

## 第12章 并发编程

同步: 高级/Synchronization: Advanced

100076202: 计算机系统导论



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## The state of the s

## 议题 Today

- 回顾:信号量、互斥和生产者-消费者 Review: Semaphores, mutexes, producer-consumer
- 使用信号量调度共享资源 Using semaphores to schedule shared resources
  - 读者-写者问题 Readers-writers problem
- 其它并发问题 Other concurrency issues
  - 线程安全 Thread safety
  - 竞争 Races
  - 死锁 Deadlocks
  - 线程和信号处理之间交互 Interactions between threads and signal handling

### 提醒:信号量

### **Reminder: Semaphores**



- Semaphore: non-negative global integer synchronization variable
- Manipulated by P and V operations:
  - P(s): [ while (s == 0); s--; ]
    - Dutch for "Proberen" (test)
  - *V(s):* [ **s++**; ]
    - Dutch for "Verhogen" (increment)
- OS kernel guarantees that operations between brackets [] are executed atomically
  - Only one P or V operation at a time can modify s.
  - When while loop in P terminates, only that P can decrement s
- Semaphore invariant: (s >= 0)

### 回顾:使用信号量通过互斥保护共享资源 Povious Using somanhores to protect

## Review: Using semaphores to protect shared resources via mutual exclusion

- 基本思想: Basic idea:
  - 将一个唯一的信号量互斥锁(mutex)(最初为1)与每个共享变量(或相关的共享变量集)相关联 Associate a unique semaphore mutex, initially 1, with each shared variable (or related set of shared variables)
  - 用P(mutex)和V(mutext)操作包围对共享变量的每次访问 Surround each access to the shared variable(s) with *P(mutex)* and *V(mutex)* operations

```
mutex = 1
P(mutex)
cnt++
V(mutex)
```

### 回顾: 使用锁进行互斥

### **Review: Using Lock for Mutual Exclusion**

- 基本思想: Basic idea:
  - 互斥锁Mutex是只有值0(锁定)或1(解锁)的信号量的特殊情况 Mutex is special case of semaphore that only has value 0 (locked) or 1 (unlocked)
  - Lock(m): [ while (m == 0); m=0; ]
  - Unlock(m): [ m=1]
  - 比使用信号量快约2倍 ~2x faster than using semaphore for this purpose
  - 而且,更清楚地表明程序员的意图 And, more clearly indicates programmer's intention

```
mutex = 1
lock(mutex)
cnt++
unlock(mutex)
```

## 关于示例的注释 Note about Examples

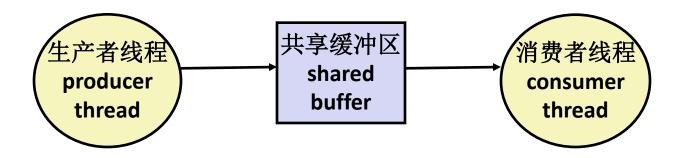


- 课程示例将使用信号量进行计数和互斥 Lecture examples will use semaphores for both counting and mutual exclusion
  - 代码比使用pthread\_mutex短得多 Code is much shorter than using pthread\_mutex

## 回顾: 生产者-消费者问题

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#### **Review: Producer-Consumer Problem**

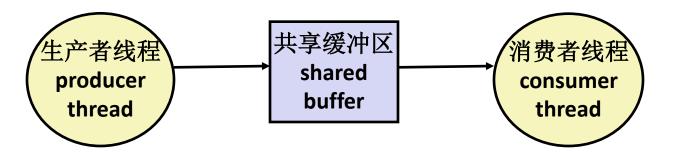


- 通用同步模式:Common synchronization pattern:
  - 生产者等待空槽位,将项目插入缓冲区,并通知消费者 Producer waits for empty slot, inserts item in buffer, and notifies consumer
  - 消费者等待**项目**,将其从缓冲区中删除,并通知生产者 Consumer waits for *item*, removes it from buffer, and notifies producer

## 回顾: 生产者-消费者问题

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#### **Review: Producer-Consumer Problem**



#### ■ 示例 Examples

- 多媒体处理: Multimedia processing:
  - 生产者创建视频帧,消费者对其进行渲染 Producer creates video frames, consumer renders them
- 事件驱动的图形用户界面 Event-driven graphical user interfaces
  - 生产者检测鼠标点击、鼠标移动和键盘点击,并在缓冲区中插入相应的事件 Producer detects mouse clicks, mouse movements, and keyboard hits and inserts corresponding events in buffer
  - 消费者从缓冲区检索事件并绘制显示 Consumer retrieves events from buffer and paints the display

# 回顾: 使用信号量协调共享资源的访问 Review: Using Semaphores to Coordinate Access to Shared Resources

- 基本思想:线程使用信号量操作通知另一个线程某些条件已变为真 Basic idea: Thread uses a semaphore operation to notify another thread that some condition has become true
  - 使用计数信号量来跟踪资源状态 Use counting semaphores to keep track of resource state.
  - 使用二元信号量通知其他线程 Use binary semaphores to notify other threads.

