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1 Graph Theory

1.1 Adjacency List

```

1 vector<int> list[5];
2
3 void Adjacency_List(){
4
5     // initial
6     for (int i = 0; i < 5; i++)
7         list[i].clear();
8
9     int a, b;    // start & end of an edge
10
11     while (cin >> a >> b)
12         list[a].push_back(b);
13         // list[b].push_back(a);
14 }

```

1.2 DFS

```

1 vector<int> G[N];
2 bitset<N> vis;
3 void dfs(int s) {
4     vis[s] = 1;
5     for (int t : G[s]) {
6         if (!vis[t])
7             dfs(t);
8     }
9 }

```

1.3 BFS

```

1 vector<int> G[N];
2 bitset<N> vis;
3 void bfs(int s) {
4     queue<int> q;
5     q.push(s);
6     vis[s] = 1;
7     while (!q.empty()) {
8         int v = q.front();
9         q.pop();
10        for (int t : G[v]) {
11            if (!vis[t]) {
12                q.push(t);
13                vis[t] = 1;
14            }
15        }
16    }

```

1.4 Disjoint Set and Kruskal

```

1 struct Edge{
2     int u, v, w;
3     // bool operator < (const Edge &rhs) const {
4         return w < rhs.w; }
5 };
6 vector<int> parent;
7 vector<Edge> E;
8
9 bool cmp(Edge edge1, Edge edge2){
10     return edge2.w > edge1.w;
11 }
12
13 int find(int x){
14     if(parent[x] < 0){
15         return x;
16     }
17     return parent[x] = find(parent[x]);
18 }
19
20 bool Uni(int a, int b){
21     a = find(a);
22     b = find(b);
23     if(a == b){
24         return false;
25     }
26     if(parent[a] > parent[b]){
27         swap(a, b);
28     }
29     parent[a] = parent[a] + parent[b];
30     parent[b] = a;
31     return true;
32 }
33
34 void Kruskal() {
35
36     int cost = 0;
37
38     sort(E.begin(), E.end()); // sort by w
39     // sort(E.begin(), E.end(), cmp);
40
41     // two edge in the same tree or not
42     for (auto it: E){
43         it.s = Find(it.s);
44         it.t = Find(it.t);
45         if (Uni(it.s, it.t)){
46             cost = cost + it.w;;
47         }
48     }
49 }
50
51 int main(){
52
53     // create N space and initial -1
54     parent = vector<int> (N, -1);
55
56     for(i = 0; i < M; i++){
57         cin >> u >> v >> w;
58         E.push_back({u, v, w});
59     }
60
61     Kruskal();
62
63     return 0;
64 }

```

1.5 Floyd-Warshall

```

1 for (k = 0; k < n; k++){

```

```

2 |   for (i = 0; i < n; i++){
3 |       for (j = 0; j < n; j++){
4 |           w[i][j] = w[j][i] = min(w[i][j],
                                   max(w[i][k], w[k][j]));

```

1.6 Dijkstra

```

1 | struct edge {
2 |     int s, t;
3 |     LL d;
4 |     edge(){};
5 |     edge(int s, int t, LL d) : s(s), t(t), d(d) {}
6 | };
7 |
8 | struct heap {
9 |     LL d;
10 |    int p; // point
11 |    heap(){};
12 |    heap(LL d, int p) : d(d), p(p) {}
13 |    bool operator<(const heap &b) const { return d >
        b.d; }
14 | };
15 |
16 | int d[N], p[N];
17 | vector<edge> edges;
18 | vector<int> G[N];
19 | bitset<N> vis;
20 |
21 | void Dijkstra(int ss){
22 |
23 |     priority_queue<heap> Q;
24 |
25 |     for (int i = 0; i < V; i++){
26 |         d[i] = INF;
27 |     }
28 |
29 |     d[ss] = 0;
30 |     p[ss] = -1;
31 |     vis.reset() : Q.push(heap(0, ss));
32 |     heap x;
33 |
34 |     while (!Q.empty()){
35 |
36 |         x = Q.top();
37 |         Q.pop();
38 |         int p = x.p;
39 |
40 |         if (vis[p])
41 |             continue;
42 |         vis[p] = 1;
43 |
44 |         for (int i = 0; i < G[p].size(); i++){
45 |             edge &e = edges[G[p][i]];
46 |             if (d[e.t] > d[p] + e.d){
47 |                 d[e.t] = d[p] + e.d;
48 |                 p[e.t] = G[p][i];
49 |                 Q.push(heap(d[e.t], e.t));
50 |             }
51 |         }
52 |     }
53 | }

