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Now that we know the difference between the pin numbering systems, we can write a simple program utilizing the GPIO pins.

WiringPI code Examples

First off when compiling, do this:

If your code file was blink.c then save as **blink.c** and compile it with the following command:

```
$ gcc -o blink blink.c -lwiringPi
```

For the following examples, specifically notice how you set pins as inputs/outputs, select pins, and read pins. Its actually very intuitive. We also recommend using the internet to find other examples if necessary.

Code Example 1: This causes an LED to blink

blink.c

```
#include <stdio.h>
#include <wiringPi.h>
#define PIN0 0
int main(void)
    printf("Raspberry Pi blink\n");
    if (wiringPiSetup() == -1)
        return 1;
    pinMode(PINO, OUTPUT); // Set wiringPi pin 0 (i.e. pin #11 on
the Pi) to output mode
    while(1) {
        digitalWrite(PINO, 1); // Send logical high to pin 0
        delay(500);
                               // Wait 500ms
        digitalWrite(PINO, 0); // Send logical low to pin 0
        delay(500);
    }
    return 0:
```

Code Example 2: This uses a button to swap LED states

button.c

```
* button.c:
#include <stdio.h>
#include <wiringPi.h>
#define LED0
                0
#define LED1
                1
#define LED2
#define BUTTON 3
int main (void)
// Enable the on-goard GPIO
 wiringPiSetup ();
  pinMode (BUTTON, INPUT) ;
  pinMode (LED0, OUTPUT) ;
  pinMode (LED1, OUTPUT) ;
  pinMode (LED2, OUTPUT) ;
                                      // LED0 off
  digitalWrite (LED0, LOW) ;
digitalWrite (LED1, HIGH) ;
                                       // LED1 on
                                        // LED2 off
  digitalWrite (LED2, LOW) ;
  for (;;)
  {
    if (digitalRead (BUTTON) == LOW) // Swap LED states
      digitalWrite (LED1, LOW) ;
      digitalWrite (LED2, HIGH) ;
      while (digitalRead (BUTTON) == LOW)
        delay(1);
      digitalWrite (LED1, HIGH) ;
      digitalWrite (LED2, LOW) ;
    delay (1);
  return 0 ;
```

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Last update: **2016/10/03 21:10**