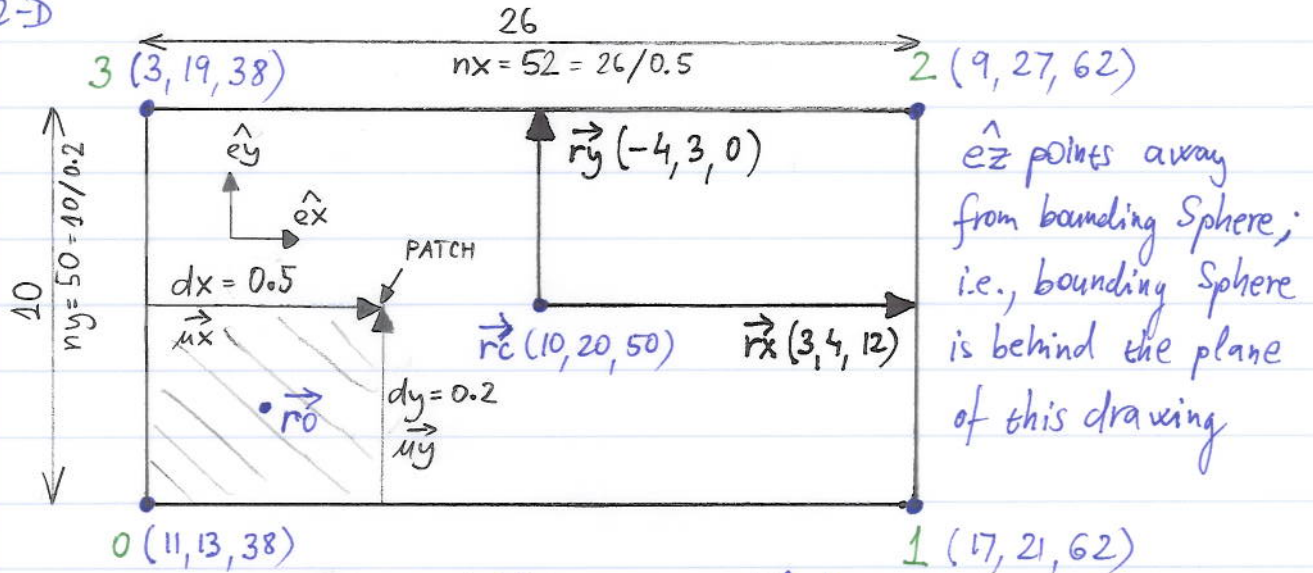


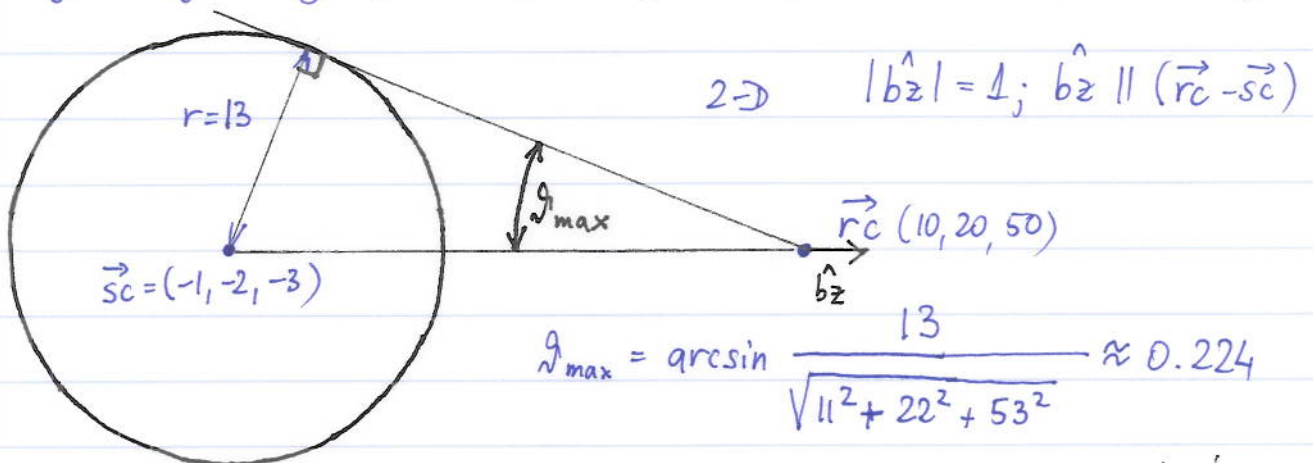
class Detector, test_Detector.cpp, detector_init.cpp

Detector is a rectangular Polygon on its own Grid of 4 Nodes.

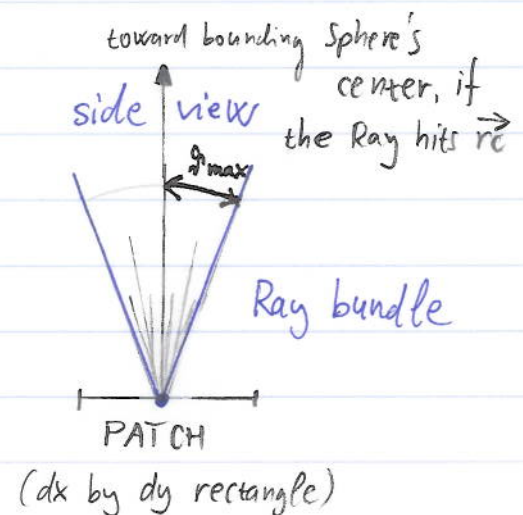
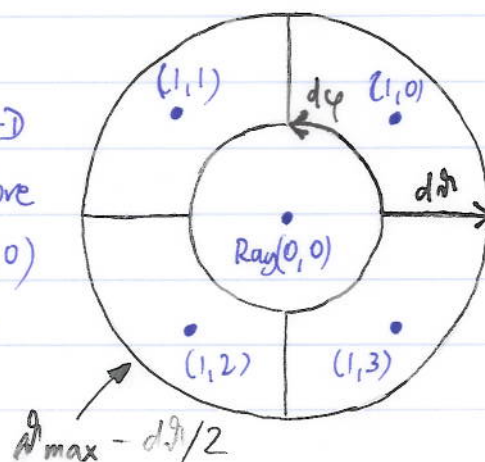
2-D



