

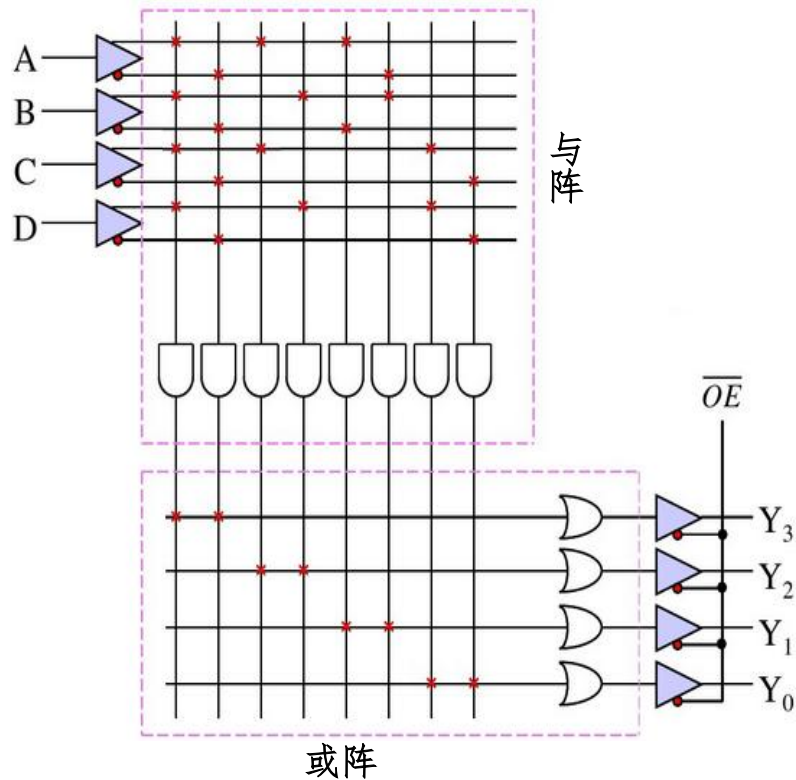
Unit 13

——Programmable Logic Devices

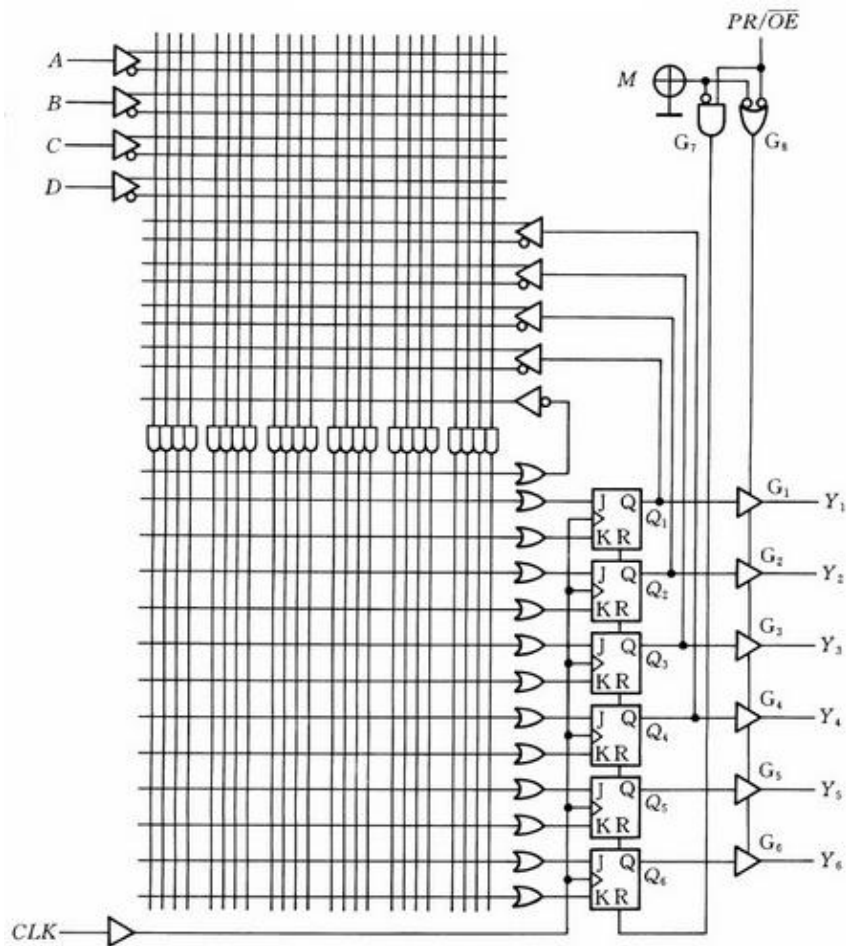
张彦航

School of Computer Science
Zhangyanhang@hit.edu.cn

组合型FPLA



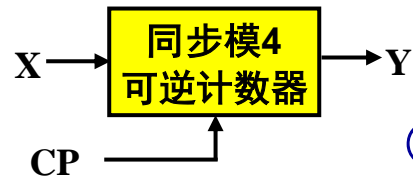
时序型FPLA



PLA及其应用

Example

例4：利用PLA设计2位二进制同步可逆计数器，假设PLA中是JK触发器。



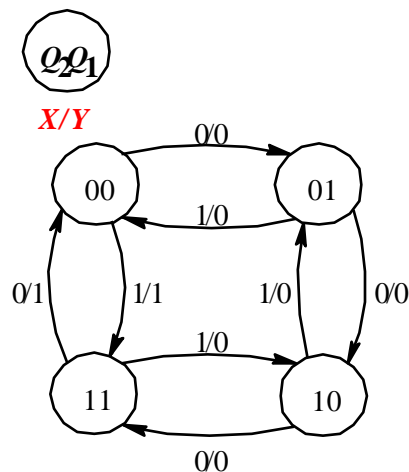
X=0:加法; X=1:减法;
Y: 进位(借位)

② transition table

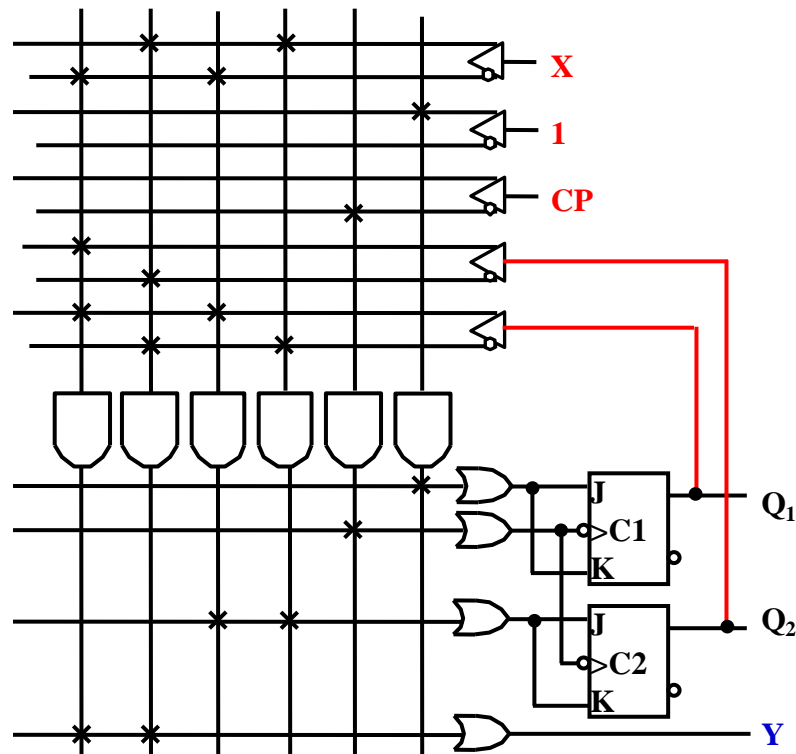
| X | Q_2^n | Q_1^n | Q_2^{n+1} | Q_1^{n+1} | Y |
|---|---------|---------|-------------|-------------|---|
| 0 | 0 | 0 | 0 | 1 | 0 |
| 0 | 0 | 1 | 1 | 0 | 0 |
| 0 | 1 | 0 | 1 | 1 | 0 |
| 0 | 1 | 1 | 0 | 0 | 1 |
| 1 | 0 | 0 | 1 | 1 | 1 |
| 1 | 0 | 1 | 0 | 0 | 0 |
| 1 | 1 | 0 | 0 | 1 | 0 |
| 1 | 1 | 1 | 1 | 0 | 0 |

$$\begin{cases} J_1 = K_1 = 1 \\ J_2 = K_2 = X\bar{Q}_1^n + \bar{X}Q_1^n \end{cases}$$

