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THE BOLTZMANN EQUATION WITH A SOFT POTENTIAL. PART II. NONLINEAR--ETC(U)

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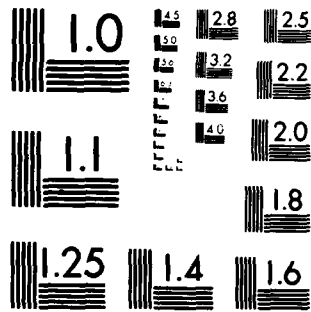
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POTENTIAL. PART II. NONLINEAR,
SPATIALLY-PERIODIC.

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REVIEW

14 MRC-TSR-2031

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MAY 6 1980

11 Jan 80

12 28

(Received June 11, 1979)

15 DAAG29-75-C-0024,
NSF-MCS78-09525

Approved for public release
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Sponsored by

U. S. Army Research Office
P. O. Box 12211
Research Triangle Park
North Carolina 27709

and

National Science Foundation
Washington, D. C. 20550

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THE BOLTZMANN EQUATION WITH A SOFT POTENTIAL.
PART II: NONLINEAR, SPATIALLY-PERIODIC

Russel Caflisch

Technical Summary Report #2031
January 1980

ABSTRACT

The results of Part I are extended to include linear spatially periodic problems - solutions of the initial value are shown to exist and decay like $e^{-\lambda t^{\frac{1}{2}}}$. Then the full non-linear Boltzmann equation with a soft potential is solved for initial data close to equilibrium. The non-linearity is treated as a perturbation of the linear problem, and the equation is solved by iteration.

AMS(MOS) Subject Classification: 82.35

Key Words: Boltzmann Equation, soft potentials, initial value problems

Work Unit Number 1 - Applied Analysis

Sponsored by the United States Army under Contract No. DAAG29-75-C-0024.
This material is based upon work supported by the National Science Foundation
under Grant Nos. MCS78-09525 and MCS76-07039.

SIGNIFICANCE AND EXPLANATION

In Part I the linear Boltzmann equation was solved. In this second part the full non-linear Boltzmann equation with a soft potential is solved, provided that the initial configuration of particles is close to equilibrium, so that the problem is nearly linear.

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THE BOLTZMANN EQUATION WITH A SOFT POTENTIAL.
PART II: NONLINEAR, SPATIALLY-PERIODIC

Russel Caflisch

I Introduction

The linear Boltzmann equation with a soft intermolecular potential was solved globally in time in Part I [1], if the initial density is a spatially homogeneous perturbation of a global Maxwellian. Moreover it was proven that this perturbation decays in L^2 or sup norm like $e^{-\lambda t^\beta}$, with $\lambda > 0$, $1 > \beta > 0$, if it is initially bounded by a Maxwellian. We will refer to formulas or results from Part I by preceeding their numbers with an "I" as in (II.7).

In this paper we find the same result even if the initial perturbation is spatially dependent in the cube with periodic boundary conditions. In addition we can solve the spatially periodic nonlinear problem globally in time if the initial perturbation is small enough, and we find that the solution decays to the Maxwellian equilibrium.

The linear, spatially-dependent Boltzmann equation is

$$(1.1) \quad \frac{\partial}{\partial t} f + \underline{x} \cdot \frac{\partial}{\partial \underline{x}} f + Lf = 0, \quad$$

$$(1.2) \quad f(t=0) = f_0 \in N, \quad$$

where f_0 and $f = f(t, \underline{x}, \underline{\xi})$ are periodic in $\underline{x} \in T^3 = [0, 2\pi]^3$, $t \geq 0$, $\underline{\xi} \in R^3$, and $N = \{g(\underline{x}, \underline{\xi}) : \int_{T^3} \int_{R^3} \psi(\underline{\xi}) g(\underline{x}, \underline{\xi}) d\underline{\xi} d\underline{x} = 0 \text{ for } \psi(\underline{\xi}) = 1, \underline{\xi}_1, \text{ or } \underline{\xi}^2\}$. The requirement that $f_0 \in N$ just means that we have chosen the right Maxwellian equilibrium to perturb about, so that it has the total mass, momentum, and energy. Our first result, Theorem 2.1, is that the solution of this problem decays like $e^{-\lambda t^\beta}$.

As in Part I we remove the null space of $L = \nu + K$ by adding on a finite rank operator. $N(L)$ is spanned by the functions $\psi_i(\underline{\xi})$ defined in

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(12.14). We define the modified linear operator

$$(1.3) \quad \bar{L} = v + \bar{K} ,$$

$$(1.4) \quad \bar{K} = K + P$$

$$(1.5) \quad P = \sum_{i=0}^4 (\psi_i, \cdot) \psi_i ,$$

where now the inner product is the $L^2(\underline{x}, \underline{\xi})$ inner product. Since ψ_i are independent of \underline{x} and $Pf_0 = 0$, the linear problem (1.1), (1.2) is not changed if we replace L by \bar{L} . Since the nonlinearity $v\Gamma$ of the Boltzmann equation is also perpendicular to ψ_i , this replacement of L by \bar{L} does not affect the nonlinear problem either.

The relevant norms, which are defined in Section 2, are L^2 norms of f and its spatial derivatives, then L^2 or sup over $\underline{\xi}$. The derivatives are introduced in order to be able to use the Sobolev inequality when estimating the nonlinear terms. For consistency they are also included in the linear theory of Sections 2 and 3 where they are not really needed. The estimates on K given in Part I all have analogues which are presented in Section 2.

