



Segmentation

Segmentation

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- Segmentation



(a) image

FLOW

1. Semantic Segmentation

- Fully Convolutional Network(FCN)
- U-Net

2. Instance Segmentation

- Methods
- YOLACT

1. YOLACT

- Image Inference : Use eval.py
- Video Inference : Use eval.py
- Image Inference : Use YOLACT Modules



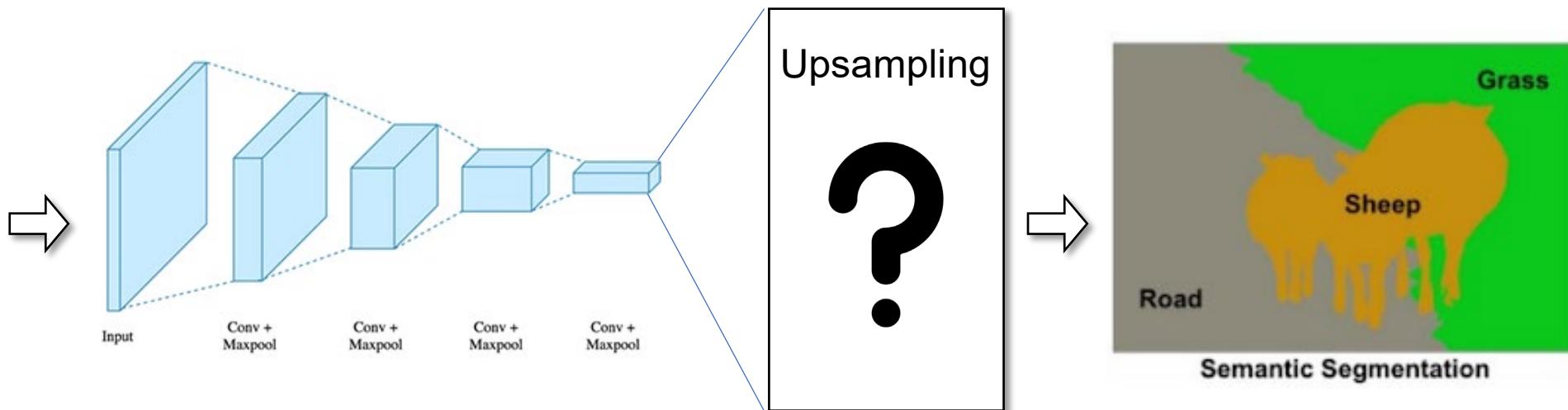
Semantic Segmentation

Dahyun, Kim

Semantic Segmentation

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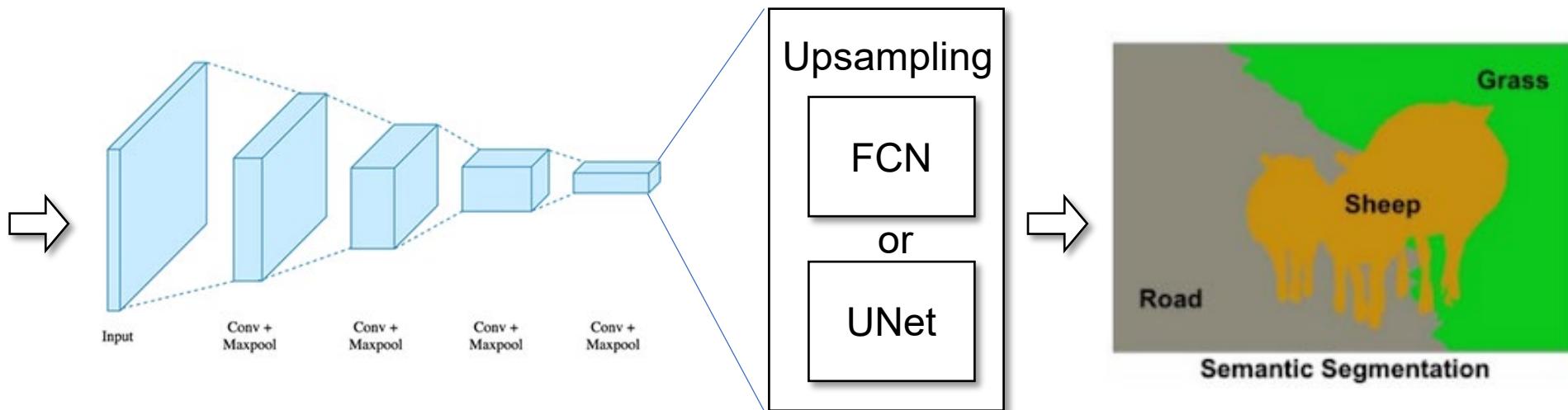
- Semantic Segmentation
 - 이미지 내 모든 픽셀이 어느 클래스에 속하는지 예측하는 문제



Semantic Segmentation

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- Semantic Segmentation
 - 이미지 내 모든 픽셀이 어느 클래스에 속하는지 예측하는 문제





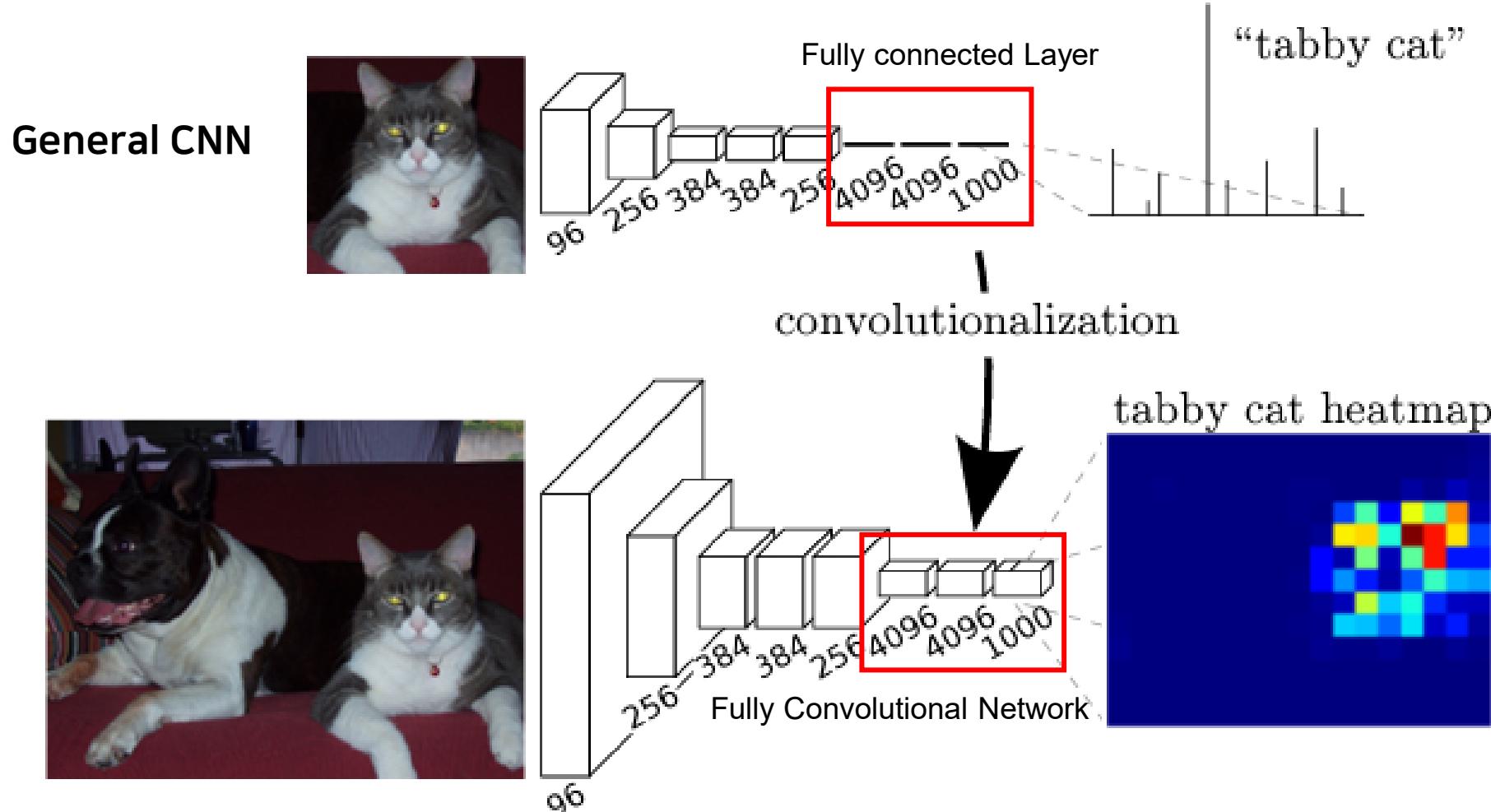
Semantic Segmentation -FCN-

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Semantic Segmentation - FCN

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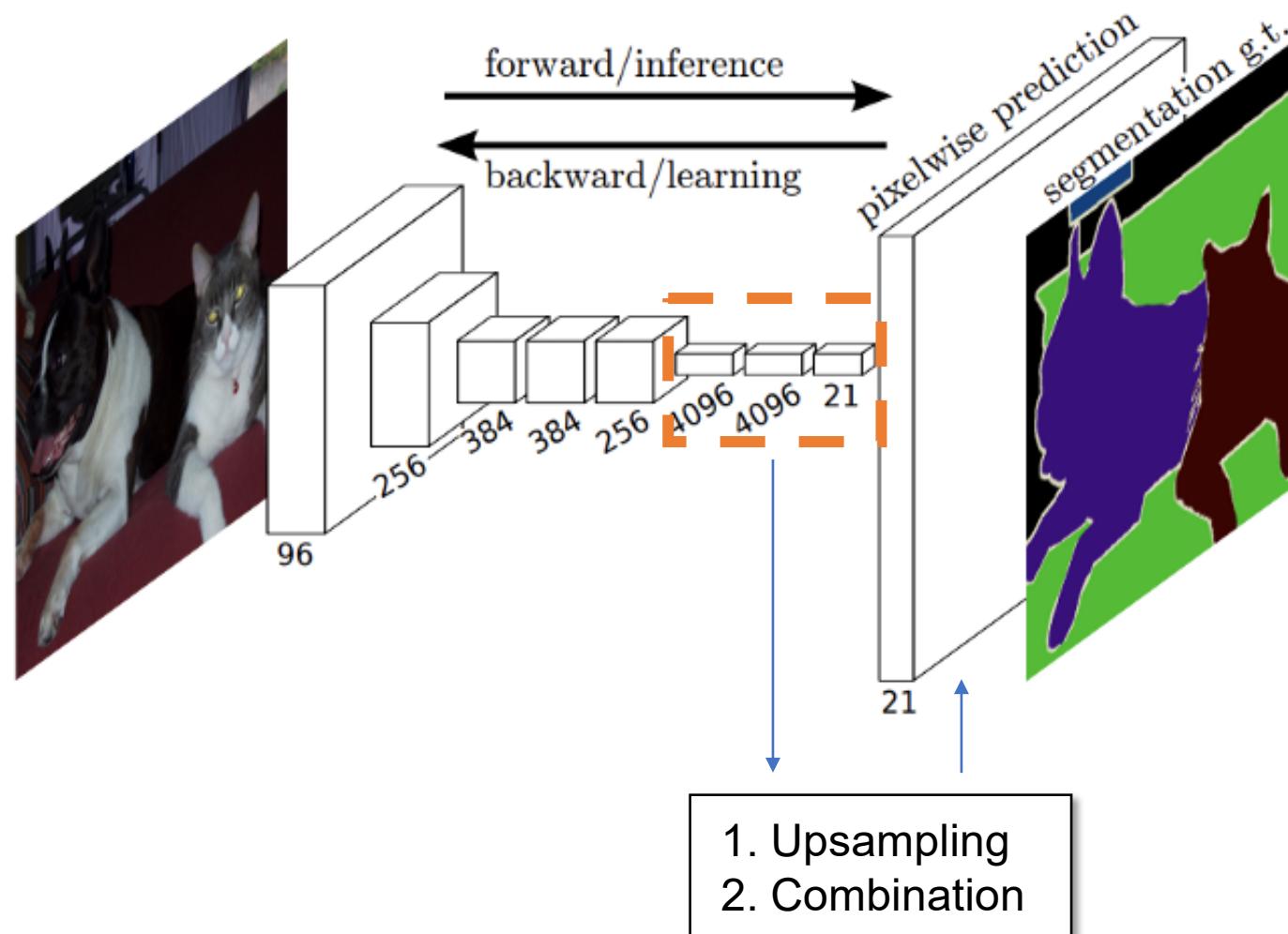
- Fully Convolutional Network



Semantic Segmentation - FCN

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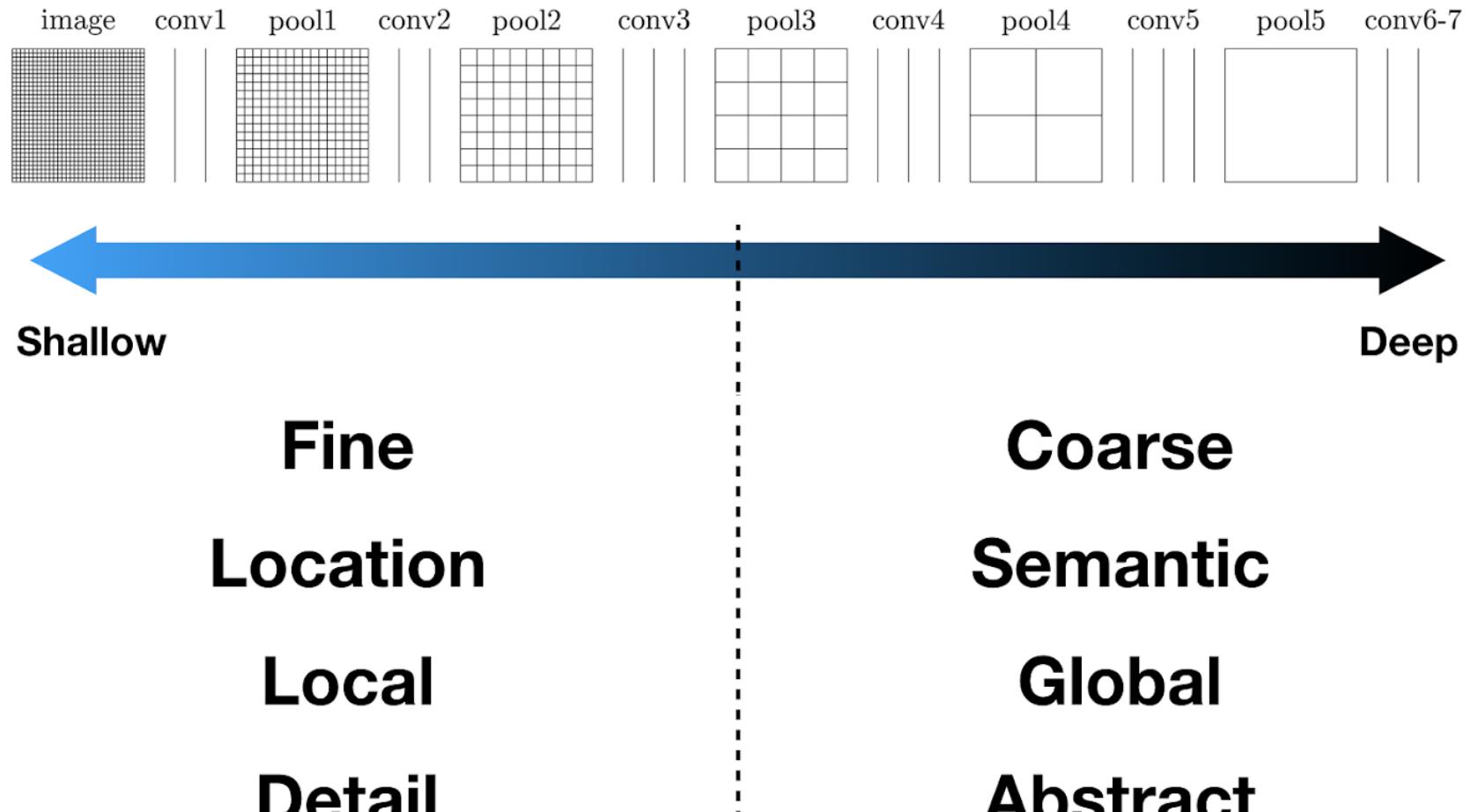
- Fully Convolutional Network