① state graph



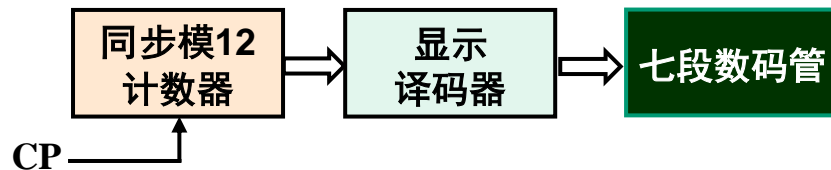
③ Realize



PLA及其应用

Example

例5：利用PLA设计模12计数器，并在七段数码管上显示计数值，假设PLA中是JK触发器。



① 设计模12计数器

| $y_4 y_3 y_2 y_1$ | $y_4^{n+1} y_3^{n+1} y_2^{n+1} y_1^{n+1}$ | $J_4 K_4$ | $J_3 K_3$ | $J_2 K_2$ | $J_1 K_1$ |
|-------------------|---|-----------|-----------|-----------|-----------|
| 0 0 0 0 | 0 0 0 1 | 0 × | 0 × | 0 × | 1 × |
| 0 0 0 1 | 0 0 1 0 | 0 × | 0 × | 1 × | × 1 |
| 0 0 1 0 | 0 0 1 1 | 0 × | 0 × | × 0 | 1 × |
| 0 0 1 1 | 0 1 0 0 | 0 × | 1 × | × 1 | × 1 |
| 0 1 0 0 | 0 1 0 1 | 0 × | × 0 | 0 × | 1 × |
| 0 1 0 1 | 0 1 1 0 | 0 × | × 0 | 1 × | × 1 |
| 0 1 1 0 | 0 1 1 1 | 0 × | × 0 | × 0 | 1 × |
| 0 1 1 1 | 1 0 0 0 | 1 × | × 1 | × 1 | × 1 |
| 1 0 0 0 | 1 0 0 1 | × 0 | 0 × | 0 × | 1 × |
| 1 0 0 1 | 1 0 1 0 | × 0 | 0 × | 1 × | × 1 |
| 1 0 1 0 | 1 0 1 1 | × 0 | 0 × | × 0 | 1 × |
| 1 0 1 1 | 0 0 0 0 | 0 × | 1 × | × 1 | × 1 |

J_4

| $y_4 y_3$ \ $y_2 y_1$ | 00 | 01 | 11 | 10 |
|-----------------------|----|----|----|----|
| 00 | 0 | 0 | 0 | 0 |
| 01 | 0 | 0 | 1 | 0 |
| 11 | × | × | × | × |
| 10 | × | × | × | × |

K_4

| $y_4 y_3$ \ $y_2 y_1$ | 00 | 01 | 11 | 10 |
|-----------------------|----|----|----|----|
| 00 | × | × | × | × |
| 01 | × | × | × | × |
| 11 | × | × | × | × |
| 10 | 0 | 0 | 1 | 0 |

J_3

| $y_4y_3 \backslash y_2y_1$ | 00 | 01 | 11 | 10 |
|----------------------------|----|----|----|----|
| 00 | 0 | 0 | 1 | 0 |
| 01 | × | × | × | × |
| 11 | × | × | × | × |
| 10 | 0 | 0 | 0 | 0 |

K_3

| $y_4y_3 \backslash y_2y_1$ | 00 | 01 | 11 | 10 |
|----------------------------|----|----|----|----|
| 00 | × | × | × | × |
| 01 | 0 | 0 | 1 | 0 |
| 11 | × | × | × | × |
| 10 | × | × | × | × |

$$\begin{cases} J_4 = y_3y_2y_1 \\ K_4 = y_2y_1 \end{cases}$$

J_2

| $y_4y_3 \backslash y_2y_1$ | 00 | 01 | 11 | 10 |
|----------------------------|----|----|----|----|
| 00 | 0 | 1 | × | × |
| 01 | 0 | 1 | × | × |
| 11 | × | × | × | × |
| 10 | 0 | 1 | × | × |

