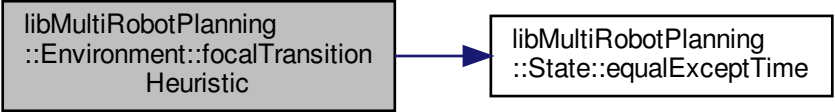


libMultiRobotPlanning  
::Environment::focalTransition  
Heuristic



```
graph LR; A["libMultiRobotPlanning  
::Environment::focalTransition  
Heuristic"] --> B["libMultiRobotPlanning  
::State::equalExceptTime"]
```

The diagram consists of two rectangular boxes connected by a blue arrow pointing from left to right. The left box has a light gray background and a black border, containing the text 'libMultiRobotPlanning', '::Environment::focalTransition', and 'Heuristic' on three lines. The right box has a white background and a black border, containing the text 'libMultiRobotPlanning' and '::State::equalExceptTime' on two lines.

libMultiRobotPlanning  
::State::equalExceptTime