

Optimisation

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Richting Wiskunde

Jaar 3BWIS

Algemeen

Dit vak bestaat uit hoorcolleges door prof. Ahookhosh waar de theorie aan bod komt en practicumssessies gegeven door de assistent Jeffrey Cornelis. In de practicumssessies implementeer je de algoritmes die in de theorie aan bod komen in Matlab om meer inzicht te verwerven. Deze oefeningensessies zijn op zich niet belangrijk voor het examen, maar het kan zijn dat er een taak komt waarbij je deze oefening kan gebruiken. (Masoud had dit beloofd, maar er is uiteindelijk toch geen taak gekomen.)

Probeer bij het studeren te zorgen dat je goed overweg kan met de basisbegrippen uit de cursus zoals: sublevelset, minimizers, sufficient descent conditions, en convergentie van algoritmes. Het examen zelf valt beter mee dan de cursus doet uitschijnen.

Examenvragen

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1. Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ be a continuous on a compact sublevelset $S(f, r)$ ($r \in \mathbb{R}$).
 - (a) Show that: f has a global minimizer and maximizer over $S(f, r)$.
 - (b) Show that: f has a global minimizer over \mathbb{R}^n
 - (c) Let g be a continuous coercive function over \mathbb{R}^n . Show that g has at least one global minimizer.
2. Prove the Second-order sufficient optimality conditions: Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ a twice continuous differentiable function over an open neighbourhood $B(x^*, r)$ for a point x^* and $r > 0$ and let $\nabla f(x^*) = 0$ and $\nabla^2 f(x^*)$ be positive definite. Then, x^* is a strict local minimizer of f .

3. Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ be continuously differentiable with Lipschitz continuous gradients ($f \in C^1, Lf \in CL^1, 1$).
- (a) Show that if d_k satisfies the sufficient descent condition $\langle \nabla f(x_k), d_k \rangle \leq -c_1 \|\nabla f(x_k)\|^2$, $\|d_k\| \leq c_2 \|\nabla f(x_k)\|$, it follows that: $f(x_k + \alpha d_k) \leq f(x_k) - \alpha(c_1 - c_2^2 L^2) \|\nabla f(x_k)\|^2$.
- (b) Show that if $\alpha \in (0, 2c_1 / Lc_2^2)$ that $f(x_{k+1}) \leq f(x_k)$.
- (c) Show that the maximum decrease is attained by $\alpha^* = c_1 / Lc_2^2$.
4. Let $f: \mathbb{R}^n \rightarrow \mathbb{R}$ be a twice continuously differentiable function, x_0 a point close enough to the minimizer x^* satisfying $\nabla f(x^*) = 0$. If the Hessian $\nabla^2 f(x^*)$ is positive definite and $\nabla^2 f(x)$ satisfies the Lipschitz condition $\|\nabla^2 f(x) - \nabla^2 f(y)\| \leq L\|x - y\|$.
- (a) Show that the Newton iteration $x_{k+1} = x_k - (\nabla^2 f(x_k))^{-1} \nabla f(x_k)$ is well-defined.
- (b) Show that the series $\{x_k\}_{k \geq 0}$ converges to x^* quadratically, i.e. $\|x_{k+1} - x^*\| \leq R \|x_k - x^*\|^2$ for some $R > 0$.
5. Let $f(x) = 100(x_2 - x_1^2)^2 + (1 - x_1)^2$ and $g(x) = x_1^4 - 4x_1x_2 + x_2^4$.
- (a) Compute the gradients and Hessians of f and g .
- (b) Find the critical points of f and g .
- (c) Identify the minimizers, maximizers and saddle points of f and g .
- (d) Determine whether they are global or local. (provide reasoning)
6. Consider the quadratic minimization function $f: \mathbb{R}^n \rightarrow \mathbb{R}$ given by $f(x) = \langle p, x \rangle + \frac{1}{2} \langle x, Qx \rangle$ for the vector $p \in \mathbb{R}^n$ and the positive definite matrix $Q \in \mathbb{R}^{n \times n}$.
- (a) Derive the formula for exact line search step-size α_k in the Conjugate Gradient Algorithm.
- (b) Let $d_0 = -\nabla f(x_0)$, $x_{k+1} = x_k + \alpha_k d_k$, $d_k = -\nabla f(x_k) + \beta_k d_{k-1}$. Derive β_0 such that d_0 and d_1 are conjugate.
- (c) Let $x_0 = [0, 0]^T$, $p = [1, 0]^T$, $G = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}$ Compute the first two iterations x_1, x_2 .

Categorieën:

- Wiskunde
- 3BWIS