## 回顾: 使用信号量协调共享资源的访问

## Review: Using Semaphores to Coordinate Access to Shared Resources

- 生产者-消费者问题 The Producer-Consumer Problem
  - 对进程之间的交互活动进行协调,一个进程产生信息,另一个 进使用该信息 Mediating interactions between processes that generate information and that then make use of that information
  - 用两个二元信号量实现单条目缓冲区 Single entry buffer implemented with two binary semaphores
    - 一个用于控制生产者的访问 One to control access by producer(s)
    - 一个用于控制消费者的访问 One to control access by consumer(s)
  - 使用信号量+环形缓冲区实现N个条目缓冲区 N-entry implemented with semaphores + circular buffer

## New York

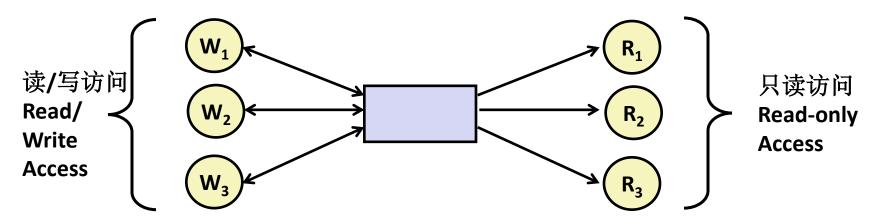
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## 读者和写者问题

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#### **Readers-Writers Problem**

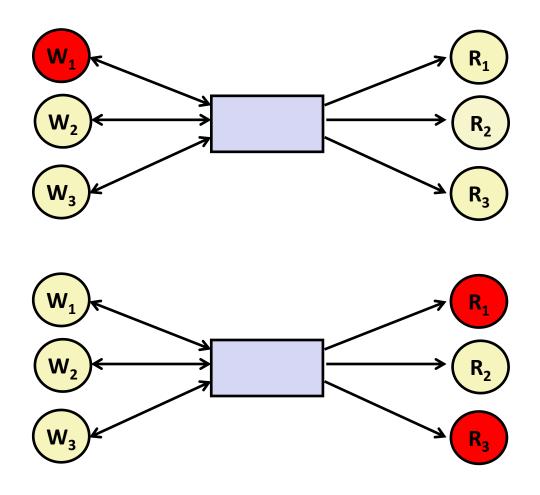


- 问题陈述: Problem statement:
  - *读者*线程仅读取对象 *Reader* threads only read the object
  - *写者*线程修改对象(读/写访问) *Writer* threads modify the object (read/write access)
  - 写者必须具有对对象的独占访问权限 Writers must have exclusive access to the object
  - 无限数量的读者可以访问该对象 Unlimited number of readers can access the object
- 在真实系统中频繁发生,例如 Occurs frequently in real systems, e.g.,
  - 在线航空预订系统 Online airline reservation system
  - 多线程缓存Web代理 Multithreaded caching Web proxy

## 读者/写者示例

## **Readers/Writers Examples**





### 读者和写者的变体 Variants of Readers-Writers

- 第一类读者-写者问题(有利于读者-读者优先)First readers-writers problem (favors readers)
  - 除非已授予写者使用对象的权限,否则不应让任何读者等待 No reader should be kept waiting unless a writer has already been granted permission to use the object.
  - 等待写者之后到达的读者比写者优先 A reader that arrives after a waiting writer gets priority over the writer.
- 第二类读者-写者问题(有利于写者-写者优先) Second readers-writers problem (favors writers)
  - 一旦写者准备好写入,它将尽快执行写入 Once a writer is ready to write, it performs its write as soon as possible
  - 在写者之后到达的读者必须等待,即使写者也要等待 A reader that arrives after a writer must wait, even if the writer is also waiting.
- 在这两种情况下都有可能出现饿死情况(线程无限期等待) *Starvation* (where a thread waits indefinitely) is possible in both cases.

#### Solution to First Readers-Writers Problem

#### 读者 Readers:

```
int readcnt; /* Initially 0 */
sem t mutex, w; /* Both initially 1 */
void reader (void)
  while (1) {
   P(&mutex);
    readcnt++;
    if (readcnt == 1) /* First in */
     P(&w);
   V(&mutex);
    /* Reading happens here */
    P(&mutex);
    readcnt--;
    if (readcnt == 0) /* Last out */
     V(\&w);
   V(&mutex);
```