Semantic Segmentation - FCN

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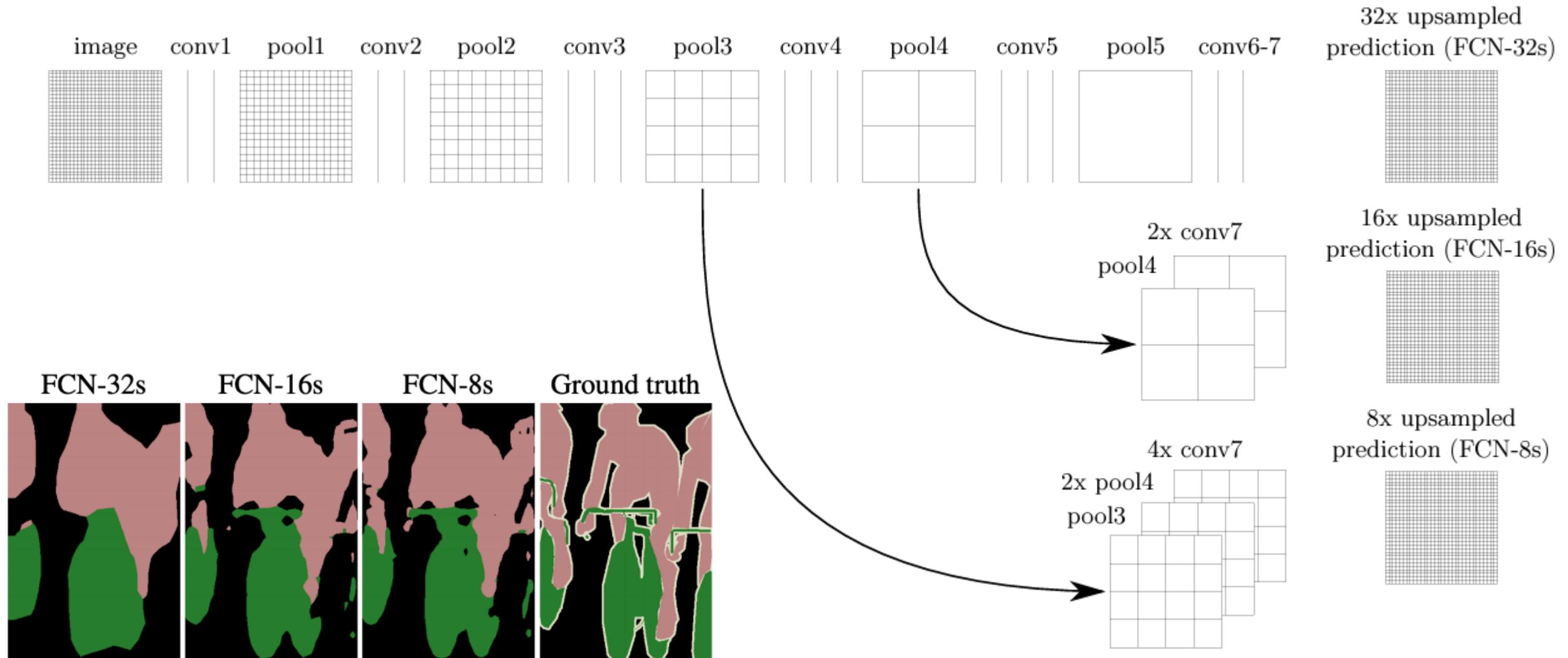
- Shallow Layer \leftrightarrow Deep Layer



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- Combination: Deep Layer(global feature) + Shallow Layer(local feature)



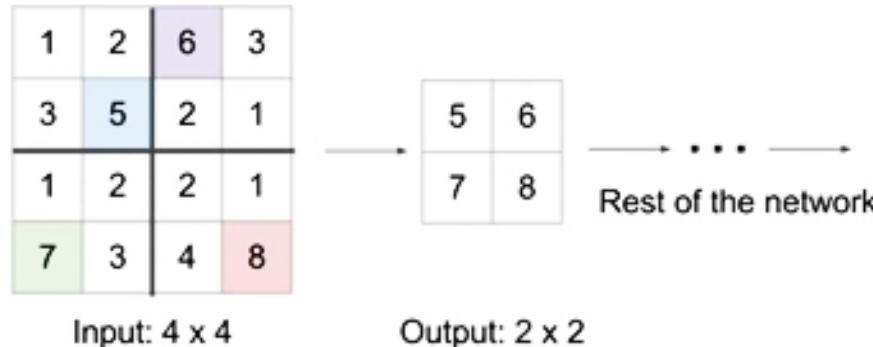
Semantic Segmentation - FCN

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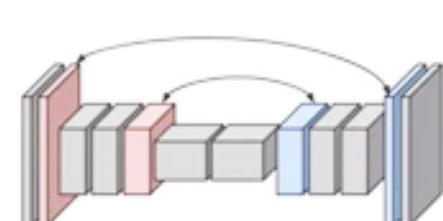
- General Upsampling Methods

Max Pooling

Remember which element was max!

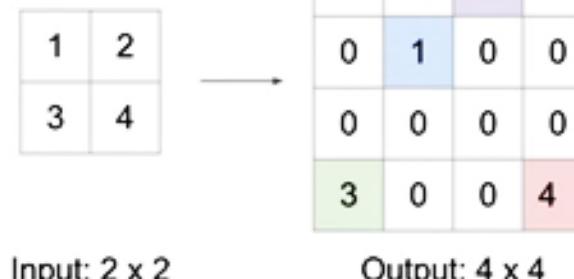


Corresponding pairs of
downsampling and
upsampling layers



Max Unpooling

Use positions from
pooling layer



Nearest Neighbor

1	1		
1	1	2	2
3	4		



1	1	2	2
1	1	2	2
3	3	4	4
3	3	4	4

Input: 2 x 2

Output: 4 x 4

“Bed of Nails”

1	2		
0	0	0	0
3	4		



1	0	2	0
0	0	0	0
3	0	4	0
0	0	0	0

Input: 2 x 2

Output: 4 x 4

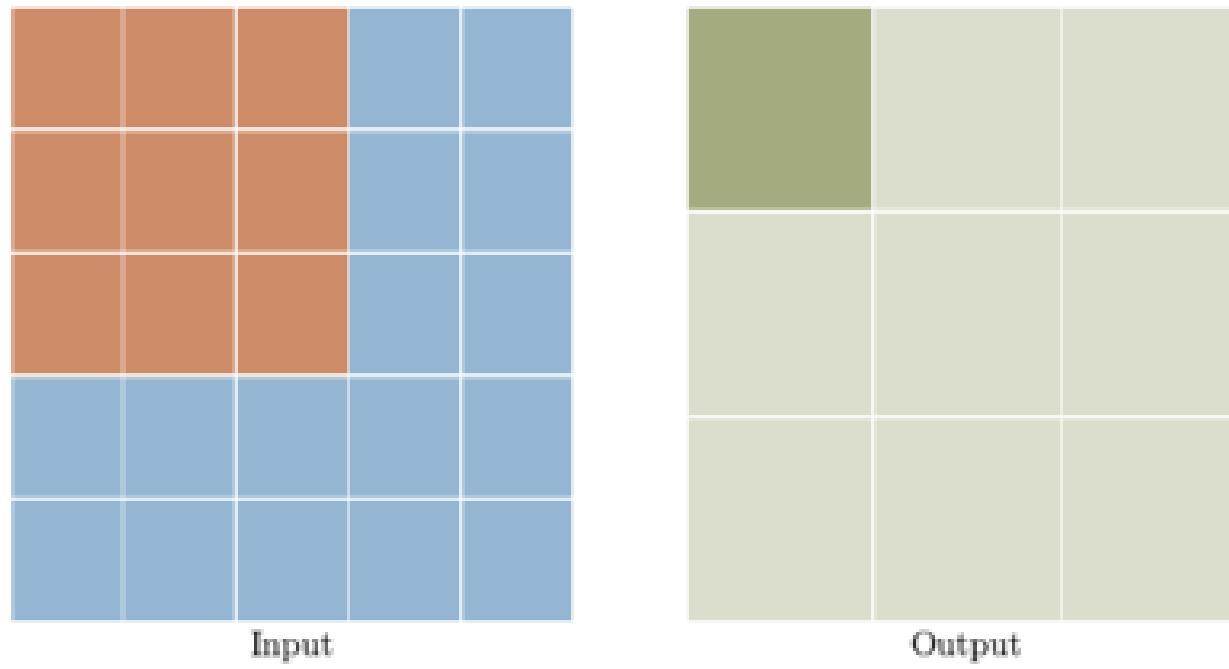
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- Transposed Convolution : Learnable upsampling

[Convolution]

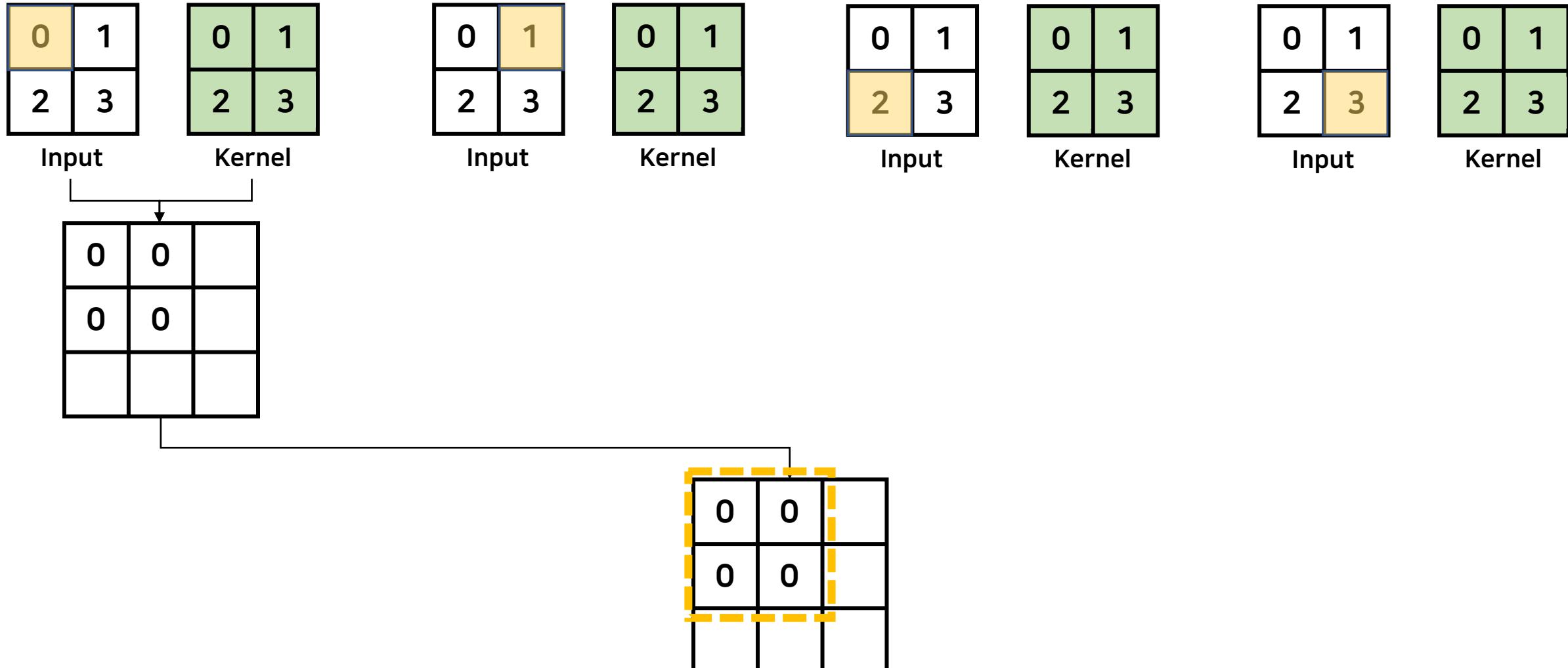
Type: conv - Stride: 1 Padding: 0



Semantic Segmentation - FCN

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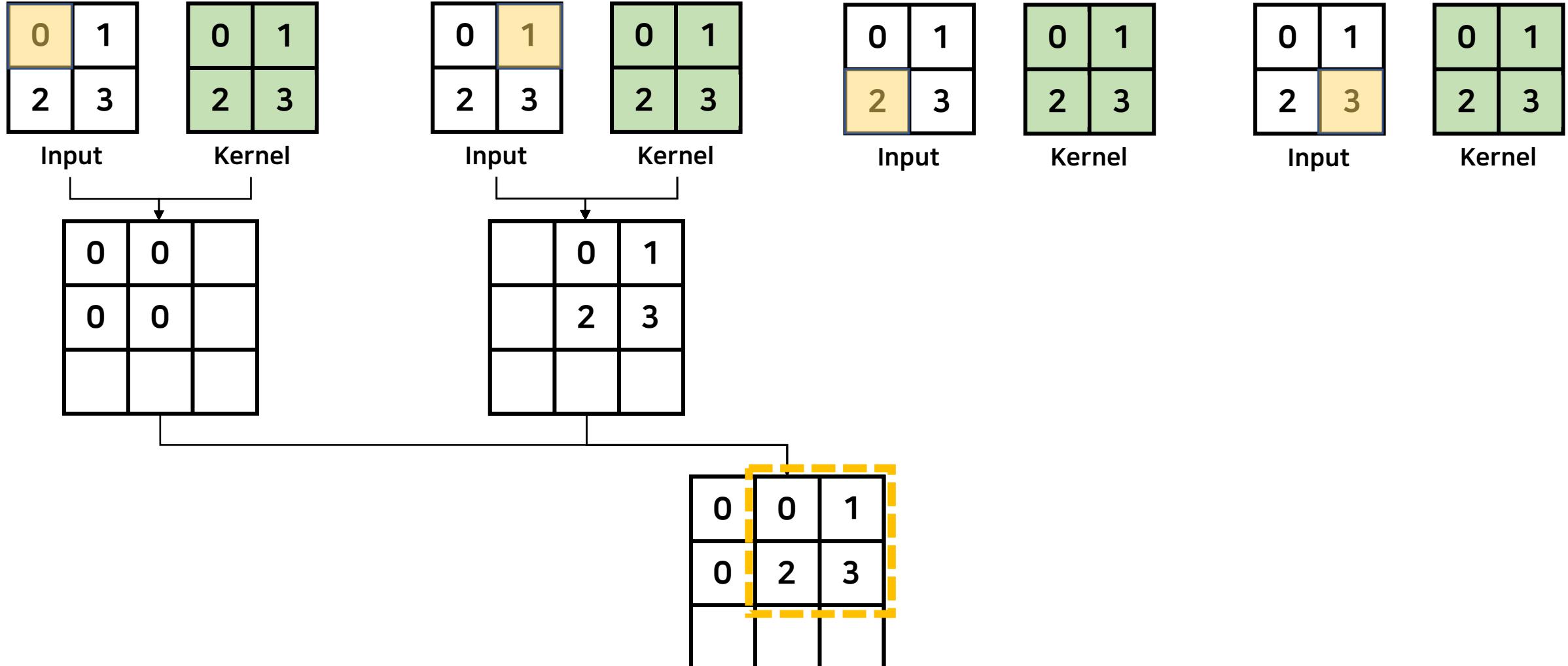
- Transposed Convolution



