(ii) preorder traversal fobaedhgi (iii) postorder traversal abdecgihf

Do you notice an interesting property of the in-order traversal? What is it?

(b) Let a binary search tree be defined by the following class:

```
public class IntTree {
    private IntTreeNode overallRoot;

// constructors and other methods omitted for clarity

private class IntTreeNode {
    public int data;
    public IntTreeNode left;
    public IntTreeNode right;

    // constructors omitted for clarity
}
```

In class, we saw how to search for an element in a binary search tree. This question will demonstrate that binary search trees are more powerful. Describe an algorithm that calculates the k'th smallest element in the tree. (k, the input, is a number in $\{1, 2, \dots, n\}$, where n is the number of nodes in the tree). You may find it helpful to modify the definition of IntTreeNode in order to accomplish this. Your algorithm should run in O(h) time, where h is the height of the tree. An O(n) solution will be given partial credit.

4. AVL Tree Implementation

Write pseudocode for the AVL tree methods Balance, RotateLeft, and RotateRight. Assume that the rest of the data structure is implemented as in the Java code here https://courses.cs.washington.edu/courses/cse373/18su/files/homework/AVLTree.java.

You may use the skeleton of Balance from that code as a guide. Note you are not required to write your solution in Java, pseudocode is sufficient.

5. Hashing

Let the capacity of the hash table be 10 and the hash function be h(x) = x. Insert elements

42, 102, 12, 33, 25, 14, 62

to a hash table

(Next page !)

- (a) that uses linear probing
- (b) that uses quadratic probing

Write down the total number of collisions and the hash table after all insertions in both cases. Why is the secondary clustering in quadratic probing less problematic than the primary clustering in linear probing (i.e. why are there fewer collisions)?

4 × 0 pream to the not of the subtree to be balanced and me should teturn the "t" are set a private method, balance to check if the hodes are balanced private Node balanced (Node t) /
if the "t" is equal to mul (leit's empty). then return it (t). If (the height of the t's left side is larger than the height of thet's right side over 1 Il ne consider the double rotate in this case. if I herght of t's left left side smaller than height of t's left night side) rotate left (t'. left) i / 1/ Rotate left Right case. rotate Right (t); 1/ Rotate por left befor Call lele if (height et t's right - height of t's left >1) [if (height of t's right right side smaller than) {
 height of t's right left side rotate Right (t. right); i // Right Right (all rotate left (1); " Right left race. return t) then we implement potablefor method: private Node rotatelegt (Nocle t) | Nede X = t.right) Node b = x. left; t. right = b; // Then adjust the height after notated to height = 1+ Marth. max (height (t. left), height (t. right)); 1. height = 1+ Math. max (height (x.left), height (x. hight)); return X;

then we implement rotate Pight (Nocle X) {

Nocle t = X. left;

Nocle b = t. Hight;

Nocle b = t. Hight;

X. left = b; 1/ adjust the reight after rotated

X. left = b; 1/ adjust the reight (X. left), height (X. right));

X. height = 1+ Math. max (height (X. left), height (t. right));

t. height = 1+ Math. max (height (t. left), height (t. right));

return t;