

CoviSim: Research into the Demonstration of Transmission of COVID-19

Final Project Report

DT211C

BSc in Computer Science (Infrastructure)

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Abstract

Computer simulation has always been an invaluable tool when it comes to researching infectious diseases, as real-life experiments have many potential risks. Over the course of the past year, countless scientists and doctors all over the world have been continuously researching Coronavirus in a global effort to overcome the pandemic and get back to normal everyday life. There have been numerous Coronavirus related simulations made over the past year focusing on a wide variety of aspects of the virus.

Many simulations offer a high-level overview of the pandemic on a large scale, having only a few variables affecting the results. These simulations tend to focus on the spread throughout a city, and the virus is transmitted when agents come within a certain range of an infected agent. While this serves as a good visualisation of spread throughout a population, it is a drastic oversimplification of how transmission can occur and does not show how the virus actually transmits between people.

This project is focused on transmission in a closed environment, highlighting the actual methods of transmission and allowing the user to truly understand how certain countermeasures affect the results. There is a surplus of medical papers and scientific studies from around the world which provide statistics on transmission rates and the effects of various countermeasures. Some of these statistics have been utilised in the simulation as parameters to give a more accurate result.

As Coronavirus continues to grow, so does misinformation about it on social media. While a small amount of information is given to the public about countermeasures that they can take to prevent transmission, the results of these countermeasures are not easy to identify. This simulation is a practical solution to this, using real figures to visualise transmission and the effectiveness of various countermeasures in a real-time closed environment.

Declaration

I hereby declare that the work described in this dissertation is, except where otherwise stated, entirely my own work and has not been submitted as an exercise for a degree at this or any other university.

Signed:

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Kyle Heffernan

Date: 31/03/2021

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Table of Contents

[1. Introduction 7](#_Toc21459636)

[1.1. Project Background 7](#_Toc21459637)

[1.2. Project Description 7](#_Toc21459638)

[1.3. Project Aims and Objectives 7](#_Toc21459639)

[1.4. Project Scope 7](#_Toc21459640)

[1.5. Thesis Roadmap 7](#_Toc21459641)

[2. Literature Review 8](#_Toc21459642)

[2.1. Introduction 8](#_Toc21459643)

[2.2. Research Topic 1 8](#_Toc21459644)

[2.3. Research Topic 2 8](#_Toc21459645)

[2.4. Existing Final Year Projects 8](#_Toc21459646)

[2.5. Conclusions 8](#_Toc21459647)

[3. Experiment Design 9](#_Toc21459648)

[3.1 Introduction 9](#_Toc21459649)

[3.2. Software Design 9](#_Toc21459650)

[3.3. Software Test plan 9](#_Toc21459651)

[3.4. Front-End 9](#_Toc21459652)

[3.5. Middle-Tier 9](#_Toc21459653)

[3.6. Back-End 9](#_Toc21459654)

[3.7. Conclusions 9](#_Toc21459655)

[4. Experiment Development 10](#_Toc21459656)

[4.1. Introduction 10](#_Toc21459657)

[4.2. Software Development 10](#_Toc21459658)

[4.3. Front-End 10](#_Toc21459659)

[4.4. Middle-Tier 10](#_Toc21459660)

[4.5. Back-End 10](#_Toc21459661)

[4.6. Conclusions 10](#_Toc21459662)

[5. Evaluation 11](#_Toc21459663)

[5.1. Introduction 11](#_Toc21459664)

[5.2. Software Evaluation 11](#_Toc21459665)

[5.3. Specific Evaluation 11](#_Toc21459666)

[5.4. Questionnaires and Interviews Evaluation 11](#_Toc21459667)

[5.5. Conclusions 11](#_Toc21459668)

[6. Conclusions and Future Work 12](#_Toc21459669)

[6.1. Introduction 12](#_Toc21459670)

[6.2. Conclusions 12](#_Toc21459671)

[6.3. Future Work 12](#_Toc21459672)

[Bibliography 13](#_Toc21459673)

# Table of Figures

[Figure 1 – Grocery Store simulation 11](#_Toc59054345)

[Figure 2 – Spread simulation 12](#_Toc59054346)

[Figure 3 – Live output 13](#_Toc59054347)

[Figure 4 – Case studies 13](#_Toc59054348)

[Figure 5 – Sample assets 18](#_Toc59054349)

[Figure 6 – Office environment 19](#_Toc59054350)

[Figure 7 - NavMesh 19](#_Toc59054351)

[Figure 8 – Prototype Agent 20](#_Toc59054352)

[Figure 9 – Movement Code 20](#_Toc59054353)

[Figure 10 - Architecture 22](#_Toc59054354)

[Figure 11 – System Diagram 22](#_Toc59054355)

[Figure 12 – View of simulation 24](#_Toc59054356)

[Figure 13 - GUI 24](#_Toc59054357)

[Figure 14 – Use Case 25](#_Toc59054358)

[Figure 15 – Class Diagram 26](#_Toc59054359)

# 1. Introduction

## Project Background

As the number of Coronavirus cases continue to grow worldwide, scientists and medical professionals from all over the world have been researching and studying the virus and its transmission to better understand and subsequently overcome it. Due to many real-life experiments being too risky to carry out, computer simulation has been an invaluable tool for developing further understanding of the virus and its transmission. This project involves creating a simulation of an environment in which transmission commonly occurs, an office.

There is a vast number of platforms available for developing in this field, but Unity stands out with its countless invaluable features and tools that enable swift and efficient development of real time simulations. The use of Unity also allows the use of various complex technologies, such as navigation mesh which creates a map of traversable areas in a scene and grants agents the ability to find the shortest path to their destination. A behaviour tree is another technology available in Unity which is a mathematical model of plan execution, meaning an artificially intelligent agent can switch between a set of tasks in a modular fashion. Unity also grants the ability to implement particle systems which can be used to simulate particles being expelled during breathing. Finally, Unity also has the entity component system, which is a new data-orientated design system which significantly boosts performance of the simulation if implemented correctly.

## Project Description

The purpose of this project is to simulate the environment of a populated office. The program starts off on a screen that allows the user to adjust certain variables which will affect the result.

Once the simulation is started, autonomous agents enter the building representing workers going about their daily work shift. The building has a navigation mesh which is utilised by the agents so they can path find through the office. At the start of the simulation, each agent goes to their respective desk, which is chosen at random at the start and begins working. Agents will intermittently do various tasks such as retrieving a file or printing something off and then return to their desks. This is due to each of the agents having a behaviour tree, so they have a set of tasks that they switch between.

One of the agents is infected with COVID-19 and is continuously spreading it throughout the office as the day goes on via a particle system that emulates breathing. The virus is spread by the particles emit, which can contaminate a surface or expose an agent if they collide with it. Agents also have a chance of becoming exposed if they touch another exposed agent or if they touch a contaminated surface. The chances of an agent becoming exposed when they come in contact with an infectious particle are affected by what the user selected at the start of the simulation, and the figures used in these calculations are taken from real studies.

As the simulation runs, the user can walk around the office to get a better view of the virus spreading, or they can look through the office security cameras. The user is also able to change the rate at which time passes, so they could have the simulation run at times ten-speed to see the results faster.

Once the working hours set by the user have ended, the agents begin to leave the office. Once they all leave, a screen is displayed to the user with statistics from the simulation that was just run, and the user has the option to run the simulation again with different options.

### Factors the user can change:

**Working Hours:** The amount of time the users stay in the office.

**If healthy agents are vaccinated**: This alters the chances of a healthy agent becoming exposed.

**If healthy agents wear masks**: This alters the chances of a healthy agent becoming exposed.

**If infected agents wear masks**: This alters the number of particles emit by the infectious agent.

**Time scale:** The rate at which time passes in the simulation.

## Project Aims and Objectives

1. Identify and review suitable literature and other references relevant to this project
2. Describe some other software systems that are like this project
3. Undertake a thorough design process, including a methodology and detailed design
4. Develop a working software system using suitable technologies
5. Test and Evaluate the developed system
6. Critically reflect on the outcomes of this entire process

## Project Scope

This project allows users to view a COVID-19 simulation in real time and alter certain variables to see how they affect the transmission results. The simulation is made using Unity, and the environment in which the simulation takes place in is a populated building with autonomous agents using behaviour trees. Navigation Mesh is used to map out the walkable paths for the agents throughout this environment. The agents have human models and custom AI allowing them to go to their assigned desk and work, intermittently going to do various tasks around the office. Then once their working hours end, they leave the office.

Infected agents emit particles using Unity’s Particle System that leave surfaces contaminated and they can expose other agents to the virus based on their susceptibility. Agents can also become exposed from a contaminated surface or from getting too close to a different exposed agent. As the simulation is running, the user can walk around or look through the office security cameras. The user can alter the time scale to speed up the simulation, and they can also adjust variables that affect the result of the simulation. When the agents all leave the office, a screen is displayed with some statistics from the simulation that was just run, and the user can then restart the simulation with different variables.

## Thesis Roadmap

### Literature Review

In this chapter, a description of the main technologies and resources researched is presented, including academic papers, tutorials, books, and websites. The main technologies involved with the system are discussed, along with some other related research. It also looks at existing virus simulations made in Unity and previous final year projects with similarities to this project.

### Experiment Design

In this chapter, the software methodology used during the development process is discussed with the reasoning behind its choice, and an overview of the system is presented. The technical architecture of the system is presented, and the design of the front-end and back-end of the system is described with the aid of numerous diagrams.

### Experiment Development

In this chapter, the entire software development process is discussed in detail. Beginning at the prototype stage and moving through the process describing the development of each feature in detail, along with the issues faced and how they were overcome.

### Evaluation

This chapter discusses how the system was tested and how feedback was considered during the development process. The chapter also contains an in-depth evaluation of the system, discussing its performance, accuracy, and comparing its results to alternative similar systems.

### Conclusions and Future Work

This chapter summarises the complete project, discussing the major concepts learned during the development process as well as the issues that arose and how they were approached. Finally, this chapter concludes with a discussion of the future of this project and how it can be expanded upon with certain features and generally improved.

# 2. Literature Review

## 2.1. Introduction

In this chapter a review of relevant research and other software is presented as it relates to the simulation system. First existing software that performs similar functions to this project are presented, and following that, the technologies be used in this system Other research including academic papers and web information are presented. Finally, two existing final year projects are discussed.

## 2.2. Alternative Existing Solutions to Your Problem

### Exploring new ways to simulate the coronavirus spread (1)

Released in May 2020, this Unity Blog is about a Coronavirus spread simulation which is developed in Unity and C#. The project contains a simulation of a grocery store, with customers coming and going to and from the store. Some customers are infected and can expose other customers to the virus if they are within a certain range for long enough. The project has a GUI at the side of the screen which allows the user to alter various parameters, apply the changes, and see how they affect the results which are also displayed on the GUI.



Figure – Grocery Store simulation

### Software Features:

**Grocery Store Environment:** The project contains a simulated grocery store, with aisles, registers, entrances etc. The shoppers travel around this simulated store.

**Shoppers:** There are agents in the shape of capsules which represent shoppers. They follow certain routes throughout the store.

**Configurable parameters:** Parameters like exposure distance and transmission probability are adjustable using the sliders in the GUI on the right of the screen. Once the “Apply and Reset” button is pressed, the actual variables which are used in the simulation are updated accordingly, and the effects will be visible.