Semantic Segmentation - FCN

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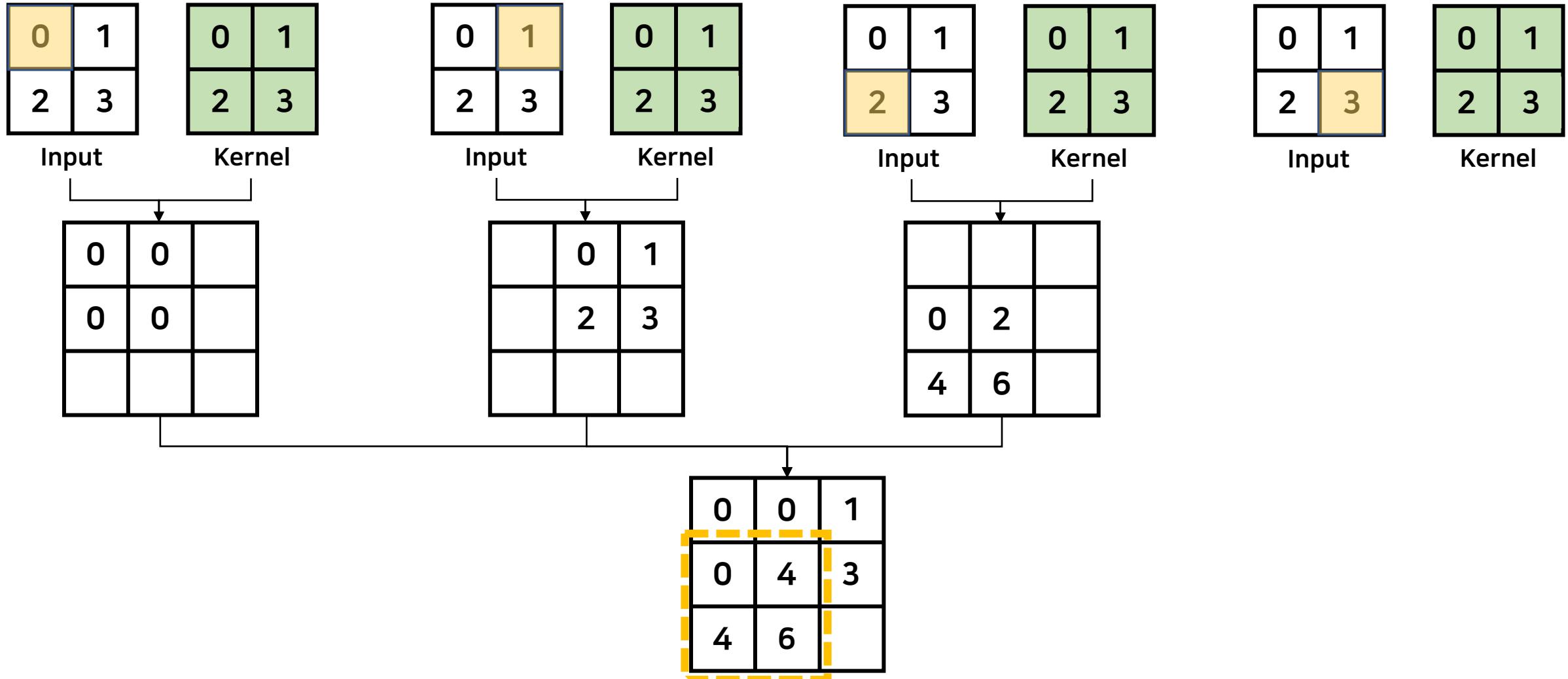
- Transposed Convolution



Semantic Segmentation - FCN

PIAI Research Department

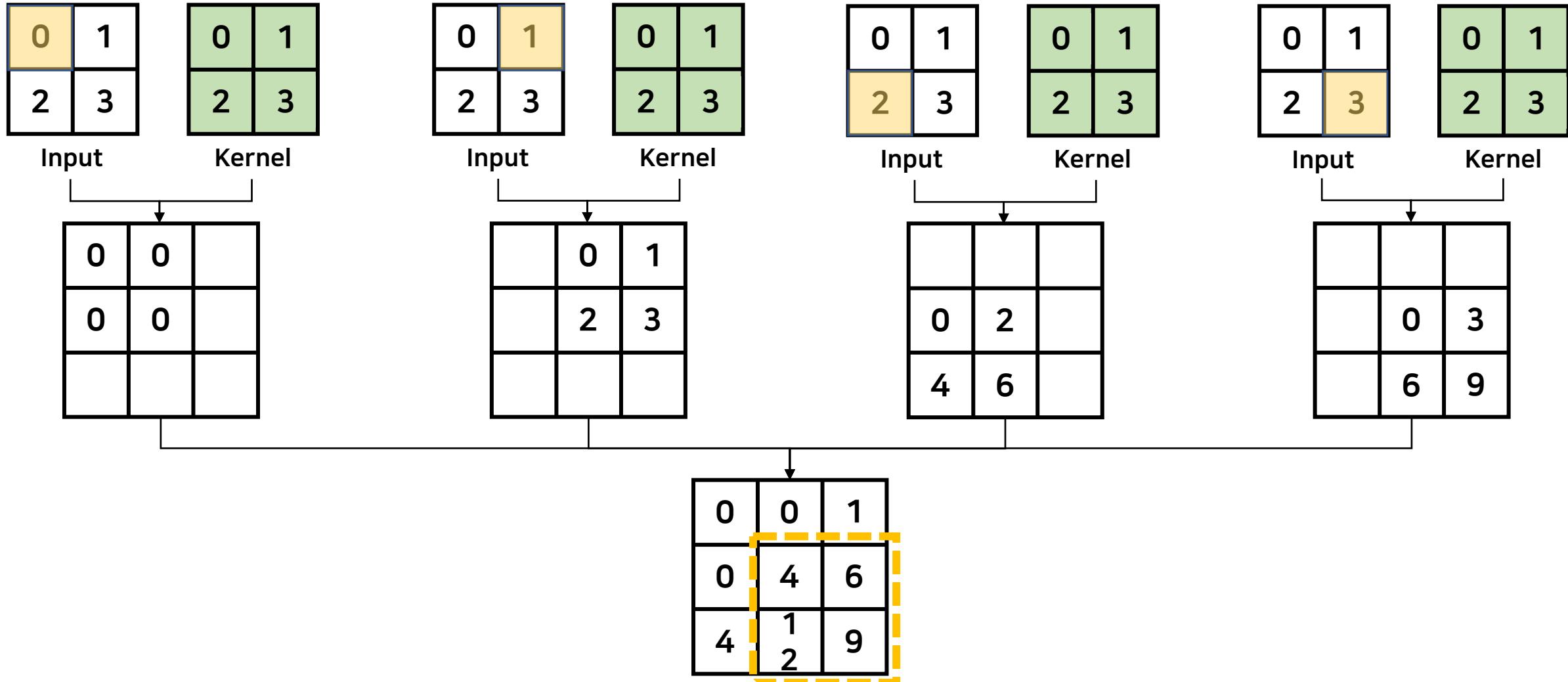
- Transposed Convolution



Semantic Segmentation - FCN

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- Transposed Convolution





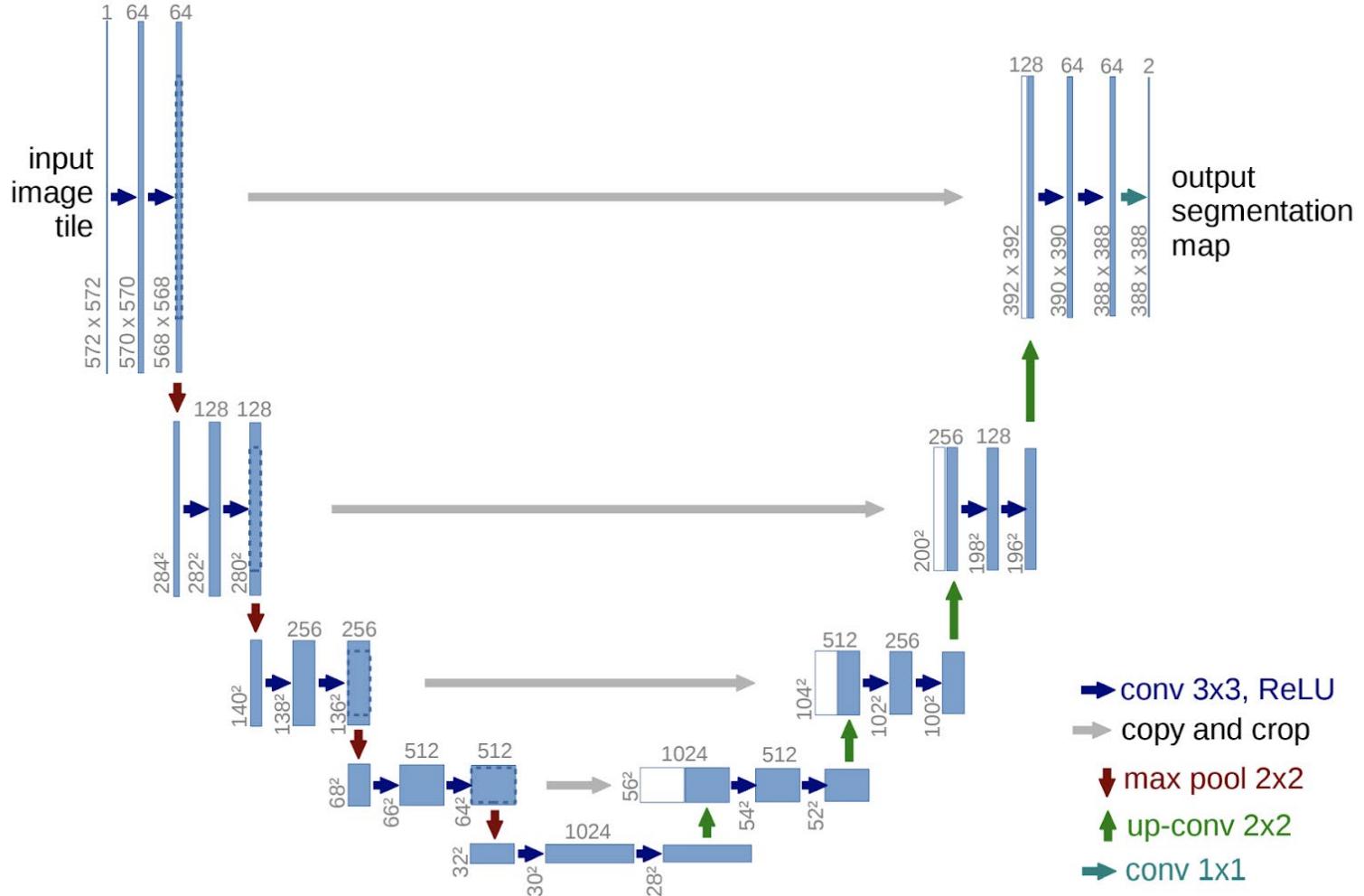
Semantic Segmentation -UNet-

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Semantic Segmentation - UNet