K_2

| $y_4y_3 \backslash y_2y_1$ | 00 | 01 | 11 | 10 |
|----------------------------|----|----|----|----|
| 00 | × | × | 1 | 0 |
| 01 | × | × | 1 | 0 |
| 11 | × | × | × | × |
| 10 | × | × | 1 | 0 |

$$\begin{cases} J_3 = \bar{y}_4y_2y_1 \\ K_3 = y_2y_1 \end{cases}$$

J_1

| $y_4y_3 \backslash y_2y_1$ | 00 | 01 | 11 | 10 |
|----------------------------|----|----|----|----|
| 00 | 1 | × | × | 1 |
| 01 | 1 | × | × | 1 |
| 11 | × | × | × | × |
| 10 | 1 | × | × | 1 |

K_1

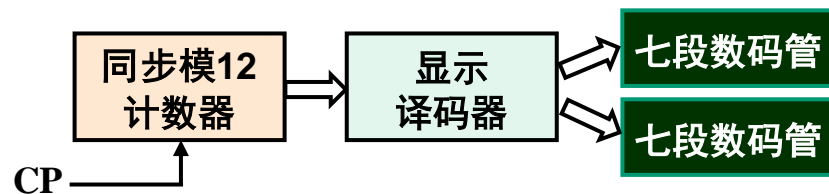
| $y_4y_3 \backslash y_2y_1$ | 00 | 01 | 11 | 10 |
|----------------------------|----|----|----|----|
| 00 | × | 1 | 1 | × |
| 01 | × | 1 | 1 | × |
| 11 | × | × | × | × |
| 10 | × | 1 | 1 | × |

