#### DSL Seminar: MCMC (7)

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- Gibbs Sampler
- Bayesian Regression with M-H algorithm



### Bayesian Regression

• Bayesian regression의 핵심은, 우리가 알아내고자 하는 모수인 회귀계수  $(\beta_i)$ 들과  $\sigma^2$ 를 확률변수 취급하는 것입니다.

$$\{y_i\}_{i=1}^n | \beta_0, \beta_1, \sigma^2 \sim^{iid} N(\beta_0 + \beta_1 x_i, \sigma^2)$$
$$\beta_0 \sim N(\mu, \tau)$$
$$\beta_1 \sim N(\mu, \tau)$$
$$\sigma^2 \sim IG(a, b)$$

- Posterior는 Prior와 Likelihood의 곱에 비례하므로,  $\pi(\beta_0, \beta_1, \sigma^2 | X, Y) \propto \prod_{i=1}^n L(\beta_0, \beta_1, \sigma^2 | X_i, Y_i) \times p(\beta_0)p(\beta_1)p(\sigma^2)$ .
- Likelihood: Normal,  $\beta$  Prior: Normal,  $\sigma^2$  Prior: Inverse-Gamma
- 모든 parameter는 서로 독립이라고 가정합니다.

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### Bayesian Regression vs. Bayesian GLM

• Bayesian GLM 역시 회귀계수에 확률분포를 가정합니다.

$$\pi(\beta_0, \beta_1|X, Y) \propto L(\beta_0, \beta_1|X, Y)p(\beta_0)p(\beta_1)$$

- Bayesian Regression과의 차이점은 Likelihood입니다!
- 일반 선형회귀에서  $Y \sim N(E[Y|X], \sigma^2)$ 이지만, GLM에서는 Y가 더이상 실수 전체를 범위로 가지지 않으므로, 정규분포가 아닌 다른 분포를 따르게 됩니다.
- 즉, Y의 분포가 바뀐다는 것인데 이는 Bayesian Regression에서 Likelihood 부분의 함수식에 영향을 미칩니다.

#### Bayesian GLM Likelihood Setting

• Logistic Regression ( $Y \sim \mathsf{Bernoulli}(\mu(X))$ ):

$$L(\beta_0, \beta_1 | X, Y) = \prod_{i=1}^n \mu(X_i)^{Y_i} (1 - \mu(X_i))^{1 - Y_i}, \ \mu(X_i) = \frac{\exp(X_i^T \beta)}{1 + \exp(X_i^T \beta)}$$
$$(X_i = (1, x_{1i}), \ \beta = (\beta_0, \beta_1))$$

• Poisson Regression ( $Y \sim \text{Pois}(\mu(X))$ ):

$$L(\beta_0, \beta_1 | X, Y) = \prod_{i=1}^n \frac{\mu(X_i)^{Y_i} \exp(-\mu(X_i))}{Y_i!}, \ \mu(X_i) = \exp(X_i^T \beta)$$

• 추정하는 회귀계수의 개수에 따라  $X_i$ 와  $\beta$ 의 차원은 달라진다.  $(X_i, \beta \in \mathbb{R}^p)$ 

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## Example] Bayesian Statistics HW3

In this assignment, we will implement MCMC algorithm for a Bayesian GLM as follows:

$$\begin{aligned} \mathbf{Y} &\sim \mathsf{Poisson}(\mu(\mathbf{X})) \\ &\log(\mu(\mathbf{X})) = \mathbf{X}\beta \\ \beta_j &\sim N(0, 10) \text{ for } j = 1, 2, 3, 4 \end{aligned}$$

- 1) Simulate the dataset as follows.
- (a) Let  $X_i \in \mathbb{R}^4$  be the predictors for ith observation. For i=1,...,1000, simulate  $X_i \sim N(0,\mathbf{I})$  independently. Here  $\mathbf{I}$  is an identity matrix.
- (b) For i=1,...,1000, simulate  $Y_i \sim \mathsf{Poisson}(\exp(X_i^T\beta))$  independetly. Set the true regression coefficient value as  $\beta=(0.5,-0.5,0,1)$ .
- 2) Implement the MCMC algorithm using the simulated dataset in Problem 1). Here you should write down the code without using any packages.
- Report the trace plots, density plots, 95% HPD intervals, posterior mean, acceptance probability, and effective sample size for all parameters.