**Time scale:** The scale of the simulation can be adjusted using the GUI, allowing the user to choose how fast they would like time to go by in the simulation.

**Mapping:** The traversable routes are determined procedurally based on criteria including entrances and exits, whether certain sections are one way only, and making sure there are no collisions.

**Movement:** When shoppers spawn, they pick random traversable paths throughout the store. These paths start at the entrance, have random amounts of intermediate goals, and end at the exit.

**Exposure:** Shoppers spawn as either healthy or infectious. When infectious shoppers come close with other shoppers, they can expose them to the virus based on some set parameters. These shoppers are then set to exposed.

**Queuing:** Before each shopper approaches the registers, they check if there are any open registers, and then get queued accordingly based on the store policy parameters.

This grocery store simulation has many similar features to this project. The concept of having a GUI screen with configurable parameters is close to the GUI that this project has, although this project has project has the GUI screen only at the start. A lot of the other features are rather similar too, such as having agents walk throughout the simulated environment with a chance of becoming exposed. The logic of having infectious agents exposing healthy agents to the virus is the same, although this project is much more in depth, having the actual particles emit from breathing being the carrier of the virus rather than just a simple collision behaviour. The grocery store itself is also similar to the simulated office in which this project takes place in, although this project offers a 3d space in which the player can move around in rather than just a top-down view.

Both the grocery store project and this project are made completely in Unity and C#, so the technologies used are closely related, although this project makes use of some more complicated technologies such as behaviour trees for AI and particle systems to emulate breathing.

How coronavirus spreads through a population and how we can beat it (2)

Published in early 2020, this article presents a simulation of the spread of certain viruses throughout a population of people. It allows the user to adjust some parameters using the sliders at the top, and then shows how the virus would spread over a period of time. As well as allowing the user to adjust these parameters, they can also select one of the case studies and see a visualisation of the spread using statistics from the actual case study.

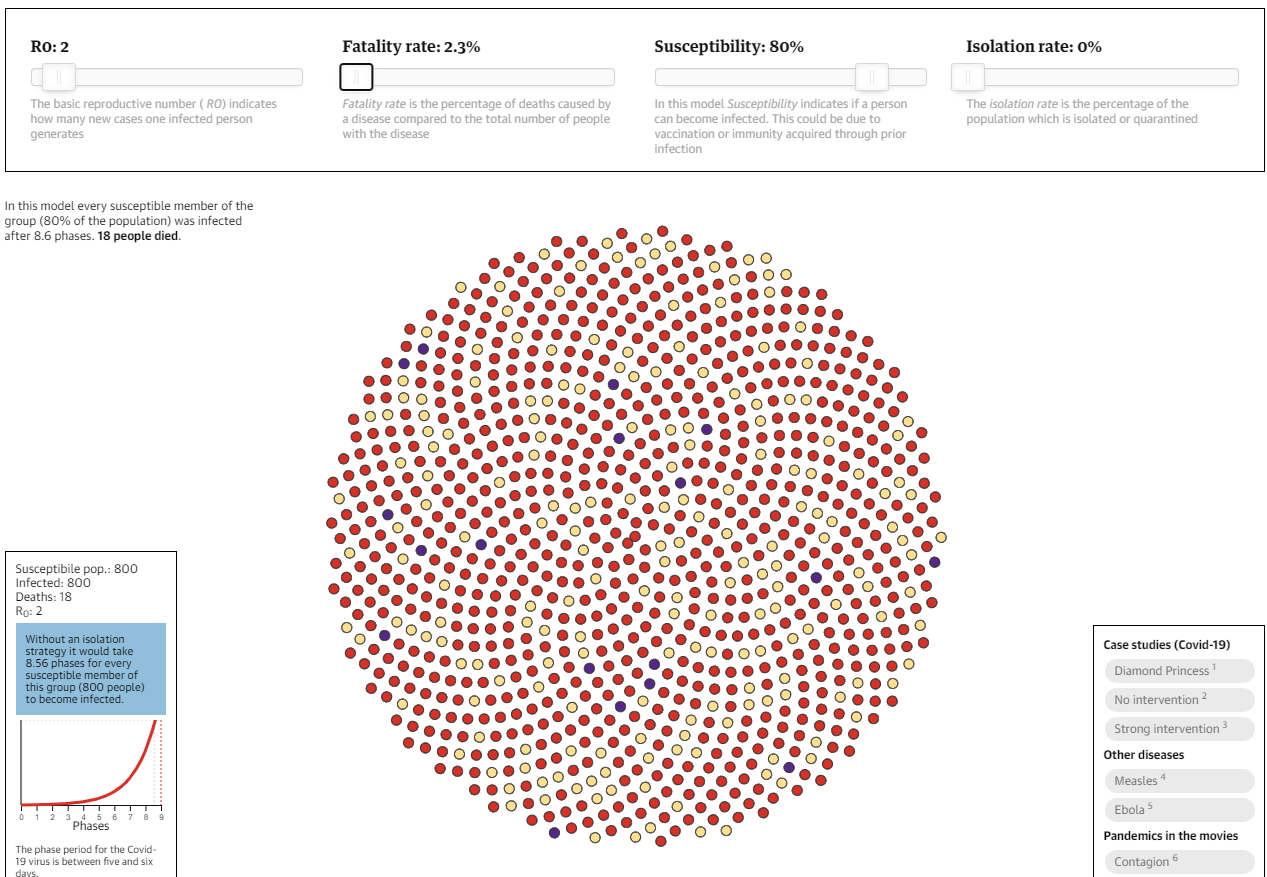


Figure – Spread simulation

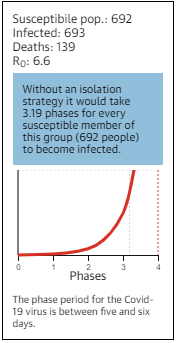


Figure – Live output

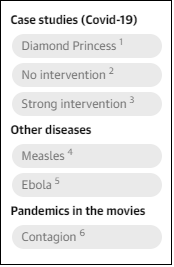


Figure – Case studies

### Software Features:

**Infectious indicators:** Members of the population start off as yellow which indicates a healthy person. Red indicates they are infected with the virus, and purple represents people who have died from the virus.

**Adjustable parameters:** As seen in the top of the screenshot, the user can move the sliders to change the parameters of the simulation. They can then see of visualisation of how the chosen values would affect the results.

**Case studies:** The user can select from a short list of case studies to see a visualisation of the spread that took place during these case studies.

**Utilising real statistics:** If a case study is chosen by the user, the simulation will run using parameters taken from real life statistics.

**Displaying results:** As the simulation runs through the phases, it updates the visualisation of the population with the corresponding colours. It also displays the numbers after each phase and displays the stage on a chart as it updates.

This population spread simulation also has numerous similarities to this project. Both projects take some statistics from real life and use them as parameters for the simulation, and also allow the user to adjust variables and see the results. They also both focus on visualising the spread of the virus, although the population spread simulation went in a completely different direction, focusing on spread over a long amount of time, and as a result it is much less detailed than this project is and does not touch on the transmission methods of the virus, in turn making it a somewhat simple system.

## 2.3. Technologies you’ve researched

### Godot (3)

Godot is an open-source game engine that is known for its node-based architecture and object-oriented API. It was released under the MIT license and runs on most operating systems. It has many useful tools for game development, such as the scene tree editor, the script editor, a script debugger, etc. It also has an asset store from which numerous plugins can be downloaded to extend functionality. Godot contains engines for physics and lighting and many other mechanics that make game development swift and efficient.

Godot is a useful tool for developing projects such as simulations due to its long list of features, although it is nowhere near as widespread or as popular as Unity, therefore there is much less documentation and tutorials available online for it.

### Unity (4)

Unity is cross platform game engine that is widely used for a variety of applications. It was developed by Unity Technologies and released in 2005. The Unity asset store has an ever-growing catalogue of assets and tools which make project development with Unity considerably faster than many alternatives. Unity is also full of useful tools such as a debugger, a script editor, a scene editor etc.

It is extremely accessible and used globally, so there is a surplus of tutorials and online resources to learn from. These resources include plenty of sample projects full of detailed documentation which allows users to develop a detailed understanding of the underlying concepts in these projects. It also excels in real-time simulation, which is perfect for this project.

### Unity Render Pipelines (5)

In Unity, a project can use one of various render pipelines. The render pipeline performs a set of operations which entail taking the contents of a scene and displaying them on the screen. Different render pipelines have different capabilities and performance, so it depends on the nature of the project. The built-in render pipeline is the default render pipeline for Unity. It has limited customisation, for general purposes. There are other render pipelines available which focus more on graphics, but this project does not centre on graphics, so it is using the built-in render pipeline.

### Unity Navigation Mesh (6)

NavMesh (Navigation Mesh) is a tool for mapping out the traversable areas of an environment and the paths that agents can take through this environment. The process entails rendering a mesh of the walkable areas, allowing agents to determine the shortest possible paths between locations. This helps AI look more natural as it travels through an environment. This project has autonomous agents following paths through the course of the simulation, so navigation mesh was an obvious choice to assist in the pathfinding.

### ParticleSystem (7)

ParticleSystem is Unity’s in-built implementation of a particle system, containing a vast number of properties and methods which can be altered to get different effects. When properties are set, they are passed immediately into native code to give the best performance. ParticleSystem is used to display a wide array of items such as fire, liquids, explosions, gasses etc.

This simulation uses ParticleSystem to emulate breathing and implement the actual virus particles being expelled from infectious agents which is the method of virus transmission.

Behaviour Trees (x)

Behaviour trees are a hierarchical branching system of nodes which all share a parent known as the root. They begin evaluating from the top and run through each child based on certain set conditions. They allow for an AI agent to follow a strictly defined set of rules based on each nodes position in the hierarchy. They have slowly become extremely popular, being used for the AI in well-known games such as Halo and The Sims.

Behaviour trees were perfect for this project as the agents need to have AI which made them enter the office, work, do random tasks, and eventually go home. Behaviour trees make this kind of AI possible and less complicated than other options.

### Entity Component System (8)

Entity Component System (ECS) is a new way to develop in Unity that focuses on data-oriented design rather than object-oriented design. It breaks the project into 3 sections:

**Entities** – The actual things in your simulation

**Components** – The data associated with these entities but organised by the data rather than by entity.

**Systems** – The behaviours that update the component data. For example, A movement system would update positions of moving entities by their velocity and time passed.

Projects using ECS have greatly improved performance, making it an extremely useful instrument for simulations with a lot going on, however it is still in beta and can be quite unreliable and buggy.

### C# (9)

C# is a modern object oriented, component orientated programming language. It was developed by Microsoft in 2000 as part of its .NET initiative, and approved as an international standard in 2002. Like Unity, due to its widespread use, there is a vast number of resources available online to assist in understanding the underlying concepts. Applications made with C# are generally quite robust due to its many supportive features. Exception handing is a feature of C# which allows the detection and recovery of errors. Garbage collection is another useful feature which automatically reclaims unused memory.

It is the language that Unity scripts are mainly written in, so the coding in this project is mostly done in C#.

