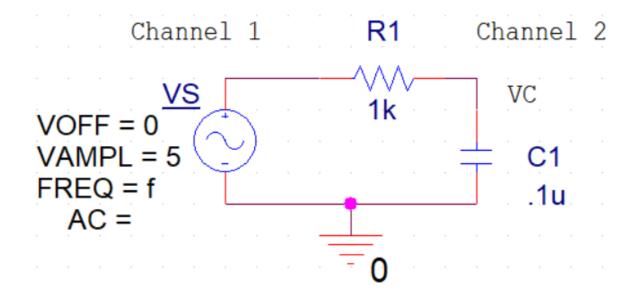
## ECE 2101L Lab #1

# The Sinusoidal Steady State Responses Of First Order RC Circuits



Kyler Martinez and Daniel Ruiz – Group 2 September 12<sup>th</sup>, 2020

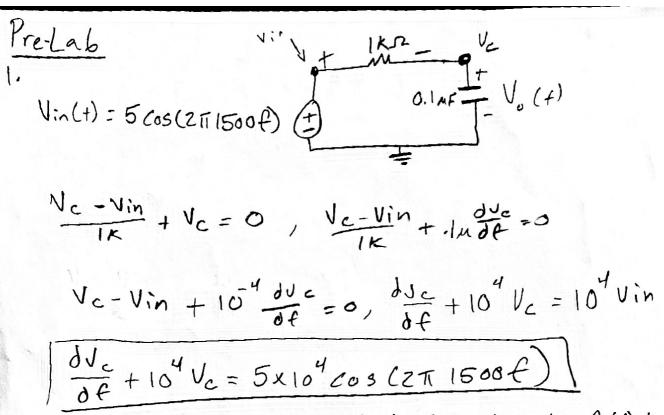
## **Objective**

The objective of the lab be able to theoretically find the steady state response of RC circuits when powered by a sinusoidal power supply and then compare that to data found through a simulation or provided by the instructor. Another objective is to be able to configure the necessary lab equipment to collect the necessary data for the lab.

## **Materials**

The necessary equipment needed for the lab are as follows

- 1. Clip leads
- 2. Breadboard
- 3. Resistors of value  $1k\Omega$  and  $2k\Omega$
- 4. Capacitor of value 0.1μF
- 5. Oscilloscope with two channel input and 4 BNC to clip connectors
- 6. Function generator
- 7. Digital multimeter and LCR meter



Assuming the solution to be of the form A COS(ZTIF(+)+0)

/sf (A cos (Z \( \pi f(\f) + \te) + 10 \( A \cos (Z \( \pi f + \te) = 5 \text{ } 10 \( Cos (Z \( \pi \) 1 \) (0 \( \pi S \) \( \pi S \) (2 \( \pi f \) (1 \) (1 \) (2 \( \pi f \) (1 \) (1 \) (2 \( \pi f \) (3 \( \pi f

T(A·10)2+(A·-211f)2 (OS(271ff+0+toin1(271ft))=5x10 (OS(211500))

A 70, so We can cancel the Variable from the tain argument

since if A=0, then the argument can't be computed.

$$A \int 10^{8} + (2\pi f)^{2} = 5 \times 10^{4}$$

$$A = \frac{5 \times 10^{4}}{\sqrt{10^{8} + (2\pi (1500)^{2})}}$$

$$A = \frac{5 \times 10^{4}}{\sqrt{10^{8} + (2\pi (1500)^{2})}}$$

$$A = 3.6386$$

$$2 \pi (1500 f) + \Theta + + an(\frac{2\pi f}{10^{4}}) = 2\pi 1500 f$$

$$\Theta = - + an(\frac{2\pi (1500)}{10^{4}})$$

$$\Theta = - + an(\frac{2\pi (1500)}{10^{4}})$$

Vin = 5 cos (2 Ti (2000) +) 2. Vin ( ) ZKR T- INF 2K ( Vc-Vin + Vc + cvc) = 0, 2Vc- 2Vin + Vc + (K) COUC = 0 3 Ve + 2 x 10 4 due 2 Vin, dVc + 1.5 x 10 4 Ve = 5x10 4 Cas(2Ti (2000)f) Assuming a solution of the form A cos(ZTf & + E) 90f (Acos (2πff+0)+3/2×104 (Acos(2πff+0) = 5×104cos(2π(2000)€) F2TIS ILA Sin(ZTIFF+0)+3/X104/A(05(ZTIFF+0)=5X104 COS(ZTICOOO) Using the tris identity c sinx + B cosx = \[ \int B^2 + C^2 \cos(x + tan'(-\fine )) \] Ve can cancel A since A to since if A=0 than tan argument