Just as in Part I the velocities are cut off by defining the characteristic function

$$(1.6) \quad \chi_w(\xi) = \begin{cases} 1 & \xi \leq w , \\ 0 & \xi > w , \end{cases}$$

and introducing

$$(1.7) \quad B_w = \underline{\xi} \cdot \frac{\partial}{\partial \underline{x}} + v(\xi) + \chi_w \bar{K} ,$$

as an operator on $L^2(\xi \leq w, \underline{x} \in T^3)$. The only new twist in the spatially dependent problem comes in the analysis of the semigroup e^{-tB_w} , given in Section 3. This employs spectral perturbation theory [4] and an argument given by Ukai [5]. The rest of the proof of Theorem 2.1 goes exactly as in Part I.

The nonlinear Boltzmann equation is

$$(1.8) \quad \frac{\partial}{\partial t} f + \underline{x} \cdot \frac{\partial}{\partial \underline{x}} f + Lf = \nu \Gamma(f, f) \quad .$$

$$(1.9) \quad f(t = 0) = f_0 \in N \quad .$$

where f and f_0 are periodic in \underline{x} . If f_0 is sufficiently small, this problem can be solved for all time and the solution $f(t)$ decays to 0, as stated in Theorem 4.1 in Section 4. The estimates on Γ in Section 5 state that if f is small, $\nu \Gamma(f, f)$ is even smaller. So this problem is just a perturbation of the linear problem, which also keeps its solution small. The solution is found by an iterative procedure described in Section 7, after the iteration equation is analyzed in Section 6.

References to previous work and more explanation of the Boltzmann equation are found in Part I. I am very grateful to Harold Grad, who suggested this problem, and to Percy Deift, George Papanicolaou and Robert Turner for a number of helpful discussions. This work was performed at the Courant Institute and the Mathematics Research Center; I am happy to acknowledge their support.

II The Linear Equation

We will use an L^2 Sobolev norm over space alone, as well as a norm over both \underline{x} and $\underline{\xi}$, which are sup or L^2 norm over $\underline{\xi}$ of the Sobolev norm over space. If the function is not spatially dependent these $(\underline{x}, \underline{\xi})$ norms are exactly those used in Part I and we will use the same notation.

Definition. Let $f = f(\underline{x}, \underline{\xi})$ be periodic in \underline{x} . Define

$$(2.1) \quad \|f(\underline{\xi}, \cdot)\|_{H_4(\underline{x})} = \left(\sum_{s=1}^4 \left(\int_{T^3} |\nabla^s f(\underline{x}, \underline{\xi})|^2 d\underline{x} \right)^{1/2} \right)^{1/2}.$$

$$(2.2) \quad \|f\| = \left(\int_{R^3} \|f(\underline{\xi}, \cdot)\|_{H_4(\underline{x})}^2 d\underline{\xi} \right)^{1/2}.$$

$$(2.3) \quad \|f\|_{\alpha, r} = \sup_{\underline{\xi}} (1 + \underline{\xi})^r e^{\alpha \underline{\xi}^2} \|f(\underline{\xi}, \cdot)\|_{H_4(\underline{x})}.$$

$$(2.4) \quad \|f\|_{\alpha} = \|f\|_{\alpha, 0}.$$

$$(2.5) \quad \|f\|_{\infty} = \|f\|_{0, 0}.$$

Denote $H_{\alpha} = \{f(\underline{x}, \underline{\xi}) : \|f\|_{\alpha} < \infty \text{ and } f \text{ periodic in } \underline{x}\}$. As in Part I, we will always refer to exponential decay and r to algebraic decay in $\underline{\xi}$. If γ ever appears in the subscript of a norm it is in the algebraic decay part. The algebraic decay is used in the following proofs, but not in the statements of the theorems. The Sobolev inequality in T^3 states that

$$(2.6) \quad \|fg\|_{H_4(\underline{x})} \leq c \|f\|_{H_4(\underline{x})} \|g\|_{H_4(\underline{x})}.$$

The main result for the linear problem is the following:

Theorem 2.1

Let $0 < \alpha < \frac{1}{4}$, and let $f_0 \in N \cap H_{\alpha}$. Then there is a unique solution of the linear Boltzmann equation (1.1) and (1.2) in H_{α} . It decays in time like

$$(2.7) \quad \|f(t)\| \leq c \|f_0\|_\alpha e^{-\lambda t^\beta}$$

$$(2.8) \quad \|f(t)\|_\infty \leq c \|f_0\|_\alpha e^{-\lambda t^\beta}$$

$$(2.9) \quad \|f(t)\|_\alpha \leq c \|f_0\|_\alpha$$

In which $\beta = \frac{2}{2+\gamma}$ and $\lambda = (1-2\epsilon) \alpha^{1-\beta} \frac{c_0}{\beta}$, for any $\epsilon > 0$. The constant c depends on ϵ .

The estimates on K are exactly as before. We first note that, since F is independent of x ,

$$(2.10) \quad \|Kf(\xi, \cdot)\|_{H_4(x)} \leq K(\|f(\cdot, \cdot)\|_{H_4(x)}) \quad (\xi)$$

Using that inequality we easily show

Proposition 2.2

$$(2.11) \quad \|Kf\|_{0, \gamma+3/2} \leq c \|f\|$$

$$(2.12) \quad \|Kf\|_{\alpha, r+\gamma+2} \leq c \|f\|_{\alpha, r}$$

$$(2.13) \quad \|Kf\| \leq c \|f\|_\infty$$

These estimates and Theorem 3.1 of the next section are used to prove Theorem 2.1 just as in Part I. In the proof we solve two types of equations:

$$(2.14) \quad \frac{\partial}{\partial t} g + B_w g = g_1, \quad \text{on } \xi < w,$$

in which $B_w = \xi \cdot \frac{\partial}{\partial x} + v + \chi_w \bar{K}$, and

$$(2.15) \quad \frac{\partial}{\partial t} h + \xi \cdot \frac{\partial}{\partial x} h + v h = h_1,$$

