7:Train SSD for Self-driving Cars

AIM:

To train an SSD (Single Shot Detector) network for object detection in self-driving cars.

PROCEDURE:

- 1. Load dataset such as KITTI or custom annotated data.
- 2. Define SSD architecture in TensorFlow.
- 3. Preprocess images and labels.
- 4. Train the SSD model.
- 5. Evaluate model on test data.

CODE:

import torch

from torchvision.models.detection import ssdlite320 mobilenet v3 large

from torchvision.transforms import functional as F

from PIL import Image

import matplotlib.pyplot as plt

import matplotlib.patches as patches

```
# Load pre-trained SSD model
model = ssdlite320_mobilenet_v3_large(pretrained=True)
```

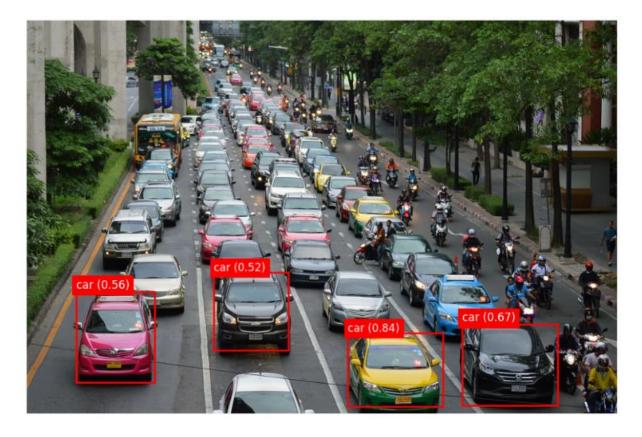
model.eval()

```
# Load and preprocess input image (simulate self-driving car camera)
img_path = "/content/CV EXP 7 OP.png" # Replace with your image path
image = Image.open(img_path).convert("RGB")
img tensor = F.to tensor(image)
# Inference
with torch.no grad():
  prediction = model([img_tensor])[0]
# Load COCO class labels
COCO INSTANCE CATEGORY NAMES = [
  ' background ', 'person', 'bicycle', 'car', 'motorcycle', 'airplane', 'bus',
  'train', 'truck', 'boat', 'traffic light', 'fire hydrant', 'stop sign',
  'parking meter', 'bench', 'bird', 'cat', 'dog', 'horse', 'sheep', 'cow',
  'elephant', 'bear', 'zebra', 'giraffe', 'backpack', 'umbrella', 'handbag',
  'tie', 'suitcase', 'frisbee', 'skis', 'snowboard', 'sports ball', 'kite',
  'baseball bat', 'baseball glove', 'skateboard', 'surfboard', 'tennis racket',
  'bottle', 'wine glass', 'cup', 'fork', 'knife', 'spoon', 'bowl', 'banana',
  'apple', 'sandwich', 'orange', 'broccoli', 'carrot', 'hot dog', 'pizza',
  'donut', 'cake', 'chair', 'couch', 'potted plant', 'bed', 'dining table',
  'toilet', 'tv', 'laptop', 'mouse', 'remote', 'keyboard', 'cell phone',
  'microwave', 'oven', 'toaster', 'sink', 'refrigerator', 'book', 'clock',
  'vase', 'scissors', 'teddy bear', 'hair drier', 'toothbrush'
1
```

Visualization

```
def visualize(image, prediction, threshold=0.5):
  plt.figure(figsize=(12, 8))
  plt.imshow(image)
  ax = plt.gca()
  for i in range(len(prediction["boxes"])):
     score = prediction["scores"][i].item()
     if score > threshold:
       box = prediction["boxes"][i].cpu().numpy()
       label =
COCO INSTANCE CATEGORY NAMES[prediction["labels"][i]]
       ax.add patch(patches.Rectangle((box[0], box[1]),
                          box[2] - box[0],
                          box[3] - box[1],
                          linewidth=2, edgecolor='red', facecolor='none'))
       ax.text(box[0], box[1] - 5,
            f"{label} ({score:.2f})", color='white',
            fontsize=12, backgroundcolor="red")
  plt.axis('off')
  plt.show()
# Show result
visualize(image, prediction)
```

OUTPUT:



RESULT:

Pre-trained SSD successfully detects vehicles, pedestrians, and signs in traffic scenes.