

Unit 12

—Asynchronous sequential circuit design

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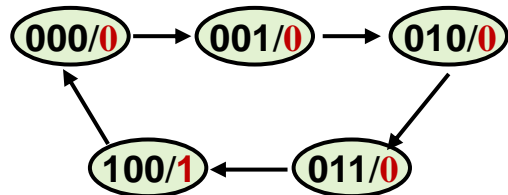
利用触发器设计异步计数器

例1：试用JK触发器设计异步模5加法计数器

① 确定触发器个数：需要3个JK触发器，↓ 触发

② 画状态转换图

③ 确定触发器CP的接法



CP	Q_3	Q_2	Q_1
↓	0	0	0
↓	0	0	1
↓	0	1	0
↓	0	1	1
↓	1	0	0
↓	0	0	0

Q_1 ——由CP提供下降沿， $CP_1 = CP$

Q_2 ——翻转两次，需两个下降沿，恰好此时 Q_1 有两个下降沿， $CP_2 = Q_1 \downarrow$

Q_3 ——翻转两次，需两个下降沿，此时 Q_2 、 Q_1 都不能提供， CP_3 只能接CP

设计原则

- 时序图中，凡是触发器状态翻转的地方，都必须为其提供时钟脉冲。
- 在满足翻转的前提下，时钟脉冲越少越好

对触发器而言：只要提供时钟，状态的保持就必须依靠输入端（如J、K）的控制来实现。

利用触发器设计异步计数器

④ 状态转换真值表

$CP_1 = CP_3 = CP \downarrow, CP_2 = Q_1 \downarrow$

确定 J_3K_3 : 看 $Q_3^n \rightarrow Q_3^{n+1}$
确定 J_1K_1 : 看 $Q_1^n \rightarrow Q_1^{n+1}$

现态			次态			输入						输出
Q_3^n	Q_2^n	Q_1^n	Q_3^{n+1}	Q_2^{n+1}	Q_1^{n+1}	J_3	K_3	J_2	K_2	J_1	K_1	Z
0	0	0	0	0	1	0	X	X	X	1	X	0
0	0	1	0	1	0	0	X	1	X	X	1	0
0	1	0	0	1	1	0	X	X	X	1	X	0
0	1	1	1	0	0	1	X	X	1	X	1	0
1	0	0	0	0	0	X	1	X	X	0	X	1

此时 Q_1 无下降沿, $J_2 K_2$ 为任意

确定 J_2K_2 :
看 $Q_1^n \rightarrow Q_1^{n+1}$

⑤ 卡诺图化简

Q_3^n	$Q_2^n Q_1^n$			
	00	01	11	10
0	0	0	1	0
1	X	X	X	X

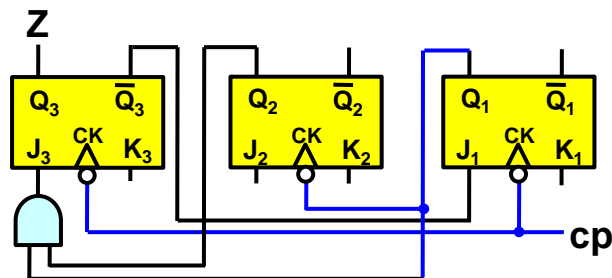
$$J_3 = Q_2^n Q_1^n$$

Q_3^n	$Q_2^n Q_1^n$			
	00	01	11	10
0	1	X	X	1
1	0	X	X	X

$$J_1 = \bar{Q}_3^n$$

$$\begin{cases} J_3 = Q_2^n Q_1^n, K_3 = 1 \\ J_2 = 1, K_2 = 1 \\ J_1 = \bar{Q}_3^n, K_1 = 1 \\ Z = Q_3^n, CP_2 = Q_1 \downarrow, CP_3 = CP_1 = CP \end{cases}$$