$$\begin{cases} J_2 = y_1 \\ K_2 = y_1 \end{cases}$$

$$\begin{cases} J_1 = 1 \\ K_1 = 1 \end{cases}$$

PLA及其应用

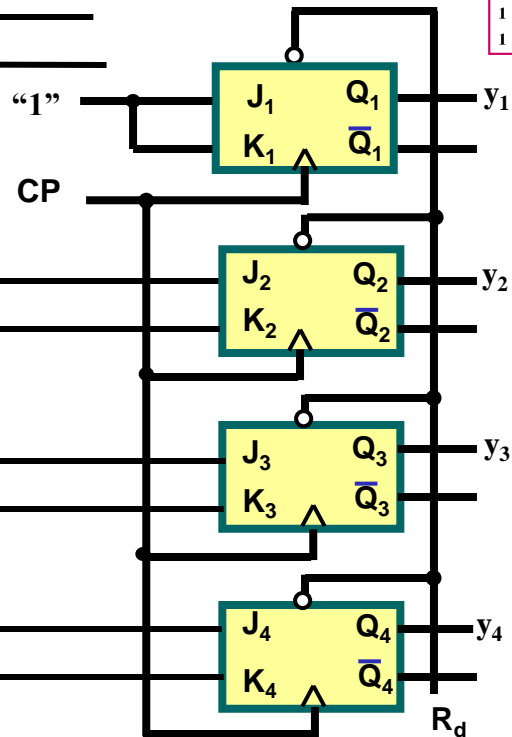
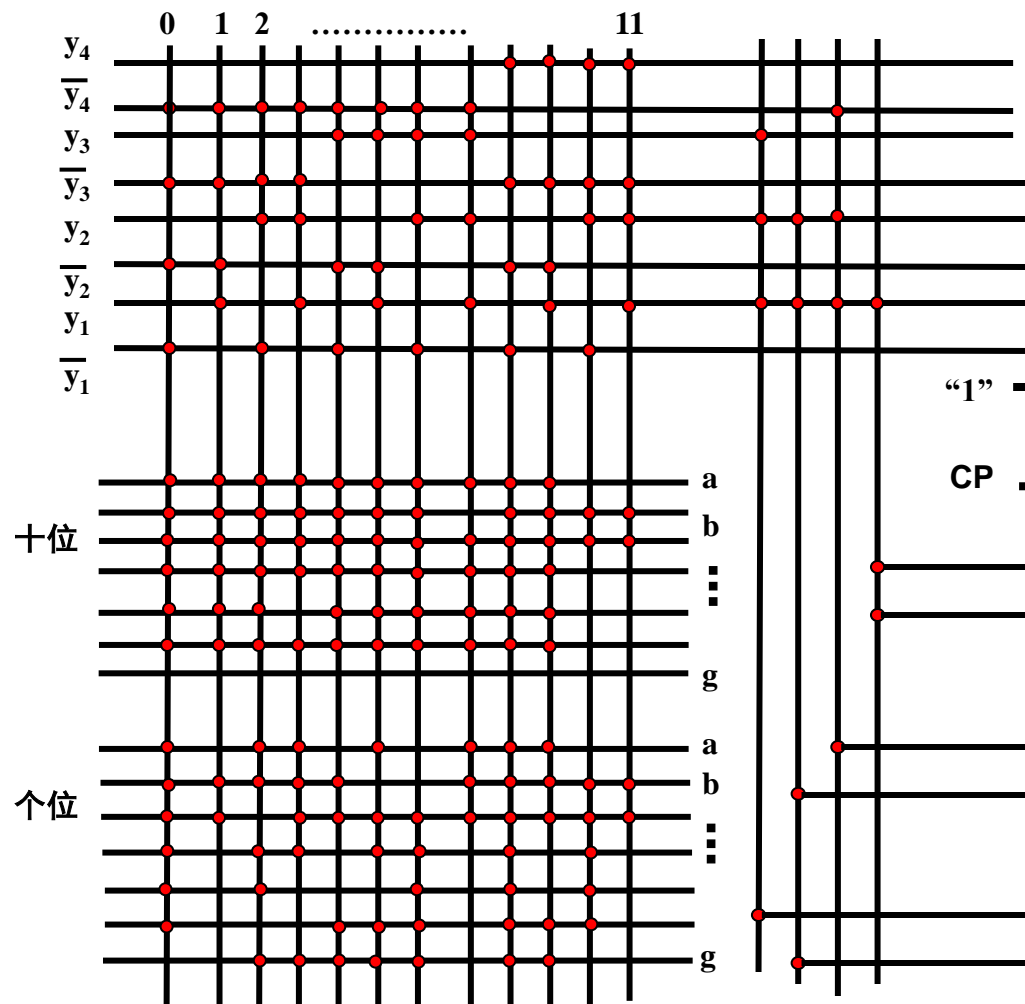
② 设计显示译码器



译码器输入：4位，来自模12计数器

译码器输出：14位，驱动两个7段数码管

| 十位 | | | | | | | | 个位 | | | | | | | | | |
|----------------|---|---|---|---|---|---|---|----|----------------|---|---|---|---|---|---|---|---|
| $y_4y_3y_2y_1$ | a | b | c | d | e | f | g | | $y_4y_3y_2y_1$ | a | b | c | d | e | f | g | |
| 0 0 0 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 0 0 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 |
| 0 0 0 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 0 0 1 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 1 |
| 0 0 1 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 0 1 0 | 1 | 1 | 0 | 1 | 1 | 0 | 1 | 2 |
| 0 0 1 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 0 1 1 | 1 | 1 | 1 | 1 | 0 | 0 | 1 | 3 |
| 0 1 0 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 1 0 0 | 0 | 1 | 1 | 0 | 0 | 1 | 1 | 4 |
| 0 1 0 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 1 0 1 | 1 | 0 | 1 | 1 | 0 | 1 | 1 | 5 |
| 0 1 1 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 1 1 0 | 0 | 0 | 1 | 1 | 1 | 1 | 1 | 6 |
| 0 1 1 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 1 1 1 | 1 | 1 | 1 | 0 | 0 | 0 | 0 | 7 |
| 1 0 0 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 1 0 0 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 8 |
| 1 0 0 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 1 0 0 1 | 1 | 1 | 1 | 0 | 0 | 1 | 1 | 9 |
| 1 0 1 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 1 | 1 0 1 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 0 |
| 1 0 1 1 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 1 | 1 0 1 1 | 0 | 1 | 1 | 0 | 0 | 0 | 0 | 1 |

