Algorithm 1 dijkstra GPU SSSP

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Input: G(V, E), source vertex s;
Output: dist(v), (v \in V), the weight of the shortest path from s to v;
 1:
 2: function initial(s, V)
        for each v \in V do
 3:
            dist(v) \leftarrow +\infty;
                                                                              \triangleright initialize dist to positive infinity;
 4:
        end for
 5:
 6:
        dist(s) \leftarrow 0;
                                                                                    \triangleright set the source distence to 0;
 7: end function
 9: function dijkstraCudaFunc(G(V, E), dist, predist) > G(V, E), the initially distance array dist, a
    temporary distance array predist;
        u0 \leftarrow threadId;
10:
                                                                                                \triangleright get the thread id;
        offset \leftarrow blockDim;
                                                                         ▶ get the number of threads in a block;
11:
        flag \leftarrow (\_shared\_\_memory) 1;
                                                                                  \triangleright whether the dist has changed;
12:
13:
        while true do
14:
            if flag = 0 then
15:
               break;
16:
            end if
17:
            flag \leftarrow 0;
18:
19:
20:
            u \leftarrow u0;
            while u < |V| do
21:
22:
               if dist(u) is not modified then

    this IF can speedup;

                    continue;
23:
                end if
24:
               for each (u, v, w) \in E do
25:
                    atomicMin(\&predist(v), dist(u) + w);
                                                                     ▶ use the atomic opt to exclusive mutually;
26:
27:
               end for
               u \leftarrow (u + offset);
                                                                                                 ▷ reuse the thread;
28:
            end while
29:
30:
            \_syncthreads();
                                                                    ▶ synchronize all threads in the same block;
31:
32:
33:
            u \leftarrow u0:
            while u < |V| do
34:
35:
               if predist(u) < dist(u) then
                   dist(u) \leftarrow predist(u);
36:
                    flag \leftarrow 1;
                                                                                         37:
                end if
38:
                u \leftarrow (u + offset);
39:
40:
            end while
41:
                                                                    ▷ synchronize all threads in the same block;
42:
            \_syncthreads();
43:
        end while
44:
45: end function
```

```
46: 47: initial(s, V);
48: 49: host\_to\_device(dist), host\_to\_device(G(V, E)); \qquad \triangleright \text{ copy the } dist \text{ and } G(V, E) \text{ from main memory to } GPU \text{ memory};
50: 51: dijkstraCudaFunc(); \qquad \qquad \triangleright \text{ call the CUDA kernal};
52: device\_to\_host(dist); \qquad \qquad \triangleright \text{ copy the } dist \text{ back};
53: 54: \textbf{return } result
```