# Riemann surfaces

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### Introduction

These are my lecture notes on the course Riemann surfaces in the year 2024/25. The lecturer that year was viš. znan. sod. dr. Rafael Benedikt Andrist.

The notes are not perfect. I did not write down most of the examples that help with understanding the course material. I also did not formally prove every theorem and may have labeled some as trivial or only wrote down the main ideas.

I have most likely made some mistakes when writing these notes – feel free to correct them.

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#### 1 Riemann surfaces

#### 1.1 Definition and holomorphic maps

**Definition 1.1.1.** A *surface* is a manifold of complex dimension 1.

**Definition 1.1.2.** A *Riemann surface* is a connected complex surface.

**Definition 1.1.3.** The *Riemann sphere* is defined as  $\widehat{\mathbb{C}} = \mathbb{C}P^1$  with the usual complex structure.<sup>1</sup>

**Definition 1.1.4.** A complex torus is given by a quotient

$$T = \mathbb{C}/a\mathbb{Z} \oplus b\mathbb{Z} ,$$

where  $a, b \in \mathbb{C}$  are  $\mathbb{R}$ -linearly independent. The parallelogram bounded by 0, a, b and a + b is called the *fundamental domain* of T.

**Theorem 1.1.5** (Identity). Let X and Y be Riemann surfaces and  $f, g: X \to Y$  be holomorphic maps. If the set  $A = \{x \in X \mid f(x) = g(x)\}$  has an accumulation point, then f = g on X.

*Proof.* We prove that the set of accumulation points is open. Take an accumulation point  $a \in X$ . Note that, by continuity, f(a) = g(a). Consider charts  $\varphi \colon U \to V$  on X and  $\psi \colon W \to Z$  on Y such that  $a \in U$ ,  $f(a) \in W$  and  $f(U) \subseteq W$ . Applying the identity theorem for holomorphic functions on the function  $\psi \circ f \circ \varphi^{-1}$ , we find that f and g agree on U, which is a neighbourhood of a. All such points are accumulation points of A.

Note that this means that the set of accumulation points of A is both open and closed. As X is connected and this set is non-empty, A = X. By continuity, f = g on A = X.  $\square$ 

**Theorem 1.1.6** (Riemann's removable singularity theorem). Let X be a Riemann surface,  $U \subseteq X$  an open set and  $a \in U$ . Suppose that  $f \colon U \setminus \{a\} \to \mathbb{C}$  is a holomorphic function that is bounded on  $U \setminus \{a\}$ . Then f can be extended uniquely to a holomorphic function  $\tilde{f} \colon U \to \mathbb{C}$  with  $\tilde{f}\big|_{U \setminus \{a\}} = f$ .

*Proof.* First note that we can shrink U down to obtain a chart  $\varphi \colon U \to \mathbb{C}$ , then apply Riemann's removable singularity theorem to the function  $f \circ \varphi^{-1}$  in the point  $\varphi(a)$  and define  $\tilde{f}(a) = (f \circ \varphi^{-1})(\varphi(a))$ . As it's a composition of holomorphic functions, is is itself holomorphic. By continuity, the extension is unique.

**Definition 1.1.7.** Let X be a Riemann surface. A meromorphic function f on X is a function  $f: X \setminus A \to \mathbb{C}$  such that  $f|_{X \setminus A}$  is holomorphic, A is a closed set of isolated points, and

$$\lim_{\substack{z \to a \\ z \in X \backslash A}} |f(z)| = \infty$$

for all  $a \in A$ . We denote the set of meromorphic functions on X by  $\mathcal{M}(X)$ .

Remark 1.1.7.1. The set  $\mathcal{M}(X)$  is a field.

<sup>&</sup>lt;sup>1</sup> Also denoted by P<sup>1</sup>.

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**Theorem 1.1.8.** Let X be a Riemann surface and  $f \in \mathcal{M}(X)$ . For each pole p of f we set  $f(p) = \infty \in \widehat{\mathbb{C}}$ . Then f is a holomorphic map from X to  $\widehat{\mathbb{C}}$ . Conversely, every holomorphic map  $f \colon X \to \widehat{\mathbb{C}}$  that is not identically  $\infty$  defines a meromorphic function on X.

*Proof.* Note that f is clearly continuous. It therefore suffices to show that f is holomorphic at every pole. Recall that a chart around  $\infty$  is given by  $\varphi \colon z \mapsto \frac{1}{z}$ . Let U be a neighbourhood of p that contains no other pole, and define  $g \colon U \setminus \{p\} \to \mathbb{C}$  by  $g(z) = (f \circ \varphi^{-1}(z))^{-1}$ . Using Riemann's removable singularity theorem, this map has a unique holomorphic extension with g(p) = 0 by continuity. But that means that the proposed extension of f is indeed holomorphic at p.

Suppose  $f: X \to \widehat{\mathbb{C}}$  is holomorphic. Define  $A = \{z \in X \mid f(z) = \infty\}$ . Then  $f|_{X \setminus A}$  is clearly a meromorphic function.

