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EXP.NO:10

EXP.NAME: FUZZY LOGIC

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Q Commands + Code + Text
     [1] !pip install scikit-fuzzy
0
        Collecting scikit-fuzzy

Downloading scikit_fuzzy-0.5.0-py2.py3-none-any.whl.metadata (2.6 kB)
()
             Downloading scikit_fuzzy-0.5.0-py2.py3-none-any.whl (920 kB)
                                                          -- 920.8/920.8 kB 16.5 MB/s eta 0:00:00
©₩
             Installing collected packages: scikit-fuzzy
             Successfully installed scikit-fuzzy-0.5.0
(2) import numpy as np
             import skfuzzy as fuzz
             from skfuzzy import control as ctrl
             # Define fuzzy variables
             experience = ctrl. Antecedent (np.arange (0, 21, 1), \ 'experience') \\
             success_rate = ctrl.Antecedent(np.arange(0, 101, 1), 'success_rate')
performance = ctrl.Consequent(np.arange(0, 101, 1), 'performance')
             # Define fuzzy membership functions
             experience['low'] = fuzz.trimf(experience.universe, [0, 0, 10])
             experience['medium'] = fuzz.trimf(experience.universe, [5, 10, 15])
             experience['high'] = fuzz.trimf(experience.universe, [10, 20, 20])
             success_rate['low'] = fuzz.trimf(success_rate.universe, [0, 0, 50])
              success_rate['medium'] = fuzz.trimf(success_rate.universe, [25, 50, 75])
              success_rate['high'] = fuzz.trimf(success_rate.universe, [50, 100, 100])
              performance['poor'] = fuzz.trimf(performance.universe, [0, 0, 50])
              performance['average'] = fuzz.trimf(performance.universe, [25, 50, 75])
              performance['excellent'] = fuzz.trimf(performance.universe, [50, 100, 100])
             # Define fuzzy rules
             rule1 = ctrl.Rule(experience['low'] & success_rate['low'], performance['poor'])
             rule2 = ctrl.Rule(experience['medium'] | success_rate['medium'], performance['average'])
rule3 = ctrl.Rule(experience['high'] & success_rate['high'], performance['excellent'])
             # Create FIS control system
              performance ctrl = ctrl.ControlSystem([rule1, rule2, rule3])
             performance_sim = ctrl.ControlSystemSimulation(performance_ctrl)
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performance['excellent'] = fuzz.trimf(performance.universe, [50, 100, 100])

# Define fuzzy rules
rule1 = ctrl.Rule(experience['low'] & success_rate['low'], performance['poor'])
rule2 = ctrl.Rule(experience['medium'] | success_rate['medium'], performance['average'])
rule3 = ctrl.Rule(experience['high'] & success_rate['high'], performance['excellent'])

# Create FIS control system
performance_ctr1 = ctrl.ControlSystem([rule1, rule2, rule3])
performance_sim = ctrl.ControlSystemSimulation(performance_ctrl)

# Provide input values
performance_sim.input['experience'] = 12
performance_sim.input['experience'] = 70

# Compute fuzzy inference
performance_sim.compute()

# Print the output
print(f"Predicted Performance Score: {performance_sim.output['performance']:.2f}")

The Predicted Performance Score: 57.52
```