We rewrite these as

$$(2.16) \quad g(\underline{x}, t, \underline{\xi}) = e^{-tB_w} g_0(\underline{x}, \underline{\xi}) + \int_0^t e^{-(t-s)B_w} g_1(\underline{x}, s, \underline{\xi}) ds,$$

$$(2.17) \quad h(\underline{x}, t, \underline{\xi}) = e^{-tv(\underline{\xi})} h_0(\underline{x} - t\underline{\xi}, \underline{\xi}) + \int_0^t e^{-(t-s)v(\underline{\xi})} h_1(\underline{x} - (t-s)\underline{\xi}, s, \underline{\xi}) ds.$$

Now take the $H_4(x)$ norm and use Theorem 3.1 to estimate

$$(2.18) \quad \|g\|_{H_4(x)}(t, \underline{\xi}) \leq e^{-\mu t v(w)} \|g_0\|_{H_4(x)}(\underline{\xi}) \\ + \int_0^t e^{-\mu(t-s)v(w)} \|g_1\|_{H_4}(s, \underline{\xi}) ds,$$

$$(2.19) \quad \|h\|_{H_4(x)}(t, \underline{\xi}) \leq e^{-tv(\underline{\xi})} \|h_0\|_{H_4(x)}(\underline{\xi}) \\ + \int_0^t e^{-(t-s)v(\underline{\xi})} \|h_1\|_{H_4}(s, \underline{\xi}) ds.$$

These are exactly like the equations treated in Sections 9-12 of Part I.

III Spectral Theory for the Cutoff Linear Operator

Consider the transport and collision operator

$$(3.1) \quad B = \underline{\xi} \cdot \frac{\partial}{\partial \underline{x}} + \nu + \bar{K}$$

on $L^2(\underline{x}, \underline{\xi})$. Recall that \bar{K} is the modification of K defined in (1.4).

We shall show that, after restriction to a bounded set of velocities, this operator generates a strictly contracting semi-group. Our main result is

Theorem 3.1

Consider the operator $B_w = \underline{\xi} \cdot \frac{\partial}{\partial \underline{x}} + \nu(\underline{\xi}) + \bar{K}_w$ on $L^2\{\underline{x}, \underline{\xi} : \underline{\xi} < w\}$.

- i) $-B_w$ is maximally dissipative
- ii) Let $0 < \mu < 1$. If w is sufficiently large,

$$(3.2) \quad \|e^{-tB_w}\| \leq e^{-t\mu\nu(w)}.$$

The theorem is proved by looking at the Fourier transform of B_w . The modification of K only affects the 0 Fourier variable, so that

$$(3.3) \quad B_{w,k} = -ik \cdot \underline{\xi} + \nu + K, \quad k \neq 0,$$

$$(3.4) \quad B_{w,0} = \nu + \bar{K},$$

where k a vector with integer components. Each $B_{w,k}$ is an operator on $L^2(\underline{\xi} < w)$ and satisfies

$$(3.5) \quad \operatorname{Re}(B_{w,k} f, f) \geq 0.$$

The following results are analogous to Theorem 7.1 and Proposition 7.2 in Part I. An important point is that the statements are independent of k .

Proposition 3.2

Let $0 < \mu < 1$. For w sufficiently large, $B_{w,k}$ has spectrum whose
real part is bigger than $\mu\nu(w)$, i.e.

$$(3.6) \quad \sigma(B_{w,k}) \subset \{\lambda : \operatorname{Re} \lambda > \mu v(w)\}.$$

Moreover the sufficient size of w is independent of k .

Proposition 3.3

Let f be an eigenfunction of $B_{w,k}$ with eigenvalue λ such that $\operatorname{Re} \lambda < \mu v(w)$. Then f is rapidly decreasing in ξ , i.e.

$$(3.7) \quad \sup_{\xi} (1 + \xi)^m |f(\xi)| \leq c_m \int f(\xi)^2 d\xi,$$

in which the constants c_m are independent of λ, w, f, k .

The following lemma will be used in the proof of Proposition 3.2.

Lemma 3.4

Let $f \in L^2$, $\theta \in \mathbb{R}$, and $k \in \mathbb{R}^3$ with $|k| = 1$. Then

$$(3.8) \quad \lim_{\epsilon \rightarrow 0} \sup_{\theta, k=1} \int_A f^2 d\xi = 0$$

in which $A = \{\xi : |k \cdot \xi + \theta| < \epsilon\}$.

Proof of Proposition 3.3

Rewrite the eigen-equation as $\chi_w Kf = \{-(v - \lambda) + ik \cdot \xi\}f$. Therefore $|Kf(\xi)| \geq (1 - \mu) v(\xi) |f(\xi)|$. Then proceed as in Proposition 17.2 using this inequality and the estimates (I6.1) and (I6.2).

Proof of Proposition 3.2

If $k = 0$, the proposition is exactly Theorem 17.1. So we consider only $k \neq 0$

a) First we show that the values $\lambda \in \sigma(B_{w,k})$ with $\operatorname{Re} \lambda < \mu v(w)$ are necessarily discrete eigenvalues with finite multiplicity. (In fact we could put here $v(w)$ instead of $\mu v(w)$). The proof is exactly as in [2] using the methods of [4].