#### 写者 Writers:

```
void writer(void)
{
  while (1) {
    P(&w);

    /* Writing here */

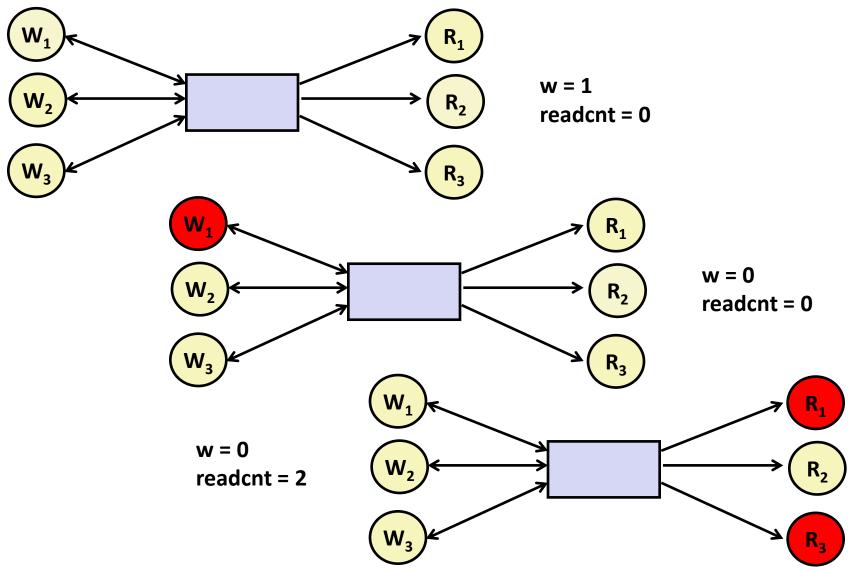
    V(&w);
  }
}
```

rw1.c

## 读者/写者示例

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## **Readers/Writers Examples**



#### Solution to First Readers-Writers Problem

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到达: Arrivals: R1 R2 W1 R3

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Readcnt == 1 W == 0

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```

rw1.c

到达: Arrivals: R1 R2 W1 R3

Readcnt == 2 W == 0

#### Solution to First Readers-Writers Problem

#### 读者 Readers:

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int readcnt; /* Initially 0 */
sem t mutex, w; /* Both initially 1 */
void reader (void)
 while (1) {
   P(&mutex);
    readcnt++;
    if (readcnt == 1) /* First in */
     P(&w);
   V(&mutex);
     * Reading happens here */
    P(&mutex);
    readcnt--;
    if (readcnt == 0) /* Last out */
     V(\&w);
   V(&mutex);
```

#### 写者 Writers:

```
void writer(void)
{
  while (1) {
    P(&w);

    /* Writing here */

    V(&w);
  }
}
```

rw1.c

到达: Arrivals: R1 R2 W1 R3

Readcnt == 2 W == 0

#### Solution to First Readers-Writers Problem

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   V(&mutex);
     * Reading happens here */
    P(&mutex);
    readcnt--;
    if (readcnt == 0) /* Last out */
     V(\&w);
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```

#### 写者 Writers:

```
void writer(void)
{
  while (1) {
    P(&w);

  /* Writing here */

    V(&w);
  }
}
```

rw1.c

到达: Arrivals: R1 R2 W1 R3

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#### Solution to First Readers-Writers Problem

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    P(&mutex);
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    P(&mutex);
    readcnt--;
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```

#### 写者 Writers:

```
void writer(void)
{
  while (1) {
    P(&w);

    /* Writing here */

    V(&w);
  }
}
```

rw1.c

到达: Arrivals: R1 R2 W1 R3

Readcnt == 1 W == 0

#### Solution to First Readers-Writers Problem

#### 读者 Readers:

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int readcnt; /* Initially 0 */
sem t mutex, w; /* Both initially 1 */
void reader(void)
  while (1) {
   P(&mutex);
    readcnt++;
    if (readcnt == 1) /* First in */
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   V(&mutex);
    /* Reading happens here */
    P(&mutex);
    readcnt--;
    if (readcnt == 0) /* Last out */
     V(&w);
    √(&mutex);
```

#### 写者 Writers:

```
void writer(void)
{
  while (1) {
    P(&w);

    /* Writing here */

    V(&w);
  }
}
```

rw1.c

到达: Arrivals: R1 R2 W1 R3

Readcnt == 0 W == 1

## 其它读者-写者版本

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#### Other Versions of Readers-Writers

- 第一类解决方案的不足 Shortcoming of first solution
  - 源源不断的读者将无限期地阻止写者 Continuous stream of readers will block writers indefinitely
- 第二个版本 Second version
  - 一旦写者出现,就会阻止以后的读者访问 Once writer comes along, blocks access to later readers
  - 一系列写入可能会阻止所有读取 Series of writes could block all reads
- 先进先出实现 FIFO implementation
  - 请参阅code目录中的rwqueue代码 See rwqueue code in code directory
  - 按顺序接收服务请求 Service requests in order received
  - 保存线程在先进先出队列中 Threads kept in FIFO
  - 每一个都有信号量,可以访问临界区 Each has semaphore that enables its access to critical section

