

EX: NO: 12

27.10.25

IMPLEMENT A DEEP CONVOLUTIONAL GAN TO GENERATE COMPLEX COLOR IMAGES

AIM

To implement a deep convolutional gan to generate complex color images.

Objective

To understand GAN architecture

To train model on color image dataset

To observe training dynamics and quality of generating images.

Pseudocode

import libraries and set device

load CIFAR-10 dataset, normalize to

$[-1, 1]$, create dataloader

Define DCGAN generator: series of conv transpose 2D, Batch Normalized, ReLU

Initialize weights (Normal with mean = 0, std = 0.02)

define loss & optimizers

for each epochs

a) Train discriminator real images

b) Train generator to fool discriminator

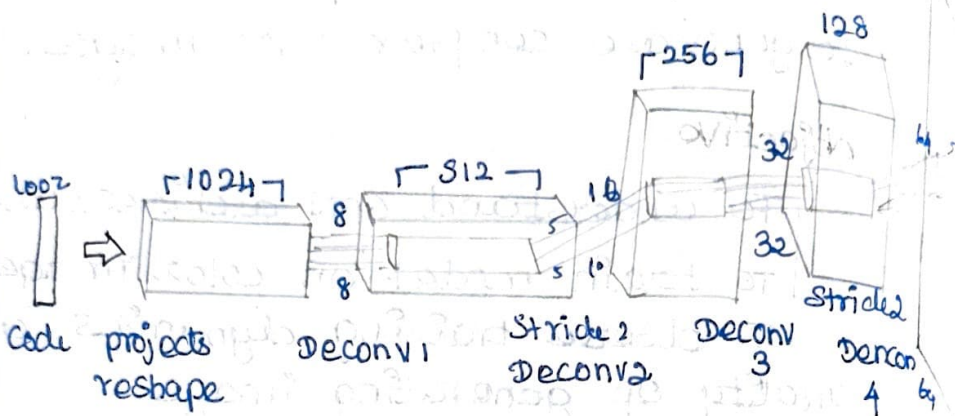
c) save generator batch of generator image for visualization.

Monitor losses

Observation

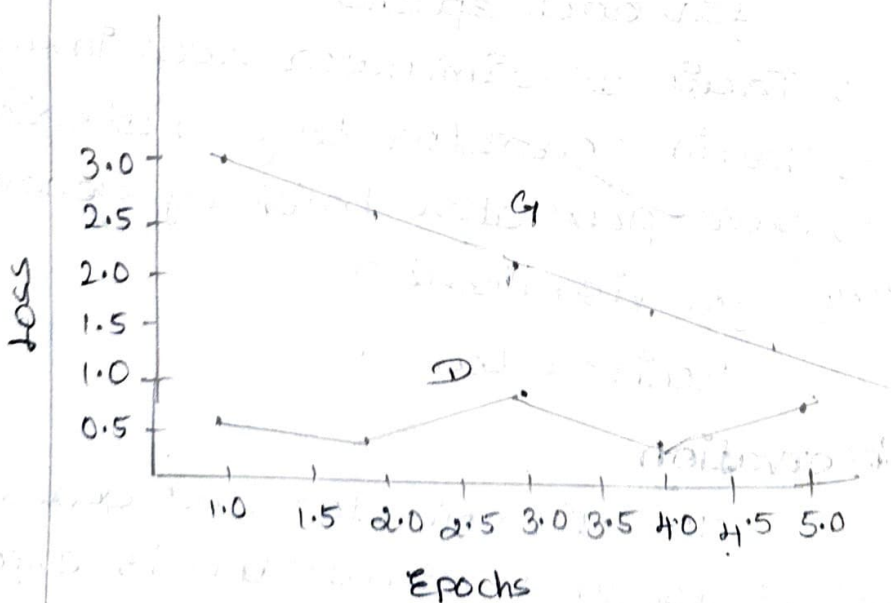
The discriminator and generator losses usually fluctuate. This is expected in GAN training as one improves, other responds.

DCGAN architecture



Output

Epoch [1/5]	LOSS D : 0.4934	LOSS G : 2.4012
Epoch [2/5]	LOSS D : 0.5894	LOSS G : 2.66182
Epoch [3/5]	LOSS D : 0.7406	LOSS G : 2.3580
Epoch [4/5]	LOSS D : 0.5590	LOSS G : 2.0222
Epoch [5/5]	LOSS D : 1.3862	LOSS G : 1.5855



initially generator images are noisy
random patterns

over epochs starts showing structure
(colours, shape)

saving images each epoch helps
visualize progression from noise \rightarrow structure
 \rightarrow clearer images.



Result

Successfully implemented DCGAN.
Eg. 1

UNDERSTANDING THE ARCHITECTURE OF
PRE-TRAINED MODEL

Aim

To understand the architecture of pre-trained model.

Objective

To learn the concept of transfer learning and how it reduces training time.

To explore the layer wise architecture of pretrained models such as VGG16, AlexNet

To identify the role

To visualize how these models extract features.

pseudocode

import libraries

Load a pre-trained model

Model Display it

observe : input and output shapes

layers names, types and no. of parameter

visualize the architecture using

Load a sample input image and

preprocess it for model

pass image through the model and

get prediction

optionally visualize activation.

output

Linear (in-features = 2048, out-features = 10)

bias = True)

VGA

(features): sequential (

(0): conv2d (3, 64, kernel_size = (3, 3), stride = (1, 1), padding = (1, 1))

(1): ReLU (inplace = True)

(2): conv2d (64, 64, kernel_size = (3, 3), stride = (1, 1), padding = (1, 1))

(3): ReLU (inplace = True)

(4): maxpool2d (kernel_size = 2, stride = 2, padding = 0, dilation = 1, cell = node = false)

(30): maxpool2d (kernel_size = 2,

stride = 2, padding = 0, dilation = 1, cell = node = false)

(avg pool) = Adaptive Avg pool (output_size = (1, 1))

(0): Linear

(1): ReLU (inplace = True)

(2): Dropout (p = 0.5, inplace = false)

Total Trainable parameters : 138357544

Observation

The pre-trained model contains millions of parameter spread across convolutional of dense layers.

Early layer extract edges and texture while deeper layers capture high level feature such as object parts.

The use of pre-trained weights drastically reduces training time and improves model accuracy for new tasks.

Result

Successfully Implemented pre-trained model.