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## Example] Bayesian Statistics HW3 (1)

- 1) Simulate the dataset as follows.
- (a) Let  $X_i \in \mathbb{R}^4$  be the predictors for ith observation. For i=1,...,1000, simulate  $X_i \sim N(0,\mathbf{I})$  independently. Here  $\mathbf{I}$  is an identity matrix.

 $X_i$  follows multivariate normal distribution. However, its covariance matrix is an identity matrix. So, 1000 iid samples from  $N_4(0,\mathbf{I})$  is equivalent with 4000 iid samples from univariate standard normal distribution.

# Example] Bayesian Statistics HW3 (2)

- 1) Simulate the dataset as follows.
- (b) For i=1,...,1000, simulate  $Y_i \sim \mathsf{Poisson}(\exp(X_i^T\beta))$  independetly. Set the true regression coefficient value as  $\beta=(0.5,-0.5,0,1)$ .

Now, you have  $1000\times 4$  data matrix X. Let  $\beta=(0.5,-0.5,0,1)$ . Multiply them, and we can get  $X^T\beta$  matrix (or vector), which has a size of  $1000\times 1$ . Then you can also easily get  $\exp(X_i^T\beta)$ .

Let  $M=\exp(X^T\beta)$ , then this means  $Y_1\sim \operatorname{Pois}(M_1),\ Y_2\sim \operatorname{Pois}(M_2),\ \cdots,\ Y_{1000}\sim \operatorname{Pois}(M_{1000}).$  You can use for loop and rpois function in order to simulate  $Y_1\sim Y_{1000}.$ 

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### Example] Bayesian Statistics HW3 (3)

$$\mathbf{Y} \sim \mathsf{Poisson}(\mu(\mathbf{X}))$$
 
$$\log(\mu(\mathbf{X})) = \mathbf{X}\beta$$
 
$$\beta_j \sim N(0, 10) \text{ for } j = 1, 2, 3, 4$$

2) Implement the MCMC algorithm using the simulated dataset.

Our goal is to find the posterior distribution of  $\beta_1 \sim \beta_4$ . Let  $\beta = (\beta_1, \beta_2, \beta_3, \beta_4)$ . Now, the posterior distribution is,

$$\pi(\beta_1, \beta_2, \beta_3, \beta_4 | X, Y) \propto L(\beta_1, \beta_2, \beta_3, \beta_4 | X, Y) p(\beta_1) p(\beta_2) p(\beta_3) p(\beta_4)$$

where 
$$L(\beta) = \prod_{i=1}^n \frac{\mu(X_i)^{Y_i} \exp(-\mu(X_i))}{Y_i!}, \ \mu(X_i) = \exp(X_i^T \beta)$$

We already have X,Y and  $\beta$ , so we can calculate the value.

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# Example Bayesian Statistics HW3 (4)

Now, let's use the Metropolis-Hastings algorithm to find the posterior distribution of  $\beta_1 \sim \beta_4$ .

One-by-one update and All-at-once update are both possible, but I'm going to update regression coefficients one-by-one (in order to control the acceptance probability more easily).

After setting the initial value,  $\beta_1^{(0)}, \beta_2^{(0)}, \beta_3^{(0)}, \beta_4^{(0)}$ , update each regression coefficient as follows:

- 1) Generate  $\beta_1' \sim N(\beta_1^{(t)}, \sigma_1^2)$ . (Normal proposal)
- 2) Find  $\log(\alpha) = \log(\pi(\beta_1^t, \beta_2^{(t)}, \beta_2^{(t)}, \beta_4^{(t)})) \log(\pi(\beta_1^{(t)}, \beta_2^{(t)}, \beta_2^{(t)}, \beta_4^{(t)})).$ Here, you can ignore the prior of  $\beta_2, \beta_3, \beta_4$ . (kernel)
- 3) Generate  $U \sim U(0,1)$ , and compare  $\log(U)$  and  $\log(\alpha)$ .
- 4) If  $\log(U) < \log(\alpha)$ ,  $\beta_1^{(t+1)} = \beta_1'$ . Else,  $\beta_1^{(t+1)} = \beta_1^{(t)}$ .
- 5) Repeat 1)  $\sim$  4) for  $\beta_2$ ,  $\beta_3$ , and  $\beta_4$ .
- 6) Repeat 1)  $\sim$  5) for some sufficient number of iterations.