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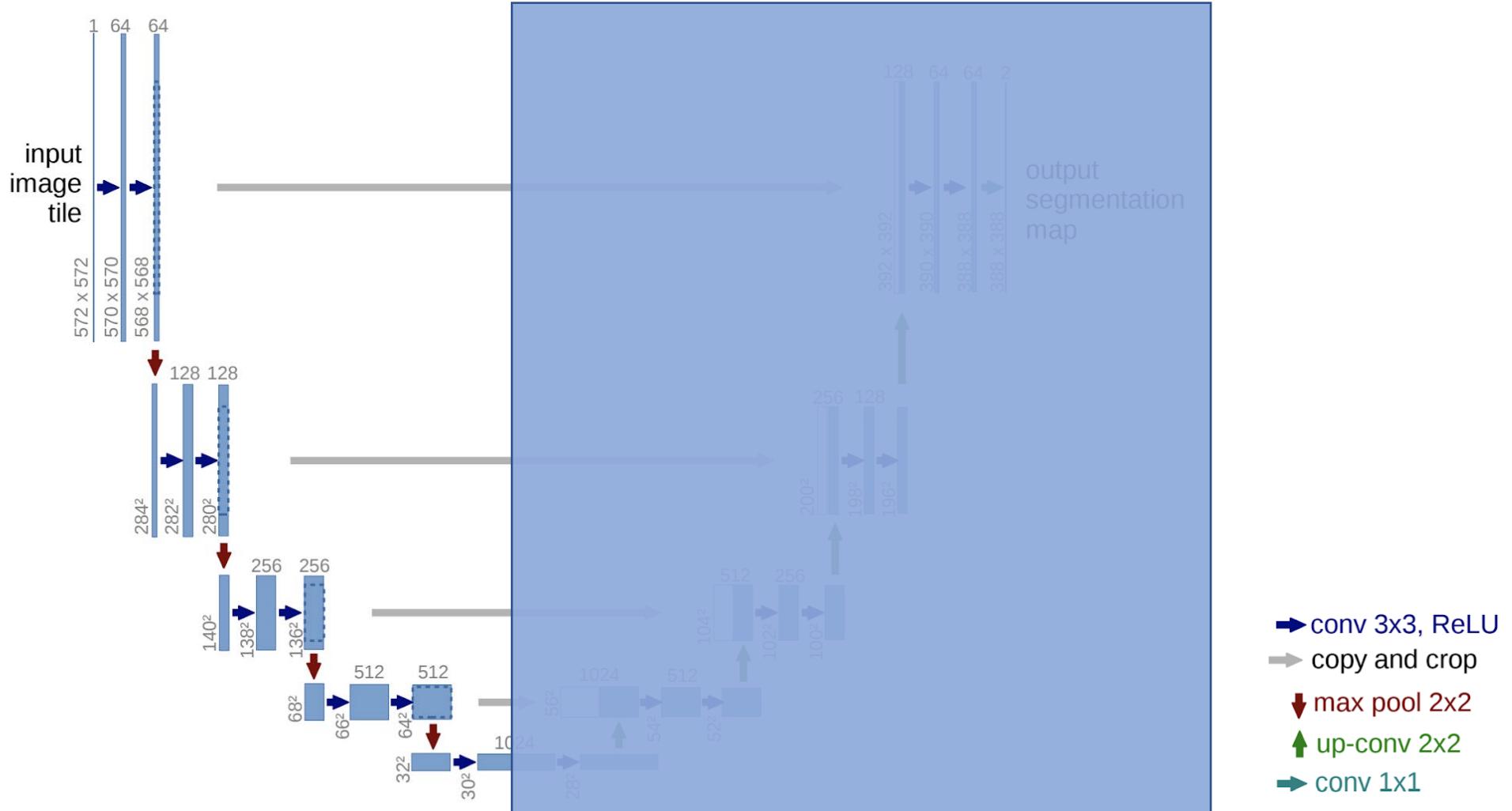
- U-Net Architecture



Semantic Segmentation - UNet

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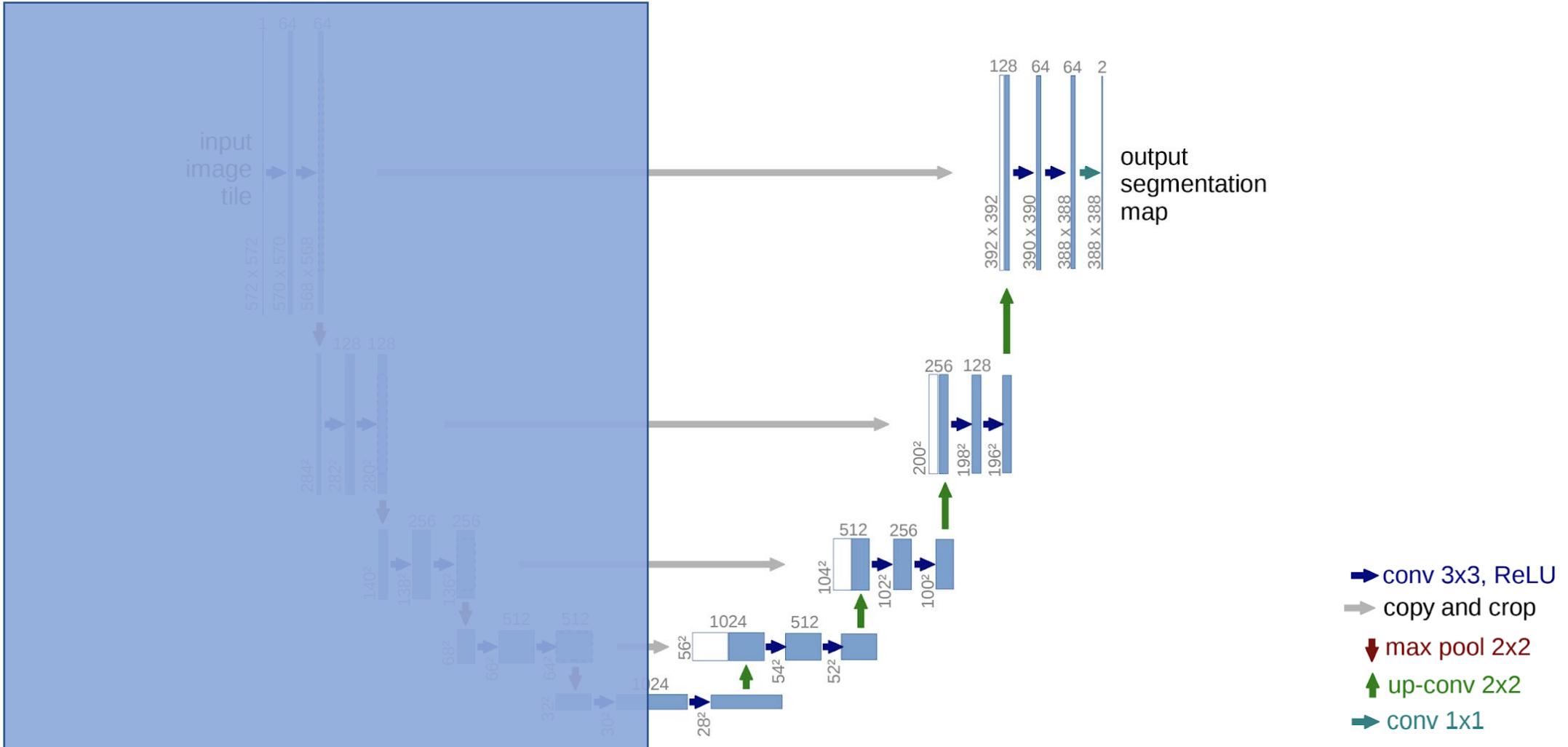
- Contracting Path : Down-Sampling 을 통해 이미지의 context 정보 추출



Semantic Segmentation - UNet

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- Expansive Path : Up-Sampling, 얇은 레이어의 Feature map 결합 수행





Instance Segmentation

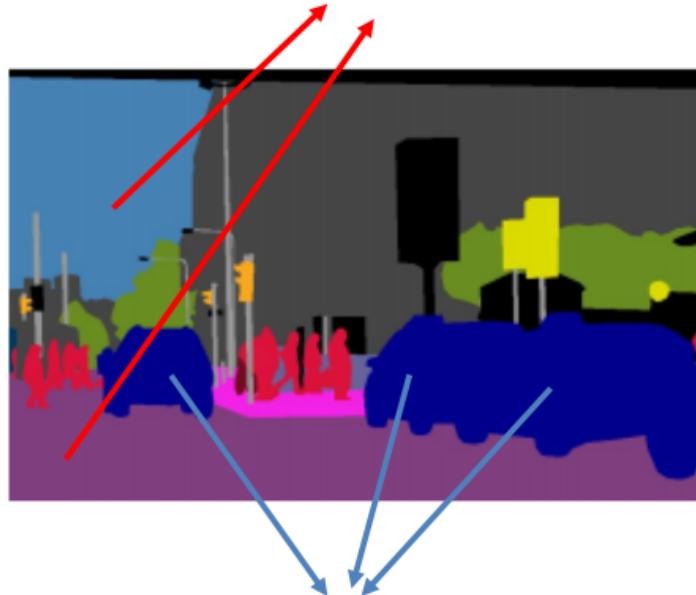
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Instance Segmentation

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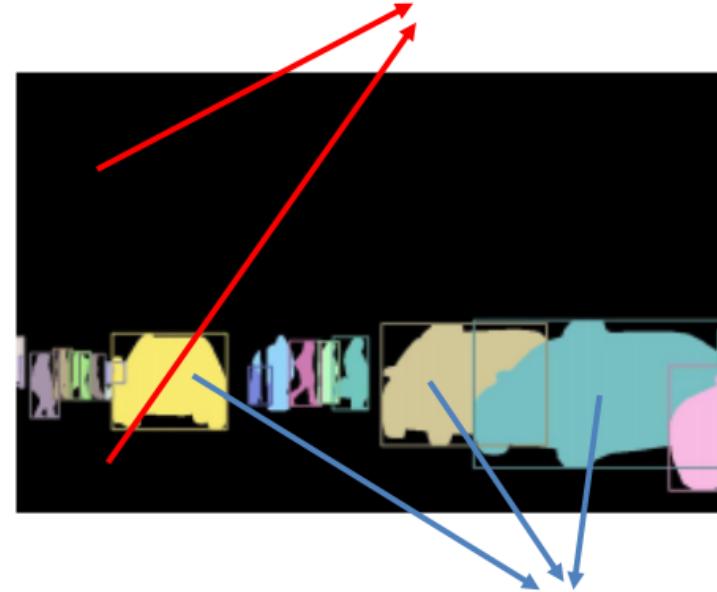
- Difference between semantic and instance segmentation

배경을 포함하여 모든 픽셀에 대하여 레이블링 (하늘, 잔디, 길 등)



같은 종류의 객체에 대해서 다른 픽셀 라벨 부여 되지 않음

셀 수 없는 객체에 대해서는 픽셀에 대한 레이블링 하지 않음 (하늘, 잔디, 길 등)



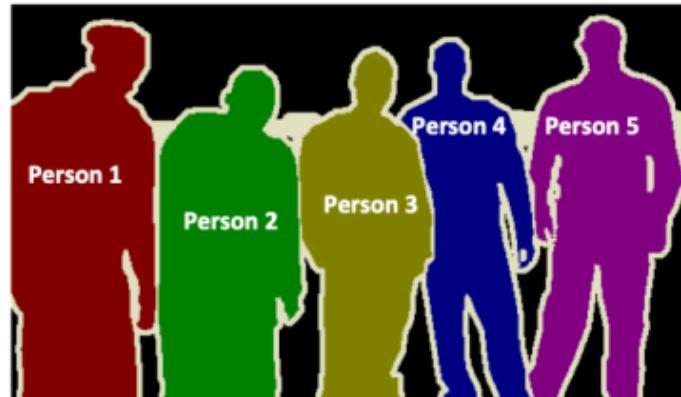
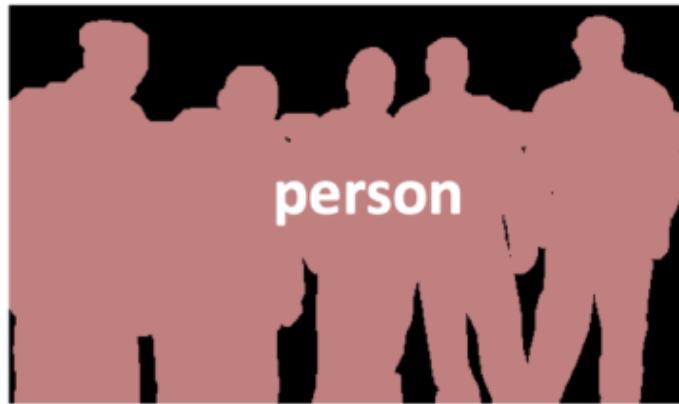
다른 종류의 객체에 대해서 다른 픽셀 라벨 부여됨

Instance Segmentation

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- Instance Segmentation methods

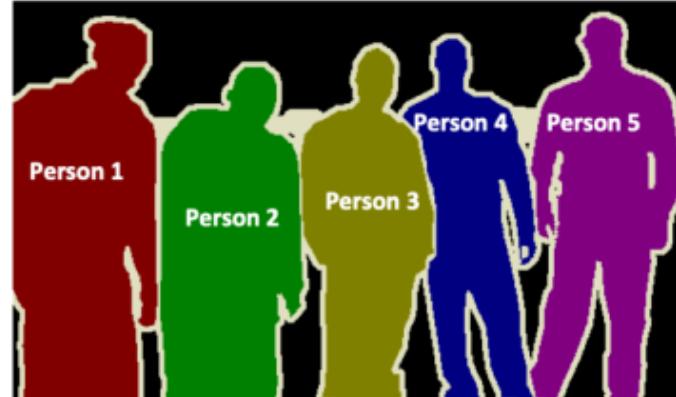
FCN-based



Proposal-based



VS.

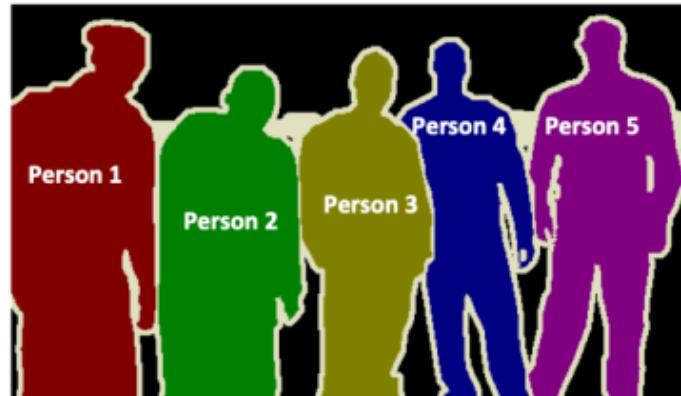
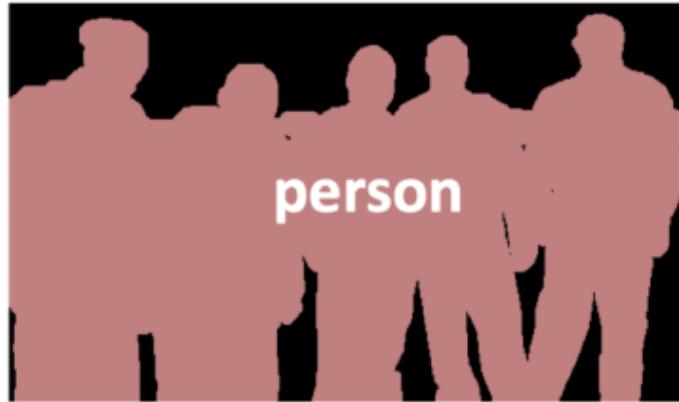


Instance Segmentation

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- Instance Segmentation methods

