## Homework 4

## Kyle Kazemini

November 10, 2020

(1)

(a)

```
import pandas as pd
import numpy as np
from numpy import linalg as LA
from scipy import linalg
from google.colab import files
files.upload()
files.upload()
files.upload()
# Question 1
x = pd.read_csv("X4.csv")
y = pd.read_csv("y4.csv")
# part (a)
def func(x, y):
 return x + y
def func_grad(vx, vy):
 dfdx = vx
 dfdy = vy
 for i in range(1, len(x)):
   dfdx = dfdx + x.iloc[i][0]
   dfdy = dfdy + y.iloc[i][0]
 return np.array([dfdx, dfdy])
#initialize location and settings
v_init = np.array([29,4])
num_iter = 10
values = np.zeros([num_iter,2])
values[0,:] = v_init
v = v_init
gamma = 0.000001
# actual gradient descent algorithm
for i in range(1,num_iter):
 v = v - gamma * func_grad(v[0],v[1])
 values[i,:] = v
```

## print(values)

## (b)

```
# part (b)
def func(x, y):
 return x + y
def func_grad(vx, vy):
 dfdx = vx
 dfdy = vy
 return np.array([dfdx, dfdy])
#initialize location and settings
v_init = np.array([5,4])
num_iter = 10
values = np.zeros([num_iter,2])
values[0,:] = v_init
v = v_{init}
gamma = 0.00025
# actual gradient descent algorithm
for i in range(1,num_iter):
 v = v - gamma * func_grad(v[0],v[1])
 values[i,:] = v
print(values)
```

 $\begin{array}{c} [[5.\ 4.\ ]\ [4.99999875\ 3.999999\ ]\ [4.9999975\ 3.999998\ ]\ [4.99999625\ 3.999997\ ]\ [4.999995\ 3.999996\ ]\ [4.99999375\ 3.999995\ ]\ [4.9999925\ 3.999994\ ]\ [4.99999125\ 3.999993\ ]\ [4.9999992\ ]\ [4.999998875\ 3.999991\ ]\ ] \\ \end{array}$ 

I prefer incremental gradient descent. I think it's a little bit easier to implement and to explain. Although the results of the data analysis method of choice are very important, I think ease of use/implementation and complexity should also be considered. It may not be worth it to get marginally better results if it's much harder to understand and explain to a non-expert. I'm thinking generally, but I prefer incremental gradient descent for these reasons.

(2)

(a)

False. The left singular vectors of A are in  $\mathbb{R}^{100}$ .

(b)

True. The right singular vectors of A are in  $\mathbb{R}^8$  and this fact follows from the properties of singular vectors.

(d)

rank(B) = 2. From the textbook, we know that  $u_j v_j^T$  is an  $n \times d$  (in this case 100 x 8) matrix with rank 1. Thus, B is the sum of two rank 1 matrices, so rank(B) = 2.

(e)

 $B \in \mathbb{R}^{100x8}$ . That is, B is a 100 x 8 matrix. It has 100 rows and 8 columns.

(f)

 $||Bv_3|| = 0$ . We know that V is an orthogonal matrix, which means that the inner product of any two columns of V is 0.  $v_3$  is one of these columns and the matrix B is constructed from two of the columns  $v_1$  and  $v_2$ . Thus, the inner product of any column of B with any column of V is 0. This implies that  $||Bv_3|| = 0$ .

(3)

(a)

```
# Question 3
A = pd.read_csv("A.csv")
A = np.matrix(A)
U, s, VT = LA.svd(A)
# part (a)
print(s[2]) # The second singular value of A.
```

4.044276734606446

(b)

```
# part (b)
print(LA.matrix_rank(A))
# Equivalently, the rank of A is the number of non-zero values in the diagonal of S, which, of
    course, is also 6.
```