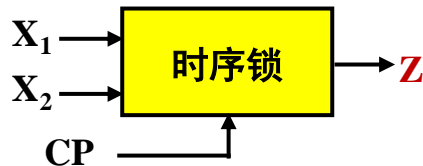


| 十位 | | | | 个位 | | | |
|---|---|---|---|----|---|---|---|
| y ₄ y ₃ y ₂ y ₁ | a | b | c | d | e | f | g |
| 0 0 0 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 0 0 0 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 0 0 1 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 0 0 1 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 0 1 0 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 0 1 0 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 0 1 1 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 0 1 1 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 1 0 0 0 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 1 0 0 1 | 1 | 1 | 1 | 1 | 1 | 1 | 0 |
| 1 0 1 0 | 0 | 1 | 1 | 0 | 0 | 0 | 1 |
| 1 0 1 1 | 0 | 1 | 1 | 0 | 0 | 0 | 1 |

PLA及其应用

例6：利用PLA设计时序锁（假设PLA中是 JK触发器）

- 输入: X_1X_2 , 输出: Z
- 该锁内部有四个状态 R 、 B 、 C 、 E
- 依次输入00、01、11, 时序锁从状态 $R \rightarrow B \rightarrow C$, 并开锁 ($Z=1$)
- 不是上述序列, 进入状态 E (error)
- 任何时候只要输入00, 都将返回状态 R



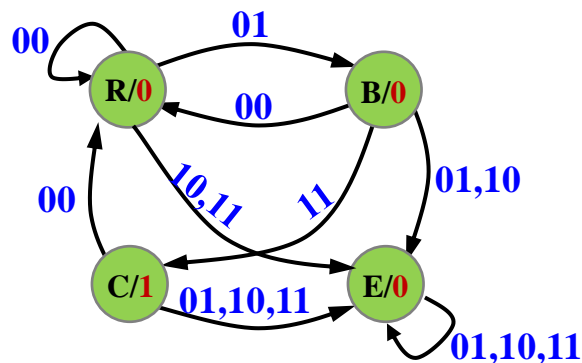
① 状态设定

R —初始状态, 输入00

B —输入00后, 再输入01

C —输入00、01后, 再输入11

E —错误状态



PLA及其应用

2. 状态化简

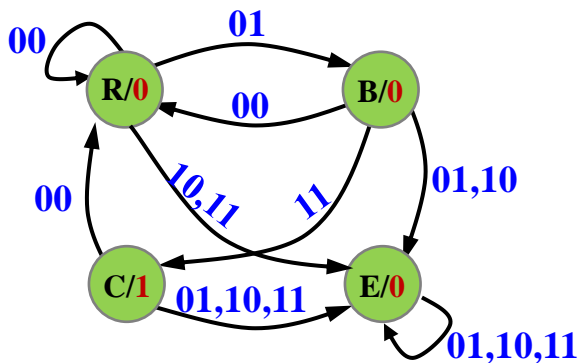
3. 状态分配

需要2个JK触发器

R: 00, B: 01

E: 10, C: 11

| | 0 | 1 |
|---|---|---|
| 0 | R | B |
| 1 | E | C |



| 现态 S_n | 次态 S_{n+1} | | | | 输出 Z |
|-------------|---------------|---------------|---------------|---------------|-----------|
| | $X_1X_2 = 00$ | $X_1X_2 = 01$ | $X_1X_2 = 11$ | $X_1X_2 = 10$ | |
| R | R | B | E | E | 0 |
| B | R | E | C | E | 0 |
| C | R | E | E | E | 1 |
| E | R | E | E | E | 0 |