The Fredholm set of $(-ik \cdot \underline{\lambda} + 1)$ is $\{\lambda : \lambda \neq \pm i \underline{\lambda} \cdot \underline{k}\}$. Since $\chi_w K$ is compact, then this is also the Fredholm set of $B_{w,k}$. Therefore the set $S = \{\lambda : \operatorname{Re} \lambda < \nu(w)\}$ is contained in a component of the Fredholm set of $B_{w,k}$. This set S contains no eigenvalues which are in the resolvent set of $B_{w,k}$ because of (3.5), so that $\operatorname{nul} (B_{w,k} - \lambda) = \operatorname{def} (B_{w,k} - \lambda) = 0$. Since the nullity and deficiency are constant in connected components of the Fredholm set, except at isolated points, $\operatorname{nul} (B_{w,k} - \lambda) = \operatorname{def} (B_{w,k} - \lambda) = 0$ in S except at isolated points. These points are isolated eigenvalues of finite multiplicity. Every other point of S is in the resolvent set.

b) Now suppose the theorem is not true, so that there are sequences $w_n, \lambda_n, \underline{k}_n$ with $\operatorname{Re} \lambda_n \in \sigma(B_{w_n, \underline{k}_n}), \lambda_n < \nu(w_n)$ and $\underline{k}_n \neq 0$. Accordingly, each λ_n is an eigenvalue for B_{w_n, \underline{k}_n} with eigenfunction f_n , i.e.,

$$(3.9) \quad B_{w_n, \underline{k}_n} f_n = \lambda_n f_n \quad \text{and} \quad \|f_n\| = 1$$

Write $\lambda_n = \varphi_n + i \theta_n$. Then just as in the proof of Theorem 17.1, $\varphi_n \rightarrow \varphi$ and $\theta_n \rightarrow \theta$, after restricting to a subsequence, with the result that $\lim_{n \rightarrow \infty} (-\nu(\xi) + i \underline{k}_n \cdot \underline{\xi} + i \theta_n) f_n = g$. As before we can divide by the factor on the right to obtain

$$(3.10) \quad f \equiv \lim_{n \rightarrow \infty} f_n = \lim_{n \rightarrow \infty} \frac{1}{-\nu(\xi) + i \underline{k}_n \cdot \underline{\xi} + i \theta_n} g.$$

Denote the function inside the last limit in (3.10) as g_n .

Next we show that $\lim k_n \neq \infty$. Suppose to the contrary it was ∞ and restrict to a subsequence with $\lim k_n = \infty$.

Choose ϵ as in Lemma 2.4, such that

$$(3.11) \quad \sup_{\epsilon, k=1} \int_A f^2 d\xi < \epsilon,$$

in which $A = \{\xi : |\underline{k} \cdot \xi + \epsilon| < \sqrt{\epsilon}\}$. Choose n large enough that $\frac{1}{k_n} < \epsilon$ and $\|f - q_n\|^2 < \epsilon$. We will obtain a contradiction by integrating f^2 over the two sets $A_n = \{\xi : |\underline{k}_n \cdot \xi + \epsilon| < \sqrt{k_n}\}$ and $A_n^c = \mathbb{R}^3 - A_n$. Denote $\hat{k}_n = \underline{k}_n / k_n$. Then $A_n = \{\xi : |\hat{k}_n \cdot \xi + \epsilon/k_n| < 1/\sqrt{k_n}\}$. Since $1/\sqrt{k_n} < \sqrt{\epsilon}$,

$$(3.12) \quad \int_{A_n} f^2 d\xi \leq \epsilon.$$

In A_n^c , $q_n^2 < \epsilon^2/k_n$ and

$$(3.13) \quad \begin{aligned} \int_{A_n^c} f^2 d\xi &\leq \int_{A_n^c} q_n^2 d\xi + \epsilon \\ &\leq \epsilon \|g\|^2 + \epsilon. \end{aligned}$$

Adding (3.12) and (3.13) together results in

$$(3.14) \quad \|f\|^2 \leq 2\epsilon + \epsilon \|g\|^2$$

By choosing ϵ small enough we get a contradiction since $\|f\| = 1$, which shows that $\lim k_n < \infty$.

Similarly θ_n must stay bounded, and we get $\underline{k}_n \rightarrow \underline{k}$ and $\theta_n \rightarrow \theta$ after restricting to a subsequence. Since \underline{k}_n is on the integral lattice, $\underline{k}_n = \underline{k}$ for n large enough and so $\underline{k} \neq 0$. Take the limit $n \rightarrow \infty$ in the eigen-equation (3.9) again and find that

$$(3.15) \quad -i\underline{k} \cdot \xi f + \nabla f + Kf = i\theta f.$$

Integrate this against f ; the real part is $(\nabla f + Kf, f) = 0$. Since

$L = \dots + K$ is a positive semi-definite self-adjoint operator, then $f \in N(L)$, which means that

$$(3.16) \quad f(\underline{x}) = a_0 + \underline{a} \cdot \underline{x} + \underline{a}_2 \cdot \underline{x}^2$$

Since $(v + K)f = 0$, then $-(\underline{k} \cdot \underline{x})f = \Delta f$, which implies that $\underline{k} = 0$.

But this is a contradiction, since $\underline{k} \neq 0$. This concludes the proof of Proposition 3.2.

Proof of Theorem 3.1

i) Since \bar{B}_w is densely defined on $L^2(\underline{x} : \underline{x} \leq \underline{x} \cdot w)$ and

$$(3.17) \quad \operatorname{Re}(\bar{B}_w f, f) = \operatorname{Re}((v + \chi_w \bar{K}) f, f) \geq 0,$$

then \bar{B}_w is maximally dissipative.

ii) This proof is exactly that of theorem 1.1 in [5], except that we have removed the null space by changing the operator K to \bar{K} . Denote

$$A_w = \underline{x} \cdot \frac{\partial}{\partial \underline{x}} + v(\underline{x}), \quad K_w = \chi_w K, \quad \text{and} \quad B_w = A_w + K_w, \quad \text{operators on}$$

$$L_w = L^2(\{\underline{x}, \underline{x} : \underline{x} \leq w\}). \quad \text{We outline the proof in the following steps}$$

a) $K_w(\lambda - A_w)^{-1}$ is compact on $L^2(\underline{x}, \underline{x})$, for $\operatorname{Re} \lambda < \mu v(w)$.

b) $\sigma(B_w) \subset \{\lambda : \operatorname{Re} \lambda < \mu v(w)\}$ for w sufficiently large.

From (a), K_w is A_w -compact so that $\sigma_e(B_w) = \sigma_e(A_w) = \{\lambda : \operatorname{Re} \lambda \geq v(w)\}$ [4].