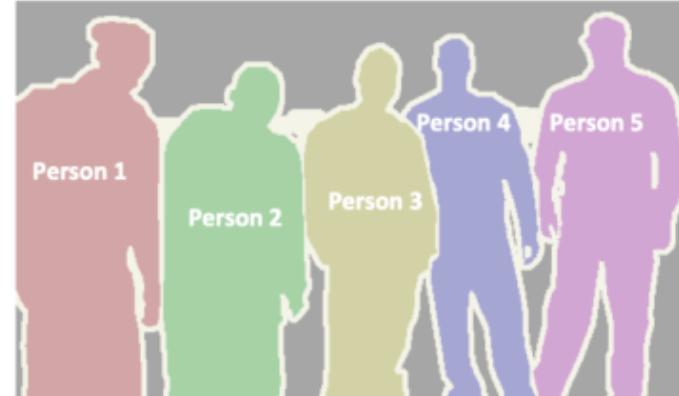
FCN-based



Proposal-based



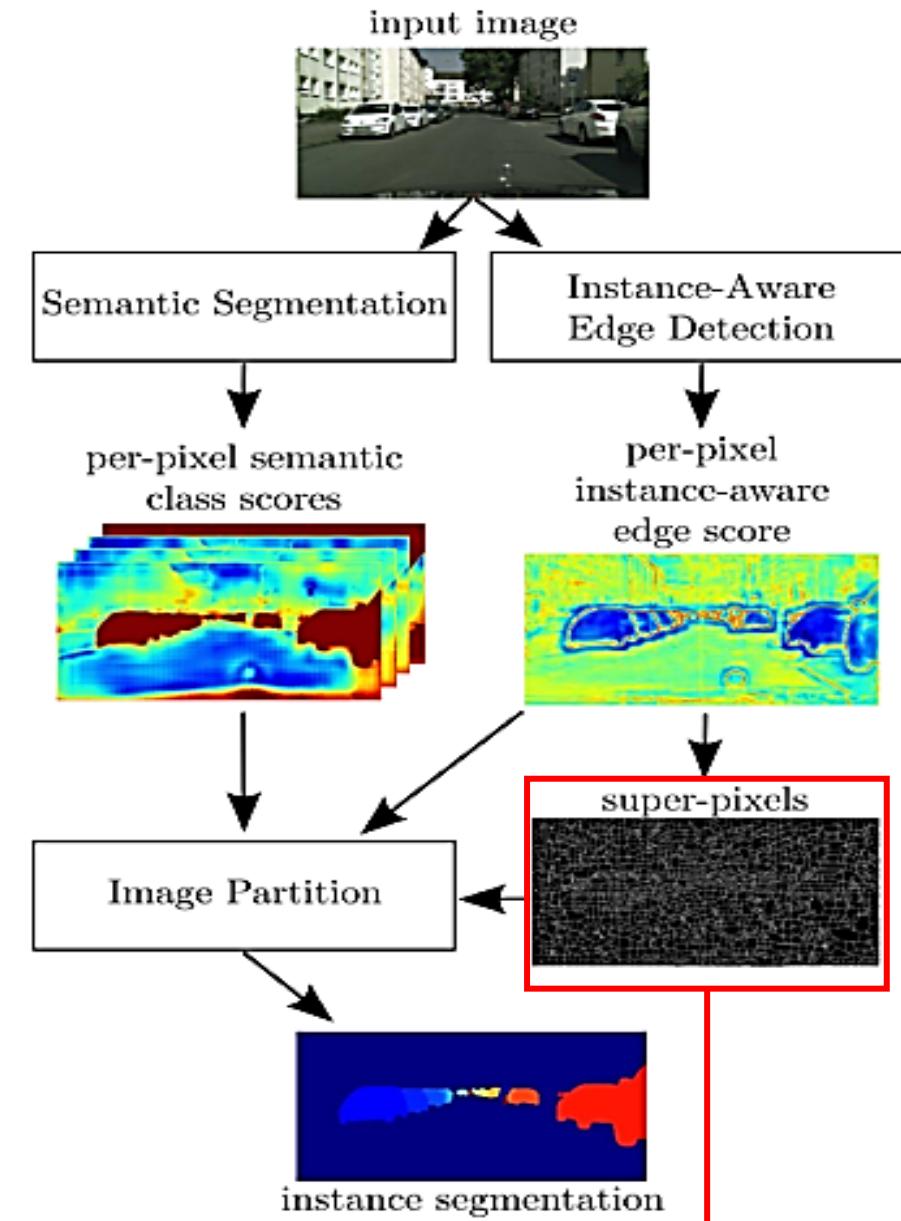
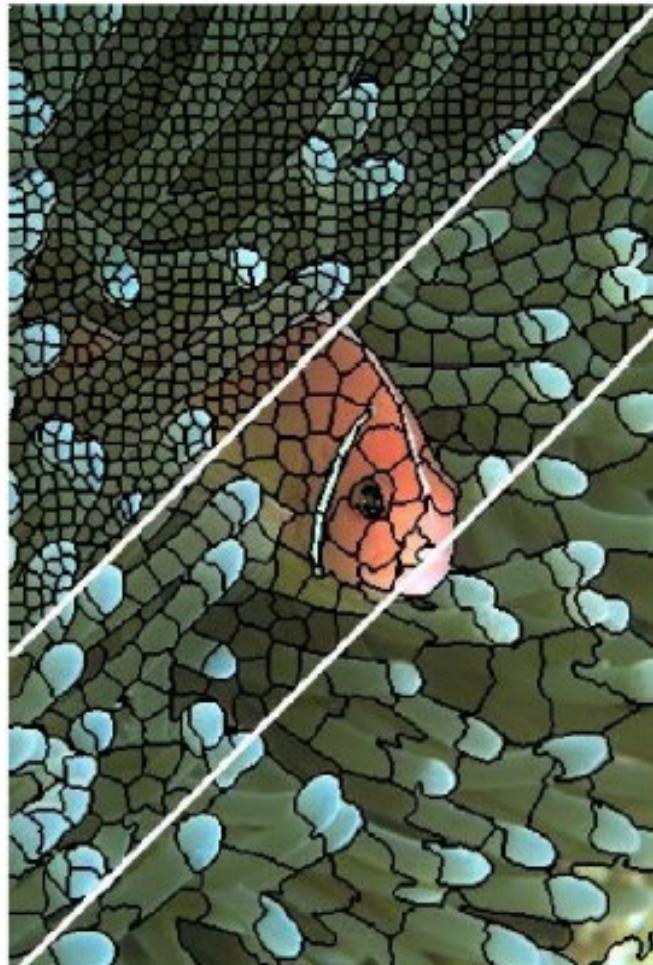
VS.



Instance Segmentation

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- FCN-based method

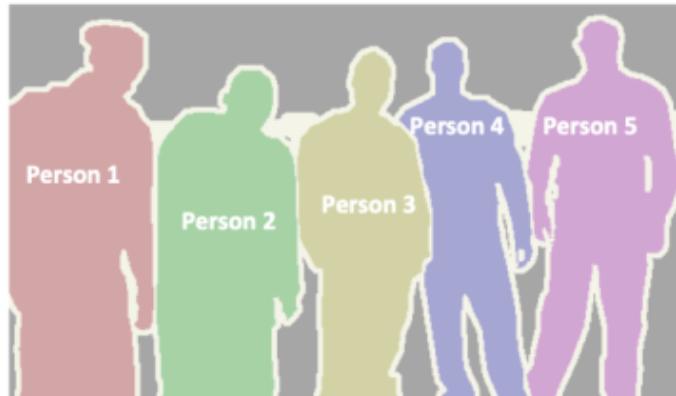


Instance Segmentation

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- Proposal-based method

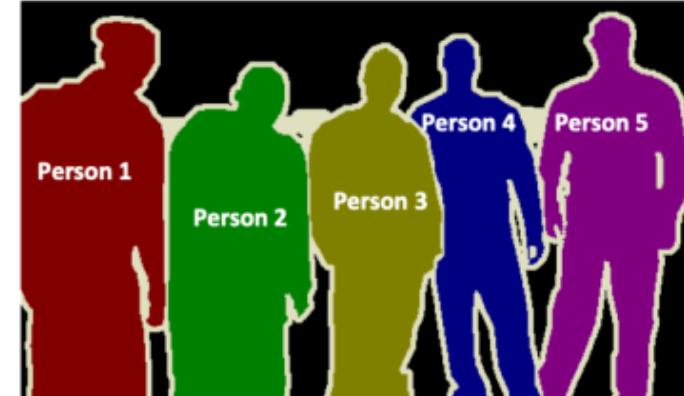
FCN-based



Proposal-based



VS.

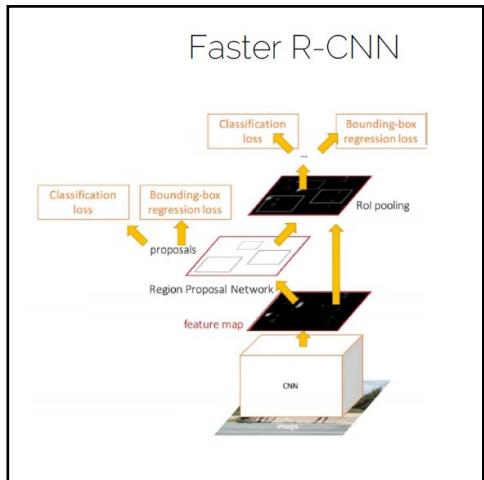


Instance Segmentation - 1,2 Stage

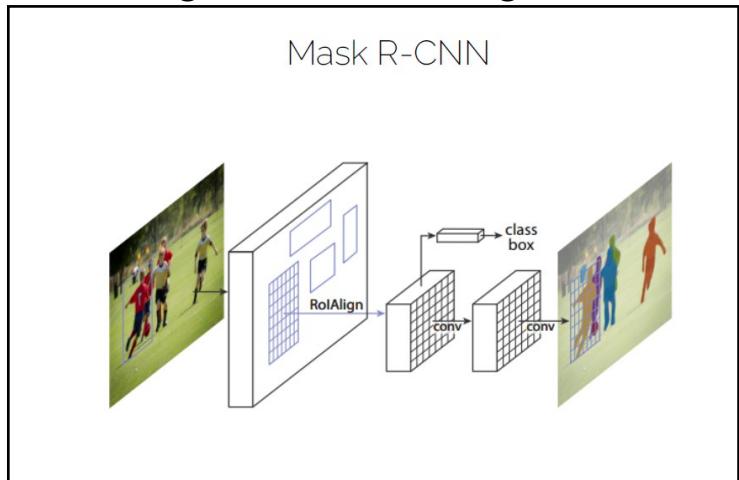
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- Object Detector \leftrightarrow Instance Segmentator