## 第二类读者-写者问题解决方案

#### **Solution to Second Readers-Writers Problem**

```
sem t rmutex, wmutex, r, w; // Initially 1
void reader(void)
 while (1) {
   P(&r);
   P(&rmutex);
   readcnt++;
   if (readcnt == 1) /* First in */
    P(&w);
   V(&rmutex);
   V(&r)
   /* Reading happens here */
   P(&rmutex);
   readcnt--;
   if (readcnt == 0) /* Last out */
     V(\&w);
   V(&rmutex);
```

## 第二类读者-写者问题解决方案

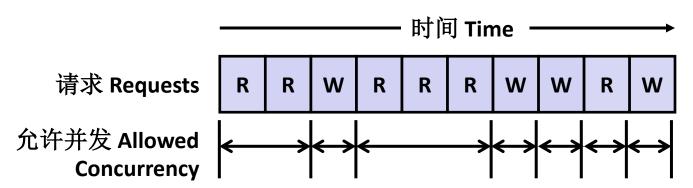
#### Solution to Second Readers-Writers Problem

```
void writer(void)
 while (1) {
    P(&wmutex);
    writecnt++;
    if (writecnt == 1)
        P(&r);
    V(&wmutex);
    P(&w);
    /* Writing here */
    V(&w);
    P(&wmutex);
    writecnt--;
    if (writecnt == 0);
        V(&r);
    V(&wmutex);
```

## 用先进先出队列管理读者/写者



### Managing Readers/Writers with FIFO



#### ■ 思想 Idea

- 读/写请求插入先进先出队列 Read & Write requests are inserted into FIFO
- 请求在从队列删除时进行处理 Requests handled as remove from FIFO
  - 如果当前空闲或正在处理读取,则允许继续读取 Read allowed to proceed if currently idle or processing read
  - 仅允许在空闲时继续写入请求 Write allowed to proceed only when idle
- 请求完成后通知控制器 Requests inform controller when they have completed

#### ■ 公平 Fairness

■ 保证最终会处理每个请求 Guarantee every request is eventually handled

## 读者写者先进先出实现



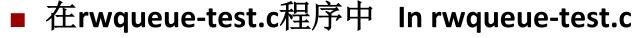
### **Readers Writers FIFO Implementation**

■ 完整代码见rwqueue.h和rwqueue.c Full code in rwqueue.{h,c}

```
/* Queue data structure */
typedef struct {
    sem_t mutex; // Mutual exclusion
    int reading_count; // Number of active readers
    int writing_count; // Number of active writers
    // FIFO queue implemented as linked list with tail
    rw_token_t *head;
    rw_token_t *tail;
} rw_queue_t;
```

### 读者写者先进先出队列使用

#### **Readers Writers FIFO Use**



```
/* Get write access to data and write */
void iwriter(int *buf, int v)
    rw token t tok;
    rw queue request write(&q, &tok);
    /* Critical section */
    *buf = v;
    /* End of Critical Section */
    rw queue release(&q);
                             /* Get read access to data and read */
                             int ireader(int *buf)
                                 rw token t tok;
                                 rw queue request read(&q, &tok);
                                 /* Critical section */
                                 int v = *buf;
                                 /* End of Critical section */
                                 rw queue release (&q);
                                 return v;
```

## 读者/写者锁的库函数

### Library Reader/Writer Lock



- 数据类型 Data type pthread\_rwlock\_t
- 操作 Operations
  - 获得读锁 Acquire read lock

```
Pthread rwlock rdlock (pthread rw lock t *rwlock)
```

■ 获得写锁 Acquire write lock

```
Pthread_rwlock_wrlock(pthread_rw_lock_t *rwlock)
```

■ 释放(其中一个)锁 Release (either) lock

```
Pthread_rwlock_unlock(pthread_rw_lock_t *rwlock)
```

- 观察 Observation
  - 必须正确使用库函数 Library must be used correctly!
    - 由程序员决定哪些需要读访问,哪些需要写访问 Up to programmer to decide what requires read access and what requires write access

## New York

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## 一个担忧: 竞争 One Worry: Races

■ 当程序的正确性取决于一个线程在另一个线程到达点y之前到达点x时,就会发生*竞争* A *race* occurs when correctness of the program depends on one thread reaching point x before another thread reaches point y

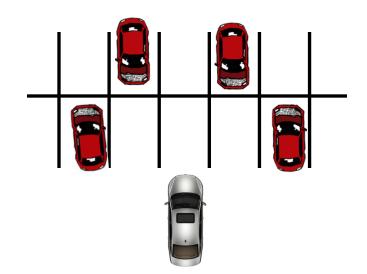
```
/* a threaded program with a race */
int main(int argc, char** argv) {
    pthread t tid[N];
    int i;
    for (i = 0; i < N; i++)
        Pthread create(&tid[i], NULL, thread, &i);
    for (i = 0; i < N; i++)
       Pthread join(tid[i], NULL);
    return 0;
/* thread routine */
void *thread(void *varqp) {
    int myid = *((int *)varqp);
    printf("Hello from thread %d\n", myid);
    return NULL;
```

## 数据竞争 Data Race













- 不要共享状态 Don't share state
  - 例如,使用malloc为每个线程生成单独的参数拷贝 E.g., use malloc to generate separate copy of argument for each thread
- 使用同步原语控制对共享状态的访问 Use synchronization primitives to control access to shared state
  - 不同的共享状态可能使用不同的原语 Different shared state can use different primitives

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### 一个担忧:死锁 A Worry: Deadlock

■ 定义: 当且仅当一个进程正在等待一个永远不会为真的条件,那么它就会*死锁* Def: A process is *deadlocked* iff it is waiting for a condition that will never be true.

