# Chaos for Linear Fractal Transformations of Shifts

#### Lucas Hawk

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#### 1 Theorem 1

The following is a well known criterion for chaos, known as the Eigenvalue Criterion. [2,3] provide proofs for the Criterion, and [9,10,12,14,15] provide examples using the Criterion.

**Theorem 1.** Let  $T: X \to X$  be an operator on a separable complex Banach space X. Consider the subspaces

$$\begin{split} X_0 &:= \mathrm{Span}\{\mathbf{x} \in \mathbf{X} : \mathbf{T}(\mathbf{x}) = \lambda \mathbf{X} \text{ for some } \lambda \in \mathbb{C}\mathrm{with}|\lambda| < 1\}, \\ Y_0 &:= \mathrm{Span}\{\mathbf{x} \in \mathbf{X} : \mathbf{T}(\mathbf{x}) = \lambda \mathbf{X} \text{ for some } \lambda \in \mathbb{C}\mathrm{with}|\lambda| > 1\}, \\ Z_0 &:= \mathrm{Span}\{\mathbf{x} \in \mathbf{X} : \mathbf{T}(\mathbf{x}) = \mathrm{e}^{\alpha\pi\mathrm{i}}\mathbf{x} \text{ for some } \alpha \in \mathbb{Q}\}. \end{split}$$

If  $X_0, Y_0$ , and  $Z_0$  are all dense in X, then T is chaotic.

Since the set of eigenvalues  $\sigma_p(B) = \mathbb{D}$  in our framework, this Criterion says that  $\varphi(B)$  is chaotic on  $l^p$  if and only if  $\varphi(\mathbb{D})$  intersects the unit circle.

## 2 Lemma 2

The following result gives a geometrical description of  $\varphi(\mathbb{D})$  when the pole of  $\varphi$  lies outside the closed unit disc.

**Lemma 2.** Let  $\varphi$  be a linear fractional transformation(LFT) with  $c \neq 0$  and |d| > |c|. Then  $\varphi(\mathbb{D})$  is the disc  $P + r\mathbb{D}$  with center P and radius r given by

$$P = \frac{b\bar{d} - a\bar{c}}{|d|^2 - |c|^2}, \ r = \frac{|bc - ad|}{|d|^2 - |c|^2}.$$

*Proof.* Note that LFTs map circles and lines to circles and lines. Indeed, if f is a LFT and E is a circle or a line in  $\mathbb{C}$ , the image of E, f(E), is mapped to a line if it passes through the pole. If E avoids the pole, f(E) is a circle.

Observe that  $\overline{\mathbb{D}} = \{z : |z| \leq 1\}$  (i.e. the closure of  $\mathbb{D}$ ) is clearly a bounded and convex set. Because we imposed that |d| > |c|, we have that |d/c| > 1 and so the pole at z = -d/c lies outside of  $\overline{\mathbb{D}}$ . Since LFTs are conformal at every point except at the pole,  $\varphi(\overline{\mathbb{D}})$  must be bounded and convex. Furthermore,  $\varphi(\overline{\mathbb{D}})$  is a circle whose boundary is  $\varphi(\partial \mathbb{D})$ , where  $\partial \mathbb{D}$  denotes the boundary of  $\mathbb{D}$ .

Now, take three distinct points in the unit circle. We choose  $z_1=1, z_2=-1$ , and  $z_3=i$  as they are three very simple points on the unit circle. Since  $\varphi$  is linear, it is also one-to-one. Thus,  $A=f(z_1), B=f(z_2)$ , and  $C=f(z_3)$  are three distinct points. Since  $z_1, z_2$ , and  $z_3$  are on the unit circle which is equivalent to  $\partial \mathbb{D}$ , A, B, and C are in fact three distinct points in the circle  $\varphi(\partial \mathbb{D})$ . That is, circle circumscribed over A, B, and C coincides with  $\varphi(\partial \mathbb{D})$ .