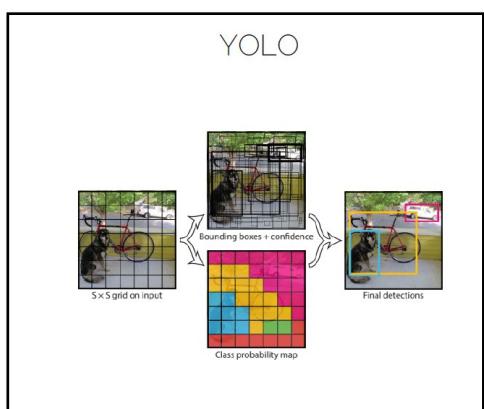
2-Stage Detector



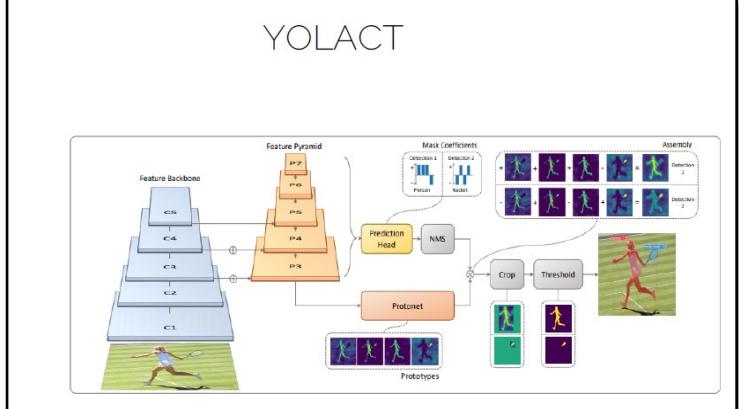
2-Stage Instance Segmentator



1-Stage Detector



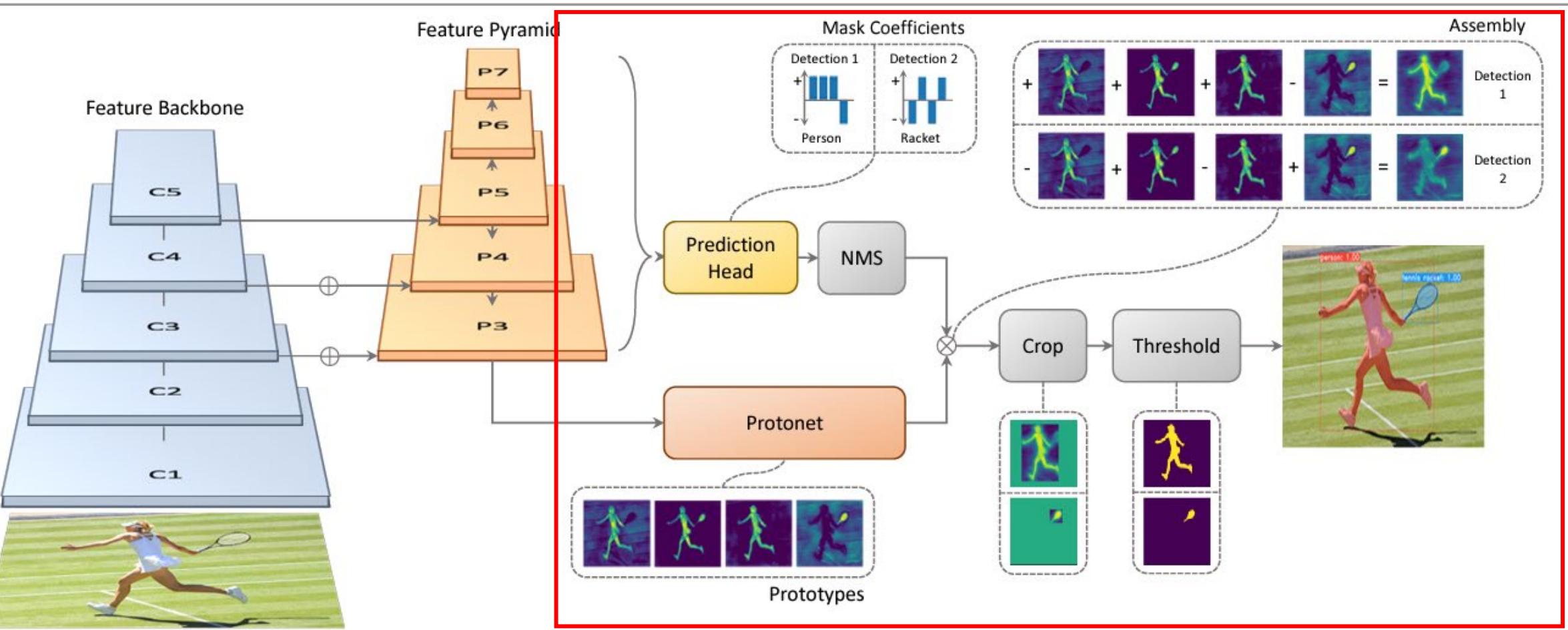
1-Stage Instance Segmentator



Instance Segmentation - YOLACT

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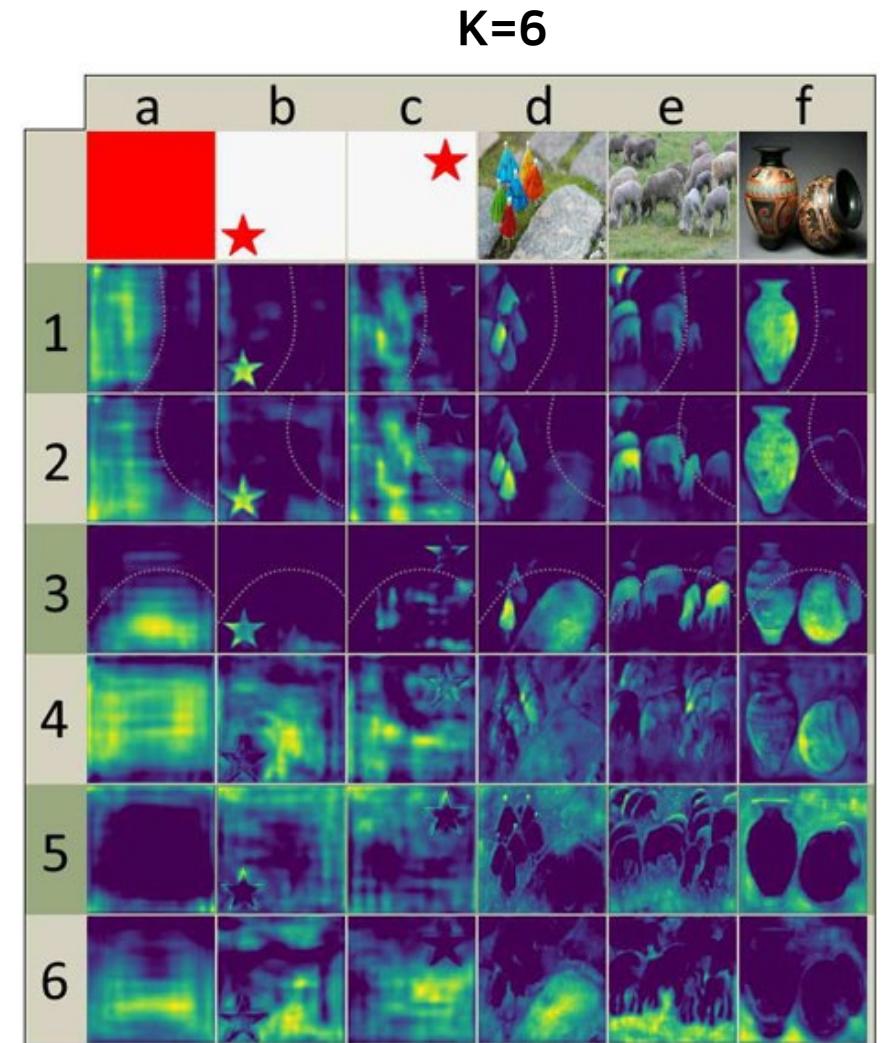
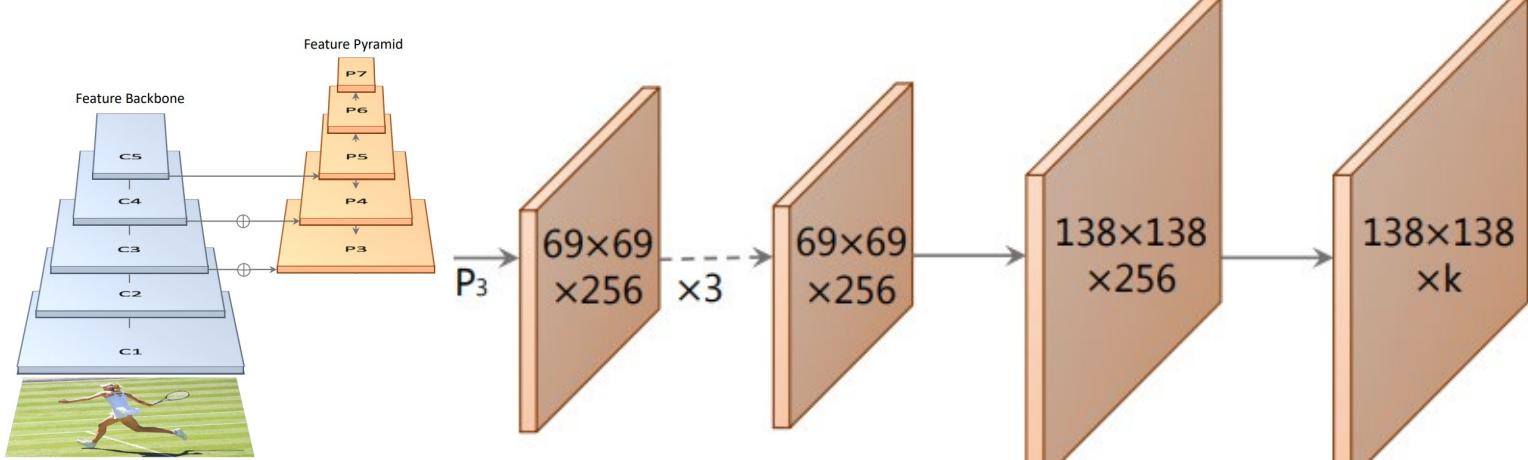
- YOLACT: You Only Look At Coefficients



Instance Segmentation - YOLACT

PIAI Research Department

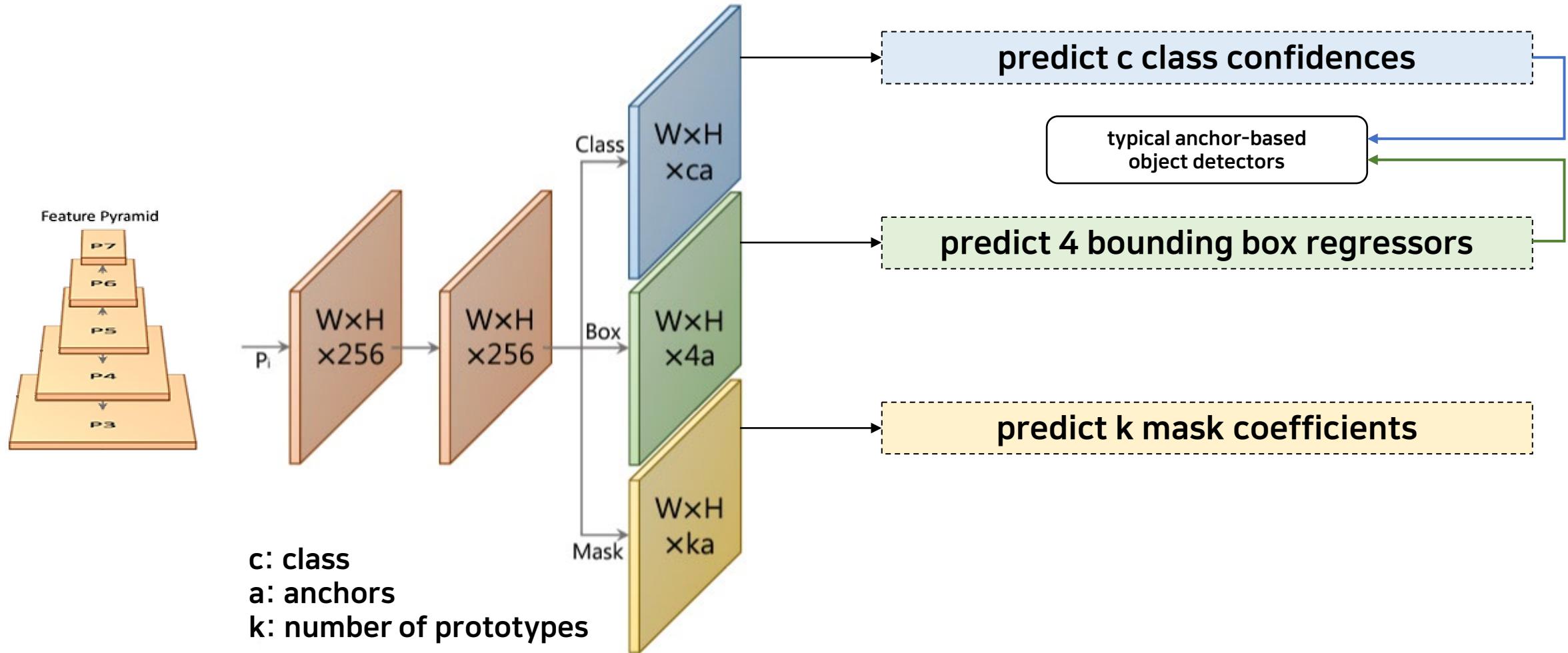
- Protonet Architecture



Instance Segmentation - YOLACT

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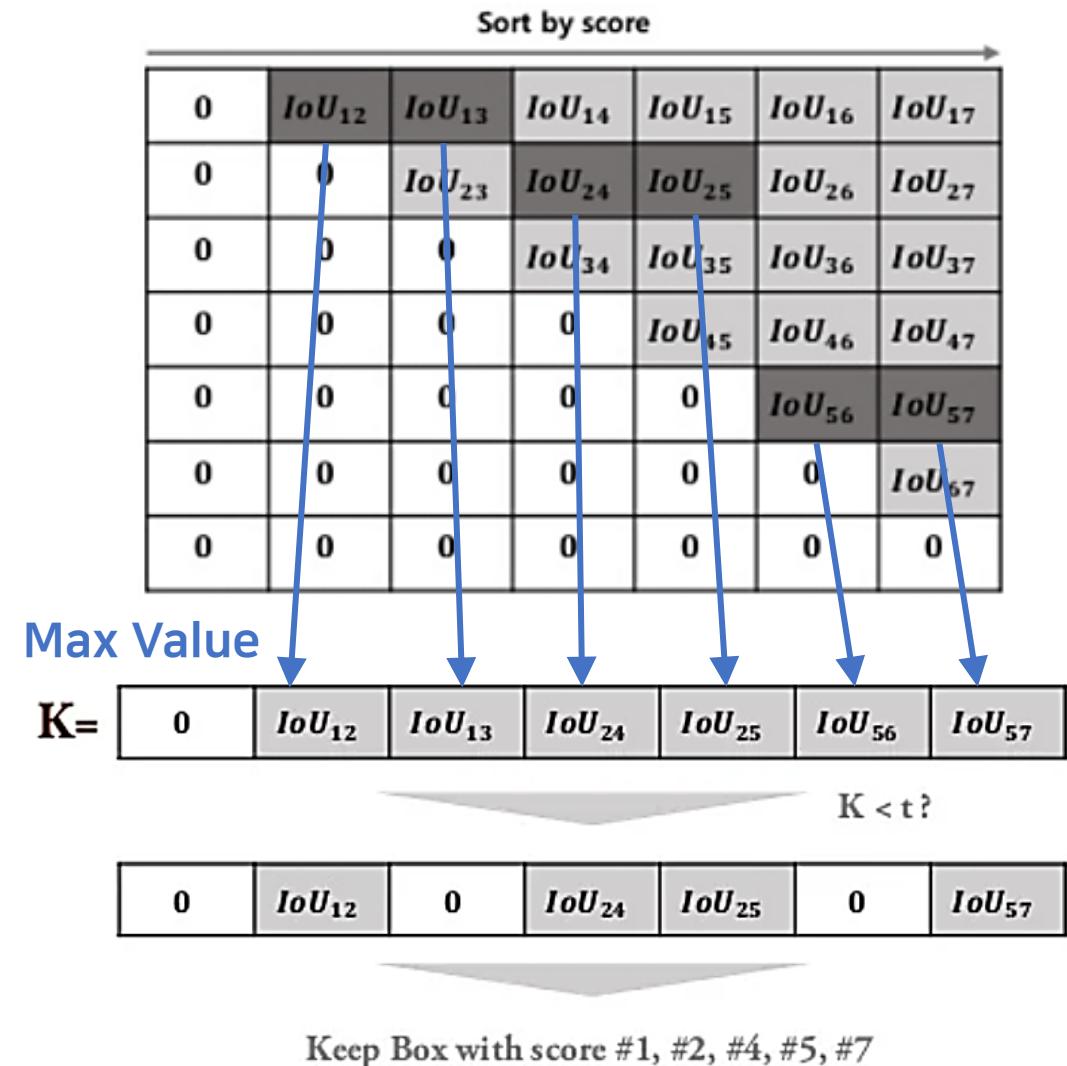
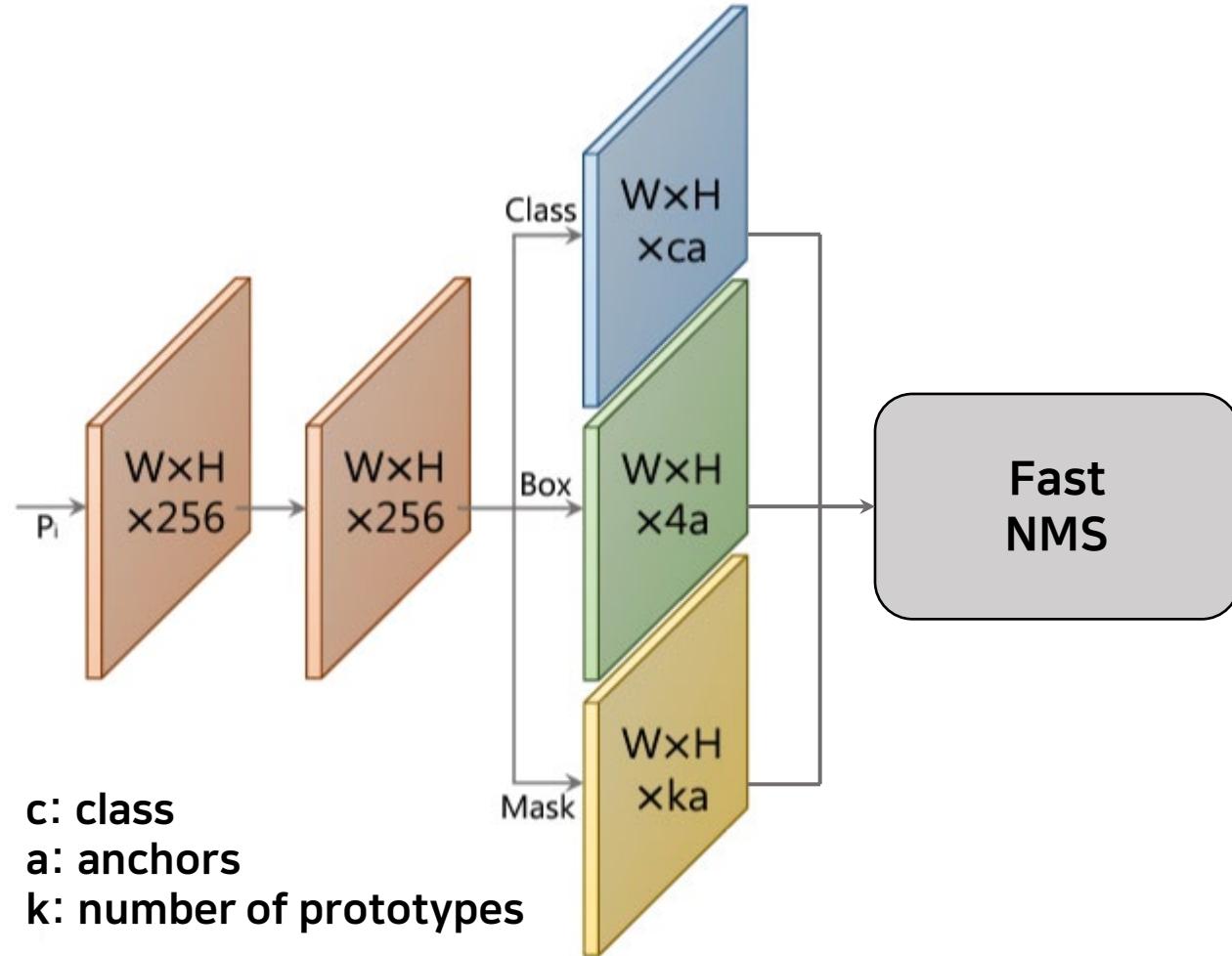
- Prediction Head Architecture