#### ■ 典型场景 Typical Scenario

- 进程1和进程2需要两个资源(A和B)才能继续 Processes 1 and 2 needs two resources (A and B) to proceed
- 进程1获取A,等待B Process 1 acquires A, waits for B
- 进程2获取B,等待A Process 2 acquires B, waits for A
- 两个进程都将永远等待! Both will wait forever!



### 一个担忧:死锁 A Worry: Deadlock

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- 更全面的知识(超出了213课程的范围),死锁有四个要求 More fully (and beyond the scope of 213), a deadlock has four requirements
  - 互斥 Mutual exclusion
  - 循环等待 Circular waiting
  - 保持和等待 Hold and wait
  - 非抢占式 No pre-emption

### 信号量死锁 Deadlocking With Semaphores

```
int main(int argc, char** argv)
{
    pthread_t tid[2];
    Sem_init(&mutex[0], 0, 1); /* mutex[0] = 1 */
    Sem_init(&mutex[1], 0, 1); /* mutex[1] = 1 */
    Pthread_create(&tid[0], NULL, count, (void*) 0);
    Pthread_create(&tid[1], NULL, count, (void*) 1);
    Pthread_join(tid[0], NULL);
    Pthread_join(tid[1], NULL);
    printf("cnt=%d\n", cnt);
    return 0;
}
```

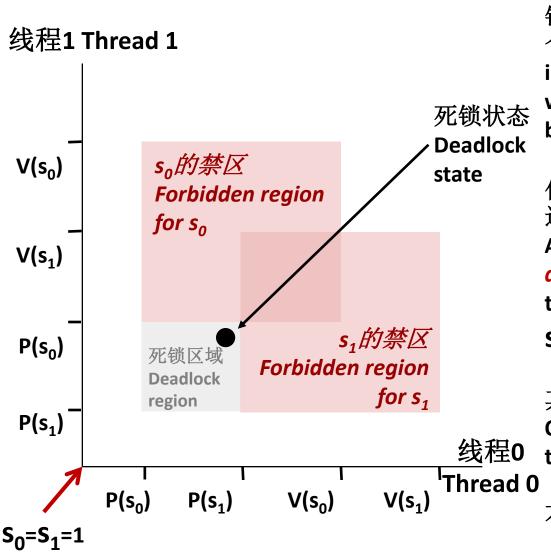
```
void *count(void *vargp)
{
    int i;
    int id = (int) vargp;
    for (i = 0; i < NITERS; i++) {
        P(&mutex[id]); P(&mutex[1-id]);
        cnt++;
        V(&mutex[id]); V(&mutex[1-id]);
    }
    return NULL;
}</pre>
```

```
Tid[0]: Tid[1]:
P(s<sub>0</sub>); P(s<sub>1</sub>);
P(s<sub>1</sub>); P(s<sub>0</sub>);
cnt++; V(s<sub>0</sub>); V(s<sub>1</sub>);
V(s<sub>1</sub>);
```

#### 进度图中显示的死锁

# - Comment of the comm

#### **Deadlock Visualized in Progress Graph**



锁定引入了*死锁*的可能性:等待一个永远不会成真的条件 Locking introduces the potential for *deadlock:* waiting for a condition that will never be true

任何进入*死锁区域*的轨迹将最终到 达*死锁状态*,等待s0或s1变为非零 Any trajectory that enters the *deadlock region* will eventually reach the *deadlock state*, waiting for either S<sub>0</sub> or S<sub>1</sub> to become nonzero

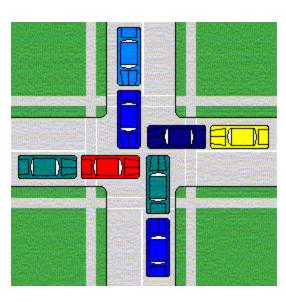
其他轨迹幸运地避开了死锁区域 Other trajectories luck out and skirt the deadlock region

不幸的事实: 死锁往往是不确定的 (竞争) Unfortunate fact: deadlock is often nondeterministic (race)









#### **Avoiding Deadlock**

Acquire shared resources in same order

```
int main(int argc, char** argv)
{
    pthread_t tid[2];
    Sem_init(&mutex[0], 0, 1); /* mutex[0] = 1 */
    Sem_init(&mutex[1], 0, 1); /* mutex[1] = 1 */
    Pthread_create(&tid[0], NULL, count, (void*) 0);
    Pthread_create(&tid[1], NULL, count, (void*) 1);
    Pthread_join(tid[0], NULL);
    Pthread_join(tid[1], NULL);
    printf("cnt=%d\n", cnt);
    return 0;
}
```