$$\begin{aligned} \vec{r}_x \parallel \vec{u}_x \parallel \hat{e}_x ; |\vec{u}_x| = dx ; |\hat{e}_x| = 1 \\ \vec{r}_y \parallel \vec{u}_y \parallel \hat{e}_y ; |\vec{u}_y| = dy ; |\hat{e}_y| = 1 ; \hat{e}_z = \hat{e}_x \times \hat{e}_y \end{aligned}$$



solid angle
elements 3-D
view from above
North Pole (0,0)
 $n_x = 2, n_y = 4$



pmh-2015-0210 (2)

Ray (θ, φ) from bundle \rightarrow direction $\vec{V} = x_e \hat{e}_x + y_e \hat{e}_y + z_e \hat{e}_z$ (local)

Since $\hat{e}_x = b_{x_x} \hat{x} + b_{x_y} \hat{y} + b_{x_z} \hat{z}$

$\hat{e}_y = b_{y_x} \hat{x} + b_{y_y} \hat{y} + b_{y_z} \hat{z}$, the local-to-global() transformation is

$\hat{e}_z = b_{z_x} \hat{x} + b_{z_y} \hat{y} + b_{z_z} \hat{z}$

$$\begin{aligned} \vec{x}_r &\rightarrow \begin{pmatrix} b_{x_x} & b_{y_x} & b_{z_x} \end{pmatrix} \underbrace{\begin{pmatrix} x_e \\ y_e \\ z_e \end{pmatrix}}_{\vec{V}} = \begin{pmatrix} \vec{x}_r \cdot \vec{V} \\ \vec{y}_r \cdot \vec{V} \\ \vec{z}_r \cdot \vec{V} \end{pmatrix} = \vec{c} \text{vec in do_Ray()}\end{aligned}$$

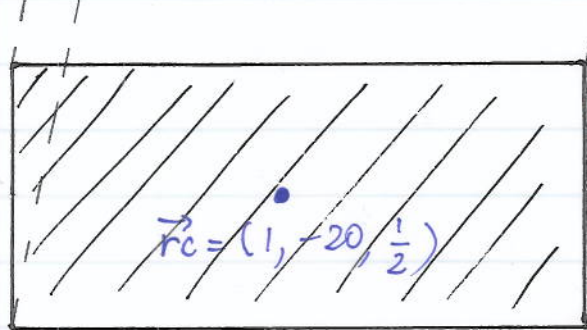
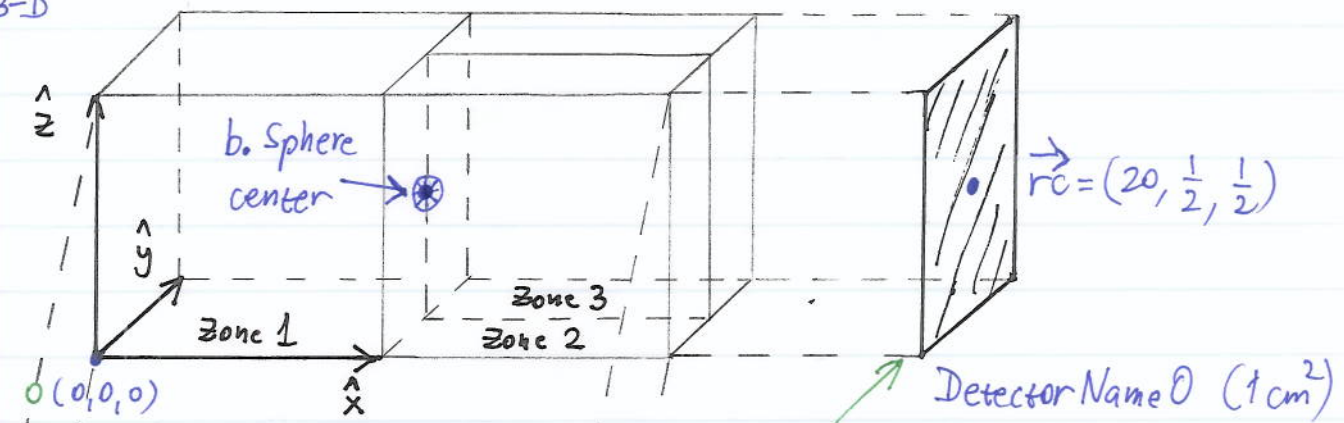
test_Diagnostics.cpp

using Mesh definitions from pmh-2014-1219;

1st time step: only Zones 0 and 1, bounding Sphere center at Node 8 *

2nd time step: all 4 Zones, bounding Sphere center at Node 16 $= (1, \frac{1}{2}, \frac{1}{2})$
bounding Sphere (not shown): radius = 13 cm

3-D Mesh



Diagnostics

parallel Ray approximation,
i.e., each patch receives a
single Ray from the
 $\theta=0, \varphi=0$ direction

DetectorName1 (2cm^2)

* shifted b. Sphere center differentiates Hydro2 from Hydro1