Instance Segmentation - YOLACT

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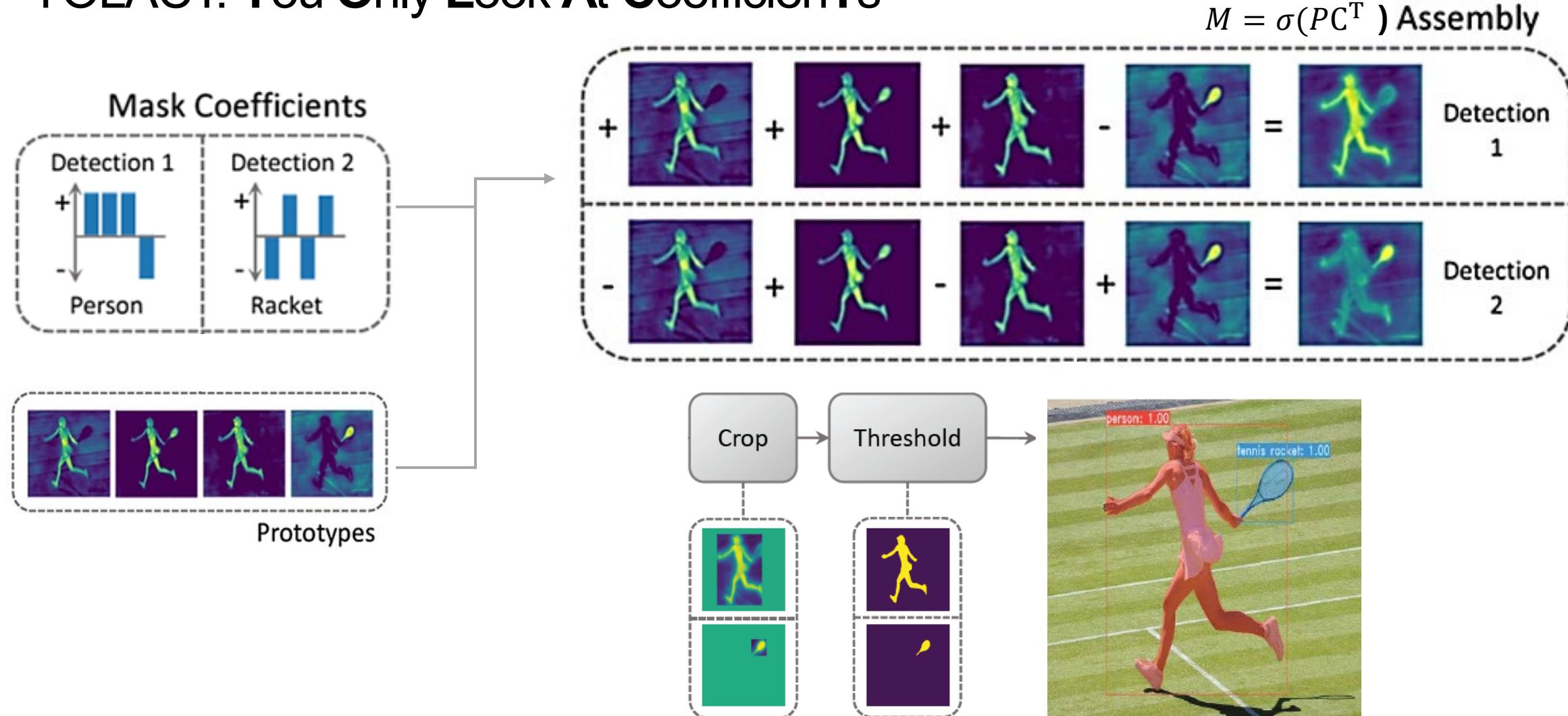
- Fast NMS(Non Maximum Suppression)



Instance Segmentation - YOLACT

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- YOLACT: You Only Look At Coefficients



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Code Running

Appendix – Annotation by labelme

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1. 기본 환경 세팅 – labelme 설치

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- **labelme는 OD/Segmentation용 라벨링 툴이며 설치 시 필요 패키지들을 먼저 설치해야 함.**
※ labelme Github : <https://github.com/wkentaro/labelme>

1. 가상환경 생성 및 가상환경 실행

- conda create -n labelme python=3.8
- conda activate labelme

2. 생성 가상환경 내 필요 패키지 설치

- conda install -c conda-forge pyside2
- conda install pyqt
- pip install pyqt5

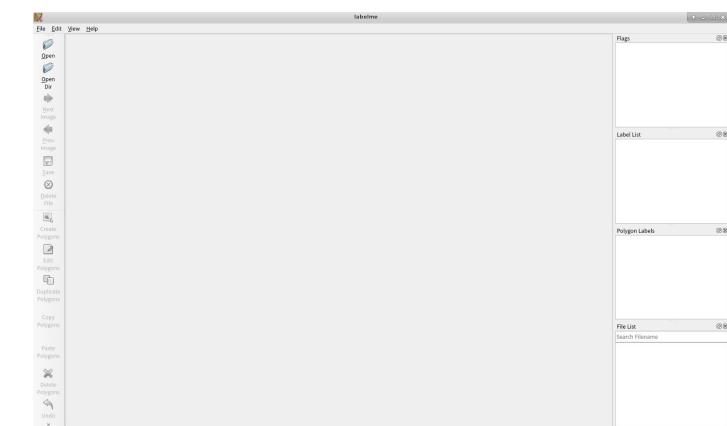
3. 생성 가상환경 내에서 labelImg 설치

- pip install labelme

4. 생성 가상환경 내에서 labelme 실행

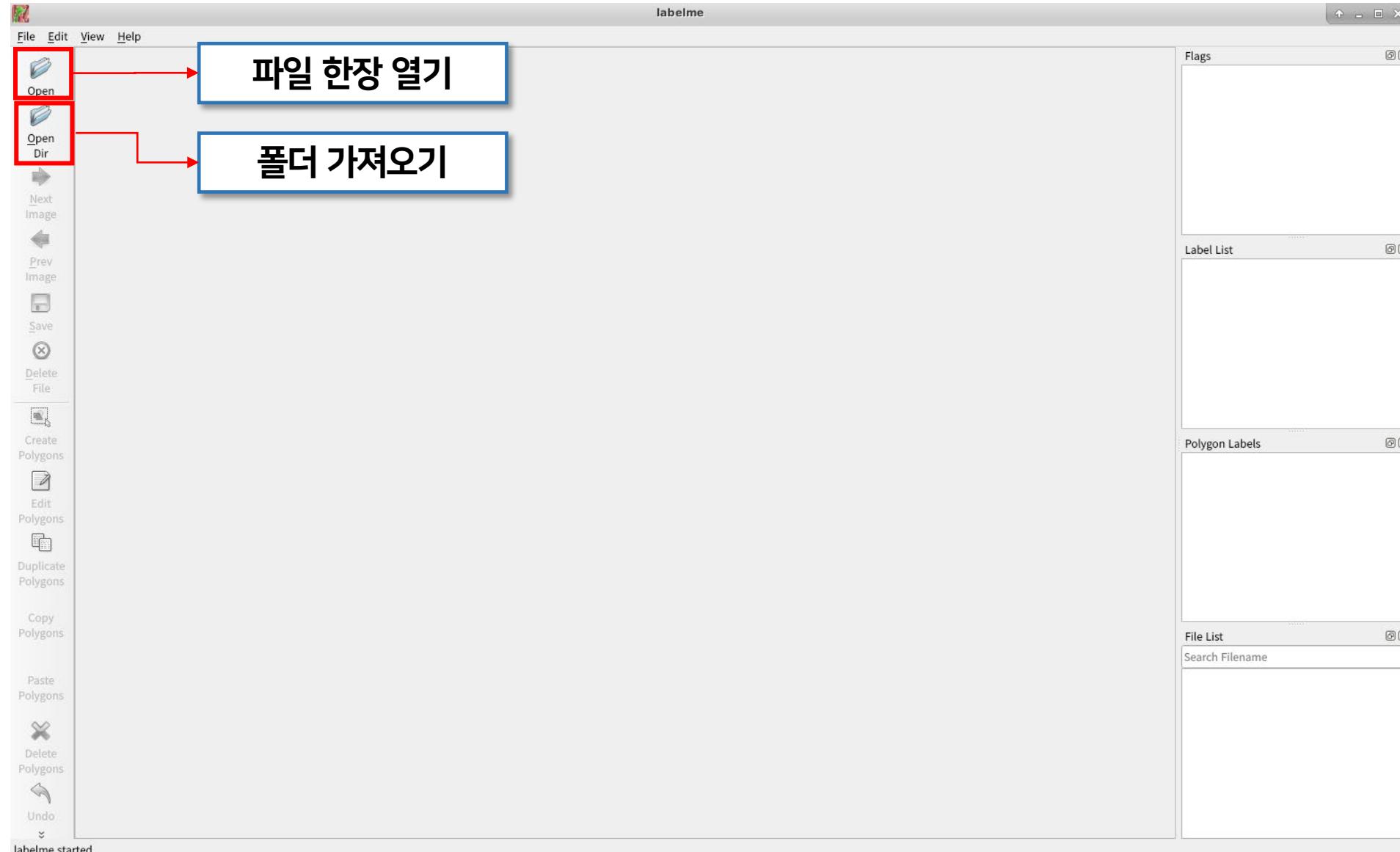
- labelme

(labelme) pirl@pirl-PowerEdge-R740:~\$ labelme



1. Labelme 기능 – 파일 및 디렉토리 열기

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1. Labelme 기능 – Open Dir 및 단축키

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단축키	기능
D	다음 이미지
A	이전 이미지
Ctrl + N	Draw Polygon
Ctrl + R	Draw Rectangle
Ctrl + Z	Undo
Ctrl + J	Edit Polygon

1. Labelme 기능 – 자동 저장 모드

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- 저장을 수동적으로 하지 않고 이전/다음 이미지로 넘어가면 자동적으로 저장하는 모드



1. Labelme 기능 – 저장 위치

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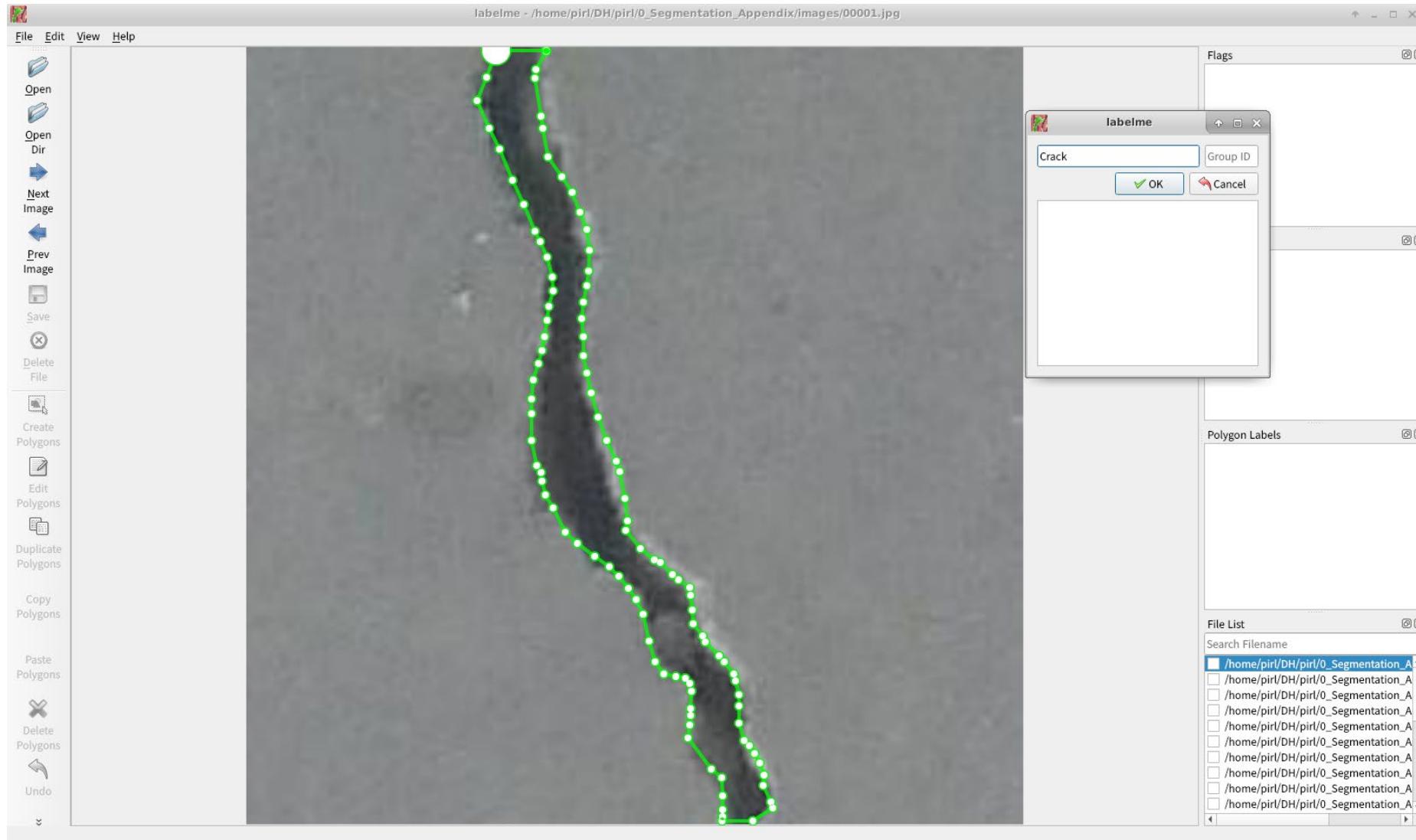
- YOLACT 학습을 위해서는 데이터를 COCO Dataset 형태로 변환을 해 줘야하는데, 이 때 이미지와 .json 라벨 모두 한 폴더 내에 존재해야함.
- File -> Save With Image Data 체크 해 두면 같은 폴더 내에 저장이 됨. 또는 Change Output Dir 해서 같은 폴더로 설정도 가능함.