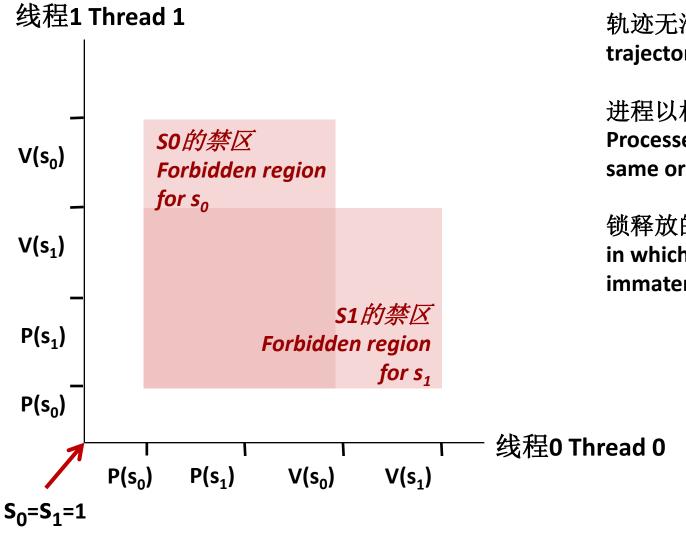
```
void *count(void *vargp)
{
    int i;
    int id = (int) vargp;
    for (i = 0; i < NITERS; i++) {
        P(&mutex[0]); P(&mutex[1]);
        cnt++;
        V(&mutex[id]); V(&mutex[1-id]);
    }
    return NULL;
}</pre>
```

```
Tid[0]: Tid[1]:
P(s<sub>0</sub>); P(s<sub>0</sub>);
P(s<sub>1</sub>); P(s<sub>1</sub>);
cnt++; Cnt++;
V(s<sub>0</sub>); V(s<sub>1</sub>);
V(s<sub>1</sub>);
```

### 在进度图中避免死锁

## The state of the s

#### **Avoided Deadlock in Progress Graph**



轨迹无法卡住 No way for trajectory to get stuck

进程以相同的顺序获取锁 Processes acquire locks in same order

锁释放的顺序无关紧要 Order in which locks released immaterial

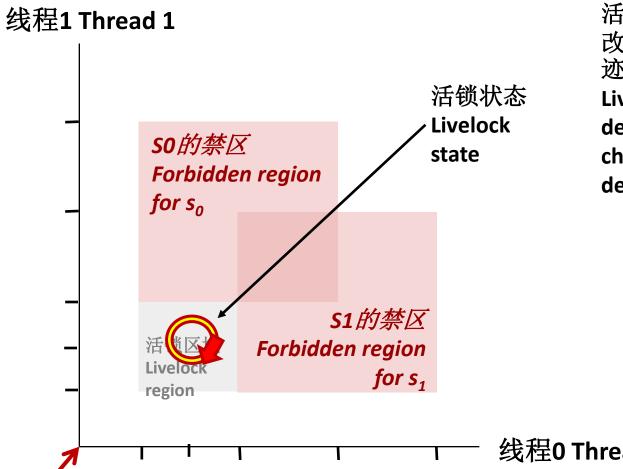


#### 演示 Demonstration

- 参见程序deadlock.c See program deadlock.c
- 100个线程,每个线程获得同样的两个锁 100 threads, each acquiring same two locks
- 风险模式 Risky mode
  - 偶数线程请求锁的顺序与奇数线程相反 Even numbered threads request locks in opposite order of odd-numbered ones
- 安全模式 Safe mode
  - 所有线程以相同的顺序获取锁 All threads acquire locks in same order

#### 在进度图中显示活锁

#### **Livelock Visualized in Progress Graph**



活锁类似于死锁,只是线程 改变状态,但仍处于死锁轨 迹中

Livelock is similar to a deadlock, except the threads change state, but remain in a deadlock trajectory.

线程0 Thread 0

#### 死锁、活锁、饿死

## The state of the s

#### Deadlock, Livelock, Starvation

#### ■ 死锁 Deadlock

■ 一个或多个线程正在等待一个永远不会为真的条件 One or more threads is waiting on a condition that will never be true

#### ■ 活锁 Livelock

■ 一个或多个线程正在更改状态,但永远不会离开死锁/活锁轨迹 One or more threads is changing state, but will never leave a deadlock / livelock trajectory

#### ■ 饿死 Starvation

■ 一个或多个线程暂时无法取得进展 One or more threads is temporarily unable to make progress

## The state of the s

### 议题 Today

- 回顾: 信号量、互斥和生产者-消费者 Review: Semaphores, mutexes, producer-consumer
- 使用信号量调度共享资源 Using semaphores to schedule shared resources
  - 读者-写者问题 Readers-writers problem
- 其它并发问题 Other concurrency issues
  - 竞争 Races
  - 死锁 Deadlocks
  - 线程安全 Thread safety
  - 线程和信号处理之间交互 Interactions between threads and signal handling

