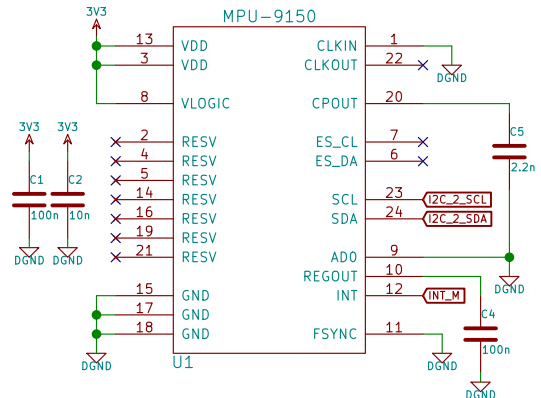
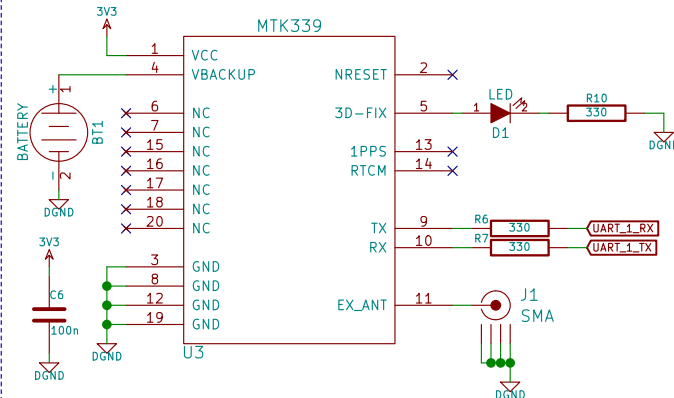


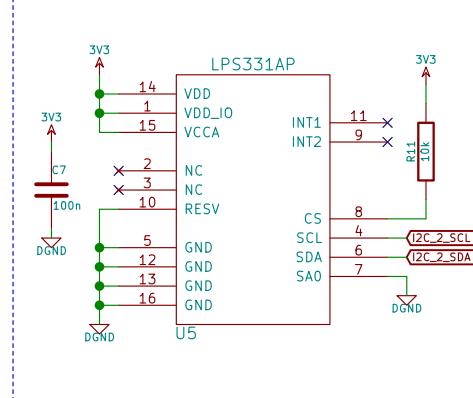
9-DOF IMU



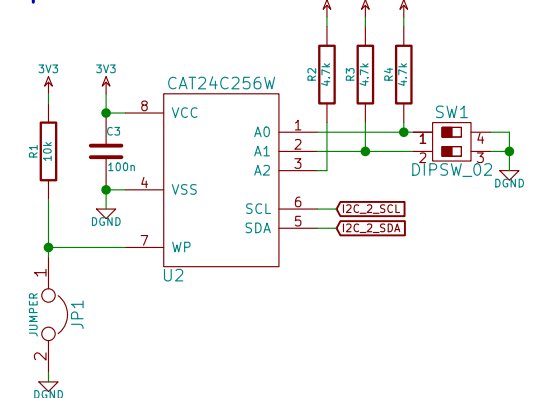
GPS



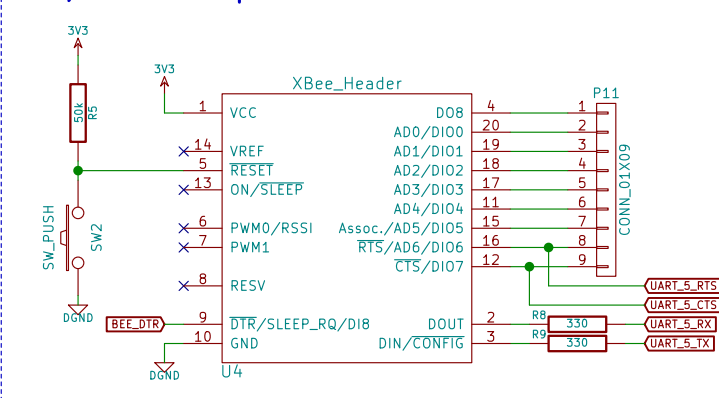
Pressure sensor



Cape address EEPROM



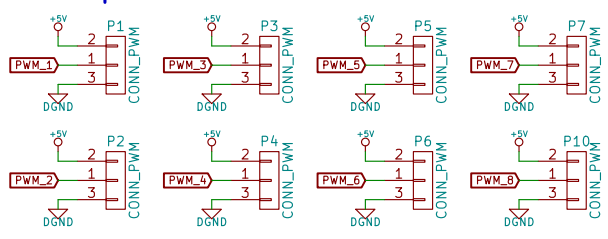
XBee/GPRS Bee Expansion Header



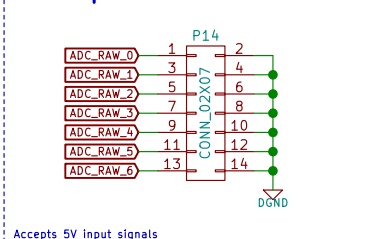
BeagleBone Connections



PWM Outputs



ADC Inputs



Designed by: Salah-Eddine Missri
Supervisor: Andrea Alessandretti

Swiss Institute of Technology, Lausanne (EPFL)

Sheet: /
File: robots-arena.sch

Title: Robots Arena BBB Cape

Size: A4 Date: 27 Nov 2014
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