```

2 Number Theory

2.1 Modulo

- $(a + b) \bmod p = (a \bmod p + b \bmod p) \bmod p$
- $(a - b) \bmod p = (a \bmod p - b \bmod p + p) \bmod p$
- $(a * b) \bmod p = (a \bmod p * b \bmod p) \bmod p$
- $(a^b) \bmod p = ((a \bmod p)^b) \bmod p$

- $((a + b) \bmod p + c) \bmod p = (a + (b + c)) \bmod p$
- $((a * b) \bmod p * c) \bmod p = (a * (b * c)) \bmod p$
- $(a + b) \bmod p = (b + a) \bmod p$
- $(a * b) \bmod p = (b * a) \bmod p$
- $((a + b) \bmod p * c) = ((a * c) \bmod p + (b * c) \bmod p) \bmod p$
- $a \equiv b \pmod{m} \Rightarrow c * m = a - b, c \in \mathbb{Z}$
 $\Rightarrow a \equiv b \pmod{m} \Rightarrow m \mid a - b$
- $a \equiv b \pmod{c}, b \equiv d \pmod{c}$
 則 $a \equiv d \pmod{c}$
- $\begin{cases} a \equiv b \pmod{m} \\ c \equiv d \pmod{m} \end{cases} \Rightarrow \begin{cases} a \pm c \equiv b \pm d \pmod{m} \\ a * c \equiv b * d \pmod{m} \end{cases}$

2.2 Linear Sieve

```

1 | vector<int> p;
2 | bitset<MAXN> is_notp;
3 | void PrimeTable(int n){
4 |
5 |     is_notp.reset();
6 |     is_notp[0] = is_notp[1] = 1;
7 |
8 |     for (int i = 2; i <= n; ++i){
9 |         if (!is_notp[i]){
10 |             p.push_back(i);
11 |         }
12 |         for (int j = 0; j < (int)p.size(); ++j){
13 |             if (i * p[j] > n){
14 |                 break;
15 |             }
16 |
17 |             is_notp[i * p[j]] = 1;
18 |
19 |             if (i % p[j] == 0){
20 |                 break;
21 |             }
22 |         }
23 |     }
24 | }

```

2.3 Prime Factorization

```

1 | void primeFactorization(int n){
2 |     for(int i = 0; i < (int)p.size(); i++){
3 |         if(p[i] * p[i] > n){
4 |             break;
5 |         }
6 |         if(n % p[i]){
7 |             continue;
8 |         }
9 |         cout << p[i] << ' ';
10 |        while(n % p[i] == 0){
11 |            n /= p[i];
12 |        }
13 |    }
14 |    if(n != 1){
15 |        cout << n << ' ';
16 |    }
17 |    cout << '\n';
18 | }

```

2.4 Exponentiating by Squaring

```

1 | T pow(int a, int b, int c){ // calculate a ^ b % c
2 |     T ans = 1, tmp = a;
3 |     for (; b; b >>= 1) {
4 |         if (b & 1){ // b is odd
5 |             ans = ans * tmp % c;
6 |         }

```

```

7 |         tmp = tmp * tmp % c;
8 |     }
9 |     return ans;
10| }

```

2.5 Euler

```

1 | int Phi(int n){
2 |     int ans = n;
3 |     for (int i: p) {
4 |         if (i * i > n){
5 |             break;
6 |         }
7 |         if (n % i == 0){
8 |             ans /= i;
9 |             ans *= i - 1;
10|            while (n % i == 0){
11|                n /= i;
12|            }
13|        }
14|    }
15|    if (n != 1) {
16|        ans /= n;
17|        ans *= n - 1;
18|    }
19|    return ans;
20| }

