

Def: A diagonal matrix is a square matrix with all the non-zero entries on the diagonal. []

e.g. $\begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$ $\begin{bmatrix} 0 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & 6 \end{bmatrix}$ Not $\rightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 1 & 3 \end{bmatrix}$

Def: A block diagonal matrix is a square matrix with all the non-zero entries in "blocks" on the diagonal.

e.g. $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 3 \\ 0 & 4 & 5 \end{bmatrix}$ $\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$ $\begin{bmatrix} 1 & 2 & 0 & 0 \\ 3 & 4 & 0 & 0 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 3 & 4 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 4 & 3 & 0 \\ 0 & 2 & 1 & 0 \\ 0 & 0 & 0 & 4 \end{bmatrix}$ $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 4 & 3 & 5 \\ 0 & 2 & 1 & 4 \\ 0 & 8 & 2 & 4 \end{bmatrix}$

Not: $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 2 & 4 \\ 0 & 3 & 5 \end{bmatrix}$ $\begin{bmatrix} 1 & 3 & 0 \\ 8 & 2 & 4 \\ 0 & 3 & 5 \end{bmatrix}$ blocks can't overlap

Why do these matter?

the determinant of a block diagonal matrix is equal to the products of the determinants of the blocks.

Ex. $\begin{bmatrix} 2 & 0 & 0 \\ 0 & 1 & 3 \\ 0 & 4 & 5 \end{bmatrix} = 2((5 \cdot 1) - (3 \cdot 4))$

the determinant of a $|x|$ block is just the value of the entry.

$$\begin{bmatrix} 1 & 2 & 0 & 0 \\ 3 & 4 & 0 & 0 \\ 0 & 0 & 6 & 2 \\ 0 & 0 & 3 & 4 \end{bmatrix} = \underbrace{(4-6)}_{(4-6)} \cdot \underbrace{(4-6)}_{(4-6)} = 4$$

Def: inverse matrices

for a square matrix A , the inverse of A (written as A^{-1}) is the matrix such that $AA^{-1} = I$ and $A^{-1}A = I$. (I is the identity matrix)

(you don't need to know)

to compute A^{-1} , create a big augmented matrix $[A | I]$ and find RREF.

If A is invertible (has inverse) then you get $[I | A]$

If A doesn't have an inverse then A is singular. Then you get all zeroes in the RREF.

Do need to know

That process works with any size square matrix A . If A is a 2×2 matrix there is

a trick for finding A^{-1} .

$$\text{if } A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad A^{-1} = \frac{1}{|A|} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$\text{ex: } \begin{bmatrix} -1 & 3 \\ 4 & 2 \end{bmatrix} \quad A^{-1} = \frac{1}{-2-12} \begin{bmatrix} 2 & -3 \\ 4 & -1 \end{bmatrix} = \begin{bmatrix} 2/14 & -3/14 \\ 4/14 & -1/14 \end{bmatrix}$$

notice if $|A|=0$ then A^{-1} does not exist.

Def: Trace of a matrix

the trace of a square matrix A is the sum of the **diagonal** entries of A .

$$\text{Ex. } \text{tr}(A) \text{ for } A = \begin{bmatrix} 1 & 2 & 3 \\ -1 & 4 & 0 \\ 2 & 3 & 5 \end{bmatrix} = 1+4+5=10$$

Invertible Matrix theorem: (Either All are True or All are false)

For a square $n \times n$ matrix A , the following properties are equivalent:

- A is invertable (A^{-1} exists)
- A has a RREF of I (identity matrix)
- The system $A\vec{x}=\vec{b}$ has exactly 1 solution (for any \vec{b})
- The columns of A are linearly independent
- The determinant of A is nonzero ($|A| \neq 0$)
- 0 is Not an eigenvalue of A .

Eigenvalues and EigenVectors:

For a square matrix A , $\vec{v} (\neq \vec{0})$ is called an eigenvector of A with

eigenvalue λ if $A\vec{v} = \lambda\vec{v}$ (note: both sides are a vector)

$$\text{Ex: } \begin{bmatrix} -5 & 2 \\ -7 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} -5+\lambda \\ -7+4 \end{bmatrix} = \begin{bmatrix} -3 \\ -3 \end{bmatrix}$$

$$\text{so } A\vec{v} = \lambda\vec{v} \quad \begin{bmatrix} -5 & 2 \\ -7 & 4 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = -3 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Important fact:

Eigenvalues are always defined up to a scalar multiple.
i.e. if you take a non zero scalar multiple of \vec{v} we don't consider it a new eigenvector, but a different way to express the same eigenvector.

We actually want to find all
the linearly independent eigenvectors.