1 Frame 37 – Derivatives with Real Variables

1.1 Definition

In the previous chapter, we looked at derivatives of complex functions of a complex variable z. Now, we look at the derivatives of a complex-valued function of a real variable t. If we write our function as

$$w(t) = u(t) + iv(t)$$

where u and v are real-valued, then we can define the derivative of w at a point t as

$$w'(t) = \frac{d}{dt}w(t) = u'(t) + iv'(t)$$

provided that u' and v' exist at t.

1.2 Properties

If $z_0 = x_0 + iy_0$ is a complex constant, then we can show that

$$\frac{d}{dt}[z_0w(t)] = [(x_0 + iy_0)(u(t) + iv(t)]'$$

$$= [x_0u(t) - y_0v(t)]' + i[y_0u(t) + x_0v(t)]'$$

$$= [x_0u'(t) - y_0v'(t)] + i[y_0u'(t) + x_0v'(t)]$$

$$= z_0w'(t)$$

as we expect.

Next, if z_0 is still a complex constant, the derivative of e^{z_0t} is

$$\frac{d}{dt}e^{z_0t} = \frac{d}{dt}e^{x_0t}(\cos y_0t + i\sin y_0t)$$

$$= \frac{d}{dt}e^{x_0t}\cos y_0t + i\frac{d}{dt}e^{x_0t}\sin y_0t$$

$$= (x_0 + iy_0)(e^{x_0t}\cos y_0t + ie^{x_0t}\sin y_0t)$$

$$= z_0e^{z_0t}$$

Many other rules carry over from standard calculus. However, some rules no longer apply. For instance, in calculus, the mean value theorem for derivatives states that

$$w'(c) = \frac{w(b) - w(a)}{b - a}$$

for some c in the interval $a \le c \le b$ as long as w is continuous. However, this is easily disproved by the function

$$w(t) = e^{it}$$

If a=0 and $b=2\pi$, then w(a)=w(b)=1 and we expect to find a point c in $[0,2\pi]$ such that w'(c)=0. However, no such points exist – the magnitude of the derivative is always 1.

2 Frame 38 – Definite Integrals of Complex Functions

2.1 Definitions

If w(t) is a complex-valued function of a real variable t, as in the previous section

$$w(t) = u(t) + iv(t)$$

then we define the **definite integral** of w(t) over the interval $a \le t \le b$ as

$$\int_{a}^{b} w(t)dt = \int_{a}^{b} u(t)dt + i \int_{a}^{b} v(t)dt$$

provided the two right-side integrals exist. Then,

$$\Re\left[\int_{a}^{b} w(t)dt\right] = \int_{a}^{b} \Re[w(t)]dt$$

$$\Im\left[\int_{a}^{b} w(t)dt\right] = \int_{a}^{b} \Im[w(t)]dt$$

Improper integrals over unbounded intervals are defined similarly.

The two real integrals will exist as long as u and v are **piecewise continuous** on the interval [a, b] – that is, continuous everywhere in the interval except possibly for a finite number of points where it has one-sided limits. When u and v are piecewise continuous, we say that w is also piecewise continuous.

2.2 Properties

The most common rules of integrals from calculus apply here as well:

- $\int z_0 w(t) dt = z_0 \int w(t)$
- $\int w_1(t) + w_2(t)dt = \int w_1(t)dt + \int w_2(t)dt$
- $\int_a^b w(t)dt = -\int_b^a w(t)dt$
- $\int_a^b w(t)dt = \int_a^c w(t)dt + \int_c^b w(t)dt$

We can also extend the fundamental theorem of calculus to complex integrals. Suppose that two functions

$$w(t) = u(t) + iv(t)$$

$$W(t) = U(t) + iV(t)$$

are continuous on the interval [a,b] and W'(t)=w(t) when $a\leq t\leq b$. Then, we can write

$$\int_a^b w(t)dt = W(b) - W(a) = W(t) \Big|_a^b$$

Example: noting that the derivative of $\frac{1}{i}e^{it}$ is

$$\frac{d}{dt}\left(\frac{1}{i}e^{it}\right) = \frac{1}{i}ie^{it} = e^{it}$$

we can evaluate $\int e^{it}dt$ as

$$\int_0^{\pi/4} e^{it} dt = \frac{e^{it}}{i} \Big|_0^{\pi/4}$$

$$= \frac{1}{i} \left[e^{\pi/4} - 1 \right]$$

$$= \frac{1}{i} \left[\frac{1}{\sqrt{2}} - 1 + \frac{i}{\sqrt{2}} \right]$$

$$= \frac{1}{\sqrt{2}} + i \left(1 - \frac{1}{\sqrt{2}} \right)$$

As in the previous section, the mean value theorem for integrals does not apply. We can show this by finding the integral $\int_0^{2\pi} e^{it} dt = 0$, even though the function is never zero on this interval.

3 Frame 39 – Contours

3.1 Definitions

In calculus, integrals are defined on intervals of the real line. In complex analysis, we instead use curves in the complex plane.

An **arc** is a set of points z = (x, y) in the complex plane such that the functions

$$x = x(t), \quad y = y(t); \quad z = z(t) = x(t) + iy(t)$$

are continuous functions of the parameter t, where $a \le t \le b$. This definition is a continuous mapping of the interval $a \le t \le b$ into the z plane.

We say that an arc is **simple** if it does not cross itself; ie:

$$z(t_1) \neq z(t_2)$$
 for all $t_1 \neq t_2$

If a simple arc starts and ends at the same point (z(a) = z(b)), it is called a **simple closed curve**. These curves are **positively oriented** when they are oriented in the counterclockwise direction.

Example: the unit circle

$$z = e^{i\theta}$$

where $0 \le \theta \le 2\pi$ is a positively oriented simple closed curve centered at the origin with a radius of 1. A more general circle is

$$z = z_0 + Re^{i\theta}$$

which is centered at z_0 and has a radius of R.

3.2 Uniqueness

Note that the parametric representation for any arc is not unique. If we know a function ϕ such that

$$t = \phi(\tau)$$

maps the interval $\alpha \leq \tau \leq \beta$ onto the interval $a \leq t \leq b$. Then, the two equations

$$z(t)$$
 $(a \le t \le b)$

and

$$z(\phi(t)) \quad (\alpha \le t \le \beta)$$

represent the same arc.

3.3 Smoothness

Suppose that the real and imaginary components of z are differentiable, and their derivatives are continuous. Then, the arc z(t) is a **differentiable arc**, and

$$|z'(t)| = |x'(t) + iy'(t)| = \sqrt{[x'(t)]^2 + [y'(t)]^2}$$

is integrable. This allows us to find the length of an arc as

$$L = \int_{a}^{b} |z'(t)| dt$$

If an arc is differentiable and z'(t) is never zero (except maybe at t = a or t = b), then we call the arc a **smooth arc**. We can write the unit tangent vector

$$\mathbf{T} = \frac{z'(t)}{|z'(t)|}$$

which has an angle of inclination of arg z'(t).

A **contour** is an arc which consists of a finite number of smooth arcs joined together. Specifically, if z(t) represents a contour, then z(t) is continuous and z'(t) is piecewise continuous. If a contour is also a simple closed arc, we call it a **simple closed contour**.

The points on a simple closed arc are the boundary points of two different domains:

- The interior of the arc, which is bounded;
- The exterior of the arc, which is unbounded.