⑥ 逻辑图

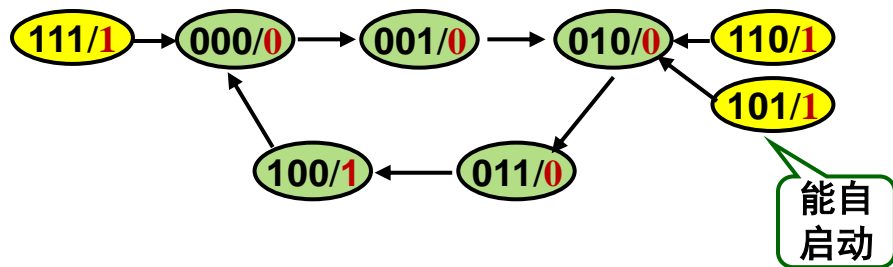


利用触发器设计异步计数器

⑦检查无关项

现态	次态			输入			输出
$Q_3^n Q_2^n Q_1^n$	Q_3^{n+1}	Q_2^{n+1}	Q_1^{n+1}	CP_3	CP_2	CP_1	Z
1 0 1	0	1	0	↓	↓	↓	1
1 1 0	0	1	0	↓	0	↓	1
1 1 1	0	0	0	↓	↓	↓	1

$$\left\{ \begin{array}{l} J_3 = Q_2^n Q_1^n, K_3 = 1 \\ J_2 = 1, K_2 = 1 \\ J_1 = \bar{Q}_3^n, K_1 = 1 \\ Z = Q_3^n, CP_2 = Q_1 \downarrow, CP_3 = CP_1 = CP \end{array} \right.$$



利用触发器设计异步计数器

例2：用D触发器设计实现十进制异步加法计数器

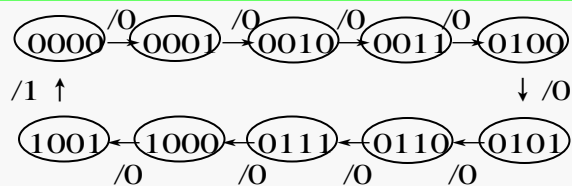
① 确定触发器个数：需要4个D触发器，↑ 触发

② 画状态转换图

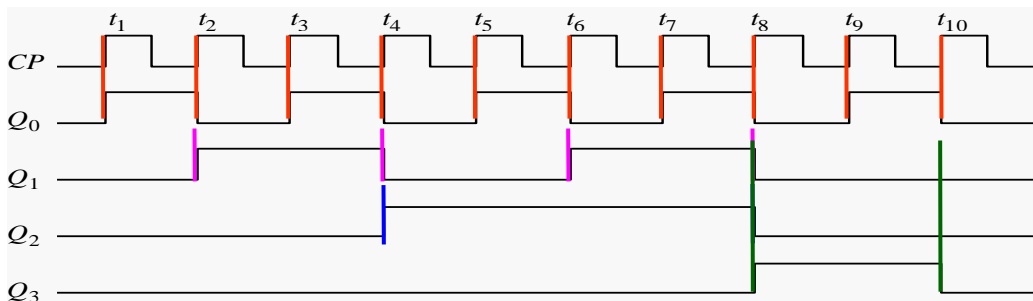
输出方程： $C = Q_3^n Q_0^n$

排列顺序：

$Q_3^n Q_2^n Q_1^n Q_0^n \xrightarrow{\text{LC}}$



③ 确定触发器CP的接法



$$\begin{cases} CP_0 = CP \\ CP_1 = \overline{Q_0} \\ CP_2 = \overline{Q_1} \\ CP_3 = \overline{Q_2} \end{cases}$$

选择时钟脉冲的基本原则：在满足翻转要求的条件下，触发沿越少越好。

利用触发器设计异步计数器

④ 状态转换真值表

$$\begin{cases} CP_0 = CP \\ CP_1 = \overline{Q_0} \\ CP_2 = \overline{Q_1} \\ CP_3 = \overline{Q_0} \end{cases}$$

现态				次态				输入							
Q_3^n	Q_2^n	Q_1^n	Q_0^n	Q_3^{n+1}	Q_2^{n+1}	Q_1^{n+1}	Q_0^{n+1}	CP_3	CP_2	CP_1	CP_0	D_3	D_2	D_1	D_0
0	0	0	0	0	0	0	1	0	0	0	↑	X	X	X	1
0	0	0	1	0	0	1	0	↑	0	↑	↑	0	X	1	0
0	0	1	0	0	0	1	1	0	0	0	↑	X	X	X	1
0	0	1	1	0	1	0	0	↑	↑	↑	↑	0	1	0	0
0	1	0	0	0	1	0	1	0	0	0	↑	X	X	X	1
0	1	0	1	0	1	1	0	↑	0	↑	↑	0	X	1	0
0	1	1	0	0	1	1	1	0	0	0	↑	X	X	X	1
0	1	1	1	1	0	0	0	↑	↑	↑	↑	1	0	0	0
1	0	0	0	1	0	0	1	0	0	0	↑	X	X	X	1
1	0	0	1	0	0	0	0	↑	0	↑	↑	0	X	0	0

