

数字世界精彩无限

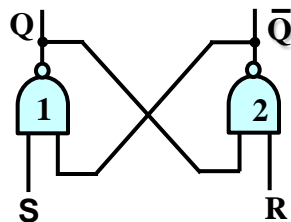
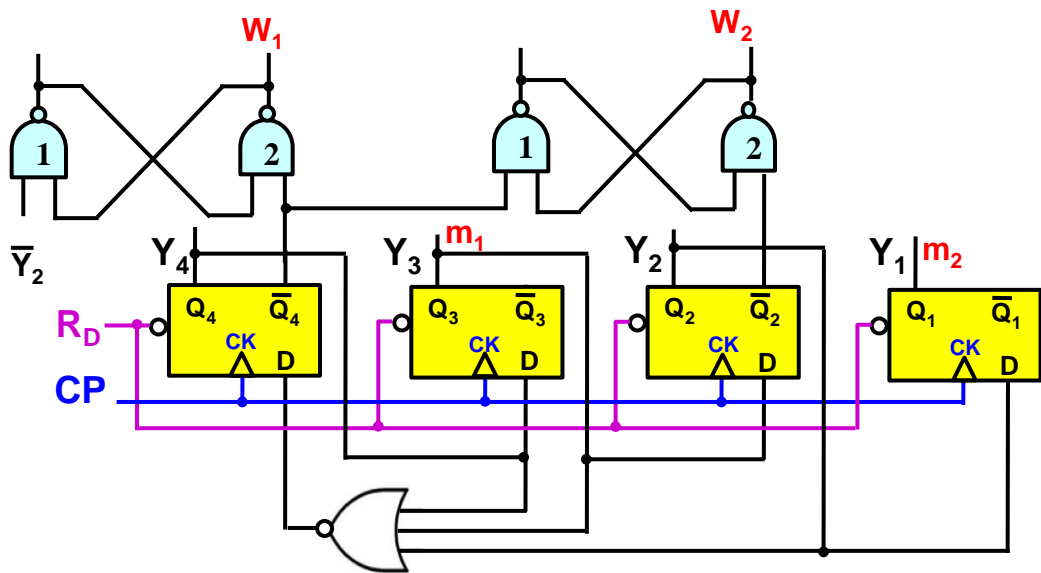
Unit 9

—Registers and Counters

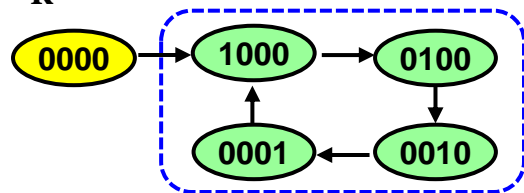
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几种典型的时序逻辑部件——节拍发生器2



④ 状态图



③ 状态转换表

现态				次态				时钟
Y_4^n	Y_3^n	Y_2^n	Y_1^n	Y_4^{n+1}	Y_3^{n+1}	Y_2^{n+1}	Y_1^{n+1}	CP
0	0	0	0	1	0	0	0	↑
1	0	0	0	0	1	0	0	↑
0	1	0	0	0	0	1	0	↑
0	0	1	0	0	0	0	1	↑
0	0	0	1	1	0	0	0	↑

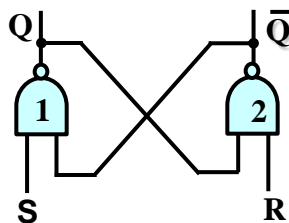
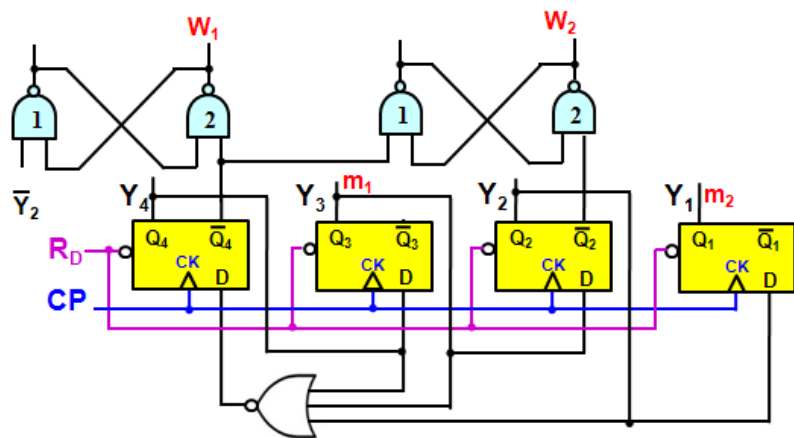
① 输入方程

$$\begin{cases} D_1 = Y_2 \\ D_2 = Y_3 \\ D_3 = Y_4 \\ D_4 = \overline{Y_4 + Y_3 + Y_2} \end{cases}$$

② 次态方程

$$\begin{cases} Y_1^{n+1} = Y_2 \\ Y_2^{n+1} = Y_3 \\ Y_3^{n+1} = Y_4 \\ Y_4^{n+1} = \overline{Y_4 + Y_3 + Y_2} \end{cases}$$

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结论：2-节拍发生器

- $W_1_m_1$: 节拍电位_节拍脉冲
- $W_2_m_2$: 节拍电位_节拍脉冲

⑤ 确定输出

R	S	Q_{n+1}	\bar{Q}_{n+1}
\bar{Y}_4	\bar{Y}_2	$(W_1=\bar{Q})$	
1	1	Q_n	\bar{Q}_n
0	1	0	1
1	0	1	0
0	0	—	—

R	S	Q_{n+1}	\bar{Q}_{n+1}
\bar{Y}_2	\bar{Y}_4	$(W_2=\bar{Q})$	
1	1	Q_n	\bar{Q}_n
0	1	0	1
1	0	1	0
0	0	—	—