### C# job system (10)

The Unity C# Job System allows users to have multithreaded code in their projects. It integrates with Unity’s native job system, so user-written code and Unity share worker threads. This ensures that there are not more threads than CPU cores. This multithreaded code can greatly improve performance of the project. The C# job System works well with the Unity Entity Component System due to its efficient way of writing code.

The C# Job System improves performance, although it can be very confusing and there is not as much documentation or resources available online.

## 2.4. Other Research you’ve done

### COVID-19 transmission research

There has been a great amount of research done in the last year regarding the transmission of COVID-19, and numerous factors have been found to influence the probability of transmission. Physical distancing has been shown to reduce transmission rates (11) as the infected particles can only be expelled a certain amount. (12) Masks have also been shown to reduce the particles expelled from an infectious person and reduce the chance of someone breathing in infectious particles. (x) Factors such as vitamin D levels (13) or age can determine a person’s susceptibility to the virus due to the strength of their immune system. Vaccinations can reduce the risk of transmission by over 95%. (x)

Closed environments have also been found to be a contributor to secondary transmission and can lead to superspreading events. (14)

This simulation has a number of parameters that the user can change and see how they alter results. The parameters this system uses have been chosen as they have been shown to have an effect on transmission.

### Data Visualisation

The use of images and simulations to visualise data has been shown to help develop a greater understanding and comprehension of data than ever before. (15) Many people struggle to truly grasp the implications of raw data without some useful kind of visualisation. Some methods of visualisation do a much better job than others though.

Game techniques and mechanisms such as real time simulations have been shown to aid in the understanding of certain topics as they are a more engaging form of learning. (16)

### SNAPS prototype asset packs (x)

SNAPS prototype asset packs are packs with collections of themed assets found on the Unity Asset Store. The asset prefabs contained are accurately scaled prefab objects, and a script is included in the pack which allows for these objects to snap together on all three axis in the Unity scene editor, making environment design quick and simple. This project is simulating a workplace, so an asset pack of accurately scaled objects that scale together are perfect for speeding up environment design.

### Mixamo (x)

Mixamo is a site that contains a vast number of template character models and animations which work with these models. The models contain numerous joints throughout their body making them easily animated. Both the character models and the animations can be downloaded as .fbx files, which can then be imported and used with an animator. This project contains autonomous agents that will walk around the scene so default models and animations would be useful for assisting in the implementation of animated agents.

## 2.5. Existing Final Year Projects

### Traffic Simulation System for Driverless Vehicles by Fionn McGuire.

A traffic simulation system for the deployment of driverless vehicles in modern day society by using Unity3D. The platform utilizes an interactive OSM map of Manhattan populated with both drivers and driverless vehicles. The vehicles generate a route to follow while perpetually responding to changes in the environment.

This traffic simulation is also made in Unity and contains many agents which populate an environment and have a set of behaviours to follow. This project has a lot of similar mechanics, as it is also simulating multiple agents in an environment which have a set of behaviours and have interactions.

### Irish Crime Data Visualisation by Max Curtis.

A system to allow for the visualization of Ireland’s crime statistics. This data is an untapped resource in its current state. This project is an application that helps users understand a mountain of data using data visualisation techniques.

This data visualisation application has some similar concepts to this project, the main one being that the application helps users develop a greater understand of the available data. There is a vast amount of data available online about Coronavirus and its transmission but having a good visualisation can help users truly comprehend what the data implies.

## 2.6. Conclusions

In this chapter, the research done for the project was shown and presented. This research included similar existing systems, technologies related to the simulation, Coronavirus transmission research, and data visualisation research. Finally, two similar existing fourth year projects were discussed. When the project was being planned, these technologies were researched and reviewed thoroughly to determine what would be used.

# 3. Experiment Design

## 3.1 Introduction

In this chapter the design of the project and simulation are discussed. First the methodology used in this project will be outlined and following this a discussion of the technical architecture will be presented. The front-end design of the system will be presented next, showing the key screens of the simulation. The back-end is also discussed with diagrams to show the design of the objects.

## 3.2. Software Methodology

Agile software methodologies focus on continuous delivery of valuable software, and the primary measure of progress is working software. (18)

The software methodology this project uses is agile scrum. Agile scrum focuses on dividing the project into sprints, which are short-timed periods in which an amount of work is set to complete, generally focusing on a specific feature of the project. Before each sprint, it is planned what work will be delivered from the sprint, and how that work will be achieved. One feature of the scrum methodology is regularly reflecting on work done and learning from it, in turn becoming more efficient as behaviour is adjusted accordingly. (19)

Scrum works well for projects with many important features, so it is perfect for this project. This project contains numerous important features which can be developed and implemented during these sprints, and then further improved with future iterations. This approach allows for many core features to be implemented successfully with some complexity, and then they can be improved and fleshed out later with less important features.

The waterfall model is a good example of a software methodology that would not work with this project. The waterfall model entails running through the entire project in a single iteration, never going back and making modifications or changes. This would not work as features of this project need to be iteratively designed, with a simple design working first, and then after some testing, reflecting, and further development, they can be revisited with a greater understanding of requirements and design.

## 3.3. Project Management

GitHub was chosen to be used for project management and keeping track of development. It is very straightforward to use, having a simple GUI program and well as a console interface. Every step of development was saved in a commit and pushed to the project, allowing for effortless version control and for making sure that no work is lost. There were multiple times during development where the project had numerous errors which were easily fixed by reverting to a previous version. GitHub also has a task board feature, allowing you to separate out the various features to be developed with tags denoting their importance and what section of the project they belong too. This was invaluable for keeping track of features during the different development stages.

## 3.4. Overview of System

### 3.4.1. Technical Architecture

As this project is entirely in Unity and C#, it’s technical architecture is a standalone system.

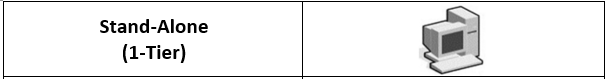


Figure -Technical Architecture

### 3.4.2. System Flowchart

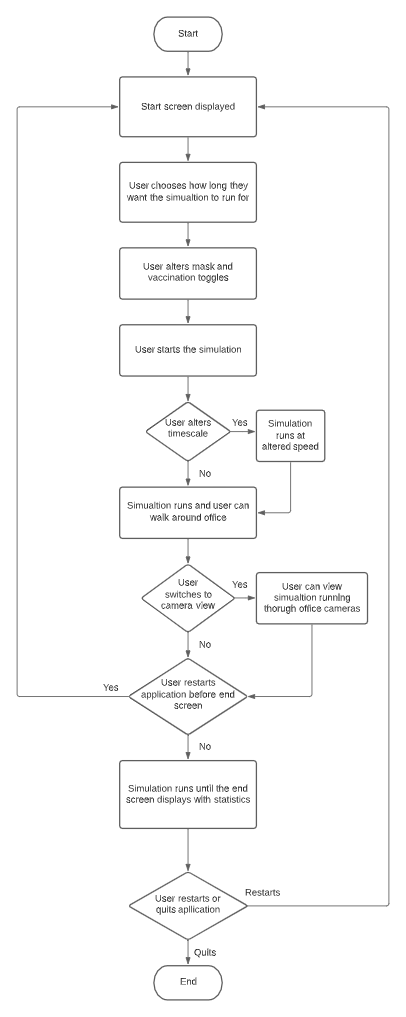


Figure – System Flowchart

This Flowchart.

### 3.4.3. Table of Requirements

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **ID** | **Name** | **Description** | **Priority** | **Version** |
| 1 | Workplace environment | The simulation will take place in a workplace environment. | High | 1.0 |
| 2 | Autonomous Agents | The agents follow certain behaviours as they path find throughout the building following various feasible paths. | High | 1.1 |
| 3 | Utilize Unity’s Navigation Mesh System | The autonomous agents in this simulation will be able to path find through the building with the help of the navigation mesh. | High | 1.0 |
| 4 | Infection system | Agents will either be healthy, infectious or exposed. Most spawn as healthy and can become exposed if they come in contact with the virus. | High | 1.1 |
| 5 | GUI with sliders | A UI will be displayed to the user showing statistics as the simulation is running. | High | 1.2 |
| 6 | Time Scale | The user can alter the time scale via the UI to have the simulation run faster or slower depending on their preferences. | High | 1.2 |
| 7 | Display Results | The user can see statistics about the number of agents exposed to the virus as the simulation runs. | High | 1.1 |
| 8 | Complex AI with behaviour trees | The autonomous agents will have complex ai with multiple behaviours, having them to tasks around the office. | High | 1.3 |
| 9 | Utilize Unity’s Particle System | The infectious agents will be emitting infectious particles from their mouths with the use of Unity’s particle system. | High | 1.4 |
| 10 | User movement and cameras. | The user will be able to walk around the scene or look through cameras throughout the scene. | Medium | 1.0 |
| 12 | Animated character models | The autonomous agents will have human character models with animations. | High | 1.5 |
| 13 | Adjustable variables | The user will be able to adjust multiple variables and see how they affect the simulation results. | High | 1.6 |
| 14 | End screen | The simulation will end off with a screen displaying the results from the simulation that was just run. | High | 1.8 |
| 15 | Medical data | The calculations made to determine whether an agent becomes infected will use data from real studies. | Medium | 1.6 |
| 16 | Contaminated surfaces | The infection will also be spread by surfaces that become contaminated from the virus. | High | 1.7 |
| 17 | Optimization | The underlying technologies will be optimized to increase performance of the simulation. | Medium | 1.9 |
| 18 | Utilize Entity Component System | The entity component system is a data-oriented way of programming which significantly increase performance. | Low | 1.9 |
| 19 | Utilize C# Job System | The C# Job System would allow for Scripts and certain processes to be multithreaded. | Low | 1.9 |

## 3.5. Front-End

### 3.5.1. Key Screens

The project contains 4 main key screens, the first of which being the start screen. A small description of the simulation is displayed, and the user can alter certain variables which will affect the results of the simulation. There is a button to start the simulation or quit the application. Finally, in the bottom corner, there is a small tip explaining that the user will be able to adjust the time scale of the simulation.



Figure X – Key Screen 1

The second screen is the actual game view of the 3D simulation, with UI components overlayed on the screen as the simulation runs. The user is able to walk around the office with the W, A, S and D keys, and switch to the office cameras with the 2, 3 and 4 keys. A panel explains this in the top left corner of the screen. The user can also press the escape key to go back to the start screen, which is also explained in a panel just below the top left corner of the screen. Statistics from the simulation currently running are displayed in a panel on the top right of the screen, and a frames per second counter is displayed in the bottom left corner of the screen.

Finally, in the bottom right corner of the screen, a panel displays the time passed, the time left, and a slider which lets the user change the time scale of the simulation.



Figure X – Key Screen 2

The third key screen is the office camera view. The main difference between this and the player view is that the user cannot move or walk around. The panel in the top left of the screen is also slightly different. There are 3 office cameras, which the user can cycle through, but the only difference between them is the location that they display.



Figure X – Key Screen 3

The fourth and final screen is the end screen, which is displayed after the workers finish their shift, and it displays statistics about the simulation that was just run allowing the user to restart or quit the simulation.



