

Rootfinding with Chebyshev Polynomials in 2 Dimensions

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Outline

- 1 The Problem
- 2 What are Chebyshev Polynomials and why use them?
- 3 The Algorithm
- 4 Results

1 The Problem

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The Problem

Global 2-D Rootfinding Problem

We want to find all solutions to

$$\begin{pmatrix} f(x, y) \\ g(x, y) \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

in a given bounded domain Ω

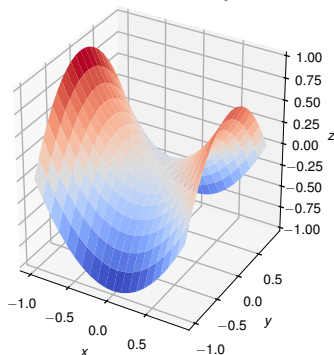
The Big Picture: `chebtools`

- `chebtools` is a C++ library for working with Chebyshev expansions developed by Ian Bell
- Inspired by the Matlab library `chebfun`
- Solving this problem will be a significant feature for `chebtools`
- With a higher level Python interface, `chebtools` could be useful for a wide range of users

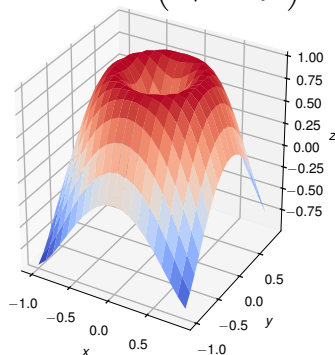
Example

$f(x, y) = x^2 - y^2$ and $g(x, y) = \sin\left(\pi\sqrt{x^2 + y^2}\right)$ with the square domain $\Omega = [-1, 1]^2$

Surface of $x^2 - y^2$



Surface of $\sin\left(\pi\sqrt{x^2 + y^2}\right)$



Local Methods May Not Be Good For Global Rootfinding

There are actually infinitely many roots outside Ω in our example. Local methods may converge to roots outside the domain of interest.

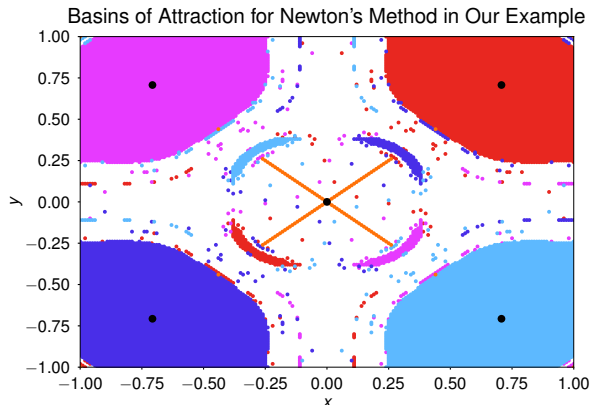


Figure: Initial guesses in white areas did not converge to roots in Ω

A Need For a Global Method

Our example illustrates a few lessons

- Many iterative and local methods like Newton's method can only guarantee convergence to a root if the initial guess is sufficiently close
- Sufficiently close depends on the problem
- This may be extremely close for some roots like $(0,0)$ in our example

Goal:

To develop a truly global rootfinding method

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What are Chebyshev polynomials?

Chebyshev polynomials

$$T_n(x) = \cos(n \arccos(x)), \quad x \in [-1, 1]$$

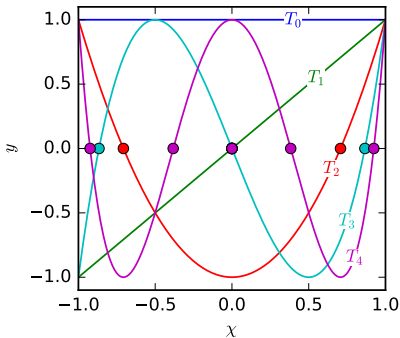
Orthogonal under a weighted inner product:

$$\int_{-1}^1 T_n(x) T_k(x) w(x) dx = 0$$

when $n \neq k$
and $w(x) = \frac{1}{\sqrt{1-x^2}}$

Numerically stable for interpolating functions

Figure: First 5 Chebyshev Polynomials



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2-D Interpolation

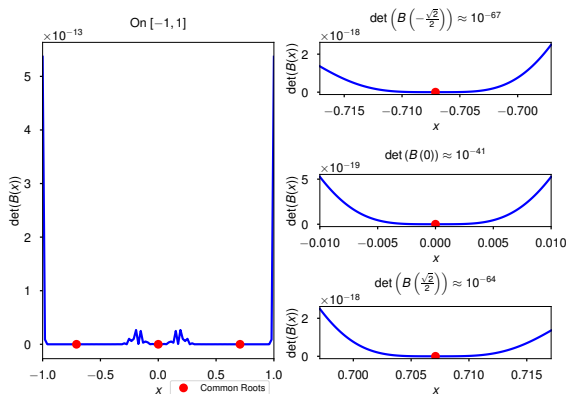
Idea:

- Pick point of maximum error
- Do 1-D interpolations in x and y directions

Bézout Matrix Polynomials

We create a matrix polynomial $B(x)$ from our Chebyshevs

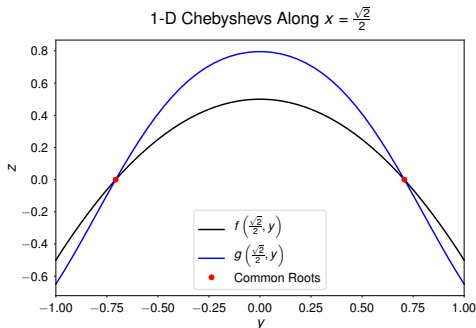
- $B(x)$ is a matrix with polynomial entries
- $\det(B(x)) = 0 \iff$ common roots along the specific x value
- Solving $\det(B(x)) = 0$ is a **matrix polynomial eigenvalue problem**



1-D Rootfinding and Local Refinement

1-D Rootfinding

- We now have the possible x values for where there are common roots
- We employ a well known 1-D rootfinding method again using Chebyshev Polynomials



Problem: Poor conditioning of matrix polynomial problem

- Need for local refinement of roots
- Refine the roots with Newton's method

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Results:

Functions	chebtools		chebfun	
	Error	Time (s)	Error	Time (s)
$F_1(x, y), F_2(x, y)$	6.97×10^{-32}	0.004268	7.7×10^{-16}	0.522
$G_1(x, y), G_2(x, y)$	6.21×10^{-16}	214.059	2.92×10^{-10}	0.294
$H_1(x, y), H_2(x, y)$	3.24×10^{-16}	195.903	2.77×10^{-11}	0.296

$$F_1(x, y) = T_3(x) - 13T_1(x)$$

$$F_2(x, y) = T_3(y) - 13T_1(y)$$

$$G_1(x, y) = \cos(\pi x)(y - 2)$$

$$G_2(x, y) = (y - .9)(x - 2)$$

$$H_1(x, y) = \cos\left(\pi x - \frac{\pi}{10}\right)(y - 2)$$

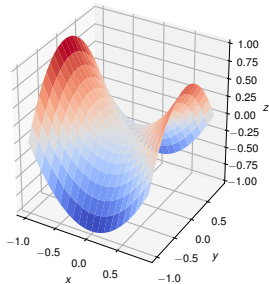
$$H_2(x, y) = (y - .1)(y - .9)(x - 2)$$

Back to Our First Example

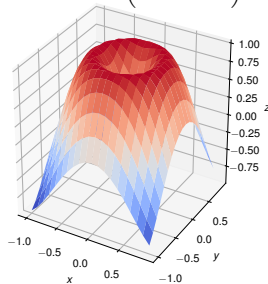
chebfun also struggled

- Found 4 of the roots with an error of 5.55×10^{-16}
- Took 208.8 seconds
- Missed the root at $(0,0)$

Surface of $x^2 - y^2$



Surface of $\sin(\pi\sqrt{x^2 + y^2})$



Conclusions and Future Work

Key Contributions:

- Made significant progress in replicating the 2-D rootfinding algorithm in `chebfun` with some modifications in C++11, which will be fully open source
- Developed ideas and have a strategy for extending the algorithm to non-rectangular domains

Future Work:

- Further develop ideas on non-rectangular domains and subdivision strategies
- Introduce GPU/parallel computing to the rootfinding process

Other Contributions while at NIST:

- Idea for using Gram-Schmidt process to create orthogonal terms for developing equations of state

Acknowledgements

- Dr. Ian Bell for the mentorship and guidance
- Dr. Bradley Alpert for the lively discussions and brainstorming
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- [3] L. N. Trefethen, *Approximation Theory and Approximation Practice*, SIAM, Philadelphia, 2013.