are frequent, and
 - 2) {i, j} hashes to a frequent bucket from Pass 1
- On middle pass, fewer pairs contribute to buckets, so fewer false positives
- Drawback: Requires 3 passes over the data

Multistage – Pass 3

- Count only those pairs {i, j} that satisfy these candidate pair conditions:
 - 1) Both i and j are frequent items
 - 2) Using the first hash function, the pair hashes to a bucket whose bit in the first bit-vector is 1
 - 3) Using the second hash function, the pair hashes to a bucket whose bit in the second bit-vector is 1

Main-Memory: Multistage



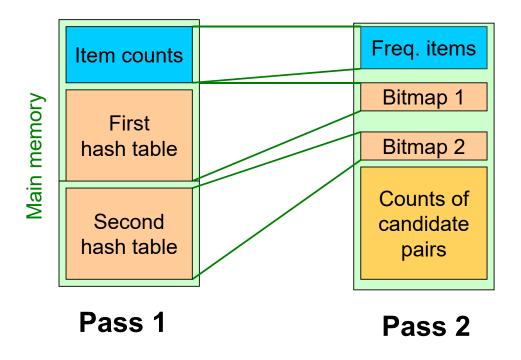
Important Points

- 1. The two hash functions have to be independent
- 2. We need to check both hashes on the third pass
 - If not, we would end up counting pairs of frequent items that hashed first to an infrequent bucket but happened to hash second to a frequent bucket

Refinement: Multihash

- Key idea: Use several independent hash tables on the first pass
- Risk: Halving the number of buckets doubles the average count
 - We have to be sure most buckets will still not reach count s
- If so, we can get a benefit like multistage, but in only 2 passes

Main-Memory: Multihash



PCY: Extensions

- Either multistage or multihash can use more than two hash functions
- In multistage, there is a point of diminishing returns, since the bit-vectors eventually consume all of main memory
- For multihash, the bit-vectors occupy exactly what one PCY bitmap does, but too many hash functions makes all counts > s

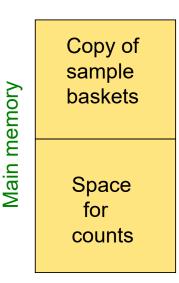
Frequent Itemsets in ≤ 2 Passes: Random sampling&SON&Toivonen(托伊沃宁算法)

Frequent Itemsets in ≤ 2 Passes

- A-Priori, PCY, etc., take k passes to find frequent itemsets of size k
- Can we use fewer passes?
- Use 2 or fewer passes for all sizes, but may miss some frequent itemsets
 - Random sampling
 - SON (Savasere, Omiecinski, and Navathe)
 - Toivonen (托伊沃宁算法, see textbook)

Random Sampling (1)

- Take a random sample of the market baskets
- Run a-priori or one of its improvements in main memory
 - So we don't pay for disk I/O each time we increase the size of itemsets
 - Reduce support threshold proportionally to match the sample size



Random Sampling (2)

- Optionally, verify that the candidate pairs are truly frequent in the entire data set by a second pass (avoid false positives)
- But you don't catch sets frequent in the whole but not in the sample
 - Smaller threshold, e.g., s/125, helps catch more truly frequent itemsets
 - But requires more space

SON Algorithm – (1)

- Repeatedly read small subsets of the baskets into main memory and run an in-memory algorithm to find all frequent itemsets
 - Note: we are not sampling, but processing the entire file in memorysized chunks
- An itemset becomes a candidate if it is found to be frequent in any one or more subsets of the baskets.

SON Algorithm – (2)

- On a second pass, count all the candidate itemsets and determine which are frequent in the entire set
- Key "monotonicity" idea: an itemset cannot be frequent in the entire set of baskets unless it is frequent in at least one subset.

SON – Distributed Version

- SON lends itself to distributed data mining
- Baskets distributed among many nodes
 - Compute frequent itemsets at each node
 - Distribute candidates to all nodes
 - Accumulate the counts of all candidates

SON: Map/Reduce

- Phase 1: Find candidate itemsets
 - Map?
 - Reduce?
- Phase 2: Find true frequent itemsets
 - Map?
 - Reduce?

第一次作业

- Here is a collection of twelve baskets. Each contains three of the six items 1 through 6. $\{1, 2, 3\}$ $\{2, 3, 4\}$ $\{3, 4, 5\}$ $\{4, 5, 6\}$ $\{1, 3, 5\}$ $\{2, 4, 6\}$ $\{1, 3, 4\}$ $\{2, 4, 5\}$ $\{3, 4, 6\}$ Suppose the support threshold is 4. On the first pass of the PCY Algorithm we use a hash table with 11 buckets, and the set $\{i, j\}$ is hashed to bucket $i \times j$ mod 11.
 - (a) By any method, compute the support for each item and each pair of items.
 - (b) Which pairs hash to which buckets?
 - (c) Which buckets are frequent?
 - (d) Which pairs are counted on the second pass of the PCY Algorithm?

备注:在学习通《大数据分析》(邀请码84967919)中作业里提交答案。最晚提交时间:2022.12.31下午6点