Figure X – Key Screen 4

### 3.5.2. Use Case Diagram

Use case diagram

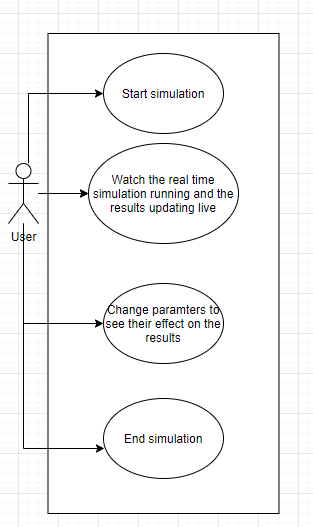
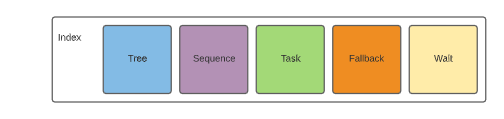


Figure – Use Case

## 3.6. Back-End

### 3.6.1 Behaviour tree diagrams





### 3.6.2 Class Diagrams

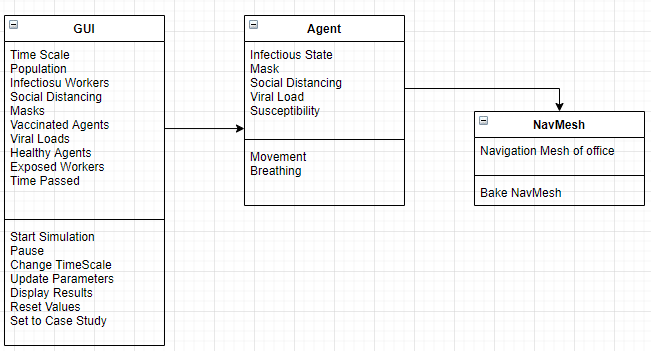


Figure – Class Diagram

## 3.7. Conclusions

In this chapter, the design of the simulation system was presented. First, the agile scrum methodology was discussed as the approach to be used in this project. Following this, the technical architecture of the system was presented.

The front-end design of the system was presented next, showing the 2 key screens of the simulation. The back-end was also discussed with a class diagram to show the design of the objects.

# 4. Experiment Development

## 4.1. Introduction

In this chapter the entire development process will be outlined and discussed. The chapter will begin with setting up the environment and the beginning of the development leading to the prototype, and then goes through the feature-based development cycle discussing the underlying technologies of each feature and the issues faced during the implementation of these features.

## 4.2. Environment Setup

Before development began, a GitHub repository was created and a Unity project and a “.gitignore” file were added. The “.gitignore” file was for making sure certain unnecessary files were not uploaded every time a commit was made. The Unity project was set up using Unity 2019.4.14f1, which is the 2019 long term support version. This version was chosen as it was the newest LTS release which are known to be more stable than other versions. A task board and Google Doc were also set up as a way to keep track of development.

## 4.3. Entity Component System

Due to the simulation having to have numerous calculations and behaviours run at real time, performance was sure to be important. The Entity Component System (ECS) would be a solution to this, as it is a great way to optimize importance due its data orientated design and multithreading capabilities.

Development began with getting some simple ECS systems working. Some online tutorials were followed to achieve this, and although they were generally unrelated to the project, they were invaluable for achieving a greater understanding of the scope of ECS and whether it would be a viable option for this project. The ECS preview packages needed to be imported into Unity for the project to work.

These tutorials comprised of getting objects to hover and spin and have a player be able to move around and collect them, having a stats counter be constantly displayed. Traditionally in Unity this could be achieved by attaching scripts to a couple game objects, but with ECS rather than game objects there were some entities in the scene with corresponding data components, and separate systems which acted as the behaviours and could be multithreaded using the C# job system. This data-oriented design over the usual object-oriented design results in the program running significantly better as it is a much more efficient method of doing things.

Even though this was a small-scale test project, many issues were encountered. The main issues being the volatile nature of ECS due it still being in beta. There were frequent updates which completely changed certain aspects of the system, making a vast amount of the available online material redundant. This was detrimental to development as it is a relatively new system and attempting to develop more complex behaviours with no material available would have would not have been possible during the length of this project. Another issue with ECS still being in beta was the fact that there were numerous bugs with every release, which could end up with certain not being possible or other features breaking with no feasible fixes.

Due to these issues, it was decided that the project would be developed in Unity without ECS, with the possibility of porting it over in future work.

## 4.4. SNAPS Tool and Navigation Mesh

After the decision to abandon ECS was made, a new project was created in the Unity 2019 LTS and added to the GitHub repository. This project was made with the standard render pipeline as graphics are not a focus. During research, an asset in the Unity Asset Store called “SNAPS” which aids in the process of environment design was discovered. This tool contains themed asset packs containing accurately scaled prefab objects, and a script to allow for these objects to snap together on all three axis in the Unity scene editor, making environment design much more efficient. Each prototype pack follows a specific theme, and due to the fact that the simulation takes place in a workplace, the SNAPS Office asset pack was imported to the project.

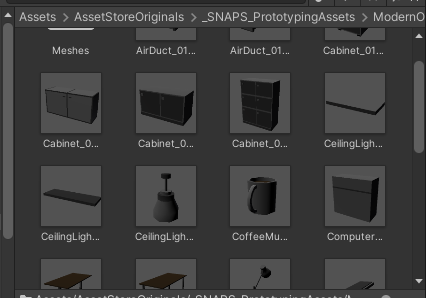


Figure – Sample assets

These prefab objects were placed in the scene and a simple office design was made. With an environment constructed, navigation mesh could now be implemented.

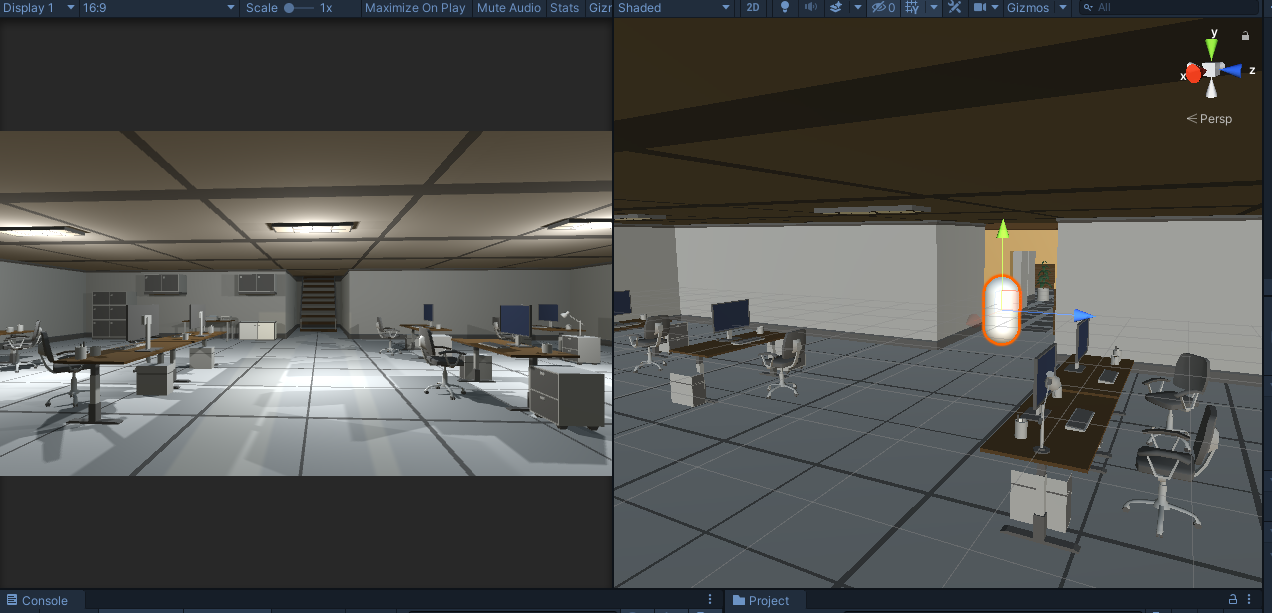


Figure – Office environment

In Unity 2019, implementing a navigation mesh is relatively straight-forward once the scene is correctly set up. Any object that should be walkable by agents must be set to “navigation static”, and then they are all used in a process called “baking” which returns a map of all the walkable surfaces in the scene. This map can be shown in the Unity scene editor with Gizmos turned on.



Figure - NavMesh

With a navigation mesh baked, objects with the “NavMesh Agent” component will be able to traverse the environment, finding the shortest paths to their destinations. To test this, a capsule was added to the scene with a NavMesh Agent component. A script was then written which takes the location clicked by the user by sending out a Raycast into the scene and sets it as the capsule’s destination. The update method is run every frame, so every frame the project was checking for any user input. This feature was presented in the prototype to show the navigation mesh working and soon removed.

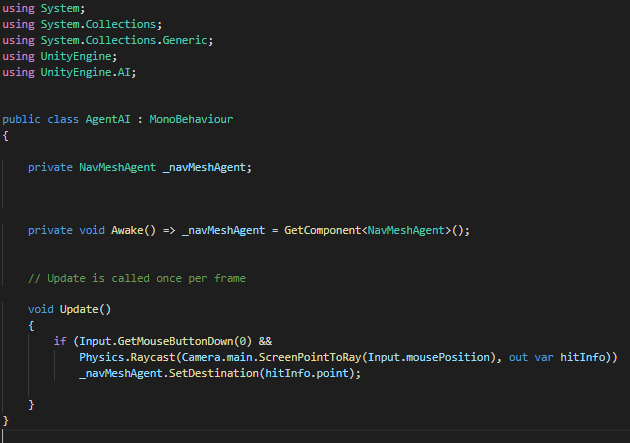


Figure – Movement Code

Another capsule was added to the scene with a separate movement script to allow the player to move around the office with keyboard controls, and the main camera was attached to this object. This script was also a placeholder script to show the office environment and would later be replaced by a more advanced script.

## 4.5. Simple path following and infection model

The next step of development was to have a simplistic prototype of the final project, with autonomous agents entering the office with a chance of becoming exposed to the virus. This was started off by adding more capsule objects with NavMesh Agent components to the scene and making a path following behaviour. Some random places in the office were added to a list of locations and a script was made which simply iterated through this list, setting these locations as destinations for the agents. This emulated the agents walking around the office and would soon be removed but was useful for the infection mechanics to take place.

With agents walking around the office, a simple infection model could be implemented. This was done using tags, with all but one of the agents being tagged as healthy and the final agent being tagged as infectious. Each agent had a capsule collider, so a simple script was made which changed the agents tag from healthy to exposed if anything tagged as infectious triggered their collider. Three corresponding materials were added to the project, with green representing healthy, yellow representing exposed and red representing infectious. The agents were set to their respective material and the script was modified so it would also change the agent’s material as well as their tag for visual clarity.



Figure x – Capsule agents

The office environment was also extended so the agents had more room to walk around the scene.

## 4.6. UI and Timescale

With a simple infection model working, some status counters which display statistics as the simulation is running were added to the corner of the screen.



Figure x – Status counter displays

These counters display the current amount of healthy, exposed and infectious agents currently in the scene. This was done by making a list of all objects in the scene with their respective tag, and then displaying the length of each list.