⑤ 卡诺图化简

$Q_3^n Q_2^n \backslash Q_1^n Q_0^n$	00	01	11	10
00	X	0	0	X
01	X	0	1	X
11	X	X	X	X
10	X	0	X	X

$$D_3 = Q_2^n Q_1^n$$

$Q_3^n Q_2^n \backslash Q_1^n Q_0^n$	00	01	11	10
00	X	X	1	X
01	X	X	0	X
11	X	X	X	X
10	X	X	X	X

$$D_2 = \overline{Q_2}^n$$

$Q_3^n Q_2^n \backslash Q_1^n Q_0^n$	00	01	11	10
00	X	1	0	X
01	X	1	0	X
11	X	X	X	X
10	X	0	X	X

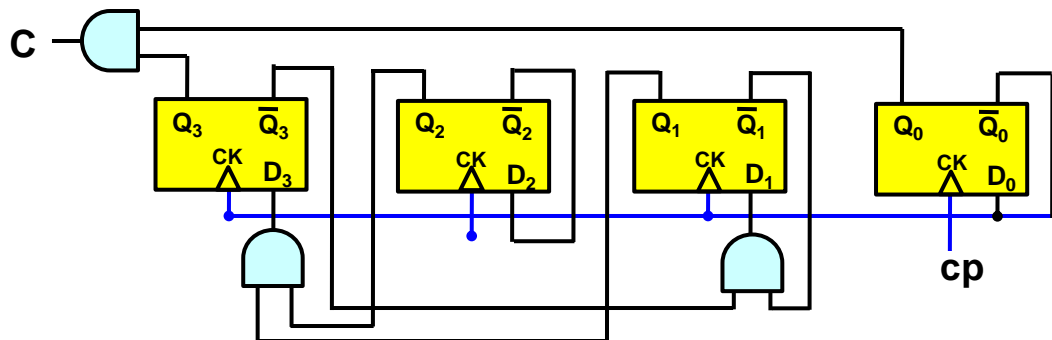
$$D_1 = \overline{Q_3}^n \overline{Q_1}^n$$

$Q_3^n Q_2^n \backslash Q_1^n Q_0^n$	00	01	11	10
00	1	0	0	1
01	1	0	0	1
11	X	X	X	X
10	1	0	X	X

$$D_0 = \overline{Q_0}^n$$

利用触发器设计异步计数器

⑥ 逻辑图



$$\begin{cases} CP_0 = CP \\ CP_1 = \overline{Q_0} \\ CP_2 = \overline{Q_1} \\ CP_3 = \overline{Q_0} \end{cases} \quad \begin{cases} D_3 = Q_2^n Q_1^n \\ D_2 = \overline{Q_2}^n \\ D_1 = \overline{Q_3}^n \overline{Q_1}^n \\ D_0 = \overline{Q_0}^n \\ C = Q_3^n Q_0^n \end{cases}$$

⑦ 检查无关项

将无效状态1010~1111分别代入状态方程,可以验证该电路能够自启动。

现态				次态				输入			
Q_3^n	Q_2^n	Q_1^n	Q_0^n	Q_3^{n+1}	Q_2^{n+1}	Q_1^{n+1}	Q_0^{n+1}	CP_3	CP_2	CP_1	CP_0
1	0	1	0	0	0	0	1	0	0	0	↑
1	0	1	1	0	1	0	0	↑	↑	↑	↑
1	1	0	0	1	1	0	1	0	0	0	↑
1	1	0	1	0	1	0	0	↑	0	↑	↑
1	1	1	0	1	1	1	1	0	0	0	↑
1	1	1	1	0	0	0	0	↑	↑	↑	↑