To verify that  $\varphi(\partial \mathbb{D})$  indeed has center P and radius r, we just need to show that

$$|A - P| = |B - P| = |C - P| = r.$$

For this, we use the equalities  $|z|^2=z\bar{z}$ , and  $|c+d|=|\bar{c}+\bar{d}|$ . So, we have

$$\begin{split} |A-P| &= \left| \frac{a+b}{c+d} - \frac{b\bar{d} - a\bar{c}}{|d|^2 - |c|^2} \right| \\ &= \frac{1}{|d|^2 - |c|^2} \left| \frac{(a+b)(|d|^2 - |c|^2) - (b\bar{d} - a\bar{c})(c+d)}{c+d} \right| \\ &= \frac{1}{|d|^2 - |c|^2} \left| \frac{ad\bar{d} - bc\bar{c} - bc\bar{d} + ad\bar{c}}{c+d} \right|, \text{ by using the first equality} \\ &= \frac{1}{|d|^2 - |c|^2} \left| \frac{(\bar{c} + \bar{d})(bc - ad)}{c+d} \right| \\ &= \frac{1}{|d|^2 - |c|^2} \left( \frac{|\bar{c} + \bar{d}||bc - ad|}{|c+d|} \right) \\ &= \frac{1}{|d|^2 - |c|^2} \left( \frac{|c+d||bc - ad|}{|c+d|} \right), \text{ by using the second equality} \\ &= \frac{bc - ad}{|d|^2 - |c|^2} \\ &= r. \end{split}$$

Showing |B - P| = r is analogous:

$$|B - P| = \left| \frac{-a + b}{-c + d} - \frac{b\bar{d} - a\bar{c}}{|d|^2 - |c|^2} \right|$$

$$= \frac{1}{|d|^2 - |c|^2} \left| \frac{(-a + b)(|d|^2 - |c|^2) - (b\bar{d} - a\bar{c})(-c + d)}{-c + d} \right|$$

$$= \frac{1}{|d|^2 - |c|^2} \left| \frac{-ad\bar{d} - bc\bar{c} + bc\bar{d} + ad\bar{c}}{-c + d} \right|, \text{ by using the first equality}$$

$$= \frac{1}{|d|^2 - |c|^2} \left| \frac{(-\bar{c} + \bar{d})(bc - ad)}{-c + d} \right|$$

$$= \frac{1}{|d|^2 - |c|^2} \left( \frac{|-\bar{c} + \bar{d}||bc - ad|}{|-c + d|} \right)$$

$$= \frac{1}{|d|^2 - |c|^2} \left( \frac{|-c + d||bc - ad|}{|-c + d|} \right), \text{ by using the second equality}$$

$$= \frac{bc - ad}{|d|^2 - |c|^2}$$

$$= r$$

Using a third equality,  $|ci + d| = |\bar{c} + \bar{d}i|$ , we have

$$|C - P| = \left| \frac{ai + b}{ci + d} - \frac{b\bar{d} - a\bar{c}}{|d|^2 - |c|^2} \right|$$

$$= \frac{1}{|d|^2 - |c|^2} \left| \frac{(ai + b)(|d|^2 - |c|^2) - (b\bar{d} - a\bar{c})(ci + d)}{ci + d} \right|$$

$$= \frac{1}{|d|^2 - |c|^2} \left| \frac{ad\bar{d}i - bc\bar{c} - bc\bar{d}i + ad\bar{c}}{ci + d} \right|, \text{ by using the first equality}$$

$$= \frac{1}{|d|^2 - |c|^2} \left| \frac{(\bar{c} + \bar{d}i)(ad - bc)}{ci + d} \right|$$

$$= \frac{1}{|d|^2 - |c|^2} \left( \frac{|\bar{c} + \bar{d}i||ad - bc|}{|ci + d|} \right)$$

$$= \frac{1}{|d|^2 - |c|^2} \left( \frac{|ci + d||ad - bc|}{|ci + d|} \right), \text{ by using the third equality}$$

$$= \frac{bc - ad}{|d|^2 - |c|^2}$$

$$= r.$$

Hence the circle circumscribed over the points A, B, and C indeed has center P and radius r. Thus  $\varphi(\partial \mathbb{D})$  has center P and radius r. Thus  $\varphi(\mathbb{D})$  is the disc  $P + r\mathbb{D}$ .