In $\{\operatorname{Re} \lambda < v(w)\}$, A_w is Fredholm and so is B_w . Moreover if $\operatorname{Re} \lambda < 0$, then

λ is in the resolvent set $\rho(B_w)$. Therefore $\{\operatorname{Re} \lambda < v(w)\} \subset \rho(B_w)$, except for

a discrete set of points which are eigenvalues of B_w . But Proposition 3.2

shows that B_w has no eigenvalues to the left of $\operatorname{Re} \lambda = \mu v(w)$ for w large enough.

$$c) \quad \lim_{|\lambda| \rightarrow \infty} \sup_{\operatorname{Re} \lambda < \mu v(w)} \|K_w(\lambda - A_w)^{-1}\| \rightarrow 0$$

d) Denote $\tilde{Z}(\lambda) = (\lambda - A_w)^{-1} (I - K_w(\cdot - A_w)^{-1})^{-1} K_w(\cdot - A_w)^{-1}$.

$(\lambda - B_w)^{-1} = (\lambda - A_w)^{-1} + \tilde{Z}(\lambda)$. Denote

$$(3.18) \quad Z_\beta(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-i\gamma t} \tilde{Z}(\varepsilon + i\gamma) d\gamma.$$

If $\beta \leq \mu\nu(w)$, $Z_\beta(t)$ converges absolutely in the weak topology and $Z_\beta(t)$ where c is independent of t and λ .

$$e) \quad e^{-tB_w} = e^{-tA_w} + e^{-\beta t} Z_\beta(t)$$

Choose $\beta = \mu\nu(w)$. Since $\|e^{-tA_w}\| \leq e^{-t\nu(w)}$, the result (ii) in Theorem 3.1 follows.

IV The Nonlinear Equation

Theorem 4.1

Let $0 < \alpha < \frac{1}{4}$. There is a positive constant ϵ , such that if
 $\|f_0\|_\alpha < \delta$, then the nonlinear Boltzmann equation (1.8) and (1.9) has a unique
solution in H_α , which satisfies

$$(4.1) \quad \|f(t)\| \leq c \|f_0\|_\alpha e^{-\lambda t^\beta}$$

$$(4.2) \quad \|f(t)\|_\infty \leq c \|f_0\|_\alpha e^{-\lambda t^\beta}$$

$$(4.3) \quad \|f(t)\|_\alpha \leq c \|f_0\|_\alpha$$

in which $\beta = \frac{2}{2+\gamma}$ and $\lambda = (1 - 2\epsilon) \left(\frac{\alpha}{2}\right)^{1-\beta} \left(\frac{c_0}{\beta}\right)^\beta$ for any $\epsilon > 0$. The
constant c depends on ϵ .

This β and λ are chosen just as in the linear problem, but they correspond to γ and $\frac{\alpha}{2}$ rather than α .

V Estimates on Γ

The nonlinearity $\Gamma(f, g)$ was analyzed by Grad in the Appendix of [3].

We decompose Γ as (this is slightly different from [3])

$$(5.1) \quad \Gamma(f, g) = \Gamma_1(f, g) + \Gamma_2(f, g) \quad ,$$

$$(5.2) \quad \nu \Gamma_1(f, g) = \frac{1}{2} \int (f g_1 + g_1 f) \omega_1^{1/2} d\underline{\Omega} \quad ,$$

$$(5.3) \quad \nu \Gamma_2(f, g) = \frac{1}{2} \int (f' g'_1 + f'_1 g') \omega_1^{1/2} d\underline{\Omega} \quad ,$$

$$(5.4) \quad d\underline{\Omega} = B(\theta, \underline{v}) d\theta d\underline{\xi}_1 \quad ,$$

in which $f'_1 = f(\xi'_1)$ as given by (2.4) in Part I, etc. The following estimates are analogous to those proved by Grad.

Proposition 5.1

$$(5.5) \quad \|\nu \Gamma_1(f, g)\|_{\alpha, r} \leq c (\|f\|_{\alpha, r-\gamma} \|g\| + \|f\| \|g\|_{\alpha, r-\gamma}) \quad .$$

$$(5.6) \quad \|\nu \Gamma_2(f, g)\|_{\alpha, r} \leq c \|f\|_{\alpha, r-k-\gamma} \|g\|_{\alpha, r-1-\gamma} \quad .$$

Proof

a) By the symmetry in Γ_1 it suffices to consider $\nu \Gamma_{11}(f, g) = \frac{1}{2} \int f g_1 \omega_1^{1/2} d\underline{\Omega}$. First take the $H_4(x)$ norm and use the Sobolev inequality (2.6). Since the integral does not involve ξ , we can factor the f term out to get

$$(5.7) \quad \|\nu \Gamma_{11}(f, g)\|_{H_4(x)} \leq c \|f\|_{H_4(x)} \frac{1}{2} \int \|g_1\|_{H_4(x)} \omega_1^{1/2} B(\theta, v) d\theta d\underline{\xi}_1 \quad .$$

Replace the first factor using

$$(5.8) \quad \|f\|_{H_4(x)}(\underline{\xi}) \leq (1 + \xi)^{-r} e^{-\alpha \xi^2} \|f\|_{\alpha, r} \quad .$$

Then use the definition (11.6) of α and the bound (12.11) on B and apply the Schwartz inequality to the integral over $\underline{\xi}_1$ to obtain

$$\int \|g_1\|_{H_4(x)}^{-1/2} d\Omega \leq c \|g\| \int_{R^3} e^{-1/2 \xi_1^2} |\underline{\xi} - \underline{\xi}_1|^{-2} d\underline{\xi}_1 \quad (5.9)$$

$$\leq c \|g\| (1 + \xi)^{-\gamma}.$$

Combining (5.8) and (5.9) results in

$$\|v \Gamma_{11}\|_{\alpha, r+\gamma} \leq c \|f\|_{\alpha, r} \|g\|, \quad (5.10)$$

from which (5.5) follows.