#### 关键概念: 线程安全

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#### **Crucial concept: Thread Safety**

- 从线程调用的函数必须是线程安全的 Functions called from a thread must be *thread-safe*
- *定义*:函数是线程安全的,只要它在从多个线程同时调用时总是产生正确的结果 *Def:* A function is *thread-safe* iff it will always produce correct results when called simultaneously from multiple threads.
- 线程不安全函数的分类: Classes of thread-unsafe functions:
  - 类1: 不保护共享变量的函数 Class 1: Functions that do not protect shared variables
  - 类2: 跨多个调用保持状态的函数 Class 2: Functions that keep state across multiple invocations
  - 类3:返回指向静态变量的指针的函数 Class 3: Functions that return a pointer to a static variable
  - 类4:调用线程不安全函数的函数 Class 4: Functions that call threadunsafe functions

#### 线程不安全函数(类1)

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#### **Thread-Unsafe Functions (Class 1)**

- 未能保护共享变量 Failing to protect shared variables
  - 修复:使用P和V信号量操作(或互斥锁) Fix: Use *P* and *V* semaphore operations (or mutex)
  - 示例: goodcnt.c Example: goodcnt.c
  - 问题:同步操作会降低代码速度 Issue: Synchronization operations will slow down code

#### 线程不安全函数(类2)

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#### **Thread-Unsafe Functions (Class 2)**

- 跨多个函数调用依赖持久状态 Relying on persistent state across multiple function invocations
  - 示例:依赖于静态状态的随机数生成器 Example: Random number generator that relies on static state

```
static unsigned int next = 1;
/* rand: return pseudo-random integer on 0..32767 */
int rand(void)
    next = next*1103515245 + 12345;
    return (unsigned int) (next/65536) % 32768;
/* srand: set seed for rand() */
void srand(unsigned int seed)
    next = seed;
```

#### 线程安全随机数生成器

#### **Thread-Safe Random Number Generator**

- 传递状态作为参数的一部分 Pass state as part of argument
  - 从而消除静态状态 and, thereby, eliminate static state

```
/* rand_r - return pseudo-random integer on 0..32767 */
int rand_r(int *nextp)
{
    *nextp = *nextp*1103515245 + 12345;
    return (unsigned int) (*nextp/65536) % 32768;
}
```

■ 结论: 使用rand\_r的程序员必须保持种子 Consequence: programmer using rand\_r must maintain seed

#### 线程不安全函数(类3)

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#### **Thread-Unsafe Functions (Class 3)**

- 返回指向静态变量的指针 Returning a pointer to a static variable
- 修复: 重写函数,以便调用方传递 变量地址以存储结果 Fix: Rewrite function so caller passes address of variable to store result
  - 需要更改调用者和被调用者
     Requires changes in caller and callee
- 修复2: 用互斥锁包装函数 Fix 2: Wrap function with mutex
  - 调用方仍需更改 Caller still has to be changed
  - 可以保留旧函数 Can preserve old function
  - 函数可能成为瓶颈 Function may become a bottleneck

#### 线程不安全函数(类4)

## The state of the s

#### **Thread-Unsafe Functions (Class 4)**

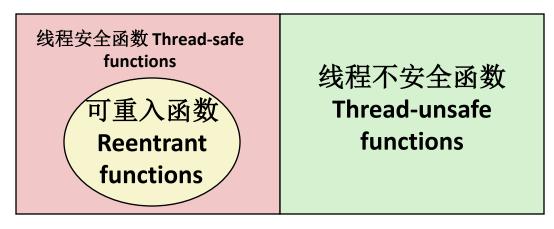
- 调用线程不安全函数 Calling thread-unsafe functions
  - 调用一个线程不安全函数会使调用它的整个函数不安全 Calling one thread-unsafe function makes the entire function that calls it thread-unsafe
  - 修复:修改函数,使其仅调用线程安全函数 Fix: Modify the function so it calls only thread-safe functions ©

#### 可重入函数 Reentrant Functions



- 定义: 当且仅当函数被多个线程调用时不访问共享变量,则该函数是*可重入*的 Def: A function is *reentrant* iff it accesses no shared variables when called by multiple threads.
  - 线程安全函数的重要子集 Important subset of thread-safe functions
    - 不需要同步操作 Require no synchronization operations
    - 使类2函数线程安全的唯一方法是使其可重入(例如rand\_r) Only way to make a Class 2 function thread-safe is to make it reentrant (e.g., rand\_r)

#### 全部函数 All functions



### 线程安全的库函数

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#### **Thread-Safe Library Functions**