## 3 Theorem 3

In [10], DeLaubenfels and Emamirad showed that, for a non-constant polynomial P(z), P(B) (where B is the backwards shift operator) is chaotic on  $l^p, 1 \leq p \leq \infty$  whenever  $P(\mathbb{D})$  intersects the unit disc. We provide a generalization of this result which can be applied to Linear Fractional Transformations.

**Theorem 3.** Let  $\varphi$  be a LFT with  $c \neq 0$  and |d| > |c|. The operator  $\varphi(B)$  is chaotic if and only if

$$||d|^2 - |c|^2 - |b\bar{d} - a\bar{c}| < |bc - ad||.$$

*Proof.* We showed in Lemma 2 that  $\varphi(\mathbb{D}) = P + r\mathbb{D}$  with center P and radius r given where

$$P = \frac{b\bar{d} - a\bar{c}}{|d|^2 - |c|^2}, \ r = \frac{|bc - ad|}{|d|^2 - |c|^2}.$$

Theorem 1, the Eigenvalue Criterion, showed that  $\varphi(B)$  is chaotic on  $l^p$  if and only if  $\varphi(\mathbb{D})$  intersects the unit circle. So, we have that  $\varphi(B)$  is chaotic if and only if the disc  $P + r\mathbb{D}$  intersects the unit circle.

In order for the disc to intersect the unit disc, we have two possibilities: the center of the disc P is contained within the unit circle, or P is outside the closed unit disc. If P is inside the unit disc, then |P| + |r| > 1; if P is outside the closed unit disc, then we must have |P| - |r| < 1.

These conditions lead to

$$-|r| < 1 - |P| < |r|.$$

After substituting in the values of P and r, we have

$$-\frac{|bc-ad|}{|d|^2-|c|^2}<1-\left|\frac{|b\bar{d}-a\bar{c}|}{|d|^2-|c|^2}\right|<\frac{|bc-ad|}{|d|^2-|c|^2}.$$

Multiplying by  $|d|^2 - |c|^2$  gives

$$-|bc - ad| < |d|^2 - |c|^2 - |b\bar{d} - a\bar{c}| < |bc - ad|.$$

So finally, we have

$$||d|^2 - |c|^2 - |b\bar{d} - a\bar{c}|| < |bc - ad|.$$

So, we have shown that if  $\varphi(B)$  is chaotic, then  $\left| |d|^2 - |c|^2 - |b\bar{d} - a\bar{c}| \right| < |bc - ad|$ . The other direction is completely analogous. It requires the exact same algebra, done in reverse, to show that if  $\left| |d|^2 - |c|^2 - |b\bar{d} - a\bar{c}| \right| < |bc - ad|$ , then  $P + r\mathbb{D}$  intersects the unit circle, and thus  $\varphi(B)$  is chaotic.

### 4 Definitions

**Definition 1.** A metric space (X,d) is a set X and a function d(the distance function) which assigns a real number d(x,y) to every pair  $(x,y) \in X$ , which satisfies the following properties:

- 1.  $d(x, y) \ge 0$
- $2. \ d(x,y) = 0 \Rightarrow x = y.$
- 3. d(x, y) = d(y, x).
- 4.  $d(x,y) + d(y,z) \ge d(x,z)$ . This last property is called the triangle inequality.

**Definition 2.** A function f is topologically transitive iff for all nonempty open subsets U, V of X, there exists  $k \in \mathbb{N}$  such that  $f^k(U) \cap V$  is nonempty.