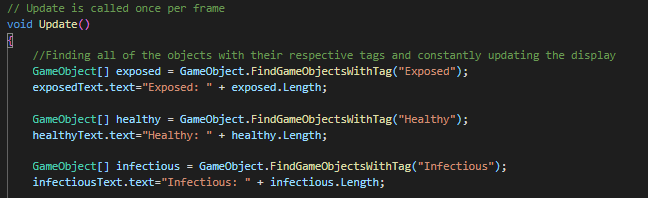


Figure x – Status counter code

The other element that was added to the screen was a timescale slider. This let the user change the speed at which the simulation runs at, so if they were to set the slider to 10, the simulation would run at times ten speed. This was done by multiplying the “Time.timescale” variable by the value of the slider. “Time.timescale” is a Unity varaible that controls the rate at which time passes.

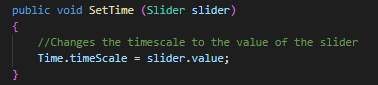


Figure x – Altering timescale

Finally, a simple start screen with a button was added which is on the screen before the simulation begins. Once the user clicks the button, the player movement, NavMesh agents and status counters are set to active. This was done by simply having them disabled by default, and having the buttons OnClick action set them to active.



Figure x – Start Button

## 4.7. Behaviour Trees

With the simulation having agents walking around, the virus spreading between them and status counters on the screen, behaviour trees were implemented and the path following behaviour was removed to make the agents follow a set list of behaviours rather than just follow the same path.

Before implementing behaviour trees, a script was written which is run on “Awake” which means it is run when the scene begins loading. This script searches the scene for all objects tagged as desks and adds them to a list. It does the same for all objects tagged as rec points. The agents will be able to take their destinations from these lists once behaviour trees are implemented.

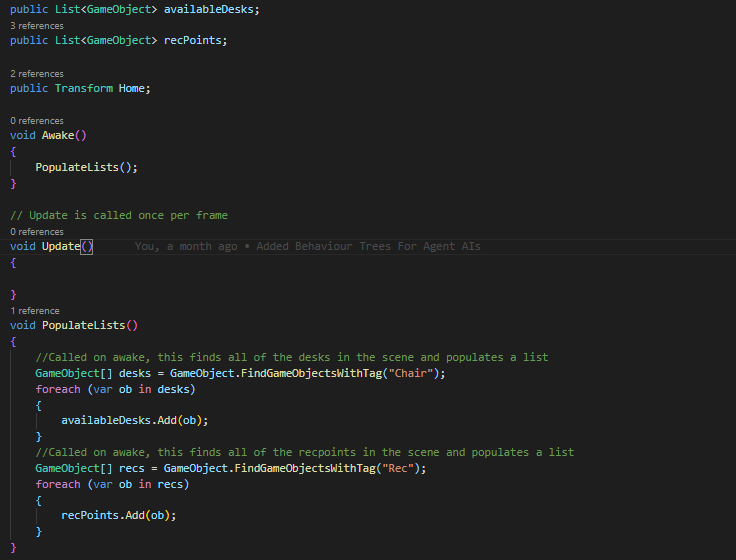


Figure x – Place Manager

The first step of implementing behaviour trees was to import the Panda BT asset from the Unity Asset Store. This asset contained a behaviour tree engine which allowed the creation of behaviour tree files which could be attached to agents as components to make them follow a set of logic written in the behaviour script.

A behaviour tree file and a behaviour script were both created after planning out and drawing a diagram of how the agents should behave. The simple plan was to have them enter the office and go to their desk, and after a set amount of time spent working, they would have a chance of leaving their desk to do a random task in the office and then go back and continue working.

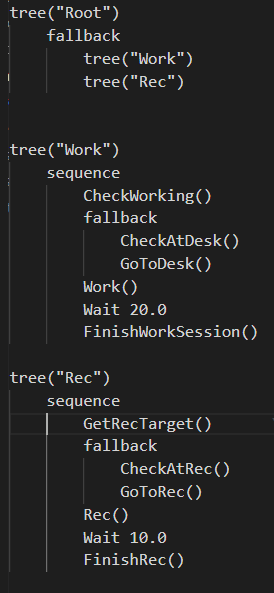


Figure x – Behaviour Tree

This is the structure of the behaviour tree, spilt into two trees, the work tree making them go to their desk and the rec tree making them go do a random task. Each element or “task” in these trees is a method in the behaviour script which is denoted as a [Task].

Once each agent is enabled by the start button, their Start method is called. In this method, the agent gets a random desk from the list mentioned above, and then removes it from the list so no agents will go to the same desk.



Figure x – Getting agents desk

After this, they run through their various tasks based on their current position in the tree. The first Task checks if they should be working, or if they should be going to a rec point. If they indeed should be working, the task is set to success and they continue in the working tree, otherwise they fallback to the rec tree.

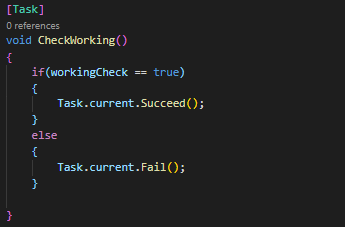


Figure x – Check working behaviour

If they continue in the work tree, they check if they are at their desk, and if they are not, their target is set to their assigned desk. This makes the agent move towards their assigned desk using the navigation mesh. It was unknown at this stage of development, but this behaviour is slightly bugged as the agent immediately succeeds this task and goes straight to the next one. This is corrected at a later stage of development.

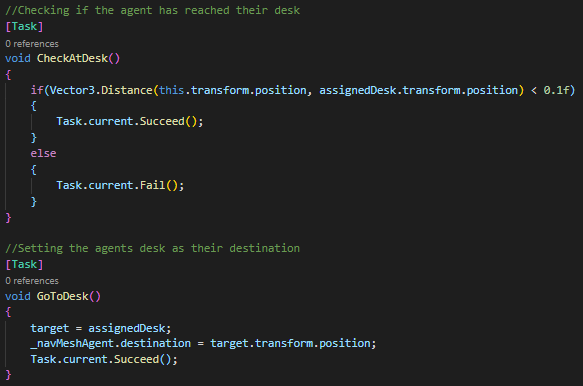


Figure x – Check and go to desk behaviour

At this point, the agent is at their desk and begins working. A 20 second timer starts before the next behaviour is started. Once this is over, there is a random number generated resulting in a 1 in 5 chance that a Boolean variable will be set to false, which results in the agent failing the check working behaviour and falling back into the rec tree.

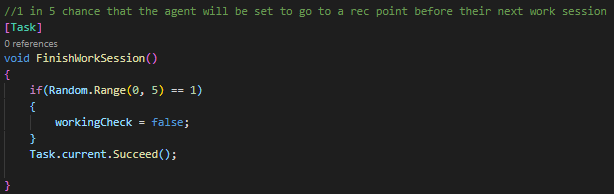


Figure x – Finish working behaviour

The Rec tree is constructed in a similar way, starting off by getting a random rec target from the list of rec points mentioned above. Each of these points represents a different task, e.g., retrieving a file or printing something off.

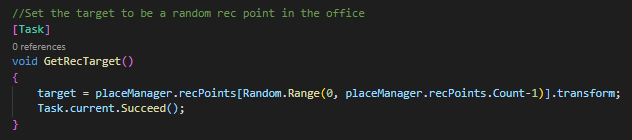


Figure x – Get rec target behaviour

Similarly, to the work tree, they check if they are at their rec target, and set their destination to their current rec target, which makes the agent move to their rec target along the navigation mesh.

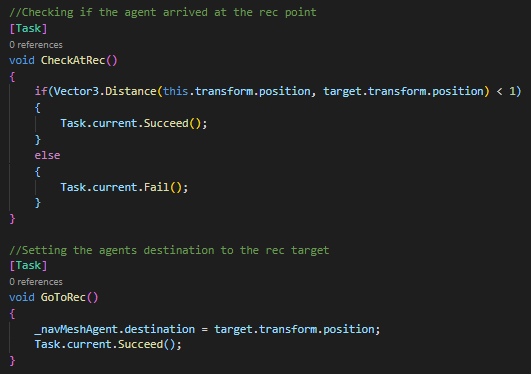


Figure x – Check and go to rec point behaviour

Now that they are at their rec point, a 10 second timer is started before the next behaviour begins. Once this finishes, the Boolean variable is set back to true, making them pass the check working behaviour and go back into the working tree.

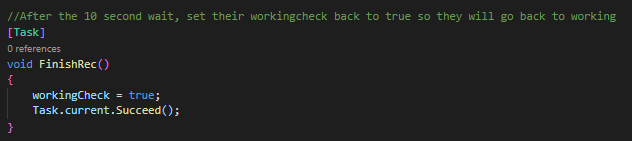


Figure x – Finish rec behaviour

These trees result in a relatively accurate simulation of how workers would generally behave as they work throughout the day in a workplace.

## 4.8. Particle simulation

At this stage in development, an interview was conducted with Dr Zach Tan, who suggested that the two main modes of transmission of the virus that should be focused on are aerosol transmission and contaminated surfaces.

Implementation of a particle system to simulate breathing then began. A particle system component was attached to the infectious agent and set to “Send Collision Messages” which would allow a script to iterate through objects that the particles collide with. A script was then written and attached which did exactly that.

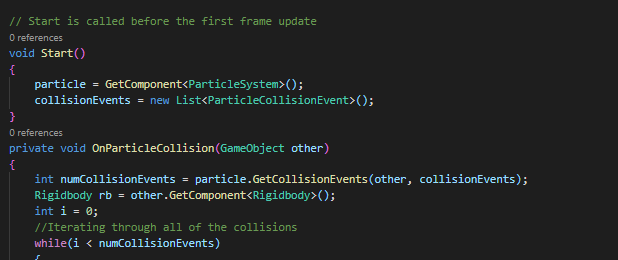


Figure x – Start of particle collision script

The particle system and a list of all the particle collision events were passed in, allowing the script to constantly check how many particle collision events there are, and then iterate through each of them.

At this stage, as the script is iterating through the collisions, it splits into 2 sections based on an if statement. The if statement checks whether the object that the particle collided with has a RigidBody or not. (Rigidbodies are components that put the object they are attached to under the control of Unity’s physics engine). If the object does have a Rigidbody, it is treated as another agent. If the object does not have a Rigidbody, it is treated as an object.

If it succeeds the if check and is treated as an agent, it is made sure that the agent is not already an infectious or exposed agent. It then makes sure that this agent has not had a collision event in the past 2 seconds. This is to prevent hundreds of unnecessary events taking place all on one agent in the space of a second or two. It then sets the tag and material of the agent to exposed.

If it fails the if check and is treated as an object, it is first made sure that the object is not tagged as ceiling, floor, wall or player. The decision to not have the ceilings, floors and walls be included here was made as it ended up being unclear what exactly was happening when the whole environment changed colour. These surfaces becoming contaminated in a real workplace would not have much if any effect on transmission anyway as workers would not be interacting with or touching them.

After this, the object tag and material are set to contaminated and exposed, respectfully. At this stage a bug was discovered in which only one of many materials was being changed on objects with multiple materials. This was fixed by getting the number of materials on the object and creating a new list of materials with the same length, and then changing all of the materials to the list just created.