6

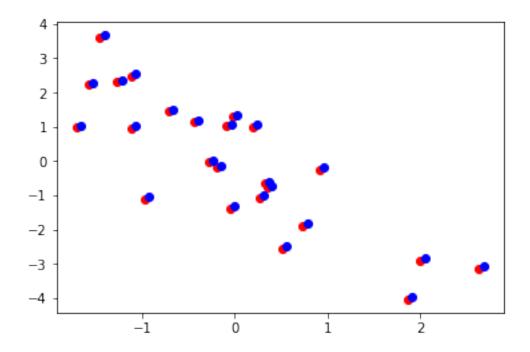
(c)

```
# part (c)
# This is one of the formulations for eigenvalues and eigenvector in relation to SVD given in the
    textbook.
V = VT.transpose()
ATA = A.transpose() @ A
ATAV = ATA @ V
values, vectors = LA.eig(ATAV)
values = np.array(values)
vectors = np.matrix(vectors)
for item in values: # iterates over the list of eigenvalues
 print(item)
for item in np.nditer(vectors): # iterates over the list of eigenvectors
 print(item)
Eigenvalues:
   (5.059811832100812+74.07158537850441j)
(5.059811832100812-74.07158537850441j)
(-6.382863207749627+4.604796316400085j)
(-6.382863207749627-4.604796316400085j)
(0.11425707371163266 + 0.8888922016380596j)
(0.11425707371163266-0.8888922016380596j)
(-1.56983268123683e-14+0j)
   Eigenvectors:
   (0.04621761376141394-0.19643866141982957j)
(0.04621761376141394 + 0.19643866141982957j)
(-0.014647891841361293+0.009796886169846628j)
(-0.014647891841361293-0.009796886169846628j)
(0.0005323507399805442 + 0.00016061845788768769j)
(0.0005323507399805442-0.00016061845788768769j)
(-5.056306957211146e-19+0j)
   (0.22143897303542198 + 0.2318447502598765j)
(0.22143897303542198-0.2318447502598765j)
(0.027643605206448714 - 0.008746534563436398j)
(0.027643605206448714 + 0.008746534563436398j)
(-0.0015853676849558835 + 0.001623538058213208j)
(-0.0015853676849558835-0.001623538058213208j)
(7.37569259419523e-17+0j)
   (-0.05661834016860583-0.1886957470177858j)
(-0.05661834016860583+0.1886957470177858j)
(-0.024837401398638798-0.18443336857974846j)
(-0.024837401398638798+0.18443336857974846j)
(0.012085721261557627 - 0.02499082867527697j)
```

```
(0.012085721261557627 + 0.02499082867527697j)
(1.0813967801868786e-16+0j)
   (0.7924700362053702+0j)
(0.7924700362053702-0j)
(-0.7885572562456546+0j)
(-0.7885572562456546-0j)
(0.0522941300381117 + 0.12641401716434617j)
(0.0522941300381117 - 0.12641401716434617j)
(1.1370940669304311e-15+0j)
   (0.24125237669841076-0.006507102898729435j)
(0.24125237669841076 + 0.006507102898729435j)
(-0.18747780301039746-0.39441207306474035j)
(-0.18747780301039746 + 0.39441207306474035j)
(0.1107537917827409 + 0.40422242818391957j)
(0.1107537917827409 - 0.40422242818391957j)
(2.135996058496008e-15+0j)
   (0.0034091889171940226 - 0.15631553672156234j)
(0.0034091889171940226 + 0.15631553672156234j)
(0.30109628118623755 + 0.020922524751886835j)
(0.30109628118623755-0.020922524751886835j)
(0.8489173061929061+0j)
(0.8489173061929061-0j)
(-3.970737886194188e-14+0j)
   (-0.23033341549060007 + 0.23221411299573305j)
(-0.23033341549060007-0.23221411299573305j)
(0.2297712189788535 + 0.08827985908846284j)
(0.2297712189788535-0.08827985908846284j)
(0.01893095623975588-0.28952997753322124j)
(0.01893095623975588 + 0.28952997753322124j)
(1+0j)
(d)
# part (d)
# Calculate the Frobenius norm using the definition from the textbook.
sum = 0
for i in s:
 if i > 4:
   sum = sum + i**2
sum
||A - A_k||_F^2 = 448.56785656660077.
```

(e)

```
# part (e)
S = linalg.diagsvd(s, 7, 7)
# Calculate the matrices for A_k where k = 3
UK = np.delete(U, np.s_[3:24], axis=1)
print(UK.shape)
S = np.delete(S, np.s_[3:7], axis=0)
SK = np.delete(S, np.s_[3:7], axis=1)
print(SK.shape)
VK = np.delete(V, np.s_[3:7], axis=1)
print(VK.shape)
AK = UK @ SK @ VK.transpose()
print(LA.norm(A - AK))
(24, 3)
(3, 3)
(7, 3)
||A - A_k||_2^2 = 2.247342094297741.
(f)
# part (f)
c = A.mean(0)
C = np.eye(24) - np.ones(24)/24
Acc = C @ A
import matplotlib.pyplot as plt
plt.plot(A[:,0],A[:,1],'ro')
plt.plot(Acc[:,0],Acc[:,1],'bo')
plt.show()
U, s, VT = LA.svd(Acc)
V = VT.transpose()
# Best 3-dimensional subspace
B = np.delete(V, np.s_[3:7], axis=1)
print(B)
# Calculate the Frobenius norm using the definition from the textbook.
sum = 0
for i in s:
 if i > 4:
   sum = sum + i**2
sum
```



 $||A - \pi_B(A)||_F^2 = 425.3664848278037.$ 

(g)

# part (g)

print(LA.norm(A - Acc))

 $||A - \pi_B(A)||_2^2 = 3.2989634685980516.$