**Definition 3.** Let X be a topological space. A set Q is <u>dense</u> in X if for any point  $x \in X$  and for any  $\epsilon > 0$ , there exists a point in  $q \in Q$  such that the distance between x and q is less than  $\epsilon$ . In other words, a set Q is dense in X if every point in X is either in Q or is a limit point in Q.

**Definition 4.** A point x is said to be a <u>periodic point</u> of a function f if there exists an integer n such that  $f^n(x) = x$ . The least positive integer n for which this is true is the period of x.

**Definition 5.** Let (X,d) be a metric space. A function  $f: X \to X$  is said to be <u>chaotic</u> on X if it satisfies the following three conditions:

- 1. f is topologically transitive.
- 2. The set of periodic points in f is dense in X. That is, that every open set in f contains a periodic point.
- 3. f has sensitive dependence on initial conditions. That is,  $\exists \delta > 0$  such that for any open set U and for any  $x \in U$ , there exists a  $y \in U$  such that  $d(f^{[k]}(x), f^{[k]}(y)) > \delta$  for some k.  $\delta$  is called a sensitivity constant.

**Definition 6.** A backward shift operator B operates on an element of a sequence to produce the previous element.

e.g. if 
$$X = \{x_1, x_2, \dots\}$$
, then  $B(X) = \{x_2, x_3, \dots\}$ .

**Definition 7.** Let  $z \in \mathbb{C}$ . That is, let z = x + yi, where x and y are real numbers. The <u>absolute value</u> or modulus of z, denoted |z| is given by

$$|z| = \sqrt{x^2 + y^2}.$$

**Definition 8.** The open unit disc of  $\mathbb{C}$ , denoted  $\mathbb{D}$ , is the region in the complex plane defined by

$$\mathbb{D} = \{ z \in \mathbb{C} : |z| < 1 \}.$$

**Definition 9.** A mapping T from a vector space  $V_1$  to a vector space  $V_2$ , i.e.  $T: V_1 \to V_2$ , is a linear transformation iff

$$T(c\vec{u} + c\vec{v}) = cT(\vec{u}) + cT(\vec{v}),$$

for all  $\vec{u}, \vec{v} \in V_1$ , and all  $c \in \mathbb{R}$ . The transformation is referred to as an <u>operator</u> if the mapping is from a vector space to itself.

**Definition 10.** Let  $U \subset \mathbb{C}$  be open and let  $f: U \to \mathbb{C}$ . If f is complex differentiable at every point in U, f is said to be holomorphic or on U.

**Definition 11.** A function f has a <u>pole</u> of order n at  $z_0$  if n is the smallest positive integer for which  $(z-z_0)^n f(z)$  is holomorphic at  $\overline{z_0}$ . A function f has a pole at infinity if  $\lim_{z\to\infty} f(z) = \infty$ .

**Definition 12.** A <u>Linear Fraction Transformation</u> is a function of the form

$$f(z) = \frac{az+b}{cz+d}$$

where  $a, b, c, d \in \mathbb{C}, ad \neq cb$ .

**Definition 13.** A vector space is a set that is closed under finite vector addition and scalar muliplication. A vector space V is complete is every Cauchy sequence of points in V converges to a point in V.

**Definition 14.** Let V be a complex vector space. A norm on V is a function

$$||\cdot||:V\to\mathbb{R}$$

that satisfies the following conditions:

- 1.  $||\vec{v}|| \ge 0, \forall \vec{c} \in V, and ||\vec{v}|| = 0 \Leftrightarrow \vec{v} = 0;$
- 2.  $||\alpha \vec{v}|| = |\alpha| ||\vec{v}||, \forall \vec{v} \in V, \alpha \in \mathbb{C};$
- 3.  $||\vec{v} + \vec{w}|| \le ||\vec{v}|| + ||\vec{w}||, \forall \vec{v}, \vec{w} \in V.$

A vector space equipped with a norm is called a normed vector space.

**Definition 15.** A Banach space is a complete normed vector space.