(Can't be computed, and if A=0, then OCOSCX) can never early 5x10 (05(xi)) AJ(275)2+(2.25x108) = 5x104 8+271(2000) f + tan' (275)=271(2000) f 0 = -tan (211f)  $A = \frac{5 \times 10^{7}}{\sqrt{(2\pi \cdot 200)^{2} + (2.25 \times 10^{8})}}$ 

A = 2.5552  $\theta = -39.955^{\circ}$ 

(Vc(+) = 2.555 cos(21162000)f -39.960)[V]

#### Procedure

To begin the lab, we first made a list of the materials that we would need to complete the lab. We then constructed the circuits shown in figures 1 and 2, see below. We then simulated the circuits in PSPICE and placed voltage probes at the different nodes, marked with channel 1 and channel two. This was done to find the information necessary to discern the voltage response of the components of the circuit. We used the measurement tools to find information to build the response such as the amplitude of the input signals, the periods of the waves, and two times where the signal equaled zero which were in the same period and either both decreasing or increasing. We found the phase shift by using the equation  $(t_S-t_c)*360/T$ , where T is the period of the signal, and  $t_S$  is the time where the voltage source equaled zero and  $t_C$  is when the component equaled zero. These calculations were performed and displayed in PSPICE for convenience. We then demonstrated this process to the professor.

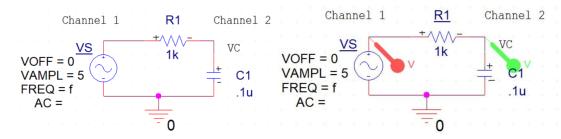


Figure 1: Circuit 1 with an AC power source and 1k Ohm resistor and .1 micro farad capacitor and version with probes

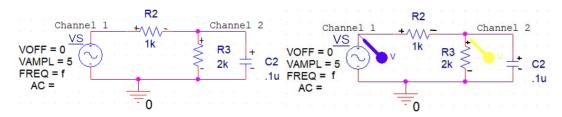


Figure 2: Circuit 1 with an AC power source and 1k & 2k Ohm resistor and .1 micro farad capacitor

## **Results**

The oscilloscope pictures have been altered to display the channel numbers that correspond with the circuit, other than that, no other alterations have been made. To represent waiting for steady state, we took measurements from time periods once steady state had been reached.

#### Circuit 1: f= 500 HZ

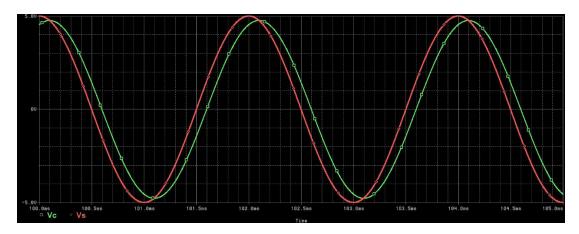


Figure 3: Vs and Vc when f= 500 Hz

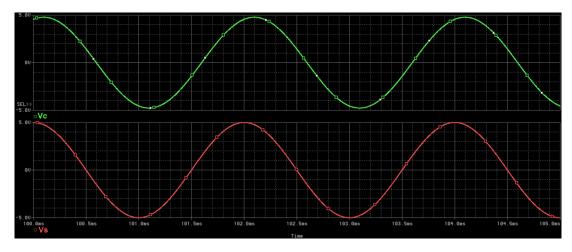


Figure 4: Vs and Vc separately when  $f=500~{\rm Hz}$ 

Evaluate	Measurement	Value
~	XatNthY(V(C1:2),0,1)	100.59689m
~	Max_XRange(V(VS:+),100ms,1s)	5
~	Max_XRange(V(C1:2),100ms,1s)	4.77014
~	Period(V(R1:2))	2.00000m
~	Period(V(VS:+))	2.00000m
~	XatNthY(V(VS:+),0,1)	100.50000m
~	1/Period(V(R1:2))	500.00000
~	1/Period(V(VS:+))	500.00000
~	(XatNthY(V(VS:+),0,1) - XatNthY(V(	-17.44061