| 输入 | | 现态 | | 次态 | | 输入 | | | | | 输出 |
|-------|-------|---------|---------|-------------|-------------|-------|-------|-------|-------|-----|----|
| X_1 | X_2 | Y_2^n | Y_1^n | Y_2^{n+1} | Y_1^{n+1} | J_2 | K_2 | J_1 | K_1 | Z | |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | X | 0 | X | 0 | |
| 0 | 0 | 0 | 1 | 0 | 0 | 0 | X | X | 1 | 0 | |
| 0 | 0 | 1 | 0 | 0 | 0 | X | 1 | 0 | X | 0 | |
| 0 | 0 | 1 | 1 | 0 | 0 | X | 1 | X | 1 | 1 | |
| 0 | 1 | 0 | 0 | 0 | 1 | 0 | X | 1 | X | 0 | |
| 0 | 1 | 0 | 1 | 1 | 0 | 1 | X | X | 1 | 0 | |
| 0 | 1 | 1 | 0 | 1 | 0 | X | 0 | 0 | X | 0 | |
| 0 | 1 | 1 | 1 | 1 | 0 | X | 0 | X | 1 | 1 | |
| 1 | 0 | 0 | 0 | 1 | 0 | 1 | X | 0 | X | 0 | |
| 1 | 0 | 0 | 1 | 1 | 0 | 1 | X | X | 1 | 0 | |
| 1 | 0 | 1 | 0 | 1 | 0 | X | 0 | 0 | X | 0 | |
| 1 | 0 | 1 | 1 | 1 | 0 | X | 0 | X | 1 | 1 | |
| 1 | 1 | 0 | 0 | 1 | 0 | 1 | X | 0 | X | 0 | |
| 1 | 1 | 0 | 1 | 1 | 1 | 1 | X | X | 0 | 0 | |
| 1 | 1 | 1 | 0 | 1 | 0 | X | 0 | 0 | X | 0 | |
| 1 | 1 | 1 | 1 | 1 | 0 | X | 0 | X | 1 | 1 | |

| 输入 现态 | | | | 次态 | | 输入 | | | | 输出 |
|-------|-------|---------|---------|-------------|-------------|-------|-------|-------|-------|-----|
| X_1 | X_2 | Y_2^n | Y_1^n | Y_2^{n+1} | Y_1^{n+1} | J_2 | K_2 | J_1 | K_1 | Z |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | X | 0 | X | 0 |
| 0 | 0 | 0 | 1 | 0 | 0 | 0 | X | X | 1 | 0 |
| 0 | 0 | 1 | 0 | 0 | 0 | X | 1 | 0 | X | 0 |
| 0 | 0 | 1 | 1 | 0 | 0 | X | 1 | X | 1 | 1 |
| 0 | 1 | 0 | 0 | 0 | 1 | 0 | X | 1 | X | 0 |
| 0 | 1 | 0 | 1 | 1 | 0 | 1 | X | X | 1 | 0 |
| 0 | 1 | 1 | 0 | 1 | 0 | X | 0 | 0 | X | 0 |
| 0 | 1 | 1 | 1 | 1 | 0 | X | 0 | X | 1 | 1 |
| 1 | 0 | 0 | 0 | 1 | 0 | 1 | X | 0 | X | 0 |
| 1 | 0 | 0 | 1 | 1 | 0 | 1 | X | X | 1 | 0 |
| 1 | 0 | 1 | 0 | 1 | 0 | X | 0 | 0 | X | 0 |
| 1 | 0 | 1 | 1 | 1 | 0 | X | 0 | X | 1 | 1 |
| 1 | 1 | 0 | 0 | 1 | 0 | 1 | X | 0 | X | 0 |
| 1 | 1 | 0 | 1 | 1 | 1 | 1 | X | X | 0 | 0 |
| 1 | 1 | 1 | 0 | 1 | 0 | X | 0 | 0 | X | 0 |
| 1 | 1 | 1 | 1 | 1 | 0 | X | 0 | X | 1 | 1 |

| $Y_2^n Y_1^n$ | | Y_2^{n+1} | | | |
|---------------|----|-------------|----|----|----|
| | | 00 | 01 | 11 | 10 |
| $X_1 X_2$ | 00 | 0 | 0 | 0 | 0 |
| | 01 | 0 | 1 | 1 | 1 |
| | 11 | 1 | 1 | 1 | 1 |
| | 10 | 1 | 1 | 1 | 1 |

$$\begin{cases} J_2 = X_2 Y_1^n + X_1 \\ K_2 = \overline{X_1} + \overline{X_2} = \overline{X_1 X_2} \end{cases}$$