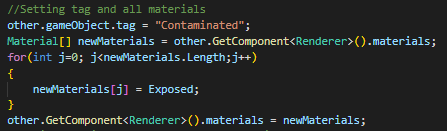


Figure x – Setting all materials of an object

Particle systems in Unity have an extremely large number of settings that can be changed, so there was a lot of trial and error in the process of making it look better. The lifetime and speed determined how fast the particles would be emit and how long they would last until they dissipated. These values were adjusted so the particles would spread to a distance close to about 2 meters, but this was relatively inconsistent. The simulation space was set to world, letting the particles spawn into the world and not move with the agent as they walked, as this would look and be very unrealistic. The particles were set to emit in a cone like shape from the mouth area of the agent, with settings such as angle and radius tailored in an attempt to be as realistic as possible. Finally, noise was added to the particle system on a random graph between two curves, to more accurately capture how particles would be emit from the mouth and get moved around by the air the further they get from the mouth. The size of the particles were also set to extremely small, they would be even smaller in a real transmission scenario but they were set to this size so the user could still see them.

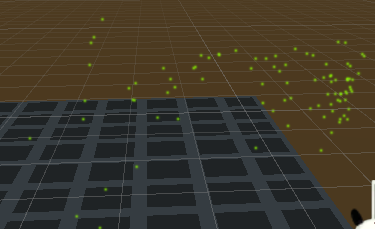


Figure x – Breath particle system– coming from right

## 4.9. Cameras and user movement

To add more intractability to the simulation, camera switching was added to the scene, allowing the user to look through various office cameras. This was a relatively simple process, entailing adding multiple cameras to the scene and making a script allowing the user to switch between them based on their input by enabling and disabling certain objects. A panel of text in the corner of the screen was added to explain this to the user.

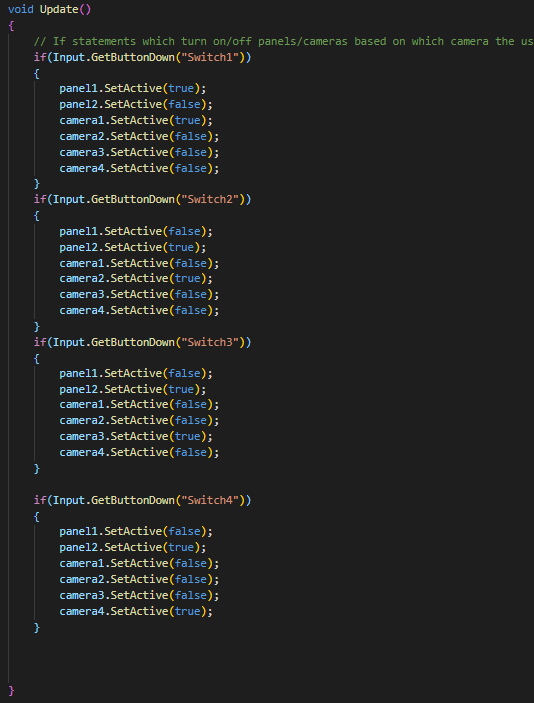


Figure x – Camera switching script

The player movement script was also improved. Due to the user being able to alter the rate at which time passes in the simulation, the user movement script had to be independent from the timescale. This was achieved by dividing by 1/timescale in the movement calculations. This meant the user could now walk at the same speed no matter what the timescale is set to.

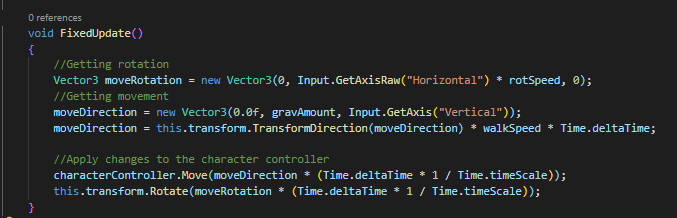


Figure x – Timescale independent movement script

The office environment was again expanded, and more desks and agents were added to the scene so it would better resemble a busy workplace.

## 4.10. Animated models

Up until this stage of development, the autonomous agents’ models were just placeholder capsule objects and they had no movement animations. To make the simulation more realistic and easier to understand, human character models with walking and idle animations were implemented. The first step of this was to download and import a basic human character model and the two basic animations from Mixamo, a site with a variety of template models and corresponding animations.

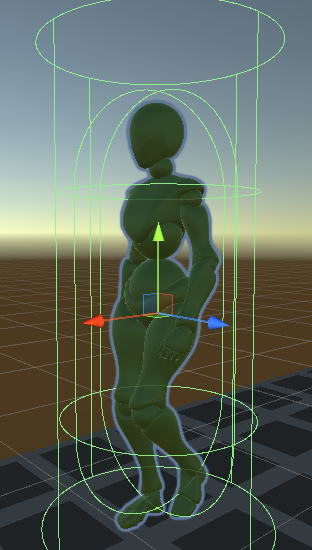


Figure x – Character model

A new agent prefab was then created using this model and an animator was attached. The animator was designed so the agent’s animations would transition between the imported idle and walking animations based on a Boolean variable.

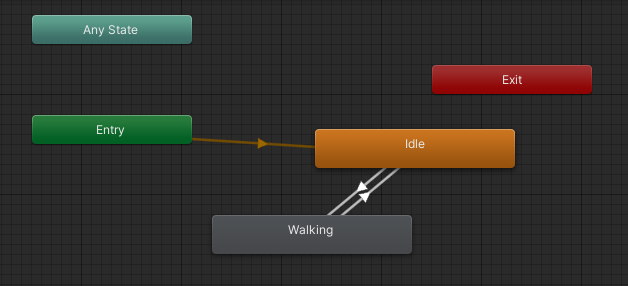


Figure x – Animator

An animation state controller script was then written and attached to the agent. This script constantly checks the magnitude of the agent, and if it is above a set threshold the walking check Boolean is set to true which makes the animator play the walking animation. Otherwise, if the magnitude is below the threshold, the walking check Boolean is set to false which makes the animator play the idle animation.

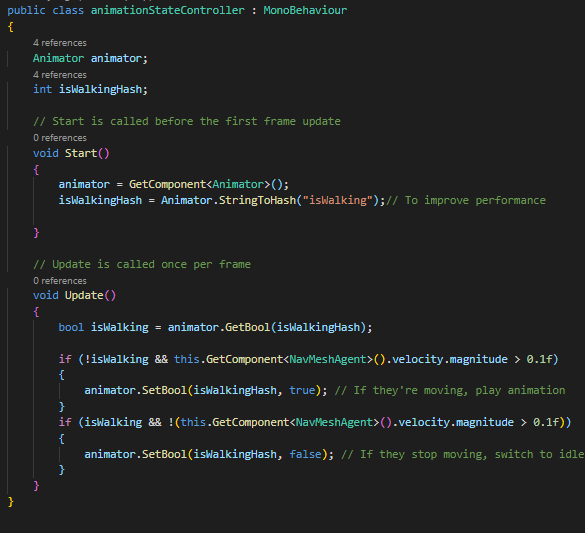


Figure x – Animation state controller

With the agents now having real models, code was added to the working behaviour which made the agent face the same direction their chair is pointing in, so they would face their desk once they arrived.

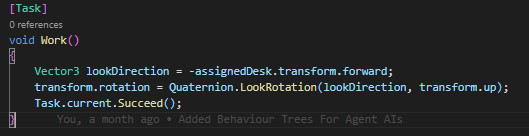


Figure x – Make agent face desk

After the successful implementation of character models and getting the agents to face their desk, a bug was discovered in the behaviour tree. As soon as the agents began moving to their desk, they went straight to the work behaviour, so they did not face their desk when they eventually arrived. This was fixed by rearranging the trees and making a move tree so the agents would only begin working once they arrived.

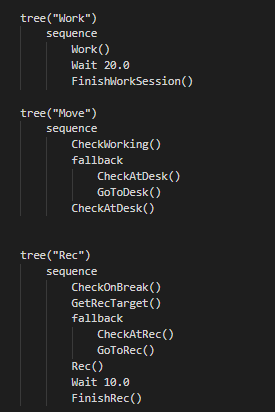


Figure x – Updated behaviour tree

Due to the agents no longer having a single material, the particle collision script was updated to change all the agent’s materials, using similar code from when an objects material is changed.

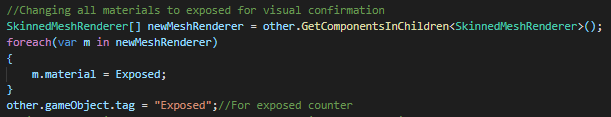


Figure x – Changing agents materials

## 4.11. Working hours and end screen

Now that the simulation has most of the core concepts implemented, a working hours mechanic and end screen were added. To begin implementing the concept of working hours, the behaviours were adjusted one final time. The concept was to have the agents only work in the office for a set amount of time, and be constantly checking if that time had ended, at which point they would leave the office. This was done by adding another behaviour tree which the agents move to and check every time they finish another tree.

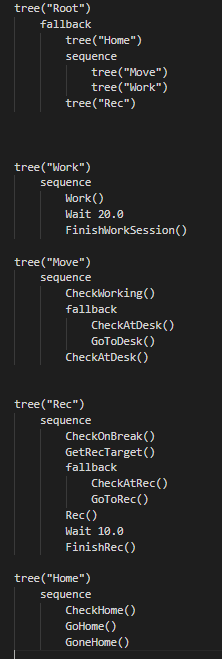


Figure x – Final behaviour tree

An empty game object was added to the scene outside the front door of the office, so once the set time has passed, the agents target is set to this location. Then once they get near the front door the agents colliders are disabled to prevent any infection taking place after they leave the office.

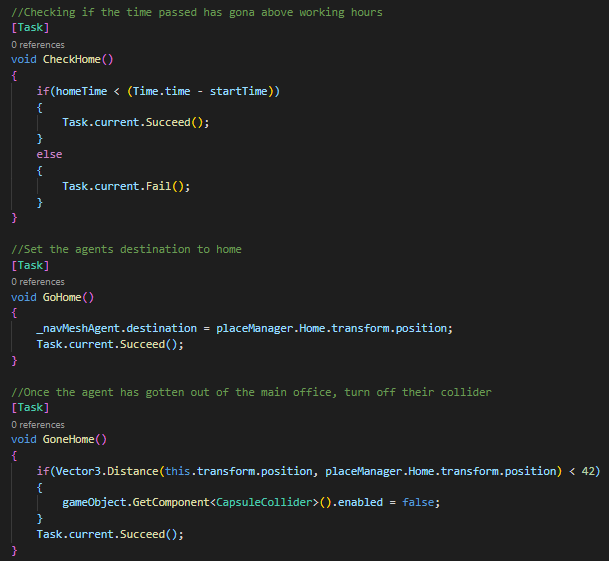


Figure x – Working hours behaviours

With the agents entering the scene at the beginning of the simulation and leaving after a set time, a slider was added to the start screen to allow the user to change the length of time the agents work in the office for. This was easily done by having the agent prefab reference this sliders value when it sets the working hours once the agent is enabled by the start button. The time at which the agents were enabled also had to be captured, so the time spent on the start screen was not considered in the check.

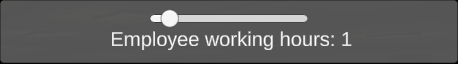


Figure x – Working hours slider

For the sake of user experience, the value on the slider was multiplied by 60 and then the working hours were set to that number of seconds. So, if the user selected 2 hours, the actual time would be set to 2 minutes.