Figure 5: Measurement Results when f = 500 Hz

Characteristic	Measured Value
V <sub>S</sub> Amplitude	5V
V <sub>C</sub> Amplitude	4.77014V
V <sub>C</sub> Period	2 ms
V <sub>C</sub> Frequency	500 Hz
Time Where V <sub>S</sub> =0 From Max (Same Period)	100.50000ms

Time Where V <sub>C</sub> =0 From Max (Same Period)	100.59689ms
Phase Angle V <sub>C</sub> to V <sub>S</sub>	$-17.44061^{0}$

Table 2: Measurements of circuit 1 when f = 500 Hz

$$V_S = 5 \cos(2\pi * 500 * t) [V]$$

 $V_C = 4.770 \cos(2\pi * 500t - 17.44^0) [V]$ 

## <u>Circuit 1: f= 1500 HZ</u>

## Oscilloscope:

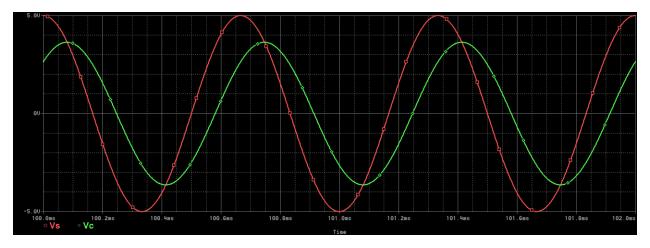


Figure 6: Vs and Vc when f= 1500 Hz

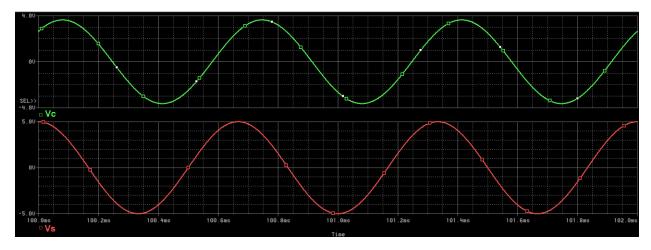


Figure 7: Vs and Vc separately when f= 1500 Hz

Evaluate	Measurement	Value
	XatNthY(V(C1:2),0,1)	100.24686m
~	Max_XRange(V(VS:+),100ms,1s)	5
~	Max_XRange(V(C1:2),100ms,1s)	3,63862
~	Period(V(R1:2))	666.66667u
~	Period(V(VS:+))	666.66667u
~	XatNthY(V(VS:+),0,1)	100.16667m
~	1/Period(V(R1:2))	1.50000k
~	1/Period(V(VS:+))	1.50000k
~	(XatNthY(V(VS:+),0,1) - XatNthY(V(	-43,30401

Figure 8: Measurement Results when f = 1500 Hz

Characteristic	Measured Value
V <sub>S</sub> Amplitude	5V
V <sub>C</sub> Amplitude	3.63862V
V <sub>C</sub> Period	666.66667µs
V <sub>C</sub> Frequency	1500 Hz
Time Where V <sub>S</sub> =0 From Max (Same Period)	100.16667 ms
Time Where V <sub>C</sub> =0 From Max (Same Period)	100.24686 ms
Phase Angle V <sub>C</sub> to V <sub>S</sub>	-43.30401 <sup>0</sup>

Table 3: Measurements of circuit 1 when f = 1500 Hz

$$V_S = 5 \cos(2\pi * 1500 * t) [V]$$

$$V_C = 3.639\cos(2\pi*1500t - 43.30^{\circ})$$
 [V]