$$Y_2^{n+1} = X_2 Y_1^n + X_1 + X_2 Y_2^n$$

$$= (Y_1^n + \overline{Y_1^n}) (X_2 Y_1^n + X_1) + X_2 Y_1^n$$

$$= (X_2 Y_1^n + X_1) \overline{Y_1^n} + (X_1 + X_2) Y_1^n$$

| $Y_2^n Y_1^n$ | | Y_1^{n+1} | | | |
|---------------|----|-------------|----|----|----|
| | | 00 | 01 | 11 | 10 |
| $X_1 X_2$ | 00 | 0 | 0 | 0 | 0 |
| | 01 | 1 | 0 | 0 | 0 |
| | 11 | 0 | 1 | 0 | 0 |
| | 10 | 0 | 0 | 0 | 0 |

一张卡诺图
确定两个输入
函数

$$Y_1^{n+1} = \overline{X_1} X_2 \overline{Y_2^n} \overline{Y_1^n} + X_1 X_2 \overline{Y_2^n} Y_1^n$$

$$\begin{cases} J_1 = \overline{X_1} X_2 \overline{Y_2^n} \\ K_1 = \overline{X_1} X_2 \overline{Y_2^n} \\ = \overline{X_2} + \overline{X_1} + Y_2^n \end{cases}$$

或者：

| $Y_2^n Y_1^n$ $X_1 X_2$ | | J_2 | | | |
|----------------------------|---|-------|----|----|----|
| | | 00 | 01 | 11 | 10 |
| 00 | 0 | 0 | X | X | |
| 01 | 0 | 1 | X | X | |
| 11 | 1 | 1 | X | X | |
| 10 | 1 | 1 | X | X | |

| $Y_2^n Y_1^n$ $X_1 X_2$ | | K_2 | | | |
|----------------------------|---|-------|----|----|----|
| | | 00 | 01 | 11 | 10 |
| 00 | X | X | 1 | 1 | |
| 01 | X | X | 0 | 0 | |
| 11 | X | X | 0 | 0 | |
| 10 | X | X | 0 | 0 | |

$$\begin{cases} J_2 = X_2 Y_1^n + X_1 \\ K_2 = \overline{X_1} + \overline{X_2} = \overline{X_1} \overline{X_2} \end{cases}$$

| $Y_2^n Y_1^n$ $X_1 X_2$ | | J_1 | | | |
|----------------------------|---|-------|----|----|----|
| | | 00 | 01 | 11 | 10 |
| 00 | 0 | X | X | 0 | |
| 01 | 1 | X | X | 0 | |
| 11 | 0 | X | X | 0 | |
| 10 | 0 | X | X | 0 | |

| $Y_2^n Y_1^n$ $X_1 X_2$ | | K_1 | | | |
|----------------------------|---|-------|----|----|----|
| | | 00 | 01 | 11 | 10 |
| 00 | X | 1 | 1 | X | |
| 01 | X | 1 | 1 | X | |
| 11 | X | 1 | 1 | X | |
| 10 | X | 0 | 1 | X | |

$$\begin{cases} J_1 = \overline{X_1} X_2 \overline{Y_2^n} \\ K_1 = \overline{X_2} + \overline{X_1} + Y_2^n \end{cases}$$

| $Y_2^n Y_1^n$ $X_1 X_2$ | | Y_2^{n+1} | | | |
|----------------------------|----|-------------|----|----|----|
| | | 00 | 01 | 11 | 10 |
| 00 | 00 | 0 | 0 | 1 | 0 |
| 01 | 01 | 0 | 0 | 1 | 0 |
| 11 | 11 | 0 | 0 | 1 | 0 |
| 10 | 10 | 0 | 0 | 1 | 0 |

$$\begin{cases}
 Z = Y_2 Y_1 \\
 J_2 = X_2 Y_1^n + X_1 \\
 K_2 = \overline{X_1} + \overline{X_2} = \overline{X_1} \overline{X_2} \\
 J_1 = \overline{X_1} X_2 \overline{Y_2}^n \\
 K_1 = \overline{X_2} + \overline{X_1} + Y_2^n
 \end{cases}$$