- 标准C语言库(K&R教材后面)中的大多数函数都是线程安全的 Most functions in the Standard C Library (at the back of your K&R text) are thread-safe
  - 示例: malloc、free、printf、scanf Examples: malloc, free, printf, scanf
  - 例外: strtok、rand、ctime Exceptions: strtok, rand, ctime
- POSIX添加了更多的异常,但也添加了不安全函数的可重入版本 POSIX adds more exceptions, but also reentrant versions of unsafe functions

线程不安全函数 Thread-unsafe function	Class	可重入版 Reentrant version
asctime	3	strftime
ctime	3	strftime
gethostbyaddr	3	getnameinfo
gethostbyname	3	getaddrinfo
inet_ntoa	3	getnameinfo
localtime	3	localtime_r
rand	2	rand_r

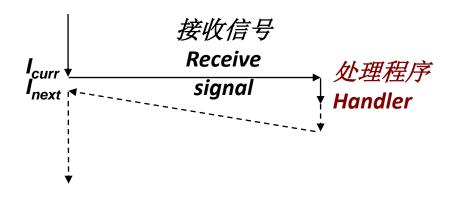
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### 信号处理回顾 Signal Handling Review





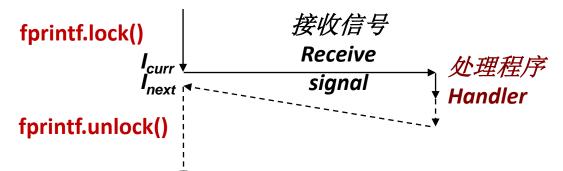
#### ■ 动作 Action

- 信号可以发生在程序执行的任何点 Signal can occur at any point in program execution
  - 除非信号被阻塞 Unless signal is blocked
- 信号处理程序在同一个线程内运行 Signal handler runs within same thread
- 必须运行到完成,然后返回到正常的程序执行 Must run to completion and then return to regular program execution

### 线程/信号交互

## The state of the s

### **Threads / Signals Interactions**

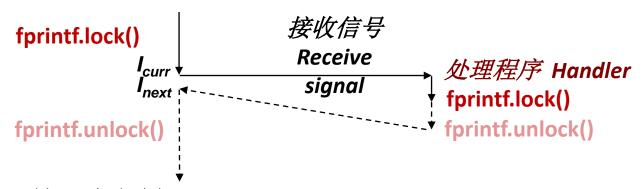


- 很多库函数有内部锁 Many library functions have internal locking
  - 为了保护隐藏状态(避免第一类线程不安全) To protect hidden state (avoid being class 1 thread-unsafe)
  - malloc
    - 释放列表 Free lists
  - fputs, fprintf, snprintf
    - 以便从多个线程的输出不会交错 So that outputs from multiple threads don't interleave
    - 内部使用malloc Internal use of malloc
- 不使用这些库函数的处理程序没有问题 OK for handler that doesn't use these library functions

#### 有问题的线程/信号交互

### - CARRY

#### **Bad Thread / Signal Interactions**



- 如果以下情况会怎样: What if:
  - 当库函数保持加锁时接收信号 Signal received while library function holds lock
  - 处理程序调用同样(或相关)库函数 Handler calls same (or related) library function
- 死锁! Deadlock!
  - 信号处理程序不能继续直到获得锁 Signal handler cannot proceed until it gets lock
  - 主程序不能继续直到处理程序完成 Main program cannot proceed until handler completes
- 关键点 Key Point
  - 线程采用对称并发 Threads employ symmetric concurrency
  - 信号处理是异步的 Signal handling is asymmetric

#### 处理线程/信号交互

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#### Handling Thread/Signal Interactions

- 临界区周围阻塞信号 Block signals around critical sections
  - pthread\_sigmask函数类似sigprocmask, 但是仅影响正调用的线程 pthread\_sigmask like sigprocmask, but only affects calling thread
- 专用于信号处理的线程 Dedicate a thread to signal handling
  - 循环调用sigsuspend()或sigwaitinfo() Loop calling sigsuspend() or sigwaitinfo()
  - 所有其他线程阻塞所有信号 All other threads block all signals
  - 信号处理线程可以使用异步信号不安全函数 Signal handling thread can use async-signal-unsafe functions
    - 因为我们知道信号只能在sigsuspend()期间传递 Because we know signals will only be delivered during sigsuspend()

### 线程小结 Threads Summary



- 线程为编写并发程序提供了另一种机制 Threads provide another mechanism for writing concurrent programs
- 线程越来越受欢迎 Threads are growing in popularity
  - 比进程开销小 Somewhat cheaper than processes
  - 易于在线程之间共享数据 Easy to share data between threads
- 然而,共享的便捷性有代价: However, the ease of sharing has a cost:
  - 易于引入细微的同步错误 Easy to introduce subtle synchronization errors
  - 小心对待线程! Tread carefully with threads!
- 有关详细信息: For more info:
  - "Posix线程编程" D. Butenhof, "Programming with Posix Threads", Addison-Wesley, 1997