## <u>Circuit 1: f= 4000 HZ</u>

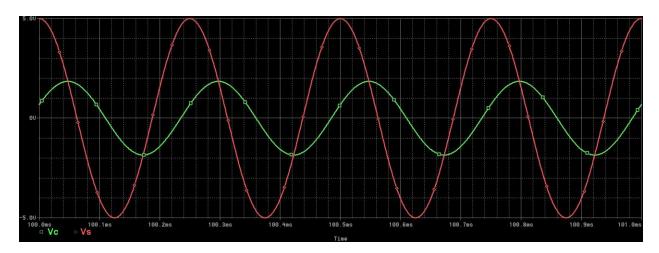


Figure 9: Vs and Vc when f= 4000 Hz

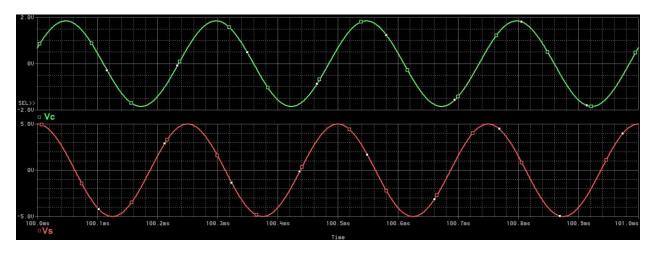


Figure 10: Vs and Vc separately when f= 4000 Hz

	Evaluate	Measurement	Value
	~	XatNthY(V(C1:2),0,1)	100.10993m
	✓	Max_XRange(V(VS:+),100ms,1s)	5
	<u>~</u>	Max_XRange(V(C1:2),100ms,1s)	1.84841
	<u>~</u>	Period(V(R1:2))	249.99999u
	~	Period(V(VS:+))	250.00000u
	<u>~</u>	XatNthY(V(VS:+),0,1)	100.06250m
	~	1/Period(V(R1:2))	4.00000k
	<u>~</u>	1/Period(V(VS:+))	4.00000k
<b>•</b>	<u>~</u>	(XatNthY(V(VS:+),0,1) - XatNthY(V(	-68.30397

Figure 11: Measurement Results when f = 4000 Hz

Characteristic	Measured Value
V <sub>S</sub> Amplitude	5V
V <sub>C</sub> Amplitude	1.84841V
V <sub>C</sub> Period	249.99999μs
V <sub>C</sub> Frequency	4000 Hz
Time Where V <sub>S</sub> =0 From Max (Same Period)	100.06250ms
Time Where V <sub>C</sub> =0 From Max (Same Period)	100.10993ms
Phase Angle V <sub>C</sub> to V <sub>S</sub>	-68.30397 <sup>0</sup>

Table 3: Measurements of circuit 1 when f = 4000 Hz

$$V_S = 5 \cos(2\pi * 4000 * t) [V]$$

 $V_C = 1.848 cos(2\pi*4000t-68.30^0)$  [V]