1. Labelme를 활용한 라벨링

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- Ctrl + N을 눌러 점들을 찍어 폴리곤 형태를 만든 뒤 라벨을 부여



이미지 하나당 한 개의 .json 파일 생성

예시)

```
열기(O) +
{
  "version": "5.0.1",
  "flags": {},
  "shapes": [
    {
      "label": "Crack",
      "points": [
        [
          72.989898989899,
          1.01010101010102
        ],
        [
          70.212121212122,
          8.838383838384
        ],
        [
          67.43434343434343,
          15.65656565656565
        ],
        [
          72.989898989899,
          1.01010101010102
        ],
        [
          70.212121212122,
          8.838383838384
        ],
        [
          67.43434343434343,
          15.65656565656565
        ]
      ]
    }
  ]
}
```



Appendix – Train YOLACT

Dahyun, Kim

1. .json 라벨 파일 → coco 데이터 형식으로 변환

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- YOLACT를 학습시키기 위해서는 JSON 형태 파일을 COCO 데이터 형식으로 변환해야함.
 ※ labelme2coco Github : <https://github.com/Tony607/labelme2coco>

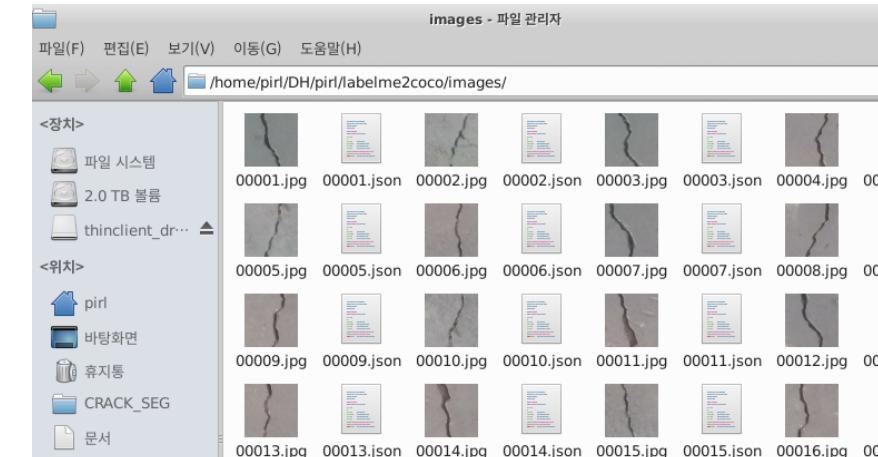
1. labelme 설치된 가상환경 Activate

- conda activate labelme

2. labelme2coco Git Clone

- git clone <https://github.com/Tony607/labelme2coco>

3. labelme2coco/images 폴더 안에 이미지 파일 및 json 파일 넣기 ➔



4. labelme2coco/labelme2coco.py 실행

- python labelme2coco.py images

```
(labelme) pirl@pirl-PowerEdge-R740:~/DH/pirl/labelme2coco$ python labelme2coco.py images
```

→ trainval.json 생성됨

2. yolact 다운로드 및 학습/검증 데이터 준비

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- Git 으로부터 YOLACT 다운로드

※ YOLACT Github : <https://github.com/dbolya/yolact>

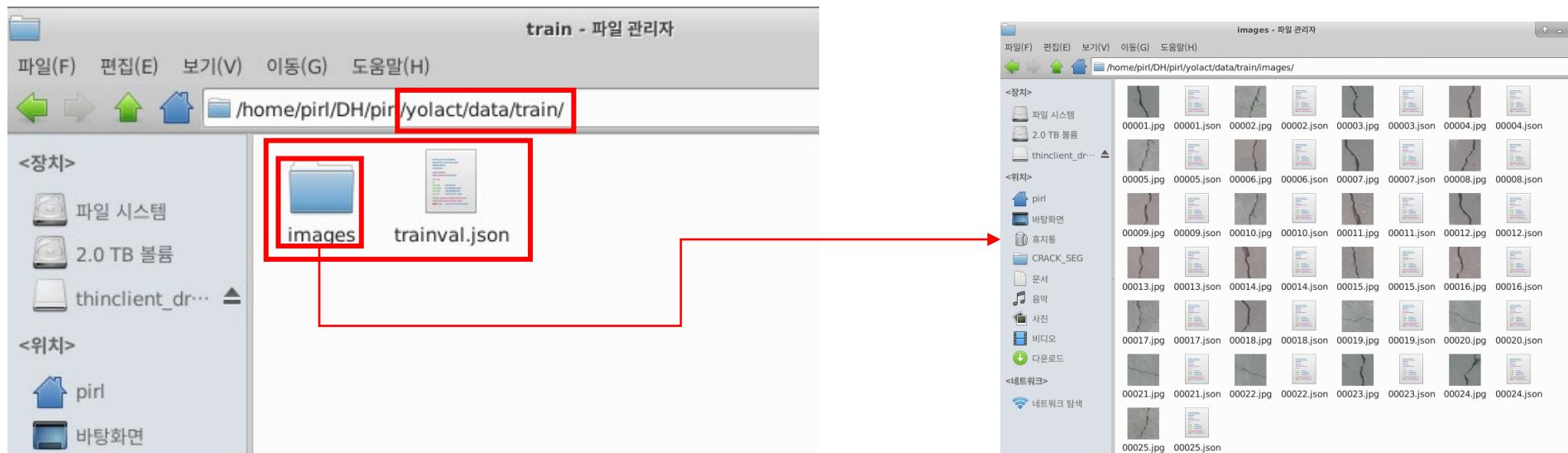
1. YOLACT requirements 설치 된 가상환경 Activate (ex. cv_edu3)

- conda activate cv_edu3

2. YOLACT Git Clone

- git clone <https://github.com/Tony607/labelme2coco>

3. clone 받은 yolact/data 폴더 내에 train 폴더 생성 후 trainval.json 과 원본 images 폴더(이미지 + json) 넣기



2. yolact 다운로드 및 학습/검증 데이터 준비

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4. yolact/data/config.py 에서 내 데이터 경로 및 라벨 정보 입력
 → Config.py 내에서 DATASETS 항목을 찾은 후 가장 마지막에 추가

```
# ----- DATASETS ----- #

dataset_base = Config({
    'name': 'Base Dataset',

    # Training images and annotations
    'train_images': './data/coco/images/',
    'train_info': 'path_to_annotation_file',

    # Validation images and annotations.
    'valid_images': './data/coco/images/',
    'valid_info': 'path_to_annotation_file',

    # Whether or not to load GT. If this is False, eval.py qual
    'has_gt': True,

    # A list of names for each of you classes.
    'class_names': COCO_CLASSES,

    # COCO class ids aren't sequential, so this is a bandage f
    # provide a map from category_id -> index in class_names +
    # If not specified, this just assumes category ids start at
    'label_map': None
})
```

가장 마지막에 추가



```
crack_dataset = dataset_base.copy({
    'name': 'Crack',

    # Training images and annotations
    'train_images': './data/train/images/',
    'train_info': './data/train/trainval.json',

    # Validation images and annotations.
    'valid_images': './data/train/images/',
    'valid_info': './data/train/trainval.json',

    # A list of names for each of you classes.
    'class_names': ('Crack'),

    # COCO class ids aren't sequential, so this is a t
    # provide a map from category_id -> index in class
    # If not specified, this just assumes category ids
    'label_map': {0:1}
})
```

라벨 인덱스 - len(class_names)+1 까지

2. yolact 다운로드 및 학습/검증 데이터 준비

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5. yolact/data/config.py 에서 내 커스텀 모델에 대한 정의 입력

→ Config.py 내에서 YOLACT v1.0 CONFIGS 항목을 찾은 후 가장 마지막에 추가

```
# ----- YOLACT v1.0 CONFIGS ----- #

yolact_base_config = coco_base_config.copy({
    'name': 'yolact_base',

    # Dataset stuff
    'dataset': coco2017_dataset,
    'num_classes': len(coco2017_dataset.class_names) + 1,

    # Image Size
    'max_size': 550,

    # Training params
    'lr_steps': (280000, 600000, 700000, 750000),
    'max_iter': 800000,

    # Backbone Settings
    'backbone': resnet101_backbone.copy({
        'selected_layers': list(range(1, 4)),
        'use_pixel_scales': True,
        'preapply_sqrt': False,
        'use_square_anchors': True, # This is for backward compatibility

        'pred_aspect_ratios': [[[1, 1/2, 2]]]*5,
        'pred_scales': [[24], [48], [96], [192], [384]],
    }),
})
```

가장 마지막에 추가



```
yolact_resnet50_crack_config = yolact_resnet50_config.copy({
    'name': 'yolact_resnet50_crack',

    # Dataset stuff
    'dataset': crack_database, → 앞 선언한 데이터셋과 동일한 이름
    'num_classes': len(crack_database.class_names) + 1,

    'backbone': yolact_resnet50_config.backbone.copy({
        'name': 'ResNet101',
        'path': 'yolact base 54 800000.pth', → 내가 사용할 weight 이름과 동일해야함
        'pred_scales': [[32], [64], [128], [256], [512]],
        'use_square_anchors': False,
    })
})
```

파라미터 종류와 값을 원하는대로 입력

2. yolact 다운로드 및 학습/검증 데이터 준비

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6. Config.py에 정의한 내 커스텀 모델 Backbone 다운받기

- 1) ResNet-50-FPN, 550(img size) : yolact_resnet50_54_800000.pth
- 2) Darknet53-FPN, 550(img size) : yolact_darknet53_54_800000.pth
- 3) Resnet101-FPN, 550(img size) : yolact_base_54_800000.pth
- 4) Resnet101-FPN, 700(img size) : yolact_im700_54_800000.pth

1. Download Pretrained Model

1. Resnet50-FPN, 550 : yolact_resnet50_54_800000.pth
2. Darknet53-FPN, 550 : yolact_darknet53_54_800000.pth
- 3) Resnet101-FPN, 550 : yolact_base_54_800000.pth
4. Resnet101-FPN, 700 : yolact_im700_54_800000.pth

```
[1]: import os

## --- YOLACT pretrained model download
## --- Make directories weights for save model weights file

if not os.path.exists('./weights'):
    os.makedirs('./weights')

# Resnet50-FPN : yolact_resnet50_54_800000.pth
# !wget -q --load-cookies /tmp/cookies.txt "https://docs.google.com/uc?export=download&confirm=$(wget --quiet --save-cookies /tmp/cookies.txt --no-checksum https://docs.google.com/uc?export=download -O- | sed s/Location: http\:///\nhttp\:///g)" -O ./weights/yolact_resnet50_54_800000.pth

# Darknet53-FPN : yolact_darknet53_54_800000.pth
# !wget -q --load-cookies /tmp/cookies.txt "https://docs.google.com/uc?export=download&confirm=$(wget --quiet --save-cookies /tmp/cookies.txt --no-checksum https://docs.google.com/uc?export=download -O- | sed s/Location: http\:///\nhttp\:///g)" -O ./weights/yolact_darknet53_54_800000.pth

# Resnet101-FPN : yolact_base_54_800000.pth
!wget -q --load-cookies /tmp/cookies.txt "https://docs.google.com/uc?export=download&confirm=$(wget --quiet --save-cookies /tmp/cookies.txt --no-checksum https://docs.google.com/uc?export=download -O- | sed s/Location: http\:///\nhttp\:///g)" -O ./weights/yolact_base_54_800000.pth

# Resnet101-FPN : yolact_im700_54_800000.pth
# !wget -q --load-cookies /tmp/cookies.txt "https://docs.google.com/uc?export=download&confirm=$(wget --quiet --save-cookies /tmp/cookies.txt --no-checksum https://docs.google.com/uc?export=download -O- | sed s/Location: http\:///\nhttp\:///g)" -O ./weights/yolact_im700_54_800000.pth
```

실습 YOLACT.ipynb 주피터 파일 1번 항목 참조

3. yolact 학습

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※ 만약 pytorch가 1.9 이상 버전이라면 학습 시 오류 발생

```
yield from torch.randperm(n, generator=generator).tolist()
RuntimeError: Expected a 'cuda' device type for generator but found 'cpu'
```

→ 해당 오류 발생 시 train.py에서 DataLoader를 검색한 후 인자에 `generator=torch.Generator(device='cuda')` 추가



```

열기(0) + train.py 2.0 TB 블루 ~/DH/pirl/yolact 저장(S) - config.py +
x x
train.py
train.py config.py
last_time = time.time()

epoch_size = len(dataset) // args.batch_size
num_epochs = math.ceil(cfg.max_iter / epoch_size)

# Which learning rate adjustment step are we on? lr' = lr * gamma ^ step_index
step_index = 0

data_loader = data.DataLoader(dataset, args.batch_size,
                             num_workers=args.num_workers,
                             shuffle=True, collate_fn=detection_collate,
                             pin_memory=True, generator=torch.Generator(device='cuda')) generator=torch.Generator(device='cuda')

save_path = lambda epoch, iteration: SavePath(cfg.name, epoch, iteration).get_path(root=args.save_folder)
time_avg = MovingAverage()

global loss_types # Forms the print order
loss_avgs = { k: MovingAverage(100) for k in loss_types }

```

3. yolact 학습

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- YOLACT 학습 - train.py
 - python train.py --config=내가 정의한 모델 config --batch=배치사이즈

예시) python train.py --config=yolact_resnet50_crack_config --batch_size=16

```
(cv_edu3) pirl@pirl-PowerEdge-R740:~/DH/pirl/yolact$ python train.py --config=yolact_resnet50_crack_config --batch_size=16
```

Calculating mAP...												
	all	.50	.55	.60	.65	.70	.75	.80	.85	.90	.95	
box	0.33	0.98	0.94	0.71	0.46	0.14	0.03	0.01	0.01	0.00	0.00	
mask	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	0.00	

학습 도중 중지 시키면 weights 폴더에 모델이 저장 되며, 중간중간 저장하도록 argument를 넘길 수 있음. 해당 내용은 train.py 내부의 argument를 확인해 볼 것