An end screen was then added for when agents leave the office. This was implemented by capturing the time at which the agents were enabled and checking if the set working hours had passed. An extra 25 seconds were added to the working hours for this check to give the agents enough time to finish their current task and then walk to the door. Once this check succeeds, the other UI elements are disabled and an end screen is displayed, which displays the number of agents that were set to exposed during the simulation. This was done by finding all the objects in the scene with the exposed tag and displaying the value. The code has a check to make sure it is only run once so values will not change once they are added to the end screen.

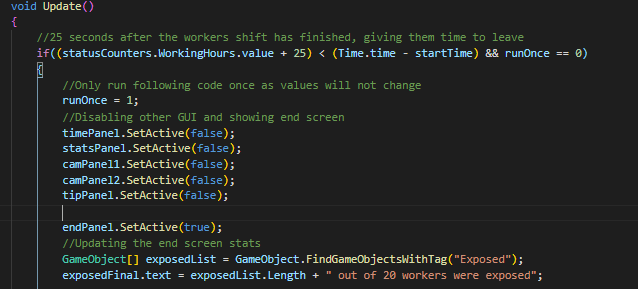


Figure x – End screen code

Buttons to restart or quit the application were then also added to the end screen. The quit button calls a method which quits the application, or if it is open in the Unity editor it just unplays the scene.

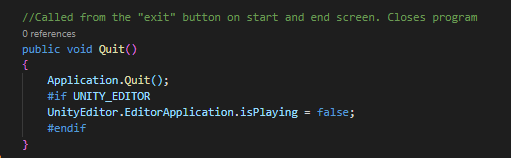


Figure x – Quit application code

The restart button just calls a method which gets the name of the scene currently running and loads it again.



Figure x – Restart scene code

During this stage of development, a bug began occurring in which some of the particle collisions were not registering. In an effort to fix this, the Unity version was updated to Unity 2020.3.1f1, which is the 2020 LTS release of Unity. After this, some debugging and further research were done and the solution was found, which was to set all the agents to “isKinematic”. This controls whether the agent’s Rigidbody is affected by physics or not and was most likely accidentally unset earlier in development.

## 4.12. Masks and vaccines

To add more intractability, some more options were added to the start screen which alter certain features of the simulation. The first toggle being whether the infectious agent is wearing a mask or not, then a toggle for whether the healthy agents wear masks, and finally a toggle for whether the healthy agents are vaccinated or not. There were more toggles planned to be implemented but development fell behind schedule and these toggles were prioritised as they would have the most visible effects on the simulation.

The first step was to make a 3d model of a mask which would be displayed on the agents face if they are set to wearing a mask. This 3d model was made with a 3d modelling tool called blender, then imported to the project, at which point colour was added and it was put onto the head of the agent prefab.

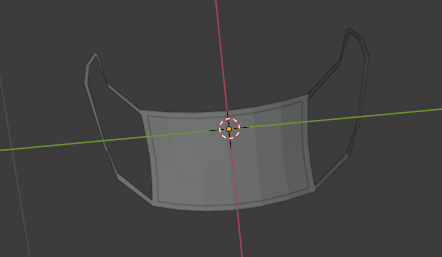


Figure x – Blender mask model

A Boolean variable was then added to each agent’s behaviour script which is changed based on the toggles. If the agent is tagged as infectious, it checks the “infectious agent wearing mask” toggle and sets the Boolean to that value. Otherwise, it checks the “healthy agent wearing mask” toggle and sets the Boolean to that value. It then checks the value of the Boolean and sets the mask to active if its true or inactive if its false.

Due to masks highly reducing the number of particles emit in a real situation, a second particle system was added to the infectious agent that is disabled by default. This particle system emits particles significantly slower that travel a much smaller distance. The number of particles emit is also cut down by 77%, which is a number taken from a WHO backed study on masks which was mentioned in the literature review.

There is then another if statement which checks if the agent is tagged as infectious and if their mask boolean is set to true. If this if succeeds, it disables the normal particle system and enables this variant particle system.

Then for vaccines a similar concept was implemented by importing a PNG of a vaccine and adding it to a canvas above the prefab agent’s head which was disabled by default. To ensure this PNG always faces the player, a script was written and attached to the canvas that was constantly changing the rotation to face the direction of the active camera.

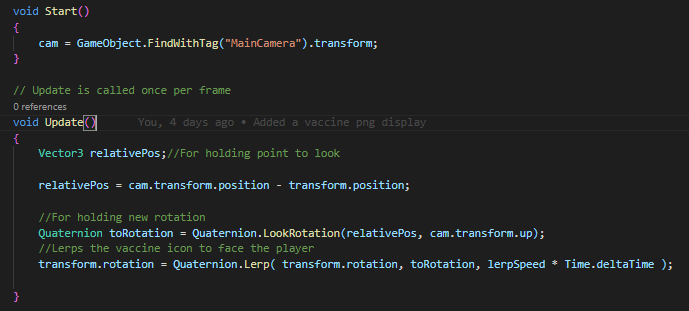


Figure x – Face player script



Figure x – Vaccine indicator

Then the same logic was used, getting the value of the vaccine toggle, and enabling the vaccine indicator if the toggle is set to true and the agent is tagged as healthy.

Finally, some code was added to the particle collision script to make these toggles have an affect on the chances of infection. This started off by having 2 variables, maskPreventionChance and vaccinePreventionChance, which are both set to negative values by default. Then, if the collided agent is wearing a mask, the maskPreventionChance is set to 0.77, representing a 77% chance of prevention which was taken from the same WHO backed study on masks mentioned earlier. If the collided agent is vaccinated, the vaccinePreventionChance is set to 0.95, representing a 95% chance of prevention which was taken from the Pfizer website, as mentioned in the literature review. The calculation is then made, generating a random value between 0 and 1 for each calculation and checking if the random values are greater than the prevention chances.

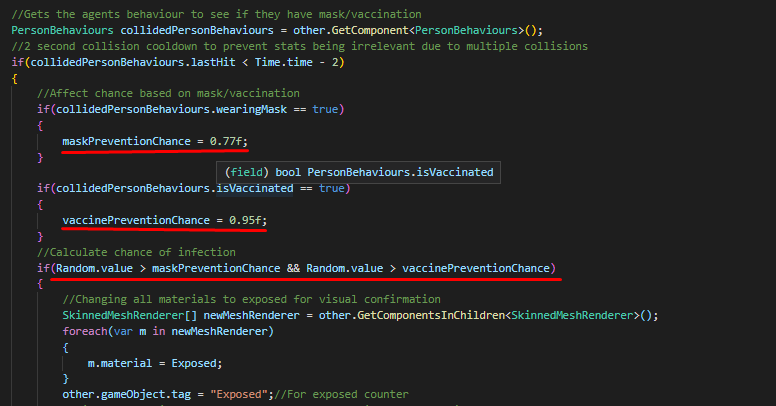


Figure x – Infection chances

If the agent were neither wearing a mask nor vaccinated, both prevention chances would still be a negative value, so the random values have a 100 % chance of being greater than them and infecting the agent.

If the agent were only wearing a mask, the vaccination prevention chance would be irrelevant as it would still be negative, so the chance of infection would be 23 % as there is a 23/100 chance the random value will be above 77.

If the agent were only vaccinated, the mask prevention chance would be irrelevant as it would still be negative, so the chance of infection would be 5 % as there is a 5/100 chance the random value will be above 95.

If the agent were wearing a mask and were vaccinated, both checks would take place. There would be a 23% chance it succeeds the first check and a 5% chance it succeeds the second check. It needs to succeed both to go forward (.23 \* .005), so the final chance of infection would only be 1.15%

## 4.13. Contaminated surfaces and agents

Now that the infection model has been expanded upon, the mechanic of agents getting infected from surfaces was implemented. This was done by first creating an empty game object with a particle system attached and saving it as a prefab. This particle system only spawns a few particles in a small area, with a small amount of noise. The particle collision script was then modified so when a particle collided with an object or surface, this particle system game object was instantiated on the collided object.



Figure x – Adding contamination particles

For agents to become exposed from these particles, a new script was added to this particle system game object prefab. This script is practically the same as the particle collision script, although this new script only registers the collisions with agents, so if the particles collide with any other objects, the infection will not be spread. This was decided as it would not make sense for a contaminated surface to be able to contaminate other surfaces.

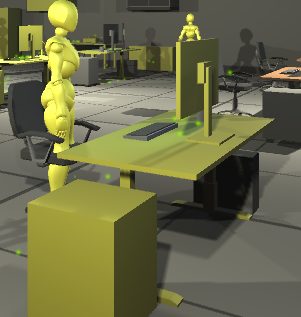


Figure x – Contaminated surface with particles

Finally, another empty game object was created with a particle system attached and saved as a prefab. This particle system also only spawns a small number of particles, but they emit in a shape similar to the shape of the character model. This is to visually demonstrate that the agents clothes are contaminated with viral particles. Both collision scripts were modified so when an agent becomes exposed, this particle system game object is instantiated on them. The same modified collision script was added to this particle system game object prefab, so exposed agents have a small chance of exposing other agents if they touch off each other, but they will not contaminate surfaces.



Figure x – Exposed agent with particles on their body.

The infection can now spread from breathing in infectious particles, interacting with a contaminated surface, or touching off another exposed agent. All of these possible transmission events take into account whether the agent is wearing a mask and/or is vaccinated.

## 4.14. Finishing UI

Now that all of the core mechanics were implemented, the start screen, end screen and other UI elements were greatly improved, and some bugs were fixed. Some black box testing was carried out which helped indicate problems with the UI and simulation.

The start screen was aligned more symmetrically, a short explanation of the system was added and a panel was added which informs the user that they will be able to adjust the timescale, in the same place that the new timescale panel is. A bug was noted that the player could walk while the start screen is being displayed, so player movement is set to disabled until the start button is pressed.



Figure x – Final start screen

Various UI elements were resized, and panel for the timescale was added in the corner. This panel also displayed the elapsed time and the time left until the working hours end. An FPS counter was also added, as during the initial black box testing the build was run on a very low-end laptop and did not seem to perform as well as other devices. Finally, an “Escape to restart” panel and behaviour was added to allow users to quickly go back to the start screen, as a black box tester noted that in order to restart that had to wait for the simulation to end or close the program.



Figure x – Final UI elements

The elapsed time and time left counters were added by displaying the time passed since the user clicked the start button and displaying the difference between the working hours and the above value. The time left value was clamped above 0 to avoid displaying negative numbers at the end of the simulation.



Figure x – Time displays

The FPS counter was implemented by displaying the value of 1 divided by unscaledDeltaTime.

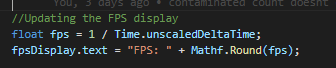


Figure x – FPS Display

Finally, many counters were added to the end screen, with buttons to restart or quit the simulation.

The values of the 4 interactable components on the start screen are displayed by simply checking what their values were set to. Then the item counts were implemented by searching for all of the items with their respective tags in the scene and displaying the number.

