# CS1555/CS2055 Recitation 13

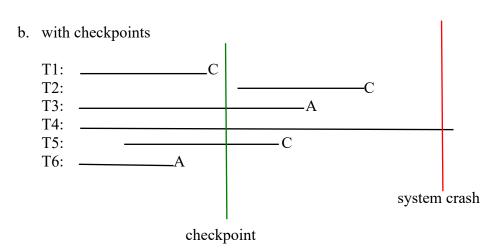
Objective: Practice recovery, operations on static hashing and extendible hashing

## Part 1. Recovery

For the following transaction executions, state what the system should do when it restarts after a crash:

a. without checkpoints:

T1: \_\_\_\_\_\_ C
T2: \_\_\_\_\_ C
T3: \_\_\_\_\_ A
T4: \_\_\_\_\_ C
T5: \_\_\_\_\_ C
T6: \_\_\_\_ A



## Part 2. Hash Files

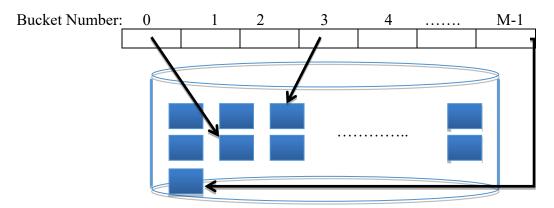
### Hashing

- Convert the key of a record into an address in which the record is stored
- Search condition must be an equality condition on a single field, called hash field
- **Hash function:** a function that is applied to the hash field value of a record and yields the *address* of the disk block in which the record is stored

## **External Hashing for disk Files**

- Target address space is made of **buckets**, each of which holds multiple records.
- A **bucket** is either one disk block or a number of contiguous disk blocks
- The *hashing function* maps a key into a relative bucket number, rather than assigning an absolute block address to the bucket

- A table maintained in the file header converts the bucket number into the address of the first disk block of the bucket
- Why target buckets and not blocks?



# 1) Static hashing:

- a) Converts the key of a record into an address in which the record is stored
- b) A fixed number of buckets, M, is allocated to match the fixed (static) Hash function range
- c) Each bucket has the same number of blocks. The number of blocks can change
- d) The collision problem is solved by using overflow buckets

Consider the following record keys: (3, 2, 1, 8, 6, 4, 14, 5, 9). Create the static hash structure, with M=4 main buckets, that will contain the provided records, using the chaining technique. Use h(k) =k mod M as a hashing function. Each bucket can hold 2 records.

### 2) Dynamic hashing:

### a) Extendible hashing:

- An array of 2<sup>d</sup> bucket addresses is maintained, where *d* is called **global depth** of the directory
- The integer value corresponding to the first(high-order) d bits of a hash value is used as an index to the array to determine a directory entry and the address in that entry determines the bucket in which the corresponding records are stored
- A local depth d' –stored with each bucket –specifies the number of bits on which the bucket contents are based
- The value of d can be increased or decreased by one at a time, thus doubling or halving the number of entries in the directory array.
- **Doubling** is required when the bucket whose local depth d', equal with the global depth d, overflows

Create an extendible hash structure for these record keys: (2, 3, 4, 8, 1, 12, 9, 7). Use the 4 bit binary representation of the keys (2=0010, 3=0011, 4=0100, 8=1000, 1=0001, 12=1100, 9=1001, 7=0111). Use a bfr=2.