b) Again we only estimate

$$v \Gamma_{21} = \frac{1}{2} \int f_1' g' \omega_1^{1/2} d\Omega$$

$$(5.11) \quad = \frac{1}{2} \int_{R^3} \int_{\underline{w}+\underline{v}} f(\underline{\xi} + \underline{v}) g(\underline{\xi} + \underline{w}) \omega^{1/2}(\underline{\xi} + \underline{v} + \underline{w})$$

$$\cdot \frac{Q(\underline{v}, \underline{w})}{v^2} d\underline{w} d\underline{v},$$

in which \underline{w} and \underline{v} are defined by (12.10) and (12.11). We continue exactly as Grad did. Resolve $\underline{\xi}$ into components $\underline{\xi}_1$ and $\underline{\xi}_2$ parallel and perpendicular to \underline{v} respectively, so that

$$(5.12) \quad \omega^{1/2}(\underline{\xi} + \underline{v} + \underline{w}) = \omega^{1/2}(\underline{v} + \underline{\xi}_1) \omega^{1/2}(\underline{w} + \underline{\xi}_2),$$

and, using also the Sobolev inequality,

$$\|f(\underline{\xi} + \underline{v}) g(\underline{\xi} + \underline{w})\|_{H_4(x)}$$

$$\leq c (1 + |\underline{\xi} + \underline{v}|)^{-r} (1 + |\underline{\xi} + \underline{w}|)^{-r} \exp \{- (|\underline{\xi} + \underline{v}|^2 + |\underline{\xi} + \underline{w}|^2)\}$$

$$\cdot \|f\|_{\alpha, r} \|g\|_{\alpha, r}$$

$$(5.13) \quad \leq c(1 + \xi)^{-r+1} (1 + \xi_1)^{-1} (1 + \xi_2)^{-1} e^{-\alpha \xi^2} \|f\|_{\alpha, r} \|g\|_{\alpha, r}.$$

After applying the $H_4(x)$ norm to $v \Gamma_{21}$ we can use (5.13) in estimating (5.11) to find

$$(5.14) \quad \|v \Gamma_{21}\|_{H_4(x)} \leq c(1 + \xi)^{-r+1} e^{-\alpha \xi^2} \|f\|_{\alpha, r} \|g\|_{\alpha, r} \\ \int_{\mathbb{R}^3} \int_{\underline{w} \perp \underline{v}} (1 + \xi_1)^{-1} (1 + \xi_2)^{-1} \omega^{1/2} (\underline{v} + \underline{\xi}_1) \omega^{1/2} (\underline{w} + \underline{\xi}_2) \frac{Q(\underline{v}, \underline{w})}{v^2} d\underline{w} d\underline{v}.$$

Denote the integral on the right by I . According to Proposition 5.2 from Part I,

$$(5.15) \quad \frac{1}{v} \int_{\underline{w} \perp \underline{v}} \omega^{1/2} (\underline{w} + \underline{\xi}_2) Q(\underline{v}, \underline{w}) d\underline{w} \leq c(1 + \xi_2 + v)^{-(\gamma+1)},$$

so that

$$(5.16) \quad I \leq \int_{\mathbb{R}^3} (1 + \xi_1)^{-1} (1 + \xi_2)^{-1} (1 + \xi_2 + v)^{-(\gamma+1)} \frac{1}{v} \omega^{1/2} (\underline{v} + \underline{\xi}_1) d\underline{v}.$$

It is easy to see that

$$(5.17) \quad (1 + \xi_2 + v)^{-(\gamma+1)} \omega^{1/4} (\underline{v} + \underline{\xi}_1) \leq c(1 + \xi)^{-(\gamma+1)}.$$

Combine this with the estimate

$$(5.18) \quad \int \frac{1}{v} (1 + \xi_1)^{-1} (1 + \xi_2)^{-1} \omega^{1/4} (\underline{\xi}_1 + \underline{v}) d\underline{v} \leq c(1 + \xi)^{-1},$$

which comes (almost exactly) from the Appendix of [3], to obtain

$$(5.19) \quad I \leq c(1 + \xi)^{-(\gamma+2)}.$$

Using this in (5.14), we find

$$(5.20) \quad \|v \Gamma_{21}\|_{H_4(x)} \leq c(1 + \xi)^{-(r+\gamma+1)} e^{-\alpha \xi^2} \|f\|_{\alpha, r} \|g\|_{\alpha, r}.$$

The result (5.6) follows after replacing r with $r + Y + 1$, dividing, and taking sup over $\underline{\xi}$.

VI The Inhomogeneous Iteration Equation

Consider the equation

$$(6.1) \quad \frac{\partial}{\partial t} f + \underline{L} \cdot \frac{\partial}{\partial \underline{x}} f + L f = v T(h_1, h_2) ,$$

$$(6.2) \quad f(t = 0) = f_0 , \quad N \supset H$$

which is an inhomogeneous version of the iteration equations that will be solved in the next section. Pick λ and β as in Theorem 4.1, i.e. corresponding to $\alpha/2$. For f_0, h_1, h_2 we require

$$(6.3) \quad \|f_0\|_{\alpha} \leq b_0 ,$$

$$(6.4) \quad \sup_t \{ \|h_i(t)\|_{\alpha}, e^{\lambda t^{\beta}} \|h_i(t)\|, e^{\lambda t^{\beta}} \|h_i(t)\|_{\infty} \} \leq b_i , \quad i = 1, 2,$$

in which the sup is taken over time as well as over the three components.

Proposition 6.1

The solution f of (6.1) and (6.2) satisfies

$$(6.5) \quad \max \{ \|f(t)\|_{\alpha}, e^{\lambda t^{\beta}} \|f(t)\|, e^{\lambda t^{\beta}} \|f(t)\|_{\infty} \} \leq c(b_0 + b_1 b_2)$$

We will employ two useful inequalities. The first is a special case of an interpolation theorem for the α, r - norms.