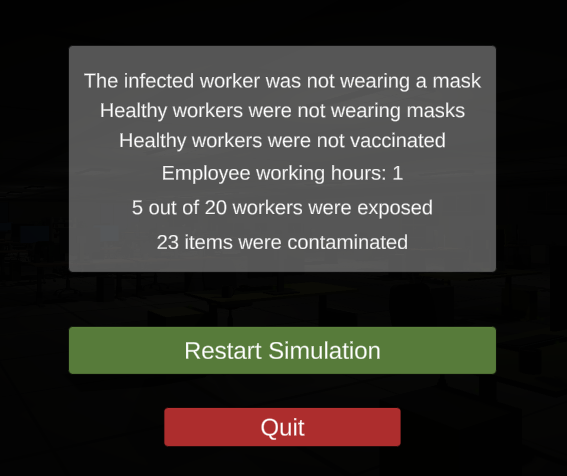


Figure x – End screen

## 4.15. Conclusions

In this chapter, the development process was outlined and discussed. The development went quite well, with the majority of the key features that were planned to be implemented ending up being successfully implemented in some way. Every section of development provided its own set of challenges, but in the end they were all great learning experiences.

There were more features planned to be added to the simulation, as well as known bugs that were planned to be fixed, but there was not enough time so they will be mentioned in the evaluation and future work chapters alongside the feedback received from the black box and white box testing.

# 5. Testing and Evaluation

## 5.1. Introduction

This chapter outlines the testing the system went through during and after the development process, and how corrections were made, and bugs were spotted. An evaluation of the project is then discussed, evaluating the system, and looking at results from the simulation itself.

## 5.2. System Testing

### 5.2.1 Testing during development

During the process of development, the implementation of each feature was followed with various self-tests to ensure the simulation was run as it was supposed to. Some black box testing was also intermittently done with third parties, by making a build of the project and sending it on to other students. This process was useful for finding overlooked solutions and fixing any bugs that weren’t easy to spot. At a few points in development, the project was also explained to and evaluated by Dr Zach Tan, who gave his opinion on what features should be prioritised and how to display the methods of transmission.

### 5.2.2 Testing after development

Once development was finished, the project was published to <https://kyleheffernan.itch.io/covisim>

Itch.io is a platform that lets independent creators upload their projects and other users can download and run them. A google form with some questions about the simulation was created and added to this page. Other Itch.io users would see this in their feed, and possibly be drawn to downloading and testing the project. This link was then also sent to numerous Discord servers focused on game development, college projects, Unity, Irish developers etc. Quite a sizeable amount of people downloaded the simulation and filled out the form.

Question 1 was just to ascertain if the user could download the project and run the simulation without problems. All but one of the answers were yes, with the outlier stating, “I have an old computer so it ran ok”. The project seemed to be able to run completely fine and smoothly on most systems, so the overall performance and optimisation of the system was deemed good. The only issue being low end systems, which could have done with better optimisation.

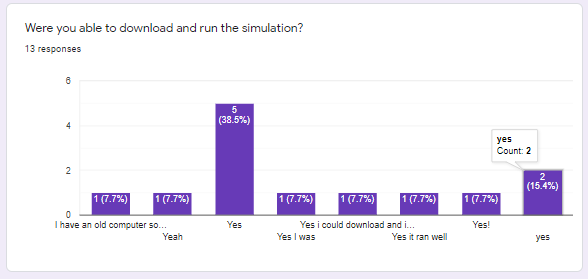


Figure x – Google form Q1

Question 2 was just to get the users overall opinion of the project. The responses to this question were all very positive.

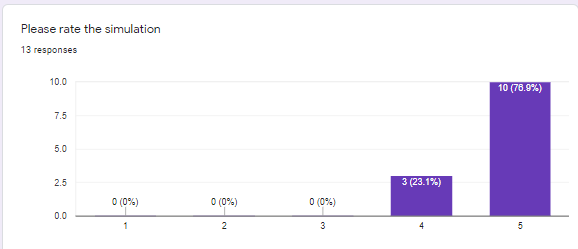


Figure x – Google form Q2

Question 3 was to ascertain whether it was clear what was happening in the simulation, as the simulation aims to make the method of transmission clear and easy to understand. The responses were again all very positive.

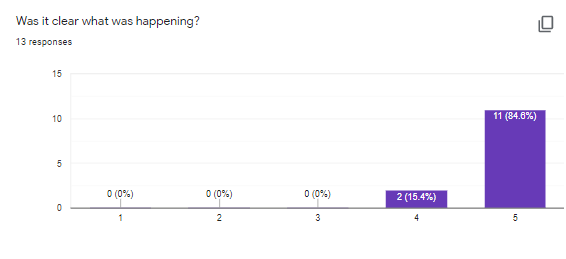


Figure x – Google form Q3

Question 4 then asked about suggestions and features to add, and there were quite a few differing answers. One response suggested adding handwashing, which was one of the lower priority features that was planned to be added but cut due to time and could be taken up in future work. Many of the answers focused on adding more customisation to the start screen, such as amount of healthy and infectious agents and more office layouts. Both of these were also planned to be implemented but were not due to time restrictions. Users also suggested more complex behaviours, more realistic models and better movement controls, which all could be undertaken in future work.

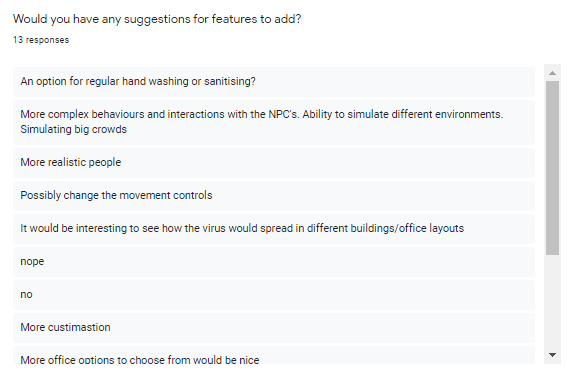


Figure x – Google form Q4

Question 5 asked the users if they experienced any bugs. The only bug found was actually a known bug which was not fixed due to time constraints. This bug occurs if the user changes the timescale but does not click off the slider before they try to move again. This will result in player input moving the slider up and down when it should only be controller their character. This may be able to be fixed by some kind of automatic deselection script, or by changing the movement controls.



Figure x – Google form Q5

Question 6 asked the user how realistic they found the simulation, and the answers were again generally quite positive.

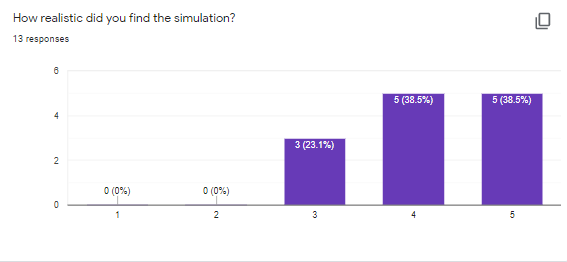


Figure x – Google form Q6

Question 7 asked about the users favourite and least favourite features. Many users enjoyed being able to change the timescale and liked how surfaces that were contaminated turned a different colour. Many users also liked visually seeing how masks and vaccinations affected the spread of the virus. One user did not like the character models and animations, which are relatively basic and could be improved in future work to add more realism to the simulation. Another user felt that the movement was clunky, which again could be improved in future work for a better user experience.



Figure x – Google form Q7

Question 8 and 9 asked if the user ran the simulation multiple times, and if they did, whether they noticed differences in results. Other than a single user that only ran the simulation once, every user noticed changes and commented on how the masks and vaccinations lower the infection rate.

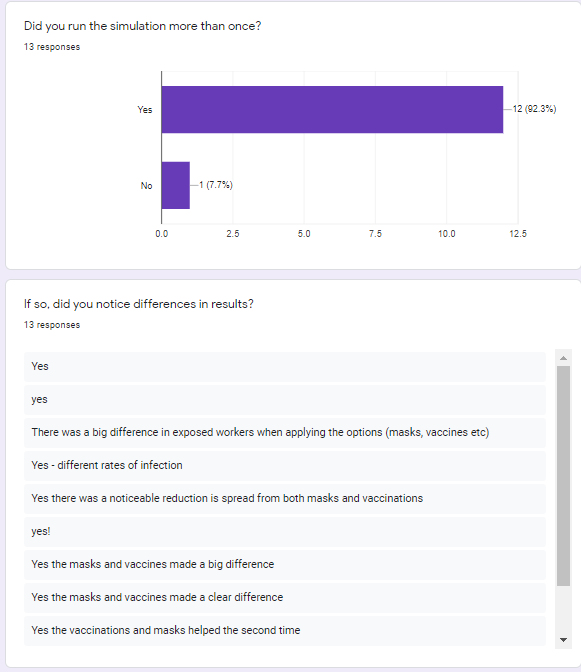


Figure x – Google form Q8, Q9

Finally, question 10 asked if the user felt they better understood the methods of transmission after using the simulation. The answers to this question were overwhelmingly positive, with most users choosing the maximum value.

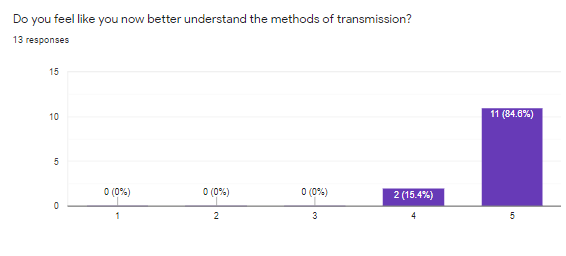


Figure x – Google form Q10

## 5.3. System Evaluation

For the purpose of system evaluation, the project was run sixty times and the number of exposed agents out of 20 were recorded in rounds of 12. The working hours were set to three for all tests to allow a reasonable amount of to pass.

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| A | B | C | D | E |
| 13 | 7 | 6 | 1 | 0 |
| 15 | 1 | 5 | 0 | 0 |
| 17 | 1 | 1 | 1 | 0 |
| 15 | 4 | 1 | 0 | 0 |
| 12 | 0 | 5 | 0 | 0 |
| 15 | 5 | 1 | 1 | 0 |
| 14 | 6 | 4 | 0 | 1 |
| 16 | 7 | 2 | 1 | 0 |
| 14 | 12 | 7 | 1 | 0 |
| 15 | 4 | 3 | 0 | 0 |
| 15 | 2 | 2 | 0 | 0 |
| 12 | 3 | 4 | 1 | 0 |

The first twelve times were run with no settings altered, which is marked as A. This resulted with an average of 14.5 agents exposed.

The next twelve times with infectious agents wearing masks, marked as B. This resulted with an average of 4.1 agents exposed.

The next twelve times with healthy agents wearing masks, marked as C. This resulted with an average of 3.4 agents exposed

The next twelve times with healthy agents vaccinated, marked as D. This resulted with and average

Of .5 agents exposed.

Finally, another twelve times with all settings altered, marked as E. This resulted with an average of 0.08 agents exposed.

Both masks and vaccines are shown to have a tremendous effect on the transmission rates, and when every agent is both wearing a mask and vaccinated the transmission rate is negligible.

## 5.4. Conclusions

In this chapter, the process of testing the simulation was outline and the feedback was discussed. An evaluation of the project is then discussed, evaluating the system, and looking at results from the simulation itself.

# 6. Conclusions and Future Work

## 6.1. Introduction

In this chapter, some reflections on the project

## 6.2. Conclusions

## 6.3. Future Work

More features – handwashing, multiple offices, amount of people coming in, amount of infected

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