Mechanism design: Multi-parameter environments

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Our goals:

- Incentivize the agents to truthfully report their values
- Choose an outcome that maximizes the social welfare

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- In general, the agents might have different values for the possible winners of the item

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- Each agent i has a private value $v_i(S)$ for every possible bundle $S \subseteq M$ of items
 - Each agent i has 2^m parameters

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• Payment rule: For a set of functions h_1, \dots, h_n such that h_i is independent of the bid of agent i,

$$p_i(\boldsymbol{b}) = h_i(\boldsymbol{b}_{-i}) - \sum_{j \neq i} b_j(\boldsymbol{x}(\boldsymbol{b}))$$

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$$\begin{aligned} u_i(\boldsymbol{b}) &= v_i\big(\boldsymbol{x}(\boldsymbol{b})\big) - p_i(\boldsymbol{b}) \\ &= v_i\big(\boldsymbol{x}(\boldsymbol{b})\big) - \left(h_i(\boldsymbol{b}_{-i}) - \sum_{j \neq i} b_j\big(\boldsymbol{x}(\boldsymbol{b})\big)\right) \\ &= v_i\big(\boldsymbol{x}(\boldsymbol{b})\big) + \sum_{j \neq i} b_j\big(\boldsymbol{x}(\boldsymbol{b})\big) \underbrace{\left(h_i(\boldsymbol{b}_{-i})\right)}_{\text{independent of } b_i} \end{aligned}$$

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• The utility of agent *i* is

$$u_{i}(\mathbf{b}) = v_{i}(\mathbf{x}(\mathbf{b})) - p_{i}(\mathbf{b})$$

$$= v_{i}(\mathbf{x}(\mathbf{b})) - \left(h_{i}(\mathbf{b}_{-i}) - \sum_{j \neq i} b_{j}(\mathbf{x}(\mathbf{b}))\right)$$

$$= v_{i}(\mathbf{x}(\mathbf{b})) + \sum_{j \neq i} b_{j}(\mathbf{x}(\mathbf{b})) + h_{i}(\mathbf{b}_{-i})$$
independent of b_{i}

The social welfare according to the true value of agent i and the bids of the other agents

 Agent i cares about the welfare of all agents (based on the reported valuations) and aims to maximize the quantity

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- Therefore every agent i truthfully reports her true values
- The mechanism is designed so that the incentives of the agents are aligned with the goal of maximizing the social welfare

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- We would like to have reasonable payment rules, that satisfy a couple of properties:
 - Individual rationality: Every agent has non-negative utility, and therefore incentive to participate
 - No positive transfers: The mechanism does not pay the agents,
 the agents pay the mechanism

Clarke payments: define

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- The payment of agent i is the difference between the maximum social welfare of the other agents when she does not participate, and the social welfare when she participates
- Agent i pays the loss in welfare due to her participation

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No positive transfers:

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Drawbacks of VCG mechanisms

- Preference elicitation: VCG mechanisms demand from each agent to communicate her values for every possible outcome
 - Not practical in many situations: communicating 2^m parameters in the case of combinatorial auctions is impossible, even for small m

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 - Not practical in many situations: communicating 2^m parameters in the case of combinatorial auctions is impossible, even for small m
- Social welfare maximization might be a hard problem
- Knapsack auctions:
 - each agent i demands w_i items and has a private value v_i
 - the seller has a total amount of W items
 - Even though every agent has only one private parameter, maximizing the social welfare is equivalent to the Knapsack problem, which is NP-hard

Single-Minded Bidders

• Each bidder has a (private) set $T_i \in M$ and there is a private parameter $v_i \in \mathbb{R}^+$ s.t.

$$v_i(S) = \begin{cases} v_i & \text{if } S \supseteq T_i \\ 0 & \text{otherwise} \end{cases}$$

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- Next we will talk about the greedy mechanism ..

Sort the bidders s.t.

$$\frac{b_1}{\sqrt{|S_1|}} \ge \frac{b_2}{\sqrt{|S_2|}} \ge \cdots \frac{b_n}{\sqrt{|S_n|}}.$$

- $W = \emptyset$ (W is the set of agents which can get their S_i 's.)
- For i from 1 to n do: if $S_i \cap (\bigcup_{j \in W} S_j) = \emptyset$, add i to W.
- Return the allocation which gives S_i to player i iff $i \in W$.

We'll set $p_i = 0$ if $i \notin W$.

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$$p_i = \frac{b_{\alpha(i)}}{\sqrt{|S_{\alpha(i)}|/|S_i|}} = b_{\alpha(i)} \sqrt{\frac{|S_i|}{|S_{\alpha(i)}|}}$$

The Analysis

- The mechanism is polynomial time and outputs a valid allocation.
- Incentive Compatibility: monotonicity and critical payment
- Social Welfare Approximately.

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$$b_{\alpha(i)}\sqrt{\frac{|S_i|}{|S_{\alpha(i)}|}} = p_i.$$

Both Properties are Enough

Theorem

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Proof.

Fix player $i \in [n]$ and all bids other than i's. Let u(b,S) be the utility that player i would get by bidding (b,S), so $u(b,S) = v_i(S) - p_i(b,S)$. By the critical payment, we know $p_i(b,S) = \inf \{x: i \text{ wins with bid } (x,S)\}$.

- non-negative utility: 0 or $v_i p_i(b, T_i) \ge 0$.
- dominant strategy: $u(v_i, T_i) \ge u(b, T_i) \ge u(b, S)$ for all (b, S) with $T_i \subseteq S$ and (b, S) is a winning bid. (Why?)



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- So for the first part, we just need to show $p_i(b,T_i) \leq p_i(b,S)$. Holds by the monotonicity property and $T_i \subseteq S$.
- $u(v_i,T_i)=u(b,T_i)$ when (v_i,T_i) is a winning bid, since (b,T_i) is a winning bid; $p_i(b,T_i)\geq v_i$ if (v_i,T_i) is not a winning bid.

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$$\sum_{j \in \mathsf{OPT}_i} v_j \leq \frac{v_i}{\sqrt{|T_i|}} \sum_{j \in \mathsf{OPT}_i} \sqrt{|T_j|} \leq \frac{v_i}{\sqrt{|T_i|}} \sqrt{|\mathsf{OPT}_i|} \sqrt{\sum_{j \in \mathsf{OPT}_i} |T_j|}.$$

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$$\sum_{i \in \mathsf{OPT}} v_i \leq \sum_{i \in W} \sum_{j \in \mathsf{OPT}_i} v_j \leq \sum_{i \in W} v_i \sqrt{m} = \sqrt{m} \sum_{i \in W} v_i.$$