Lemma 6.2

$$(6.6) \quad \|f\|_{\alpha/2} \leq 2 \|f\|_{\alpha}^{1/2} \|f\|_{\infty}^{1/2}$$

Proof For any $\xi_0 > 0$,

$$\|f\|_{\alpha/2} \leq e^{\frac{\alpha}{2}\xi_0^2} \sup_{\xi < \xi_0} |f(\xi)| + e^{-\frac{\alpha}{2}\xi_0^2} \sup_{\xi > \xi_0} |f(\xi)|$$

$$(6.7) \quad \leq e^{\frac{\alpha}{2}\xi_0^2} \|f\|_{\infty} + e^{-\frac{\alpha}{2}\xi_0^2} \|f\|_{\alpha} \\ \leq 2 \sqrt{\|f\|_{\infty} / \|f\|_{\alpha}}.$$

By choosing $e^{\frac{\alpha}{2}\xi_0^2} = \sqrt{\|f\|_{\infty} / \|f\|_{\alpha}}$.

Lemma 6.3

For $0 < \beta < 1$,

$$(6.8) \quad \int_0^t \exp \{-\lambda(t-s)^{\beta} - \lambda s^{\beta}\} ds \leq c(1+t)^{-1} e^{-\lambda t},$$

where c depends on β .

Proof

Just use the estimate $(t-s)^{\beta} - (t^{\beta} - s^{\beta}) > c \{(t/2)^2 - (s-t/2)^2\}$ in the integral.

Proof of Proposition 6.1

a) First we infer from Lemma 6.2 and (6.4) that

$$(6.9) \quad \|h_i(t)\|_{\alpha/2} \leq c b_i e^{\frac{1}{2} \lambda t^{\beta}}.$$

According to Proposition 6.1 and (6.4),

$$(6.10) \quad \|\vee \Gamma_1(h_1, h_2)(t)\|_{\alpha} \leq c b_1 b_2 e^{-\lambda t^{\beta}},$$

$$(6.11) \quad \|\vee \Gamma_2(h_1, h_2)(t)\|_{\alpha, \gamma+1} \leq c b_1 b_2,$$

$$(6.12) \quad \|\vee \Gamma(h_1, h_2)(t)\|_{\alpha/2} \leq c b_1 b_2 e^{-\lambda t^{\beta}}.$$

Note that the $\frac{\alpha}{2}$ - norm decays, while the α - norm does not. This is the reason for using the $\alpha/2$ and will be needed in the next estimate.

b) Using the estimates (2.7) and (2.8) for the linear problem and (6.12) and Lemma 6.3, we find that (recall that β corresponds to $\alpha/2$)

$$\begin{aligned}
 \max \{ \|f(t)\|, \|f(t)\|_{\infty} \} &\leq c e^{-\lambda t^{\frac{\beta}{2}}} \|f_0\|_{\alpha/2} + c \int_0^t e^{-\lambda(t-s)^{\frac{\beta}{2}}} \|v\|_{H_4(x)} (s, \xi) ds \\
 (6.13) \quad &\leq c e^{-\lambda t^{\frac{\beta}{2}}} b_0 + c \int_0^t e^{-\lambda(t-s)^{\frac{\beta}{2}}} e^{-\lambda s^{\frac{\beta}{2}}} ds b_1 b_2 \\
 &\leq c e^{-\lambda t^{\frac{\beta}{2}}} (b_0 + b_1 b_2) .
 \end{aligned}$$

c) To estimate $\|f(t)\|_{\alpha}$ we go back and redo the linear estimate. As in (2.19) we estimate

$$\begin{aligned}
 \|f(t, \xi)\|_{H_4(x)} &\leq e^{-tv(\xi)} \|f_0\|_{H_4(x)} + \\
 (6.14) \quad &\int_0^t e^{-(t-s)v(\xi)} (\|Kf\|_{H_4(x)}(s, \xi) + \|v\|_{H_4(x)}(s, \xi)) ds
 \end{aligned}$$

Using the argument in Section 12 of Part I, we find that

$$\begin{aligned}
 \sup_{\xi} \{ e^{\alpha \xi^2} e^{-(t-s)v(\xi)} \|Kf\|_{H_4(x)}(s, \xi) \} \\
 (6.15) \quad &\leq c(1+t-s)^{-1-\gamma/2} (e^{\alpha \xi_0^2} \|f(s)\| + (1+\xi_0)^{-3/2} \|f(s)\|_{\alpha})
 \end{aligned}$$

for any ξ_0 . Choose ξ_0 large enough and use (6.13) to obtain

$$\begin{aligned}
 \int_0^t \sup_{\xi} \{ e^{\alpha \xi^2} e^{-(t-s)v(\xi)} \|Kf\|_{H_4(x)}(s, \xi) \} ds \\
 (6.16) \quad &\leq \frac{1}{2} \sup_{0 \leq s \leq t} \|f(s)\|_{\alpha} + c(b_0 + b_1 b_2) .
 \end{aligned}$$

The last term in (6.14) is split into two parts using $\Gamma = \Gamma_1 + \Gamma_2$ (cf. (5.1)). The reason for going back to the linear equation was to estimate the term containing Γ_2 :

$$\begin{aligned}
 & \sup_{\xi} e^{\alpha \xi^2} e^{-(t-s)v(\xi)} \|v \Gamma_2\|_{H_4(x)}(s, \xi) \\
 (6.17) \quad & \leq \sup_{\xi} (1 + \xi)^{-1-1/2} e^{-(t-s)v(\xi)} \cdot \dots \\
 & \leq c(1+t-s)^{-1-v/2} b_1 b_2,
 \end{aligned}$$

where we used Lemma II2.1 and (6.11) in the last step. Since this is integrable over time,

$$(6.18) \quad \int_0^t \sup_{\xi} \{e^{\alpha \xi^2} e^{-(t-s)v(\xi)} \|v \Gamma_2\|_{H_4(x)}(s, \xi)\} ds \leq c b_1 b_2.$$

The term containing Γ_1 is easily estimated

$$\begin{aligned}
 & \int_0^t \sup_{\xi} \{e^{\alpha \xi^2} e^{-(t-s)v(\xi)} \|v \Gamma_1\|_{H_4(x)}(s, \xi)\} ds \\
 (6.19) \quad & \leq \int_0^t \|v \Gamma_1\|_A ds \leq c b_1 b_2,
 \end{aligned}$$

because of (6.10).