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### Gibbs Sampler

- Gibbs Sampler는 특수한 형태의 Metropolis-Hastings algorithm입니다.
- 우리의 target distribution이 multivariate이면서, fully conditional distribution을 알아낼 수 있다면 사용할 수 있는 방법입니다.
- 즉, 앞서 예시에서처럼 target distribution  $\pi$ 가,  $\pi(\beta_1, \beta_2, \beta_3, \beta_4 | X, Y)$ 처럼 다변량 함수로 주어져 있을 때. 그것들의 fully conditional distribution인  $\pi(\beta_1|\beta_2,\beta_3,\beta_4,X,Y), \pi(\beta_2|\beta_1,\beta_3,\beta_4,X,Y),$  $\pi(\beta_3|\beta_1,\beta_2,\beta_4,X,Y), \pi(\beta_4|\beta_1,\beta_2,\beta_3,X,Y)$ 을 모두 찾아낼 수 있다면 이 함수들을 이용해 Gibbs sampler를 사용할 수 있습니다.
- Gibbs sampler의 장점은, acceptance rate가 1이라는 점입니다.
- 따라서 Gibbs sampler에서는 threshold value를 계산하는 단계나, 해당 값과 U를 비교해 proposed value(x')를 사용할지 말지를 결정하는 단계도 필요가 없습니다.
- Gibbs sampler를 Gibbs sampling이라고 하기도 합니다.

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### Gibbs Sampler Algorithm

- **1** Initialize t = 0 and  $\mathbf{X}_0 = (X_1^{(0)}, ..., X_d^{(0)})$ .
- Sample in turn:

$$X_1^{(t+1)} \sim f_{1|-1}(x_1|X_2^{(t)}, X_3^{(t)}, ..., X_d^{(t)})$$

$$X_2^{(t+1)} \sim f_{2|-2}(x_2|X_1^{(t+1)}, X_3^{(t)}, ..., X_d^{(t)})$$

...

$$X_d^{(t+1)} \sim f_{d|-d}(x_d|X_1^{(t+1)}, X_2^{(t+1)}, ..., X_{d-1}^{(t+1)})$$

- **3** Set  $\mathbf{X}_{t+1} = (X_1^{(t+1)}, ..., X_d^{(t+1)}).$
- $\bullet$  Set t = t + 1 and go to step 2.

## Gibbs sampler의 acceptance rate가 항상 1인 이유

$$\text{Let } x_o = (x_1, ..., x_i, ..., x_d), x' = (x_1, ..., x', ..., x_d), \\ \text{and } q(x'|x_o) = \frac{1}{d} f_{i|-i}(x'|x_j, j \neq i) = \frac{1}{d} \frac{f(x')}{f(x_1, ..., x_{i-1}, x_{i+1}, ..., x_d)}. \\ \text{Then, } \frac{f(x')q(x_o|x')}{f(x_o)q(x'|x_o)} = \frac{f(x')\frac{1}{d}\frac{f(x_o)}{f(x_1, ..., x_{i-1}, x_{i+1}, ..., x_d)}}{f(x_o)\frac{1}{d}\frac{f(x')}{f(x_1, ..., x_{i-1}, x_{i+1}, ..., x_d)}} = \frac{f(x')f(x_o)}{f(x_o)f(x')} = 1.$$

Therefore, 
$$\alpha = \min(\frac{f(x')q(x_o|x')}{f(x_o)q(x'|x_o)}, 1) = \min(1, 1) = 1.$$

위의 증명과정을 통해 Gibbs sampler는 Metropolis-Hastings algorithm의 특수한 경우라는 것과, Gibbs sampler는 항상 acceptance rate가 1임을 알 수 있습니다.

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