**Theorem 1.1.9.** Let X and Y be Riemann surfaces and  $f: X \to Y$  a holomorphic map. For any point  $p \in X$  there exist charts  $\varphi: U \to V$  and  $\psi: Z \to W$  such that  $p \in U$ ,  $f(p) \in Z$ ,  $\varphi(p) = 0 = \psi(f(p))$ ,  $f(U) \subseteq Z$  and

$$\psi \circ f \circ \varphi^{-1}(z) = z^k$$

for some integer  $k \in \mathbb{N}_0$ . This integer is determined uniquely.

Proof. Let  $\tilde{\varphi} \colon U \to V$  be a chart on X with  $p \in U$  such that  $\tilde{\varphi}(p) = 0$ . Furthermore, let  $\psi \colon Z \to W$  be a chart on Y with  $f(U) \subseteq Z$  and  $\psi(f(p)) = 0$ . Define  $g = \psi \circ f \circ \tilde{\varphi}^{-1}$ . Then  $g(z) = z^k \cdot h(z)$ , where  $k \ge 1$ ,  $h(0) \ne 0$  and h is a holomorphic function. Locally, h has a k-th root, hence

$$g(z) = \left(z \cdot \sqrt[k]{h(z)}\right)^k = w(z)^k.$$

Taking  $\varphi = w \circ \tilde{\varphi}$ , we get the sought charts on small enough domains. As k is equal to the number of preimages of points distinct from p, it is unique.

**Definition 1.1.10.** Such integer k is called the *multiplicity* of f in p.

Corollary 1.1.10.1. Every non-constant holomorphic map  $f: X \to Y$  is open.

*Proof.* In the charts from the above theorem, disks around  $\varphi p$  map to disks.

Corollary 1.1.10.2. Let X and Y be Riemann surfaces and  $f: X \to Y$  a bijective holomorphic map. Then  $f^{-1}: Y \to X$  is holomorphic.

*Proof.* As f is not constant, it is open, hence  $f^{-1}$  is continuous. In local coordinates, f is of the form  $z \mapsto z^k$ . As f is bijective, k = 1, hence the inverse is locally  $z \mapsto z$ , which is holomorphic.

Corollary 1.1.10.3 (Maximum principle). Let X be a Riemann surface and  $f: X \to \mathbb{C}$  a non-constant holomorphic function. Then |f| does not attain its maximum.

*Proof.* The map f is open.

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**Theorem 1.1.11.** Let X and Y be Riemann surfaces and  $f: X \to Y$  a non-constant holomorphic map. If X is compact, then Y is compact and f is surjective.

*Proof.* Note that f(X) is an open and closed subset of Y, which is connected.

**Corollary 1.1.11.1.** If  $f: X \to \mathbb{C}$  is a holomorphic function for a compact Riemann surface X, then f is constant.

*Proof.* The proof is obvious and need not be mentioned.

**Theorem 1.1.12** (Liouville). Every bounded holomorphic function on complex numbers is constant.

*Proof.* We can extend f to a function  $\widehat{\mathbb{C}} \to \mathbb{C}$  by Riemann's removable singularity theorem. Applying the above theorem, we get that f is constant as  $\mathbb{C}$  is not compact.

**Theorem 1.1.13** (Fundamental theorem of algebra). Every non-constant polynomial with complex coefficients has a complex root.

*Proof.* The polynomial can be extended to a holomorphic map  $p: \widehat{\mathbb{C}} \to \widehat{\mathbb{C}}$ , which is surjective by theorem 1.1.11. As  $p(\infty) = \infty$ , the set  $p^{-1}(0)$  contains a complex number.

**Theorem 1.1.14.** Every holomorphic function  $f: \widehat{\mathbb{C}} \to \widehat{\mathbb{C}}$  is either a rational function or  $f \equiv \infty$ .

*Proof.* If  $f \not\equiv \infty$ , the set  $A = \{z \in \mathbb{C} \mid f(z) = \infty\}$  is finite – otherwise, it'd have an accumulation point. Let  $A = \{a_i \mid i \leq n\}$ . If needed, replace f by  $\frac{1}{f}$  so that  $\infty \not\in A$ , and repeat the argument. Now consider the function

$$g = f - \sum_{i=1}^{n} \sum_{k=1}^{N_i} d_{i,k} \cdot \frac{1}{(z - a_i)^k},$$

where  $d_{i,k}$  are obtained from principal parts of Laurent series around  $a_i$ . As  $g: \widehat{\mathbb{C}} \to \mathbb{C}$  is a holomorphic function, it is constant, hence f is a rational function.

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#### 1.2 Homotopy and the fundamental group

**Definition 1.2.1.** Denote the *homotopic* relation by  $\sim$ .

**Proposition 1.2.2.** Not all paths in  $\mathbb{C}^*$  are homotopic.

*Proof.* Consider  $\gamma(t) = e^{2\pi it}$  and  $\delta(t) = e^{-2\pi it}$ . Recall that

$$\frac{1}{2\pi i} \cdot \int\limits_{\gamma(t)} \frac{1}{z} \, dz = 1$$

and

$$\frac{1}{2\pi i} \cdot \int_{\delta(t)} \frac{1}{z} \, dz = -1.$$

As integrals are a homotopy invariant,  $\gamma$  and  $\delta$  are not homotopic.

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