

Escape Room: A Configurable Testbed for Hierarchical Reinforcement Learning



Motivation

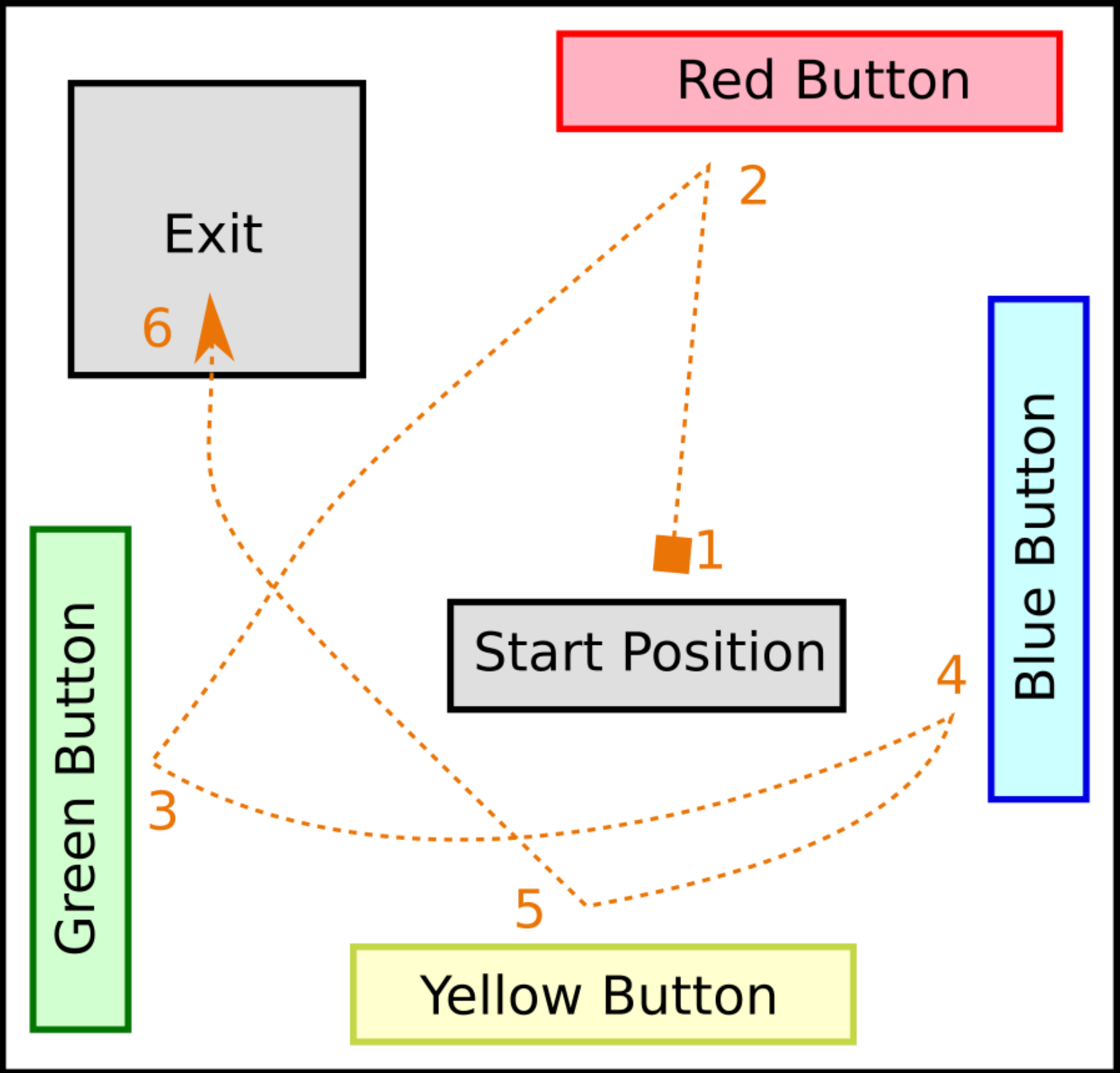
- Traditional domains for Hierarchical Reinforcement Learning are too simple for evaluation of modern algorithms (Taxi, LightBox/BitFlip, etc).
- Modern alternatives lack explicit hierarchical structure (Montezuma’s Revenge)
- The Escape Room Domain is an extensible alternative that allows for comparison between HRL algorithms in a structured environment.

Background

- Escape Rooms are a modern problem-solving task that can be found in real-world cooperative team games and in modern media.
- An Escape Room is a locked room that requires a series of puzzles to be solved in order for the room to be “escaped”.

Contribution

- We present a new extensible testbed domain that meets the following criteria:
 - Availability:** The domain is freely available for research online.
 - Accessibility:** The domain is constructed and documented in a way that conforms to the norms of the research community.
 - Flexibility:** The domain is built on an open-source framework and can be readily adapted to the varying needs of individual researchers.
 - Scalability:** The domain contains built-in mechanisms for iteratively rescaling its difficulty to provide a gradient of successive challenges.



The Escape Room

An extensible testbed domain for research and benchmarking on autonomous learning agents.



MDP Description

State

The state vector consists of the following:

- 6-DoF agent position
- N_p puzzle-specific dimensions
- N_j joint-specific dimensions

➡ (6+Np+Nj)-dim vector

Actions

| Action | Displacement |
|--|--------------|
| Move Forward/Back | 1 Meter |
| Strafe Left/Right | 1 Meter |
| Turn Left/Right | 10 Degrees |
| Actuate Joint (Increment or Decrement) | 10 Degrees |

Puzzles

- Subtasks embedded in the overarching “core” MDP.
- Each puzzle must be solved for the agent to successfully escape.
- Puzzle variable states and actions are concatenated onto the core MDP’s state/action vectors.

Implementation

- Written in Python
- Completely Open Source
- Panda3D Graphics Engine
- OpenAI Gym Compatible

Applications

- Hierarchical Reinforcement Learning
- Simulated robotics
- Autonomous 3D game playing
- Gaming prosthetics interfaces