## Circuit 2: f= 1000 HZ

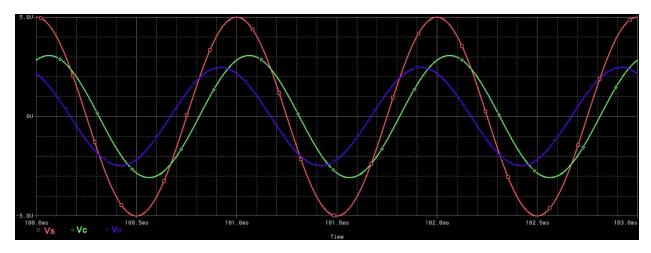


Figure 12: Vs, Vc, and  $V_R$  when f=1000~Hz

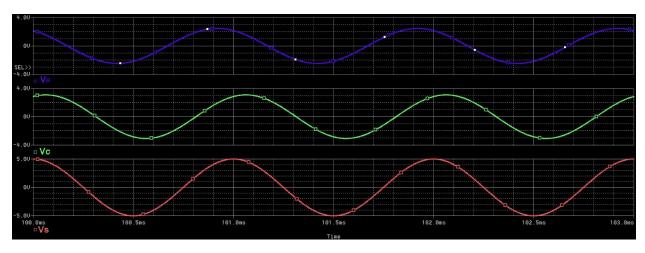


Figure 13: Vs, Vc, and  $V_R$  separately when f= 1000 Hz

Measurement	Value	
XatNthY(V(C2:2),0,1)	100.31313m	
Max_XRange(V(V2:+),100ms,1s)	5	
Max_XRange(V(C2:2),100ms,1s)	3.07450	
Period(V(C2:2))	1.00000m	
Period(V(V2:+))	1.00000m	
XatNthY(V(V2:+),0,1)	100.25000m	
1/Period(V(C2:2))	1000.00000	
1/Period(V(V2:+))	1000.00000	
(XatNthY(V(V2:+),0,1) - XatNthY(V(C2:2),0,1))*360 /(Period_XRange(V(V2:+),100ms,1s))	-22.72785	
Max_XRange((V(V2:+)-V(C2:2)),100ms,1s)	2.46878	
XatNthY((V(V2:+)-V(C2:2)),0,1)	100.17011m	
Period((V(V2:+)-V(C2:2)))	1.00000m	
1/Period((V(V2:+)-V(C2:2)))	1000.00000	
(XatNthY(V(V2:+),0,1) - XatNthY((V(V2:+)-V(C2:2)),0,1) )*360 /(Period_XRange(V(V2:+),100ms,1s))	28.76035	

Figure 14: Measurement Results when f = 1000 Hz

Characteristic	Measured Value
V <sub>S</sub> Amplitude	5V
V <sub>C</sub> Amplitude	3.07450V

V <sub>R</sub> Amplitude	2.46878V
V <sub>C</sub> Period	1.00000ms
V <sub>R</sub> Period	1.00000ms
V <sub>C</sub> Frequency	1000 Hz
V <sub>R</sub> Frequency	1000 Hz
Time Where V <sub>S</sub> =0 From Max (Same Period)	100.25000ms
Time Where V <sub>C</sub> =0 From Max (Same Period)	100.31313ms
Time Where V <sub>R</sub> =0 From Max (Same Period)	100.17011ms
Phase Angle V <sub>C</sub> to V <sub>S</sub>	$-22.72785^{0}$
Phase Angle V <sub>R</sub> to V <sub>S</sub>	$28.76035^{0}$

Table 4: Measurements of circuit 2 when f = 1000 Hz

$$V_S = 5 \cos(2\pi * 1000*t) [V]$$

$$V_C\!=\!3.075cos(2\pi^*1000t-22.73^0)\text{ [V]}$$

$$V_R = 2.47 cos(2\pi*1000t + 28.76^0)$$
 [V]