The three terms estimated in (6.16), (6.18), and (6.19) plus the initial term in (6.14) are just what appear on the right side of (6.14) after multiplying by $e^{\alpha \xi^2}$ and taking sup over ξ . The result is that

$$(6.20) \quad \|f(t)\|_A \leq c(b_0 + b_1 b_2) + \frac{1}{2} \sup_{0 \leq s \leq t} \|f(s)\|_A,$$

from which it follows that

(6.21)

$$f(t)F_1 \leq c(E_0 + E_1 F_0)$$

This concludes the proof of the Proposition.

4.1. *PROOF OF THEOREM 4.1*

The nonlinear Boltzmann equation (1.8) and (1.9) is solved by an iteration, starting with

$$(7.1) \quad f_1(t) = e^{-\lambda t} f_0$$

and proceeding by

$$(7.2) \quad \frac{\partial}{\partial t} f_{n+1} + \frac{\partial}{\partial x} f_{n+1} + L f_{n+1} = v F(f_n, f_n), \quad f_{n+1}(t=0) = f_0$$

First we show the boundedness and decay of f_{n+1} . Denote $\|f_n\| = b_n$ and suppose that

$$(7.3) \quad \max \{ \|f_n\|, e^{\lambda t} \|f_n\|, e^{\lambda t^2} \|f_n\| \} \leq E.$$

We need in addition that $b \geq b_0$ in order to get the induction started.

According to Proposition (6.1), the estimate (7.3) will also be true for f_{n+1} if $b \geq c(E_0 + b^2)$. This can be fulfilled as long as b_0 is small enough, and we can even make b as small as desired.

Next we estimate the difference $h_{n+1} = f_{n+1} - f_n$. For h_{n+1} we have the equation

$$(7.4) \quad \frac{\partial}{\partial t} h_{n+1} + \frac{\partial}{\partial x} h_{n+1} + L h_{n+1} = v F(h_n, f_n + f_{n-1}), \quad h_{n+1}(t=0) = 0.$$

Denote $|||h||| = \sup_t \{ \|h(t)\|_\alpha, e^{\lambda t^2} \|h(t)\|, e^{\lambda t^2} \|h(t)\|_\infty \}$. Then $|||h_2||| \leq 2b$

from (7.3), and using Proposition 6.1 again, $|||h_{n+1}(t)||| \leq 2cb |||h_n|||$.

After choosing $b < \frac{1}{2c}$, we find that $\sum_{n=2}^{\infty} |||h_{n+1}(t)||| < \infty$, and it follows that

$$(7.5) \quad f_n \rightarrow f$$

in the norm $||| \cdot |||$. Moreover f solves equations (1.8) and (1.9). This concludes the proof of Theorem 4.1.

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REPORT DOCUMENTATION PAGE		READ INSTRUCTIONS BEFORE COMPLETING FORM
1. REPORT NUMBER 2031	2. GOVT ACCESSION NO. AD-A083 813	3. RECIPIENT'S CATALOG NUMBER
4. TITLE (and Subtitle) The Boltzmann Equation with a Soft Potential. Part II: Nonlinear, Spatially-Periodic		5. TYPE OF REPORT & PERIOD COVERED Summary Report - no specific reporting period
		6. PERFORMING ORG. REPORT NUMBER
7. AUTHOR(s) Russel Caflisch		8. CONTRACT OR GRANT NUMBER(s) MCS76-07039 DAAG29-75-C-0024 MCS78-09525
9. PERFORMING ORGANIZATION NAME AND ADDRESS Mathematics Research Center, University of 610 Walnut Street Madison, Wisconsin 53706		10. PROGRAM ELEMENT, PROJECT, TASK AREA & WORK UNIT NUMBERS Work Unit Number 1 - Applied Analysis
11. CONTROLLING OFFICE NAME AND ADDRESS See Item 18 below		12. REPORT DATE January 1980
		13. NUMBER OF PAGES 24
14. MONITORING AGENCY NAME & ADDRESS (if different from Controlling Office)		15. SECURITY CLASS. (of this report) UNCLASSIFIED
		15a. DECLASSIFICATION/DOWNGRADING SCHEDULE
16. DISTRIBUTION STATEMENT (of this Report) Approved for public release; distribution unlimited.		
17. DISTRIBUTION STATEMENT (of the abstract entered in Block 20, if different from Report)		
18. SUPPLEMENTARY NOTES U. S. Army Research Office and National Science Foundation P. O. Box 12211 Washington, D. C. 20550 Research Triangle Park North Carolina 27709		
19. KEY WORDS (Continue on reverse side if necessary and identify by block number) Boltzmann Equation, soft potentials, initial value problems		
20. ABSTRACT (Continue on reverse side if necessary and identify by block number) The results of Part I are extended to include linear spatially periodic problems - solutions of the initial value are shown to exist and decay like $e^{-\lambda t^{\beta}}$. Then the full non-linear Boltzmann equation with a soft potential is solved for initial data close to equilibrium. The non-linearity is treated as a perturbation of the linear problem, and the equation is solved by iteration. $\exp(-\lambda \omega^{\beta} (t - t_0))$		