```

3 Dynamic Programming

3.1 Fibonacci

```

1 | // f(n) = f(n - 1) + f(n - 2)
2 | // f(0) = 0, f(1) = 1
3 | int dp[30];
4 | int f(int n){
5 |     if (dp[n] != -1){
6 |         return dp[n];
7 |     }
8 |     return dp[n] = f(n - 1) + f(n - 2);
9 | }
10|
11| int main(){
12|     memset(dp, -1, sizeof(dp));
13|     dp[0] = 0;
14|     dp[1] = 1;
15|     cout << f(25) << '\n';
16| }

```

3.2 Pascal Triangle

```

1 | // init: f(i, 0) = f(i, i) = 1
2 | // trans: f(i, j) = f(i - 1, j) + f(i - 1, j - 1)
3 | int main(){
4 |     int dp[30][30];
5 |     memset(dp, 0, sizeof(dp));
6 |     for (int i = 0; i < 30; ++i){
7 |         dp[i][0] = dp[i][i] = 1;
8 |     }
9 |     for (int i = 1; i < 30; ++i){
10|        for (int j = 1; j < 30; ++j){
11|            dp[i][j] = dp[i - 1][j] + dp[i - 1][j - 1];
12|        }
13|    }
14| }

```

3.3 Robot

```

1 | // f(1, j) = f(i, 1) = 1
2 | // f(i, j) = f(i - 1, j) + f(i, j - 1)
3 | int dp[105][105];
4 | dp[1][1] = 1;
5 | for(int i = 1; i <= 100; ++i){
6 |     for(int j = 1; j <= 100; ++j){
7 |         if(i + 1 <= 100) dp[i + 1][j] += dp[i][j];
8 |         if(j + 1 <= 100) dp[i][j + 1] += dp[i][j];
9 |     }
10| }

```

3.4 Max Interval Sum

```

1 | // No Limit
2 | int ans = A[1];
3 | sum[1] = dp[1] = A[1];
4 |
5 | for(int i = 2; i <= n; ++i){
6 |     sum[i] = A[i] + sum[i - 1];
7 |     dp[i] = min(dp[i - 1], sum[i]);
8 |     ans = max(ans, sum[i] - dp[i - 1]);
9 | }
10|
11| // length <= L
12| int a[15] = {0, 6, -8, 4, -10, 7, 9, -6, 4, 5, -1};
13| int sum[15];
14|
15| int main(){
16|     int L = 3, ans = 0;
17|     for (int i = 1; i <= 10; ++i)
18|     {
19|         sum[i] = a[i] + sum[i - 1];
20|     }
21|     deque<int> dq;
22|     dq.push_back(0);
23|     for (int i = 1; i <= 10; ++i){
24|         if (i - dq.front() > L){
25|             dq.pop_front();
26|         }
27|         ans = max(ans, sum[i] - sum[dq.front()]);
28|         while(!dq.empty() && sum[i] < sum[dq.back()]){
29|             dq.pop_back();
30|         }
31|         dq.push_back(i);
32|     }
33|     cout << ans << '\n';
34| }

```

3.5 Max Area

```

1 | const int N = 25;
2 |
3 | int main(){
4 |     int n;
5 |     cin >> n;
6 |     vector<int> H(n + 5), L(n + 5), R(n + 5);
7 |     for (int i = 0; i < n; ++i){
8 |         cin >> H[i];
9 |     }
10|    stack<int> st;
11|    // calculate R[]
12|    for (int i = 0; i < n; ++i){
13|        while (!st.empty() && H[st.top()] > H[i]){
14|            R[st.top()] = i - 1;
15|            st.pop();
16|        }
17|        st.push(i);
18|    }
19|    while (!st.empty()){
20|        R[st.top()] = n - 1;
21|        st.pop();

```

```
22 |     }
23 |     // calculate L[]
24 |     for (int i = n - 1; i >= 0; --i){
25 |         while (!st.empty() && H[st.top()] > H[i]){
26 |             L[st.top()] = i + 1;
27 |             st.pop();
28 |         }
29 |         st.push(i);
30 |     }
31 |     while (!st.empty()){
32 |         L[st.top()] = 0;
33 |         st.pop();
34 |     }
35 |     int ans = 0;
36 |     for (int i = 0; i < n; ++i){
37 |         ans = max(ans, H[i] * (R[i] - L[i] + 1));
38 |         cout << i << ' ' << L[i] << ' ' << R[i] <<
39 |             '\n';
40 |     }
41 |     cout << ans << '\n';
41 | }
```