## <u>Circuit 2: f= 2000 HZ</u>

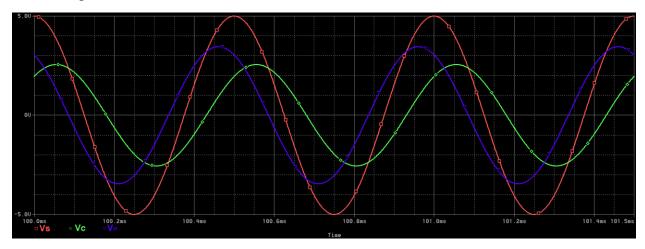


Figure 15: Vs, Vc, and  $V_R$  when f=2000 Hz

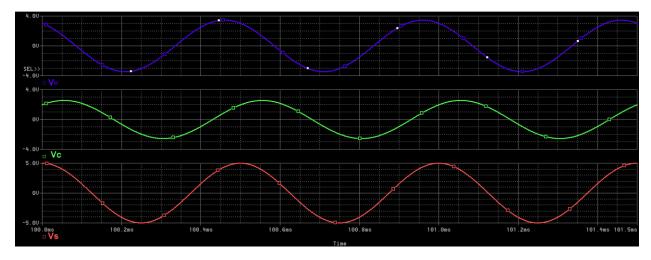


Figure 16: Vs, Vc, and  $V_R$  separately when f=2000 Hz

Evaluate	Measurement	Value
<u> </u>	XatNthY(V(C2:2),0,1)	100.18049m
<u> </u>	Max_XRange(V(V2:+),100ms,1s)	5
<u>v</u>	Max_XRange(V(C2:2),100ms,1s)	2.55515
<u> </u>	Period(V(C2:2))	500.00000u
<u> </u>	Period(V(V2:+))	500.00000u
<u>v</u>	XatNthY(V(V2:+),0,1)	100.12500m
<u>~</u>	1/Period(V(C2:2))	2.00000k
<u>~</u>	1/Period(V(V2:+))	2.00000k
<b>▽</b>	(XatNthY(V(V2:+),0,1) - XatNthY(V(C2:2),0,1) )*360 /(Period_XRange(V(V2:+),100ms,1s))	-39.95522
<u>~</u>	Max_XRange((V(V2:+)-V(C2:2)),100ms,1s)	3.45577
<u>~</u>	XatNthY((V(V2:+)-V(C2:2)),0,1)	100.08563m
<u>~</u>	Period((V(V2:+)-V(C2:2)))	500.00000u
<u>~</u>	1/Period((V(V2:+)-V(C2:2)))	2.00000k
~	(XatNthY(V(V2:+),0,1) - XatNthY((V(V2:+)-V(C2:2)),0,1) )*360 /(Period_XRange(V(V2:+),100ms,1s))	28.34801

Figure 17: Measurement Results when f = 2000 Hz

Characteristic	Measured Value
V <sub>S</sub> Amplitude	5V
V <sub>C</sub> Amplitude	2.55515V
V <sub>R</sub> Amplitude	3.45577V
V <sub>C</sub> Period	500μs
V <sub>R</sub> Period	500μs
V <sub>C</sub> Frequency	2000 Hz
V <sub>R</sub> Frequency	2000 Hz
Time Where V <sub>S</sub> =0 From Max (Same Period)	100.12500ms
Time Where V <sub>C</sub> =0 From Max (Same Period)	100.18049ms
Time Where V <sub>R</sub> =0 From Max (Same Period)	100.08563ms
Phase Angle V <sub>C</sub> to V <sub>S</sub>	$-39.95522^{0}$
Phase Angle V <sub>R</sub> to V <sub>S</sub>	$28.34801^{0}$

Table 5: Measurements of circuit 2 when f = 2000 Hz

$$V_S = 5 \cos(2\pi * 2000 * t) [V]$$

$$V_C = 2.555\cos(2\pi * 2000t - 39.96^0)$$
 [V]

$$V_R = 3.46\cos(2\pi * 2000t + 28.35^0)$$
 [V]

#### Circuit 2: f= 4000 HZ

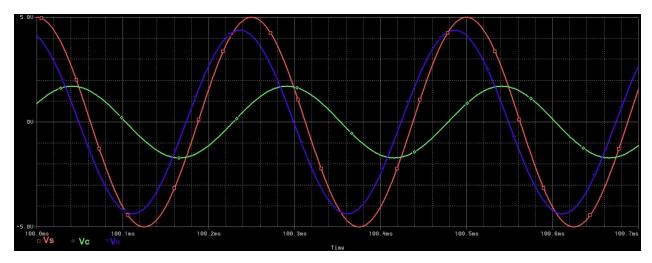


Figure 18: Vs, Vc, and  $V_R$  when f= 4000 Hz

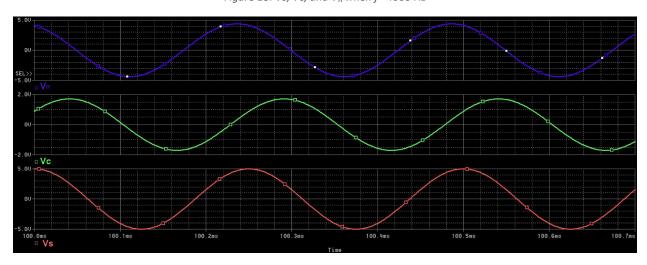


Figure 19: Vs, Vc, and  $V_R$  separately when f= 4000 Hz

Measurement	Value	
XatNthY(V(C2:2),0,1)	100.10359m	
Max_XRange(V(V2:+),100ms,1s)	5	
Max_XRange(V(C2:2),100ms,1s)	1,70825	
Period(V(C2:2))	249.99999u	
Period(V(V2:+))	250.00000u	
XatNthY(V(V2:+),0,1)	100.06250m	
1/Period(V(C2:2))	4.00000k	
1/Period(V(V2:+))	4.00000k	
(XatNthY(V(V2:+),0,1) - XatNthY(V(C2:2),0,1))*360 /(Period_XRange(V(V2:+),100ms,1s))	-59,17119	
Max_XRange((V(V2:+)-V(C2:2)),100ms,1s)	4,37765	
XatNthY((V(V2:+)-V(C2:2)),0,1)	100.04890m	
Period((V(V2:+)-V(C2:2)))	250.00001u	
1/Period((V(V2:+)-V(C2:2)))	4.00000k	
(XatNthY(V(V2:+),0,1) - XatNthY((V(V2:+)-V(C2:2)),0,1))*360 /(Period_XRange(V(V2:+),100ms,1s))	19.57751	

Figure 20: Measurement Results when f = 4000 Hz

Characteristic	Measured Value
V <sub>S</sub> Amplitude	5V

V <sub>C</sub> Amplitude	1.70825V
V <sub>R</sub> Amplitude	4.37765V
V <sub>C</sub> Period	249.99999µs
V <sub>R</sub> Period	250.00001μs
V <sub>C</sub> Frequency	4000 Hz
V <sub>R</sub> Frequency	4000 Hz
Time Where V <sub>S</sub> =0 From Max (Same Period)	100.06250ms
Time Where V <sub>C</sub> =0 From Max (Same Period)	100.10359ms
Time Where V <sub>R</sub> =0 From Max (Same Period)	100.04890ms
Phase Angle V <sub>C</sub> to V <sub>S</sub>	$-59.17119^0$
Phase Angle $V_R$ to $V_S$	19.57751 <sup>0</sup>

Table 6: Measurements of circuit 2 when f = 4000 Hz

$$V_S = 5 \cos(2\pi * 4000 * t) [V]$$

$$V_C = 1.708\cos(2\pi *4000t - 59.17^0)$$
 [V]

$$V_R = 4.378\cos(2\pi *4000t + 19.58^0)$$
 [V]

#### **Problems**

1.

Percent difference was calculated using the following equation

$$\frac{|\textit{V}_{\textit{CTheortical}} - \textit{V}_{\textit{CSimulated}}|}{\textit{V}_{\textit{CTheortical}}} * 100$$

For phase angle, we substituted the phase angle values for the voltage.

	Theoretical	Simulated	Percent Difference
Vc Amplitude	3.6386 V	3.63862V	5.5 x 10 <sup>-4</sup> %
Vc Phase Angle	-43.304 <sup>0</sup>	-43.30401 <sup>0</sup>	2.3 x 10 <sup>-5</sup> %

Table 7: Comparisons of circuit 1 when f = 1500 Hz

	Theoretical	Simulated	Percent Difference
Vc Amplitude	2.5552V	2.55515V	1.96 x 10 <sup>-3</sup> %
Vc Phase Angle	$-39.955^{0}$	$-39.95522^{0}$	5.51 x 10 <sup>-4</sup> %

Table 8: Comparisons of circuit 2 when f = 2000 Hz

The percent difference between the theoretical and simulated values for the voltage across the capacitor and the phase shift of the voltage compared to the voltage source is small. This is because the simulated values are calculated similarly to the theoretical calculations and thus would not include factors such as noise. If we had access to the materials in a lab environment, the percent different would have been much greater than what we found.

2.

As the frequency increased, the magnitude of  $V_{\rm C}$  decreased and if the frequency had increased towards infinity, the capacitor would have acted as a wire with no resistance. As frequency increases, the phase shift of  $V_{\rm C}$  decreases and becomes more negative.

# Question #3

$$\frac{1}{c}\int_{0}^{\pi}i\delta f + V_{co} + V_{R} df = (As \cos(2\pi f f))df$$

$$\frac{1}{c}i(f) + \frac{dV_{R}}{df} = -(As)(2\pi f) \sin(2\pi f f) = As(2\pi f)\cos(2\pi f f + \Phi)$$

$$\sqrt{\left(\frac{A}{Rc}\right)^{2} + \left(AZ\Pi S\right)^{2}}$$
 (05(Z\(TS(H) + \text{dun'}\)\(\frac{2\pi S}{1/Rc}\)+\(\phi\) = As (Z\(T\) f) (05(Z\(T\) S\(F\) + 96°)